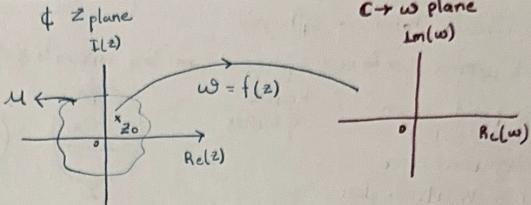


## Riemann Surfaces

Goals

- Idea of Riemann surface
- Example of Riemann surface



- \$z\$ plane is complex plain.
- \$\Omega\$ is open set in complex plain (\$z\$)
- \$f\$ is a function that takes complex value and splits complex values
- function is define in the open set \$\Omega\$

Recall:

\$f(z)\$ is said to be analytical or holomorphic at \$z\_0\$ if the following 3 equivalent conditions holds:

- (i) If we write \$w = u + iv\$ then \$u = \operatorname{Re}(f)\$ then we want partial derivatives.  
If then first condition is satisfied \$v = \operatorname{Im}(f)\$ then \$u\_x = \frac{\partial u}{\partial x}\$; \$u\_y = \frac{\partial u}{\partial y}\$; \$v\_x = \frac{\partial v}{\partial x}\$; \$v\_y = \frac{\partial v}{\partial y}\$ exists and are continuous. and further satisfies Cauchy-Riemann Equations

$$u_x = v_y \text{ and } v_x = -u_y \text{ in a neighborhood of } z_0$$

- iii) the limit  $\lim_{\Delta z \rightarrow 0} \frac{f(z+\Delta z) - f(z)}{\Delta z}$  exist

at point \$z\$ in a neighborhood of \$z\_0\$

- iv) \$\exists\$ a power series of the form  $\sum_{n=0}^{\infty} a_n(z-z_0)^n$  which is convergent to \$f(z)\$ for each point \$z\$ in the neighborhood of \$z\_0\$

→ Connection B/w i) & ii) If we want to express the derivative of a function in the neighborhood of \$z\_0\$ then we can use iii) to write.

$$\frac{df}{dz} \quad \frac{df}{dz} = \frac{\partial F}{\partial x} = u_x + i v_x$$

Connection B/w ii) & iii) It say that if a function is differential at a point once then it's infinitely differentiable.

→ A convergent power series allows you to differentiate it term by term and the resulting series is also differentiable with the same radius.

→ One differentiable  $\Rightarrow$  always differentiable in the neighborhood i.e. \$w\$ differentiable.

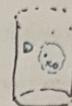
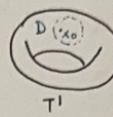
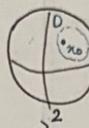
$$a_n = f^{(n)}(z_0); f^{(n)}(z_0) = \frac{d^n f}{dz^n}$$

so that  $\sum a_n(z-z_0)^n$  is the first Taylor expansion of \$f\$ around \$z\_0\$

The idea of Riemann Sphere

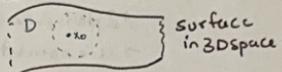
start with a surface; sphere can be visualized in  $\mathbb{R}^3$

→ Given point  $x_0$  on surface select a cylinder neighborhood of  $x_0$  that look like a disc.



\* Disc is not flat it's curved since sits on surface

\* Topologically the disc is flat in complex plane



Imagine a complex valued function  $f$  (It is always defined on the Disc  $D$ ) it takes complex values.

(neighborhood)  $D \xrightarrow{f} \mathbb{C}$

Now we want to define when's this function is holomorphic? at  $x_0$  (holomorphic)

So we want to do the same complex analysis on the plane (which we usually do) we want to do this complex analysis on 3d surfaces.

Hence the idea of Riemann Surface is to do complex analysis on 3D surfaces.

Q1. How do you define  $f$  to be holo at any point in  $D$  (neighborhood)

One way to do so is:

Topologically identify  $D$  with an open subset, say a unit disc.

$$\Delta = \{z \in \mathbb{C} \mid |z| < 1\} \text{ this is an open unit disc.}$$

Since  $|z| < 1$

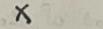
By choosing a homeomorphism. (It's topological isomorphism)

$\phi: D \rightarrow \Delta$  and requiring  $f \circ \phi^{-1}$  is holo at  $\phi(x_0)$

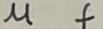
Complex plane



Surface



Complex function



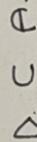
→  $D$  contains  $x_0$

→  $D$  is situated inside the surface  $X$

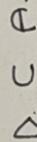
→ we have function defined on  $D$  that take complex values.

→ aim is to say  $f$  is holomorphic at point in  $D$

Unit disc



Complex plane number



$\phi$

$\phi^{-1}$

$f \circ \phi^{-1}$

To say that  $f$  is holo at a point in  $D$  we take a topological isomorphism  $\phi$  into the unit disc in the complex plain  $\mathbb{C}$

( $\Delta$ )

we apply composition  $\phi^{-1}$ . ( $\because$  the map  $\phi$  is topological isomorphism that means  $\phi^{-1}$  exist)

$f \circ \phi^{-1}$  (to move from one complex plane to another) Complex number

→  $f \circ \phi^{-1}$  gives us the map from unit disc of complex plane to complex numbers.

