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## Tutorial for Cyber-Physical Systems - Discrete Models Exercise Sheet 9

### Exercise 1: Safety & Liveness

8 Points

The goal of this exercise is that you think carefully about the role of finite trace prefixes for safety and liveness properties.

Consider the categories (a)-(d) of linear-time properties over the set  $AP = \{a, b\}$  below. For each of them, give two examples of properties that fall into this category: a safety property and a liveness property (if such examples exist). Use set notation to express the properties. If no example exists, argue why this is the case.

# △ Careful reading required. △

- (a) A property E is in this category, if for every trace  $\pi = A_0 A_1 A_2 \dots \in (2^{AP})^{\omega}$  with  $\pi \models E$ , it is sufficient to examine a finite prefix  $A_0 A_1 \dots A_n$  of  $\pi$  to determine that  $\pi$  satisfies property E.
- (b) A property E is in this category, if it is **not** sufficient for every trace  $\pi = A_0 A_1 A_2 ... \in (2^{AP})^{\omega}$  with  $\pi \models E$  to examine a finite prefix  $A_0 A_1 ... A_n$  of  $\pi$  to determine that  $\pi$  satisfies property E. Instead, in some cases the whole trace must be examined.
- (c) A property E is in this category, if for every trace  $\pi = A_0 A_1 A_2 \ldots \in (2^{AP})^{\omega}$  with  $\pi \not\models E$ , it is sufficient to examine a finite prefix  $A_0 A_1 \ldots A_n$  of  $\pi$  to determine that  $\pi$  violates property E.
- (d) A property E is in this category, if it is **not** sufficient for every trace  $\pi = A_0 A_1 A_2 \ldots \in (2^{AP})^{\omega}$  with  $\pi \not\models E$  to examine a finite prefix  $A_0 A_1 \ldots A_n$  of  $\pi$  to determine that  $\pi$  violates property E. Instead, in some cases the whole trace must be examined.

#### Exercise 2: Safety-Liveness Decomposition

5 Points

The goal of this exercise is to understand the relation between any LT property and safety and liveness properties, by applying the decomposition theorem.

According to the decomposition theorem, any LT property P can be decomposed into a safety property  $P_{safe}$  and a liveness property  $P_{live}$ , such that the property P is equal to their intersection, i.e.,

$$P = P_{safe} \cap P_{live} .$$

Apply the construction in the proof of the decomposition theorem to find the decomposition for the following properties with  $AP = \{a, b\}$ . Use set notation to express  $P_{safe}$  and  $P_{live}$ .

- $P_1 = \{ A_0 A_1 A_2 \dots \in (2^{AP})^{\omega} \mid \forall i \in \mathbb{N}. (a \in A_i \to b \in A_{i+1}) \}$ (Every a is immediately followed by b.)
- $P_2 = \{ A_0 A_1 A_2 \ldots \in (2^{AP})^{\omega} \mid \forall i \in \mathbb{N}. \ \exists j \in \mathbb{N}. \ (j > i \land a \in A_j) \}$  (The atomic proposition a holds infinitely often.)
- $P_3 = \{ A_0 A_1 A_2 \dots \in (2^{AP})^{\omega} \mid |\{i \in \mathbb{N} \mid a \in A_i\}| = 3 \}$  (At exactly 3 points of time, a holds.)
- $P_4 = \{ A_0 A_1 A_2 \dots \in (2^{AP})^{\omega} \mid a \in A_0 \wedge \forall i \in \mathbb{N}. \exists j \in \mathbb{N}. (j > i \wedge a \in A_j) \}$  (a holds initially and infinitely often.)
- $P_5 = \{ A_0 A_1 A_2 \dots \in (2^{AP})^{\omega} \mid true \}$ (True)

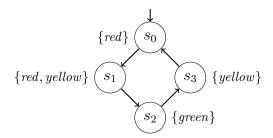
Hint: Some tasks may require very little work.

## Exercise 3: Model Checking

10 Points

In this exercise, we arrive at a goal towards which we have worked since the beginning of the semester: For a cyber-physical system (given as a transition system) and desired correctness properties, we are able to determine if the system satisfies these properties.

The following transition system T models the behaviour of a traffic light with the set of atomic propositions  $AP = \{red, yellow, green\}$ :



(a) Draw an NFA  $\mathcal{A}_T$  over the alphabet  $\Sigma = 2^{AP}$  such that  $\mathcal{A}_T$  accepts exactly the finite prefixes of Traces(T), i.e.,  $\mathcal{L}(\mathcal{A}_T) = pref(Traces(T))$ .

**Note:** You can construct  $A_T$  as you prefer, you do not necessarily need to follow the construction introduced in the lecture (it still has to accept the correct language of course).

- (b) Consider the following safety properties:
  - $(P_1)$  "It is always the case that if the green light is on, then the red light will be off in the next step."
  - $(P_2)$  "It is always the case that if the red light is on, then the green light will be off in the next step."

Give automata over the alphabet  $\Sigma = 2^{AP}$  for the bad prefixes of these properties, i.e., draw NFAs  $\mathcal{A}_{P_1}$  and  $\mathcal{A}_{P_2}$  that accept exactly the bad prefixes of the property  $P_1$  respectively  $P_2$ .

(c) Draw the intersection NFAs of  $\mathcal{A}_T$  with  $\mathcal{A}_{P_1}$  respectively  $\mathcal{A}_{P_2}$ . For both intersection NFAs, check if the accepted language is empty (i.e. no accepting state can be reached) to determine if T satisfies the respective property. Explain your answer.