# **LigthGBM**

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### **Timetable**

Question List to Chapter 7

**BREAK** 

Jupyter-Notebook
Presentation LightGBM

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# **LightGBM**

- = **light g**radient-**b**oosting **m**achine
- Published 2016
- Free and open-source, https://github.com/Microsoft/LightGBM
- Originally developed by Microsoft
- Won many machine learning competitions
- Faster for data sets with more than 10,000 instances
- Can work in parallel

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# **Background**

- Gradient Boosting Decision Trees build a series of decision trees which correct the losses of the processor.
- For big data set there is a *tradeoff between accuracy and efficiency*: The longer the series of trees the better the accuracy but also the number of computations to fit the trees:
  - Gradient Boosting Decision Trees computational complexities are proportional to the number of features and the number of instances.

### Three special techniques to reduce both:

- Histogram-based building of the decision tree
- Gradient-Based One-Side Sampling (GOSS)
- Exclusive Feature Bundling (EFB)

# Histogram-based decision tree

### **Ordinary Decision Tree:**

- Finding the best split in a decision tree is the most time-consuming part
- The features values has to be pre-sorted for every split.

### Histogram-based decision tree:

- Histogram-based algorithms buckets continuous feature values into discrete bins
- These bins are used to construct histograms during training.
- The histograms are used to find the best split.
- Since the number of bins is much smaller than the number of instances, it is much faster.

In Scikit-learn HistGradientBoostingClassifier and –Regressor use this technique as well.

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# Histogram-based decision tree

Example for building the histogram:

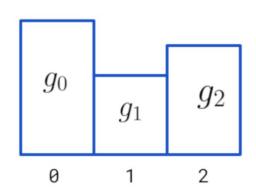
Original data set has 4 instances with continuous parameters:

$$\begin{bmatrix}
1.5 & 0.0 \\
0.0 & 5.5 \\
0.3 & 7.0 \\
5.5 & 8.5
\end{bmatrix}$$

We bucket them into 3 bins. The we get:

$$\left[ egin{array}{ccc} 1 & 0 \ 0 & 1 \ 0 & 2 \ 2 & 2 \ \end{array} 
ight]$$

The residual error = the gradient is stored just for each bin and not for each instance:



Taken from: https://robotenique.github.io/posts/gbm-histogram/

# **Gradient-Based One-Side Sampling (GOSS)**

Down sampling of the data instances

#### Idea:

- Keep those instances with large gradients (than a pre-defined threshold or among the top percentiles)
- Drop only those instances with small gradients randomly

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# **Exclusive Feature Bundling (EFB)**

In real applications usually the feature space is quite sparse.

Many features are almost exclusive, i.e. they rarely take nonzero values simultaneously, for example one-hot-encoded features.

#### Idea:

Bundle such exclusive features

Exclusive Feature Bundling uses an efficient algorithm by transforming the bundling problem into a graph coloring problem and solving this with a greedy algorithm.