

# Modeling measurement data

Stat 340: Bayesian Statistics

1. Inference for  $\mu$  with known  $\sigma$   
(Problem topics 1-5)

## Change from 2016 to 2020

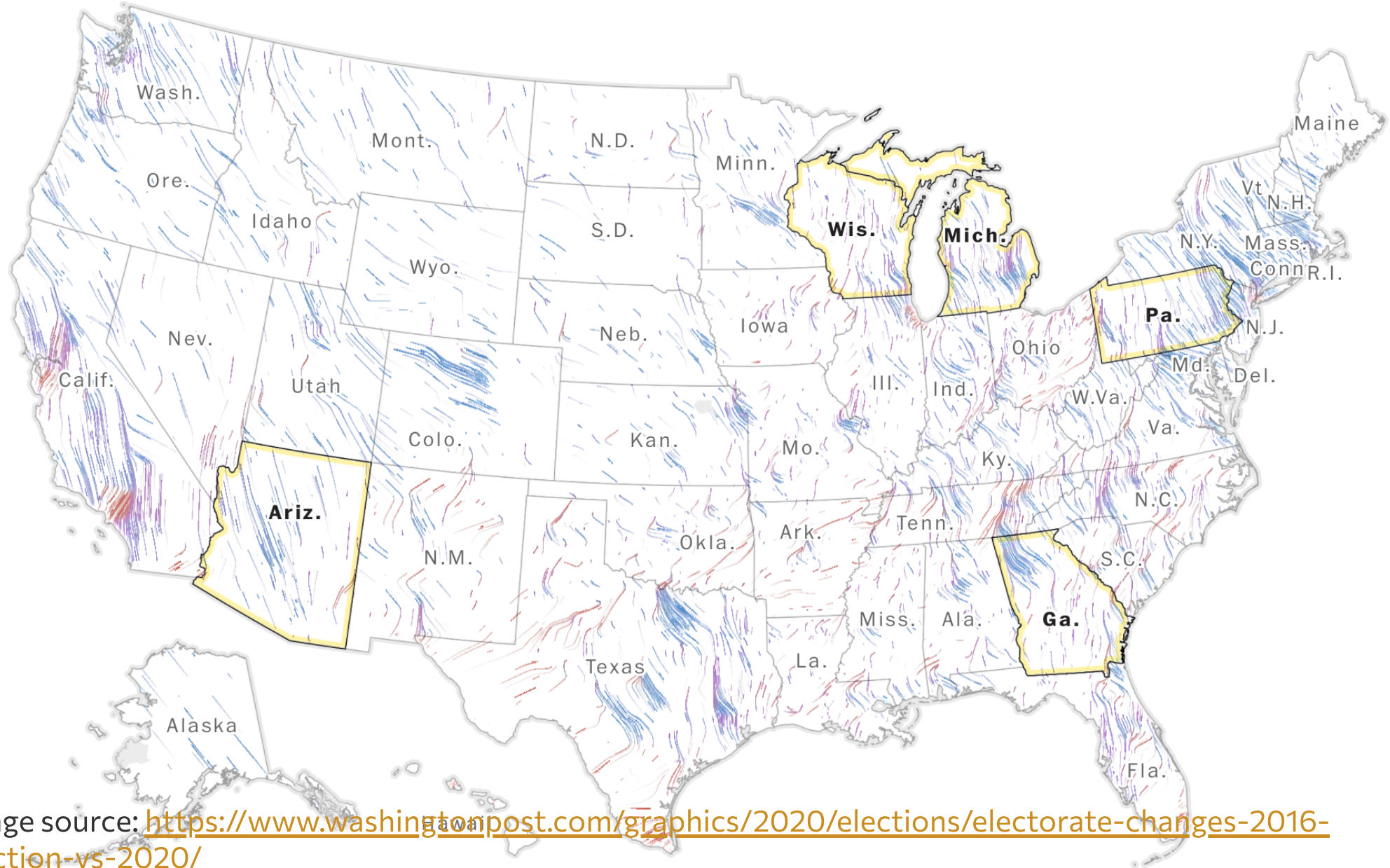


Image source: <https://www.washingtonpost.com/graphics/2020/elections/electorate-changes-2016-election-vs-2020/>

