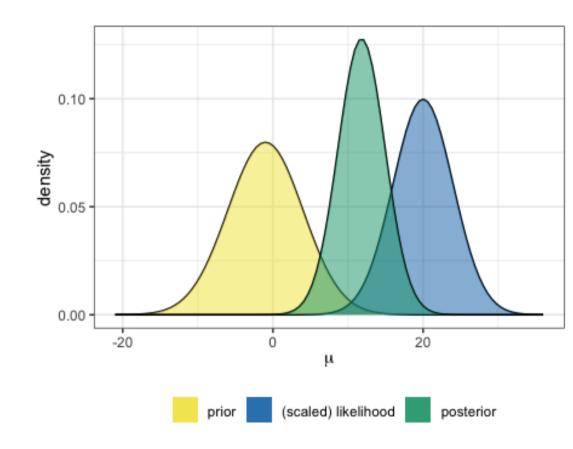
Using a continuous prior distribution

Stat 340: Bayesian Statistics



- 1. Continuous prior
- 2. Posterior analysis
- 3. Prediction
- (Problem topics 1-4)

Blindsight design, redux

Data: NNNBBNNNBNNNNN(14 Ns; 3 Bs)

Data model (likelihood):

Some true proportion of guesses, p

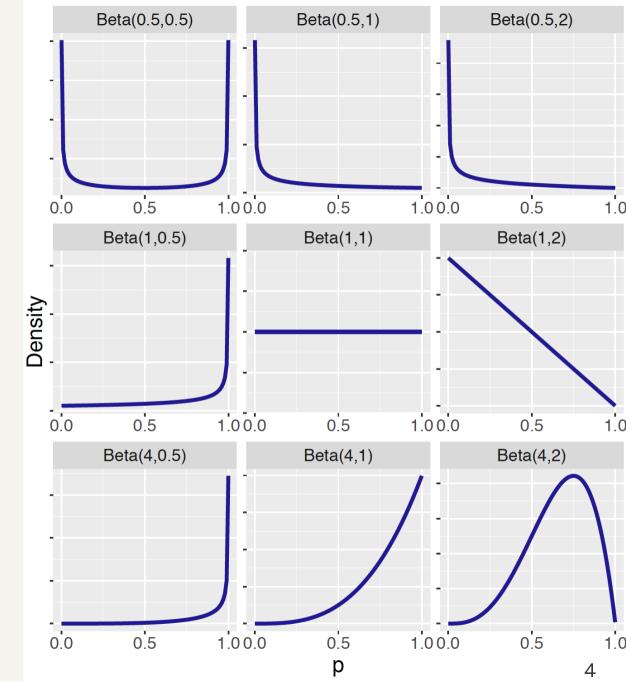
Toss a coin with probability of heads, p

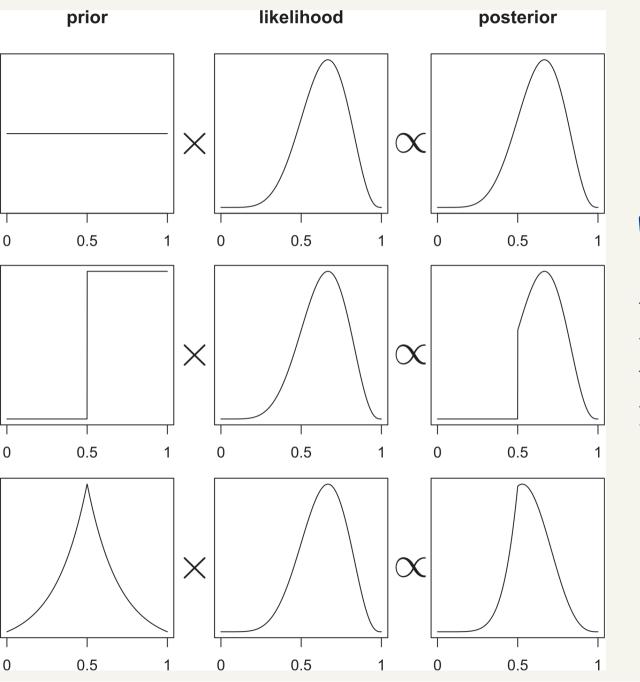
Belief about p:

Uniform over (0, 1)

Beta distribution

- $ullet f(x|a,b) = rac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} x^{a-1} (1-x)^{b-1}$
- Parameter space: a>0, b>0
- Support: 0 < x < 1





"The prior is proportional to the prior times the likelihood"

