Homework 3

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2 Kernel PCA

1. Solution:

Because any principal component w is the eigenvector of $X \cdot X^T$, where columns of X are the n data points. So,

$$(\boldsymbol{X} \cdot \boldsymbol{X}^T) \cdot \boldsymbol{w} = \lambda \boldsymbol{w} \tag{1}$$

where λ is the eigenvalue of matrix $X \cdot X^T$ corresponding to eigenvector w. So we can get that:

$$w = \frac{X \cdot X^{T} \cdot w}{\lambda}$$

$$= X \cdot \frac{X^{T} \cdot w}{\lambda}$$
(2)

Set \boldsymbol{a} to $\frac{\boldsymbol{X}^T \cdot \boldsymbol{w}}{\lambda}$, so we can get the following equation from equation (2).

$$\boldsymbol{w} = \boldsymbol{X} \cdot \boldsymbol{a} \tag{3}$$

Thus, any principal component w can be written as a linear combination of the data points $\{x_i\}_{i=1}^n$.

2. Solution:

From the lecture, I can get the objective of maximizing variance between projected data points ($1^{s}t$ PC vector).

$$\max_{\boldsymbol{w}} \boldsymbol{w}^T (\boldsymbol{X} \cdot \boldsymbol{X}^T) \boldsymbol{w} \tag{4}$$

From previous problem, we can get that every principal component \boldsymbol{w} can be written as a linear combination of the data points, so:

$$\boldsymbol{w} = \boldsymbol{X} \cdot \boldsymbol{a} \tag{5}$$

Replace w in equation (4) with equation (5), we can get the following fomulation:

$$\max_{\boldsymbol{a}} \boldsymbol{a}^T \cdot \boldsymbol{X}^T (\boldsymbol{X} \cdot \boldsymbol{X}^T) \boldsymbol{X} \cdot \boldsymbol{a}$$
$$= \max_{\boldsymbol{a}} \boldsymbol{a}^T \cdot (\boldsymbol{X}^T \boldsymbol{X} \cdot \boldsymbol{X}^T \boldsymbol{X}) \cdot \boldsymbol{a}$$
(6)

Because we can express the matrix G as:

$$G = X^T \cdot X \tag{7}$$

So the objective of maximizing variance between projected data points is:

$$\max_{\boldsymbol{a}} \boldsymbol{a}^T \cdot \boldsymbol{G}^2 \cdot \boldsymbol{a} \tag{8}$$

3. Solution:

The variance of data points in the direction of principle component w is:

$$var = w^T (X \cdot X^T) w \tag{9}$$

Because w is unit vector, so:

$$\boldsymbol{w}^T \cdot \boldsymbol{w} = 1 \tag{10}$$

Given equation (1) and (10), equation (10) can be written as:

$$var = w^{T}(X \cdot X^{T})w = \lambda w^{T} \cdot w = \lambda$$
(11)

From problem 1, we know that:

$$a = \frac{X^T \cdot w}{\lambda} \tag{12}$$

where $X^T \cdot w$ denotes the vector of projections of data points onto the principal component w. From equation (11), the variance of data points in that direction is λ .

Obviously, a is the vector of projections of data points onto the principal component, normalized by the variance of data points in that direction.

4. Solution:

Because the data is not centered, the mean of feature is:

$$\overline{X} = \frac{1}{n} \sum_{i=1}^{n} x_i = \frac{1}{n} \cdot X \cdot 1$$
 (13)

After centering, the new data would be:

$$\mathbf{X}' = \mathbf{X} - \overline{\mathbf{X}}$$

$$= \mathbf{X} - \frac{1}{n} \cdot \mathbf{X} \cdot \mathbf{1}$$
(14)

According to equation (4), (5), (6), we can get a new objective by replacing X in (6) with X'. Equation (5) would be:

$$\boldsymbol{w} = \boldsymbol{X}' \cdot \boldsymbol{a} \tag{15}$$

Therefore, the new objective is:

$$\max_{\boldsymbol{a}} \boldsymbol{a}^{T} \cdot (\boldsymbol{X}^{'T} \boldsymbol{X}^{'} \cdot \boldsymbol{X}^{'T} \boldsymbol{X}^{'}) \cdot \boldsymbol{a}$$
 (16)

From equation (14), we can get:

$$X^{\prime T} \cdot X^{\prime}$$

$$= (X^{T} - \frac{1}{n} \cdot \mathbf{1}^{T} \cdot X^{T}) \cdot (X - \frac{1}{n} \cdot X \cdot \mathbf{1})$$

$$= X^{T} \cdot X - \frac{1}{n} \cdot \mathbf{1}^{T} \cdot X^{T} \cdot X$$

$$- \frac{1}{n} \cdot X^{T} \cdot X \cdot \mathbf{1} + \frac{1}{n^{2}} \cdot \mathbf{1} \cdot X^{T} \cdot X \cdot \mathbf{1}$$

$$= G - \frac{1}{n} \cdot \mathbf{1}^{T} \cdot G - \frac{1}{n} \cdot G \cdot \mathbf{1} + \frac{1}{n^{2}} \cdot \mathbf{1} \cdot G \cdot \mathbf{1}$$
(17)

So the final solution for objective is:

$$\max_{\boldsymbol{a}} \boldsymbol{a}^T \cdot \boldsymbol{G}^{'2} \cdot \boldsymbol{a} \tag{18}$$

where
$$G^{'}$$
 is $G - \frac{1}{n} \cdot \mathbf{1}^{T} \cdot G - \frac{1}{n} \cdot G \cdot \mathbf{1} + \frac{1}{n^{2}} \cdot \mathbf{1} \cdot G \cdot \mathbf{1}$.

3 SVM and Newton's Method

1. Task 3

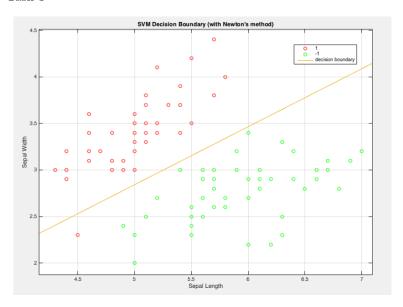


Figure 1: Result Visualization