# Change in the democratic vote

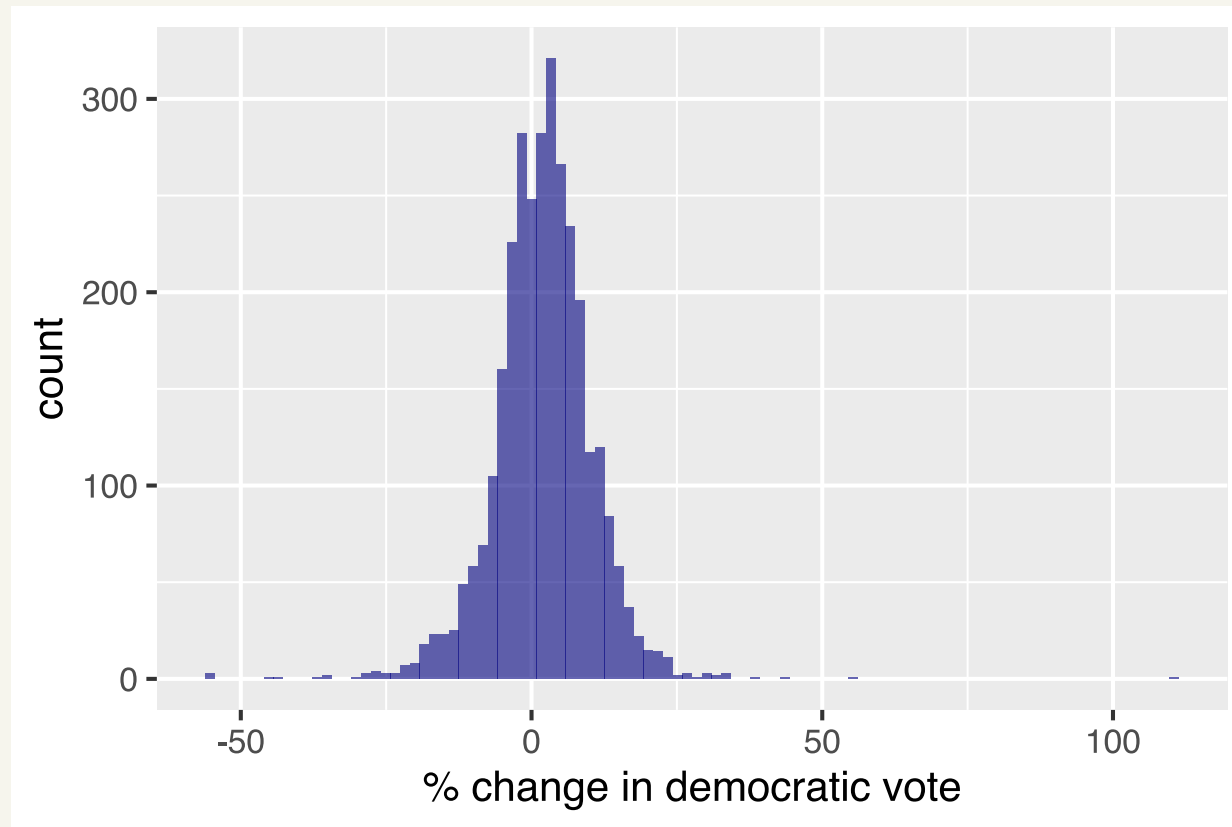
- How did democratic share of the two party vote change from 2016 to 2020?
- MIT Election Data and Science Lab has county-level election results
- We'll look at the percent change in the two-party vote

