Winkelbeschleunigung, Halterung leer - NonLinearFit1 **Dataset**: HalterungLeer_2 Function: $(x/1000*g*r_z-M_r)/(I_H+x/1000*(r_z)^2)$ (rad/s \ 7) $Chi^2/doF = 6.1547e-03$ $R^2 = 0.9998$ I H = 3.4888e-03 +/- 3.7380e-05 $\bar{\mathbf{M}}_{\mathbf{r}} = 7.1587e-03 + /- 4.0136e-04$ g = 9.81 (constant) $r_z = 0.0255$ (constant) Winkelbeschleunigung 4∟ 80 ___ 4 260 **Zugmasse (g)**