

# 1 Structural estimation of fuel consumption

Consider the following parameterization of structural model of fuel consumption. For ship  $i$  in hour  $j$ , let

$$\frac{W_{ME,ij}}{W_{ME,ref}} = C \tilde{t}_{ij}^{0.66} \tilde{v}_{ij}^3 \quad (1)$$

with  $\tilde{t}_{ij} := \frac{t_{ij}}{t_{ref}}$  and  $\tilde{v}_{ij} := \frac{v_{ij}}{v_{ref}}$  and

$$SFC_{ME_{ij}} = SFC_{base} \cdot \left( \beta_1 - 1.6\beta_2 \frac{W_{ME,ij}}{W_{ME,ref}} + \beta_2 \left( \frac{W_{ME,ij}}{W_{ME,ref}} \right)^2 \right) \quad (2)$$

where the choice of  $-1.6\beta_2$  is motivated by the assumption that  $SFC_{ME_{ij}}$  is minimized at fuel efficient point of  $\frac{W_{ME,ij}}{W_{ME,ref}} = 0.8$ .<sup>1</sup> Here, the unknown parameters are  $C$ ,  $\tilde{\theta}_1$ , and  $\tilde{\theta}_3$ .

Then, from (1)-(2),

$$FC_{ME,ij} = W_{ME,ij} SFC_{ME_{ij}} = \theta_1 \tilde{t}_{ij}^{0.66} \tilde{v}_{ij}^3 + \theta_2 (\tilde{t}_{ij}^{0.66} \tilde{v}_{ij}^3)^2 + \theta_3 (\tilde{t}_{ij}^{0.66} \tilde{v}_{ij}^3)^3$$

where  $\theta_1 := \beta_1 C$ ,  $\theta_2 := -1.6\beta_2 C^2$ , and  $\theta_3 := \beta_2 C^3$ .

Because we observe aggregate fuel consumption over the period of one year, we sum up over  $j$ 's to obtain a specification for annual fuel consumption as

$$\frac{FC_{ME,i}}{W_{ref} SFC_{base}} = \theta_1 \sum_j \tilde{t}_{ij}^{0.66} \tilde{v}_{ij}^3 + \theta_2 \sum_j (\tilde{t}_{ij}^{0.66} \tilde{v}_{ij}^3)^2 + \theta_3 \sum_j (\tilde{t}_{ij}^{0.66} \tilde{v}_{ij}^3)^3 \quad (3)$$

Let  $y_i = \frac{FC_{ME,i}}{W_{ref} SFC_{base}}$ ,  $\boldsymbol{\theta} = (\theta_0, \theta_1, \theta_2)^\top$ , and  $\mathbf{x}_i = (x_{1i}, x_{2i}, x_{3i})^\top$  with  $x_{1i} := \sum_j \tilde{t}_{ij}^{0.66} \tilde{v}_{ij}^3$ ,  $x_{2i} := \sum_j (\tilde{t}_{ij}^{0.66} \tilde{v}_{ij}^3)^2$ , and  $x_{3i} := \sum_j (\tilde{t}_{ij}^{0.66} \tilde{v}_{ij}^3)^3$ . Then, we may estimate  $\boldsymbol{\theta}$  by

$$\hat{\boldsymbol{\theta}} = \min_{\boldsymbol{\theta} \in \Theta} \sum_{i=1}^n (y_i - \mathbf{x}_i^\top \boldsymbol{\theta})^2.$$