$$Y_i = 100 (A_i / B_i - 1)$$

$A_i$  = % of two-party vote cast for democrats in 2020

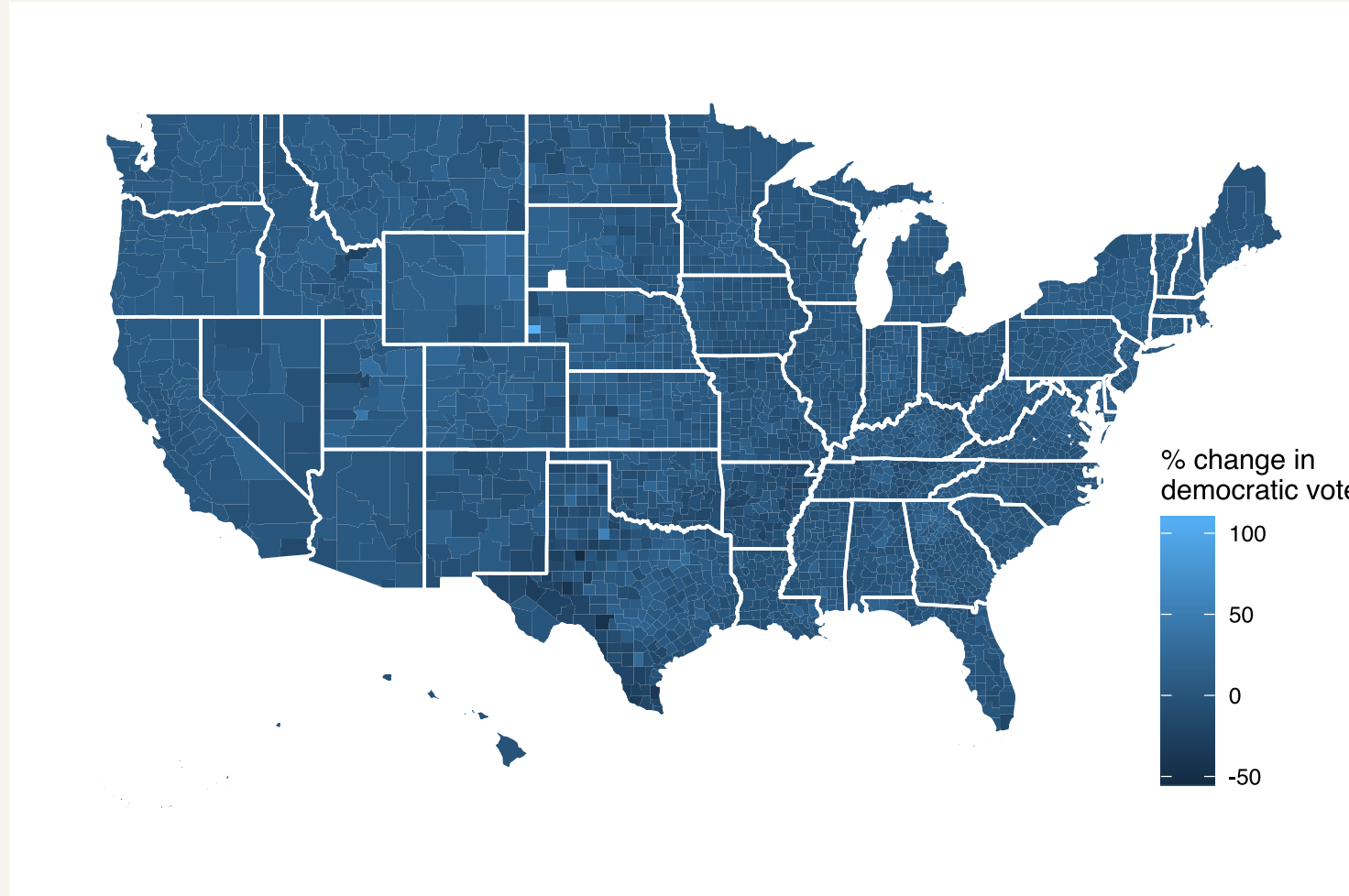
$B_i$  = % of two-party vote cast for democrats in 2016