Your turn 1

- Work with your neighbors
- Work through the R code to simulate kernels of the beta distribution
- You can copy/paste the code from the course webpage
- Develop your understanding of the kernel of a distribution

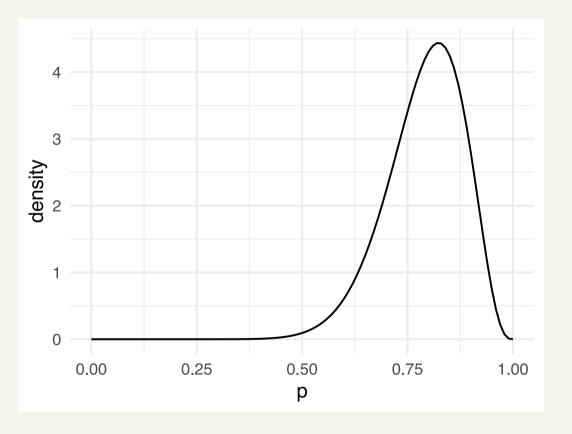
Your turn 2

- Work with your neighbors
- Derive the posterior
- Are you working with a conjugate family?

Posterior analysis

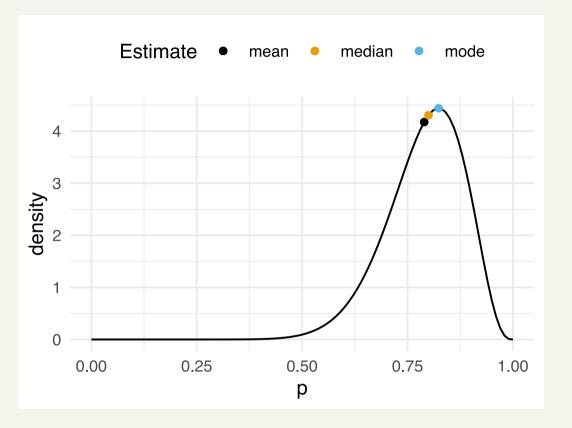
To a Bayesian, the best information one can ever have about θ is to know the posterior density.

Christensen, et al; BayesianIdeas and Data Analysis, p. 31

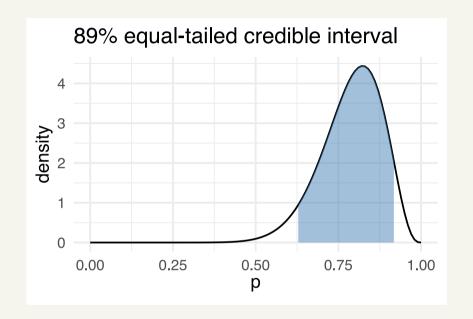


Point estimates

- Posterior mean
- Posterior median
- Posterior mode
 i.e. maximum a posteriori (MAP)
 estimate



Credible intervals

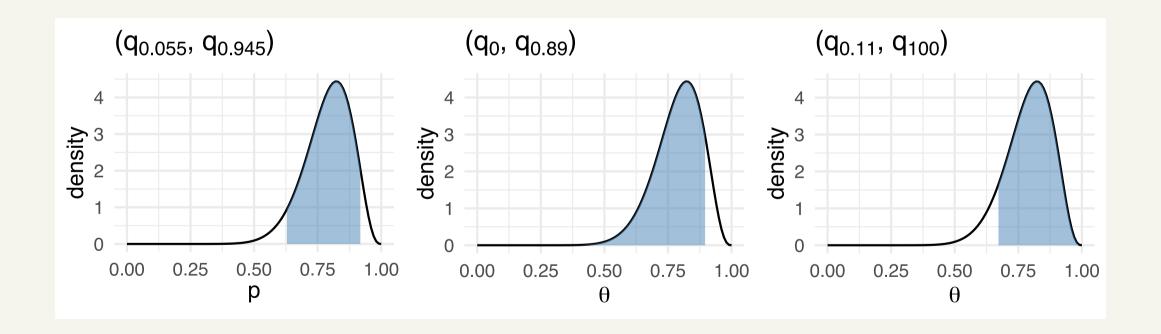


```
# q*() functions calculate quantiles from the specified distribution c(lower = qbeta(0.055, 15, 4), upper = qbeta(1 - 0.055, 15, 4))
```

```
## lower upper ## 0.6288166 0.9177940
```