We may also extend the above model by specifying so that  $\theta_0$ ,  $\theta_1$ , and  $\theta_2$  depend on  $\mathbf{1} \left\{ \frac{W_{ME,ij}}{W_{ME,ref}} > 0.8 \right\}$  to allow for the asymmetry around the optimal fuel efficiency point. Specifically, we may allow  $\tilde{\theta}_1$  and  $\tilde{\theta}_3$  to depend on  $\mathbf{1} \left\{ \frac{W_{ME,ij}}{W_{ME,ref}} > 0.8 \right\}$  in Equation (2) so that  $\tilde{\theta}_1 = \tilde{\theta}_{10} + \tilde{\theta}_{11} \mathbf{1} \left\{ \frac{W_{ME,ij}}{W_{ME,ref}} > 0.8 \right\}$  and  $\tilde{\theta}_3 = \tilde{\theta}_{30} + \tilde{\theta}_{31} \mathbf{1} \left\{ \frac{W_{ME,ij}}{W_{ME,ref}} > 0.8 \right\}$ . Then, repeating the above argument and

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<sup>1</sup>The first order condition of minimizing  $f(x) = \theta_1 + \tilde{\theta}_2 x + \tilde{\theta}_3 x^2$  gives  $x = -\tilde{\theta}_2/\tilde{\theta}_3$ . When  $x = 0.8$ ,  $\tilde{\theta}_2 = -1.6\tilde{\theta}_3$ .

aggregating over  $j$ 's gives

$$\begin{aligned} \frac{FC_{ME,i}}{W_{ref}SFC_{base}} &= \theta_1 \cdot \sum_j \frac{W_{ME,ij}}{W_{ME,ref}} + \theta_2 \sum_j \left( \frac{W_{ME,ij}}{W_{ME,ref}} \right)^2 + \theta_3 \cdot \sum_j \left( \frac{W_{ME,ij}}{W_{ME,ref}} \right)^3 \\ &+ \theta_4 \cdot \sum_j \mathbf{1} \left\{ \frac{W_{ME,ij}}{W_{ME,ref}} > 0.8 \right\} \frac{W_{ME,ij}}{W_{ME,ref}} + \theta_5 \sum_j \mathbf{1} \left\{ \frac{W_{ME,ij}}{W_{ME,ref}} > 0.8 \right\} \left( \frac{W_{ME,ij}}{W_{ME,ref}} \right)^2 \\ &+ \theta_6 \cdot \sum_j \mathbf{1} \left\{ \frac{W_{ME,ij}}{W_{ME,ref}} > 0.8 \right\} \left( \frac{W_{ME,ij}}{W_{ME,ref}} \right)^3. \end{aligned}$$

We may test the assumption of symmetry by testing  $\theta_4 = \theta_5 = \theta_6 = 0$ .

Furthermore, we may specify  $\theta_0$ ,  $\theta_1$ , and  $\theta_2$  in terms of observed ship characteristics.

## 2 Extended structural model

As an extension, we treat the exponents of  $\tilde{t}_{ij}$  and  $\tilde{v}_{ij}$  as unknown parameters as:

$$\frac{W_{ME,ij}}{W_{ME,ref}} = C \tilde{t}_{ij}^{\alpha_1} \tilde{v}_{ij}^{\alpha_2}. \quad (4)$$

Then, because the annual fuel consumption is determined as  $FC_{ME,i} = \sum_j SFC_{ME,ij} W_{ME,ij}$ , we have

$$\frac{FC_{ME,i}}{W_{ref}SFC_{base}} = \theta_1 \sum_j \tilde{t}_{ij}^{\alpha_1} \tilde{v}_{ij}^{\alpha_2} + \theta_2 \sum_j (\tilde{t}_{ij}^{\alpha_1} \tilde{v}_{ij}^{\alpha_2})^2 + \theta_3 \sum_j (\tilde{t}_{ij}^{\alpha_1} \tilde{v}_{ij}^{\alpha_2})^3, \quad (5)$$

where  $\theta_1 = C\beta_1$ ,  $\theta_2 = -1.6C^2\beta_2$ , and  $\theta_3 = C^3\beta_2$ .