# EDA

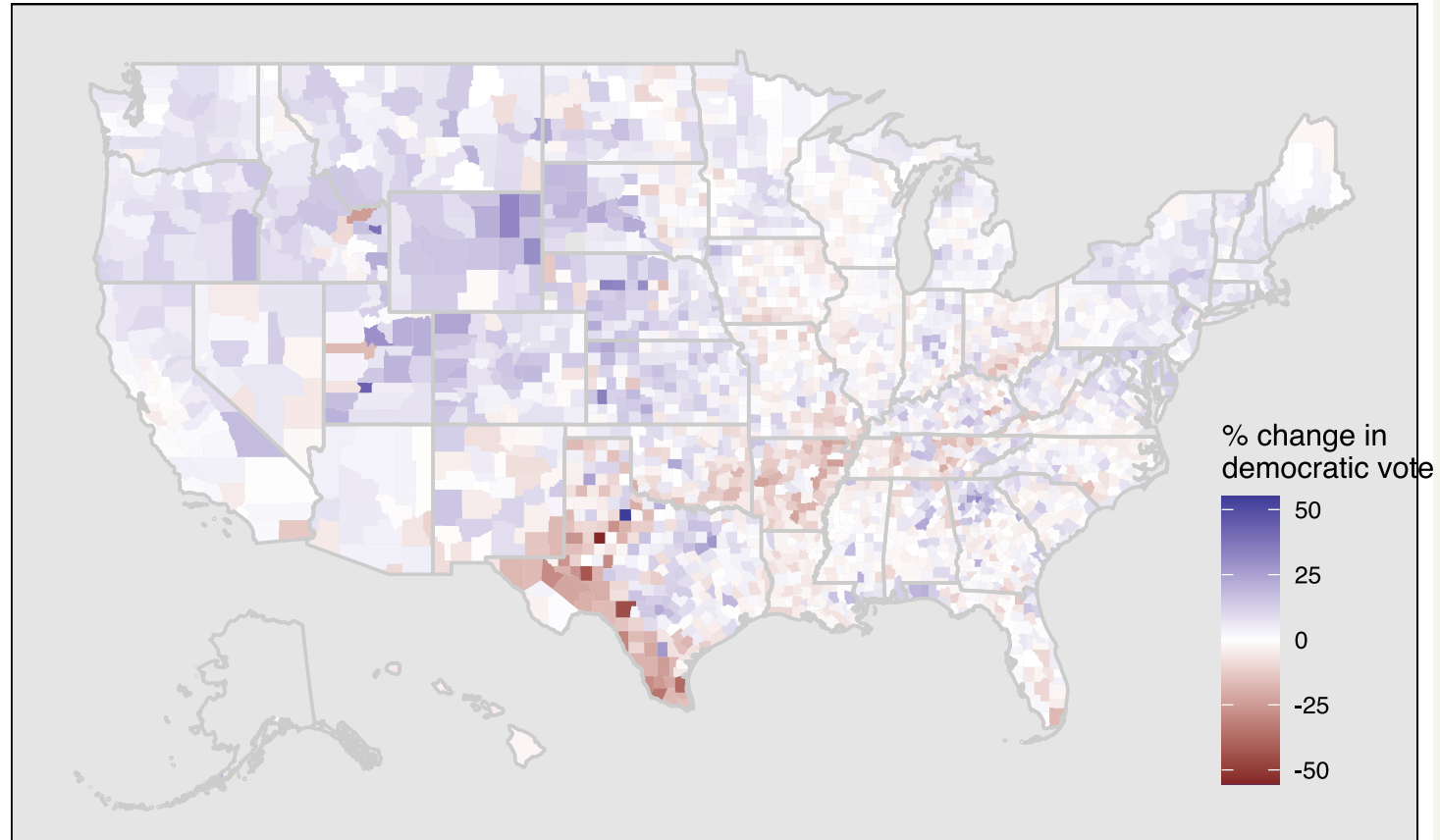


- Normal model seems reasonable
- Potential outliers

# EDA

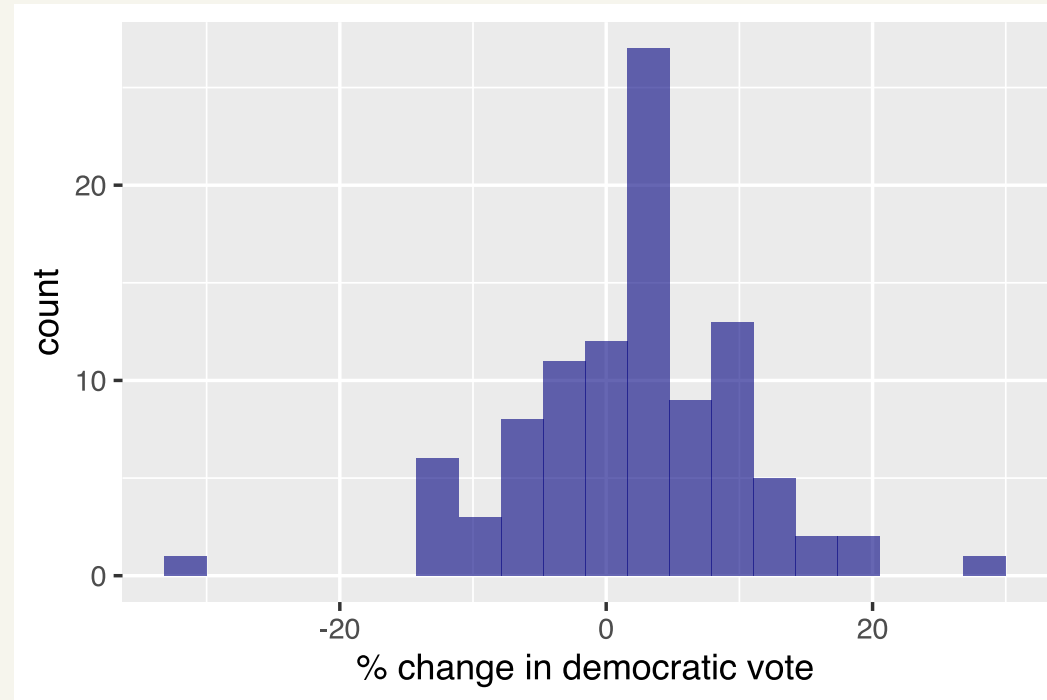


# Without outliers



# Hypothetical sample

We'll work with a hypothetical sample of 100 counties





# Your turn 1

Derive the likelihood if we assume  $Y_i \stackrel{\text{iid}}{\sim} \mathcal{N}(\mu, \sigma)$

Normal PDF:

$$f(y) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y-\mu)^2}{2\sigma^2}\right), \quad -\infty < y < \infty, \quad -\infty < \mu < \infty, \quad \sigma > 0$$

02:30

# Your turn 2

For simplicity, assume that  $\sigma = 8$ .

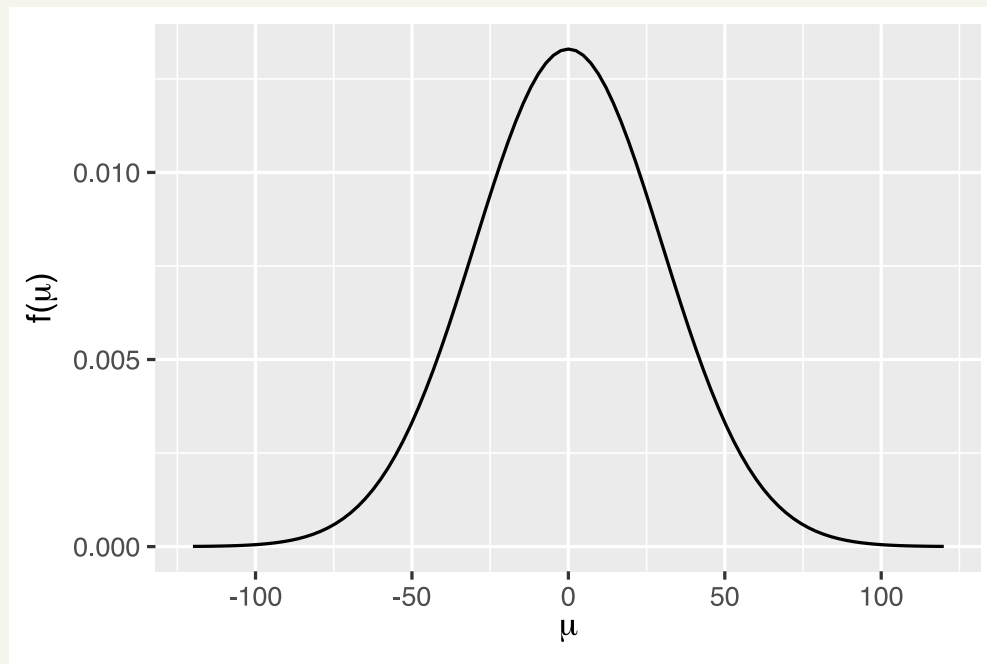
Prior for  $\mu$ :  $\mu \sim \mathcal{N}(\mu_0, \sigma_0)$

Derive the posterior for  $\mu$ .