Credible intervals are not unique

Here are three 89% credible intervals

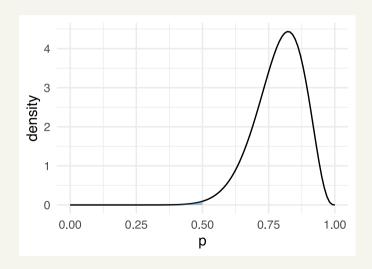


Testing a hypothesis

Suppose the researchers were interested in testing

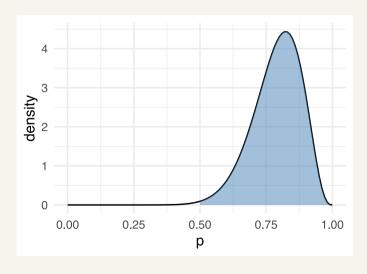
$$H_0: p \le 0.5$$

$$P(p \le 0.5|Y = 14) = 0.004$$



$$H_1: p > 0.5$$

$$P(p > 0.5|Y = 14) = 0.996$$



Predicting a new observation

To make predictions, we need to work with the **posterior predictive** distribution:

$$egin{aligned} f(\widetilde{Y} = \widetilde{y}|Y = y) &= \int_0^1 f(\widetilde{Y} = \widetilde{y}, p|Y = y) dp \ &= \int_0^1 f(\widetilde{Y} = \widetilde{y}|p, Y = y) \pi(p|Y = y) dp \ &= \int_0^1 f(\widetilde{Y} = \widetilde{y}|p) \pi(p|Y = y) dp \end{aligned}$$

Monte Carlo simulation for prediction

Suppose we wish to make predictions for a new set of 20 "guesses" made by PS

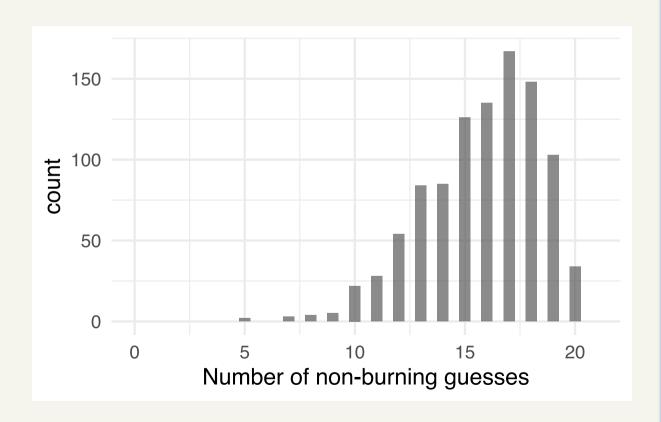
Posterior predictive

$$f(\widetilde{Y}= ilde{y}|Y=14)=\int_0^1 f(\widetilde{Y}= ilde{y}|p)\pi(p|Y=14)dp$$

Integration via simulation:

```
n <- 20  # No. of new binomial trials
S <- 1000 # No. simulations
sim_p <- rbeta(S, 15, 4)
sim_y <- rbinom(S, size = n, prob = sim_p)</pre>
```

Posterior predictive distribution



janitor::tabyl(sim_y)

```
##
    sim_y
             n percent
##
                 0.002
##
                 0.003
##
                 0.004
                 0.005
##
##
                 0.022
       10
##
            28
                 0.028
##
            54
                 0.054
       13
                 0.084
##
           84
##
           85
                 0.085
##
       15 126
                 0.126
##
       16 135
                 0.135
##
       17 167
                 0.167
##
       18 148
                 0.148
##
       19 103
                 0.103
##
           34
                 0.034
       20
```

Prediction intervals

How can we construct an 89% prediction interval?

Put in the most likely values until the probability is at least 0.89

```
post_pred_dsn <- janitor::tabyl(sim_y)[, -2]
LearnBayes::discint(post_pred_dsn, prob = 0.89)</pre>
```

```
## $prob
## [1] 0.902
##
## $set
## [1] 12 13 14 15 16 17 18 19
```

Your turn 3

Let p denote the proportion of U.S. adults that do not believe in climate change. Of 1000 survey respondents, 150 responded that it was "not real at all".

- 1. Using a Beta(1, 2) prior distribution, what is the posterior distribution of p?
- 2. Simulate 1000 draws from the posterior distribution.
- 3. Use your simulated draws to calculate a 93% credible interval equal-tailed for p. Interpret this interval in context.
- 4. Suppose you were to survey 100 more adults. Approximate the probability that at least 20 of the 100 people don't believe in climate change.