

Topics Covered

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I Random Variables

- X_1, \dots, X_n are independent if $P(X_1 \in A_1, \dots, X_n \in A_n) = \prod_{i=1}^n P(X_i \in A_i)$
- IID - independent identically distributed variables X_1, \dots, X_n IID $\rightarrow \langle X_1, \dots, X_n \rangle$ is a *random sample of size n*.
- A function of an RV is also an RV.
- Sample mean $\bar{X} = \frac{X_1 + \dots + X_n}{n}$

Assume X_1, \dots, X_n are IID, with

$$E(X_i) = \mu$$

$$V(X_i) = E(X - E(X))^2 = \sigma^2$$

Then:

$$E(\bar{X}) = \mu$$

$$V(\bar{X}) = \frac{\sigma}{n}$$

Evaluating with the sample mean gives:

$$E(\bar{X}) = \frac{nE(X_1)}{n}$$

$$= E(X_1)$$

$$\begin{aligned}
E(\bar{X} - \mu)^2 &= E\left(\frac{\sum_{i=1}^n n(X_i - \mu)}{n}\right)^2 \\
&= \frac{1}{n^2} \left(\sum_{i=1}^n n(X_i - \mu)^2 + \sum_{i \neq j} n(X_i - \mu)(X_j - \mu) \right) \\
&= \frac{1}{n^2} \cdot n\sigma^2 \\
&= \frac{\sigma^2}{n}
\end{aligned}$$

So \bar{X} is an unbiased estimator of the true value (a.k.a. the population mean). What is an unbiased estimator of the variance $\sum_i (X_i - \bar{X})^2$?

$$\begin{aligned}
E\left(\sum_i (X_i - \bar{X})^2\right) &= E\left(\sum_i (X_i^2 - 2X_i\bar{X} + \bar{X}^2)\right) \\
&= E\left(\sum_i X_i^2 - 2\left(\sum_i X_i\right)\bar{X} + n\bar{X}^2\right) \\
&= E(nX^2 - 2n\bar{X}^2 + n\bar{X}^2) \\
&= nE(nX^2) - nE(\bar{X}^2)
\end{aligned}$$

What is $E(X^2)$?

$$\begin{aligned}
\sigma^2 &= E(X - \mu)^2 \\
&= E(X^2 - 2\mu X + \mu^2) \\
&= E(X^2) - 2\mu^2 + \mu^2 \\
&= E(X^2) - \mu^2
\end{aligned}$$

So

$$E(X^2) = \sigma^2 + \mu^2 \tag{1}$$

So we get

$$\begin{aligned}
E\left(\sum_i (X_i - \bar{X})^2\right) &= n \cdot (\sigma^2 + \mu^2) - n \cdot \left(\frac{\sigma^2}{n} + \mu^2\right) \\
&= n\sigma^2 + n\mu^2 - \sigma^2 - n\mu^2 \\
&= n\sigma^2 + \sigma^2 \\
&= (n-1)\sigma^2
\end{aligned}$$

So an unbiased variance estimator is

$$\frac{1}{n-1} \sum_i (X_i - \bar{X})^2 \quad (2)$$

II Likelihood

Assume you have a coin with $P(H) = p$ which is unknown. You toss it 16 times and get

HHTHTHHHTTHHTHHT

For what value of p is such an outcome *most likely*? We have 10 heads so intuitively p should be $\frac{10}{16}$. To show this, start with

$$\begin{aligned} P(p) &= p^{10}(1-p)^6 \\ \frac{\partial P}{\partial p} &= 10p^9(1-p)^6 + p^{10} \cdot 6(1-p)^5(-1) \\ &= p^9(1-p)^5(10(1-p) - 6p) \\ &= p^9(1-p)^5(10 - 10p - 6p) \end{aligned}$$

So $P(p)$ has a maximum value

$$\begin{aligned} 16p &= 10 \\ p &= \frac{10}{16} \end{aligned}$$

The likelihood function is **not** a probability function on the space of parameters. It is equal to:

1. In the discrete case: The probability to have such an outcome given the unknown parameters.
2. In the continuous case: The probability density function for such an outcome.

Example 1

Assume you have *n* **unbiased** sensors with an unknown but equal standard deviation. You have n readings X_1, \dots, X_n of the same quantity. How would you estimate the true value μ and σ ?

