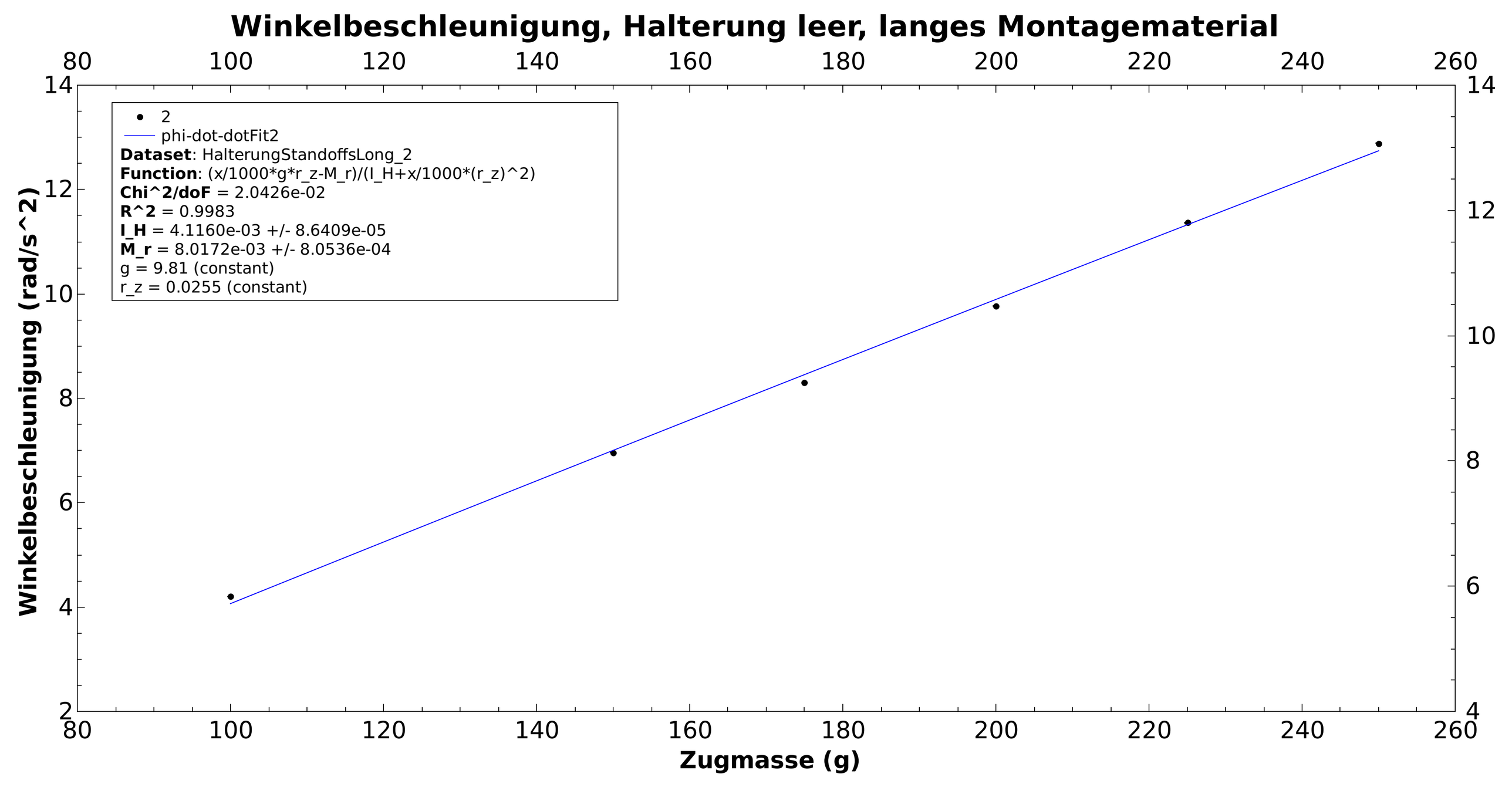
Winkelbeschleunigung, Halterung leer, langes Montagematerial
2
phi-dot-dotFit2
Dataset: HalterungStandoffsLong_2
Function: (x/1000*g*r_z-M_r)/(I_H+x/1000*(r_z)^2)
Chi^2/doF = 2.0426e-02
R^2 = 0.9983
I_H = 4.1160e-03 +/- 8.6409e-05
M_r = 8.0172e-03 +/- 8.0536e-04
g = 9.81 (constant)
r_z = 0.0255 (constant)
Winkelbeschleunigung (rad/s^2)
Zugmasse (g)
80
100
120
140
160
180
200
220
240
260
2
4
6
8
10
12
14