03:00

# Using a weak prior

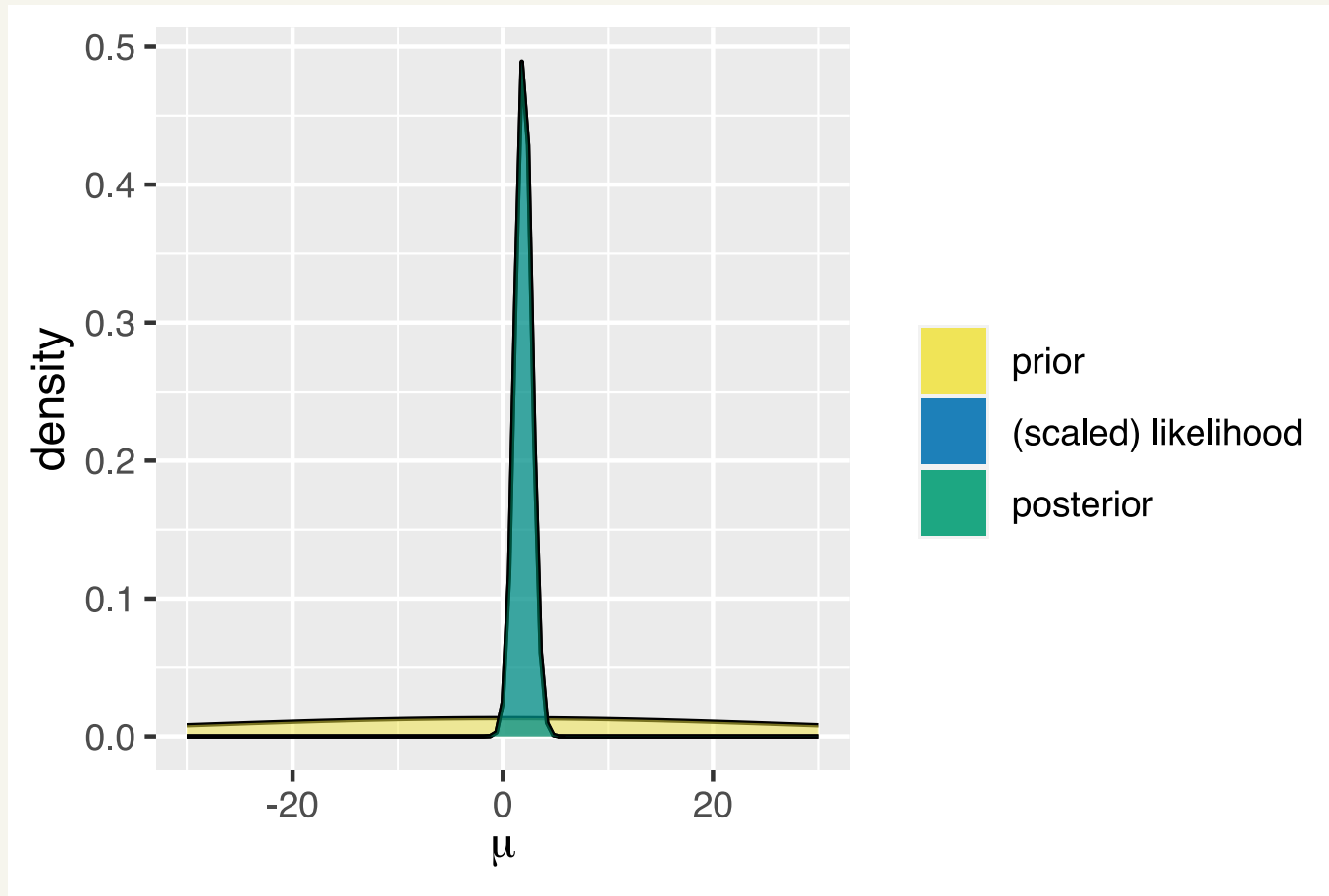
Suppose we thought the election was a toss up, then a weakly informative prior would be reasonable



$$\mu \sim \mathcal{N}(0, 30)$$

- swings to either the left or right possible
- more likely to be closer to 0 (no change) than an extreme swing

# Posterior



# Bayesian hypothesis tests

How do we test  $H_0 : \mu \leq 0$  vs.  $H_1 : \mu > 0$ ?

How do we test  $H_0 : \mu = 0$  vs.  $H_1 : \mu > 0$ ?

# Posterior predictive checks

```
sigma <- 8    # known sigma
n      <- 100  # sample size
post_mean <- 1.96 # posterior mean
post_sd   <- 0.64 # posterior sd
S <- 1000    #number of sims

# First draw S mus from the posterior
mu_draws <- rnorm(S, post_mean, post_sd)
y_draws  <- matrix(nrow = S, ncol = 100)

# Then, simulate 20 observations for each mu
for(i in 1:S) {
  y_draws[i,] <- rnorm(100, mu_draws[i], sigma)
}
```

# Posterior predictive checks

We need to calculate some testing function,  $T(\tilde{y})$ , on each replicated data set

```
y_bar_sims <- rowMeans(y_draws)
```