We also consider a more flexible specification of  $\frac{W_{ME,ij}}{W_{ME,ref}}$  given by

$$\frac{W_{ME,ij}}{W_{ME,ref}} = C\psi_1(\tilde{t}_{ij}; \gamma_1)\psi_2(\tilde{v}_{ij}; \gamma_2)$$

with

$$\begin{aligned} \psi_1(\tilde{t}_{ij}; \gamma_1) &= \sum_{k=0}^K \gamma_{1k} B_k(\tilde{t}_{ij}) \quad \text{and} \\ \psi_2(\tilde{v}_{ij}; \gamma_2) &= \sum_{k=0}^K \gamma_{2k} B_k(\tilde{v}_{ij}). \end{aligned}$$

In this case, we have

$$\begin{aligned} \frac{FC_{ME,i}}{W_{ref}SFC_{base}} &= \beta_1 \underbrace{\sum_j \psi_1(\tilde{t}_{ij}; \gamma_1) \psi_2(v_{ij}; \gamma_2)}_{:=\Psi_{1i}(\gamma)} \\ &\quad + \beta_2 \underbrace{\sum_j \left( -1.6 \left( \psi_1(\tilde{t}_{ij}; \gamma_1) \psi_2(v_{ij}; \gamma_2) \right)^2 + \left( \psi_1(\tilde{t}_{ij}; \gamma_1) \psi_2(v_{ij}; \gamma_2) \right)^3 \right)}_{:=\Psi_{2i}(\gamma)}. \end{aligned} \tag{6}$$

### 3 Framework

Consider a random sample of  $n$  observations  $S = \{(X_i, Y_i)\}_{i=1}^n$ , where  $(X_i, Y_i) \stackrel{iid}{\sim} F(x, y)$ . We assume that the data is generated as

$$Y_i = m(X_i) + \epsilon_i, \quad \epsilon_i | X_i \stackrel{iid}{\sim} F_\epsilon$$

from some  $m(x)$ .

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### 4 Structural model vs. non-parametric model

We are interested in evaluating the predictive performance of different models when we use the test set in which the support of covariates does not overlap with that in the training set.

Let  $\{Y_i, X_i\}$  be a sample of size  $n$  independently drawn from  $F(y, x)$ . We are interested in predicting the mean value of  $Y$  when  $X = x_0$ , where  $x_0$  is located outside of the support of  $F(y, x)$ . Let  $f(x)$  be the probability density function  $X$ .

The predictive ability of estimated models depends on how far away the location of  $x_0$  is from the distribution of  $X_i$  in the effective sample used in the estimation of predictive models.

Let  $\rho : \mathcal{P} \times \mathcal{X} \rightarrow \mathbb{R}$  be a distance measure between a distribution function and a point. For example, when we use the Euclidean distance between the mean of the distribution and the point as a measure,  $\rho(f(x), x_0) = \|\int x f(x) dx - x_0\|$ .

**Example 1 (Local linear regression)** *Given  $x_0$ , we construct a predictive model based on local polynomial regression at  $x_d$  given a bandwidth  $h$  as:*

$$\hat{\theta}(x_d, h) = \arg \min_{\theta} \sum_{i=1}^n w_h(|X_i - x_d|) (Y_i - X_i^\top \theta)^2.$$

*In this case, the “effective” sample distribution that is used for estimating this local polynomial regression is given by*

$$g_{h,x_d}(x) = \frac{f(x) \times w_h(|x - x_d|)}{\int f(x) \times w_h(|x - x_d|) dx}.$$

Then, we define the distance between the effective sampling distribution  $g_{h,x_d}$  and  $x_0$  by  $\rho(g_{h,x_d}, x_0)$ .

**Example 2 (Structural models)** *The structural models (3)-(6) are estimated using the sample distribution  $f(x)$ . Therefore, the distance between the sample distribution and the evaluation point  $x_0$  is  $\rho(f(x), x_0)$ .*

We expect that the bias is an increasing function of the distance between the effective sampling distribution and the evaluation point  $x_0$ . On the other hand, the variance is a decreasing function of the effective sample size.

For each predictive model, we will illustrate how the bias and the variance depends on the distance between the effective sampling distribution and the evaluation point as well as the effective sample size.

Suppose we want to evaluate the predictive performance at  $x_0$ .