$$\begin{aligned}
\mathcal{L}_n(\mu, \sigma) &= \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(X_i - \mu)^2}{2\sigma^2}} \\
\frac{\partial \mathcal{L}_n}{\partial \mu} &= \frac{\partial}{\partial \mu} \left(\frac{1}{(2\pi\sigma^2)^{\frac{n}{2}}} e^{-\frac{\sum_i (X_i - \mu)^2}{2\sigma^2}} \right) \\
&= \frac{1}{(2\pi\sigma^2)^{\frac{n}{2}}} e^{-\frac{\sum_i (X_i - \mu)^2}{2\sigma^2}} \cdot \frac{-2}{2\sigma^2} \sum_i (X_i - \mu) \text{ because } \mu = \frac{\sum_i X_i}{n} \\
&= -n(2\pi)^{-\frac{n}{2}} \sigma^{-n-1} e^{-\frac{\sum_i (X_i - \mu)^2}{2\sigma^2}} + (2\pi)^{-\frac{n}{2}} \sigma^{-n} e^{-\frac{\sum_i (X_i - \mu)^2}{2\sigma^2}} (-2) \frac{-\sum_i (X_i - \mu)^2}{2\sigma^3}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial \mathcal{L}_n}{\partial \mu} = 0 &\leftrightarrow -n + (\sigma^{-1})^2 = 0 \\
&\leftrightarrow \sum_i (X_i - \mu)^2 = 0 \\
\sigma^2 &= \frac{\sum_i (X_i - \mu)^2}{n}
\end{aligned}$$

We found that $\mu = \bar{X}$, so

$$\sigma^2 = \frac{\sum_i (X_i - \bar{X})^2}{n}$$

is a biased estimator.

Example 2

Given n sensors with known variances $\sigma_1^2, \dots, \sigma_n^2$ and n readings X_1, \dots, X_n . What is the maximum likelihood estimation of μ ?

$$\begin{aligned}
\mathcal{L}_n(\vec{X}, \mu, \sigma) &= \prod_{i=1}^n \frac{1}{(2\pi)^{\frac{n}{2}} \sigma_i} e^{-\frac{(X_i - \mu)^2}{2\sigma_i^2}} \\
&= (2\pi)^{-\frac{n}{2}} \prod_{i=1}^n n\sigma_i^{-1} \cdot e^{-\sum_i \frac{(X_i - \mu)^2}{2\sigma_i^2}} \\
\frac{\partial \mathcal{L}_n}{\partial \mu} &= (2\pi)^{-\frac{n}{2}} \prod_{i=1}^n n\sigma_i^{-1} \cdot e^{-\sum_i \frac{(X_i - \mu)^2}{2\sigma_i^2}} - 2 \sum_i \frac{X_i - \mu}{2\sigma_i^2}
\end{aligned}$$

So

$$\begin{aligned}\frac{\partial \mathcal{L}_n}{\partial \mu} = 0 &\leftrightarrow \sum_i \frac{X_i}{\sigma_i} = \sum_i \frac{1}{\sigma_i} \mu \\ &\leftrightarrow \mu = \frac{\sum_i \frac{1}{\sigma_i} X_i}{\sum_k \frac{1}{\sigma_k}}\end{aligned}$$

III Maximum Likelihood Estimates

Is the ML estimate always a "good" one?

Example 1

You have a box with a certain number of balls, numbered consecutively 1, 2, 3, 4, You pick one at random, see its number and have to estimate the total number of balls in the box.

Maximum Likelihood Estimate: If you picked a ball with a number k , such a ball is most likely if there are k balls in the box, because then the probability of picking this ball is $\frac{1}{k}$. The expected value of your estimate is

$$\begin{aligned}\frac{1 + 2 + \dots + n}{n} &= \frac{n(n+1)}{2n} \\ &= \frac{n+1}{2}\end{aligned}$$

So your ML is heavily biased! On the other hand, if your estimate is $2X - 1$ then

$$\begin{aligned}E(2X - 1) &= \sum_i \frac{2 \cdot i - 1}{n} \\ &= \frac{2n(n+1) - n}{n} \\ &= n\end{aligned}$$

hence this estimate is unbiased.

Then to evaluate

$$T_i = C - \frac{1}{m_i} \sum_{i \rightarrow p} (E_{ip} - \sqrt{p})^2$$

We maximise

$$\begin{aligned}
 \tau &= \sum_i m_i T_i^2 \\
 &= \sum_i m_i \left(C - \frac{1}{m_i} \sum_{i \rightarrow p} (E_{ip} - \sqrt{p})^2 \right)^2 \\
 \frac{\partial \tau}{\partial \sqrt{k}} &= 4 \sum_{i \rightarrow k} m_i \left(C - \frac{1}{m_i} \sum_{i \rightarrow p} (E_{ip} - \sqrt{p})^2 \right)^2 \cdot \frac{E_{ik} - \sqrt{k}}{m_i} \\
 &= 4 \sum_{i \rightarrow k} T_i (E_{ik} - \sqrt{k}) \\
 &= 4 \sum_{i \rightarrow k} T_i E_{ik} - \left(\sum_{i \rightarrow k} T_i \right) \sqrt{k}
 \end{aligned}$$

Equating the derivative to zero

$$\frac{\partial \tau}{\partial \sqrt{k}} = 0 \Leftrightarrow \sqrt{k} = \frac{\sum_{i \rightarrow k} T_i E_{ik}}{\sum_{i \rightarrow k} T_i}$$

Example 2

What is the likelihood of obtaining readings E_{ip} if all sensors have variance σ^2 ?