→ This means that  $f \circ \phi^{-1}$  is holomorphic at a point in unit disc where the point on unit disc is the image of point  $z_0$  that is in  $D$ .

→ we have showed that the neighbourhood of a surface is a disc in Complex plane and this plane maps to Complex numbers and most importantly  $f \circ \phi^{-1}$  is holomorphic at  $\phi(z_0)$

Unit disc  $\phi$  that is mapped from  $D$  to Complex plane (disc  $\Delta$ )

→ In the same way we say that ~~that~~  $f$  is holomorphic on  $D$  if  $f \circ \phi^{-1}$  is holomorphic on  $\Delta$ . The pair  $(D, \phi)$  is called a Complex Coordinate chart.

### Coordinate chart:

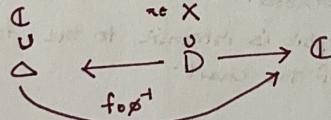
We have seen that the identification of  $\phi$  and this disc like neighbourhood is a pair and this is called complex coordinate chart  $(D, \phi)$  (This provides you with coordinate chart to do Complex Analysis)

So one intuitive way to see a Riemann Surface is to think them as they come up. They help us to do Complex analysis on Surfaces.

### Formal definition of Coordinate chart:

It's a pair  $(M, \phi)$  where  $\phi$  is an open subset of  $X$ ,

$\phi: M \xrightarrow{\sim} V$  is a homeomorphism of  $M$  onto an open subset  $V$  of  $\mathbb{C}$



Call a varying point in  $x \in X$

Then the map of this  $x$  in the unit disc  $\Delta$  is  $\phi(x)$

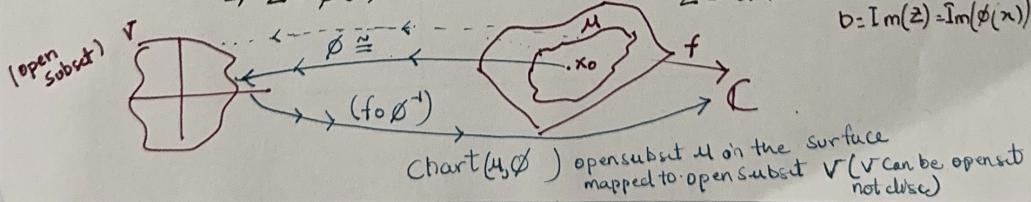
$\Rightarrow z = \phi(x)$  &  $z$  is a coordinate

$$z \in \mathbb{C} \text{ plane}$$

$$z = a + ib$$

$$a = \operatorname{Re}(z) = \operatorname{Re}(\phi(x))$$

$$b = \operatorname{Im}(z) = \operatorname{Im}(\phi(x))$$



## Preliminary Def of Riemann Surface:

A Surface  $X$  Covered by a Collection of charts  $\{(U_\alpha, \phi_\alpha) | \alpha \in I\}$

$$(X = \bigcup_{\alpha} U_\alpha)$$

$I = \text{index}$ : we run into issue with the above definition

Suppose  $U_{\alpha_1}$  and  $U_{\alpha_2}$  both contain a point  $x_0$

Union for all Belonging to Index.

we see that

$$x_0 \in (U_{\alpha_1} \cap U_{\alpha_2})$$

then the problem is that

how do we tell  $f$  is

holomorphic at  $x_0$ ?

Since the index, chart can

be arbitrary how to define hol of function  $f$ ?

$\{(U_\alpha, \phi_\alpha) | \alpha \in I\}$  what happens if  $x_0$  belongs to two  $(U_1, \phi_1)$  &  $(U_2, \phi_2)$

$f$  is holomorphic at  $x_0$  then

(i) From one subset  $(U_{\alpha_1}, \phi_{\alpha_1})$  if  $f \circ \phi_{\alpha_1}^{-1}$  is holo at  $z_1 = \phi_{\alpha_1}(x_0)$

(ii) from two subset  $(U_{\alpha_2}, \phi_{\alpha_2})$  if  $f \circ \phi_{\alpha_2}^{-1}$  is holo at  $z_2 = \phi_{\alpha_2}(x_0)$

Since the chart are arbitrary to define hol at  $x_0$  we have to define the property intrinsic to  $f$  the function not dependent on the chart or the neighbourhood.

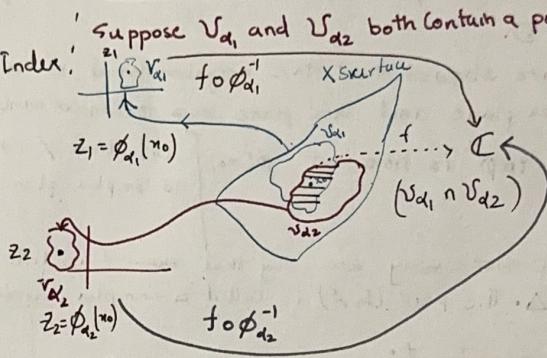
As we have seen that the holomorphic is intrinsic to the function and does not depend on the selection of the chart. (Re parametrization)

How to avoid a situation that where from one chart you get the definition?

$f \circ \phi_{\alpha_1}^{-1}$   $\alpha_1$  is the chart selected in this case.

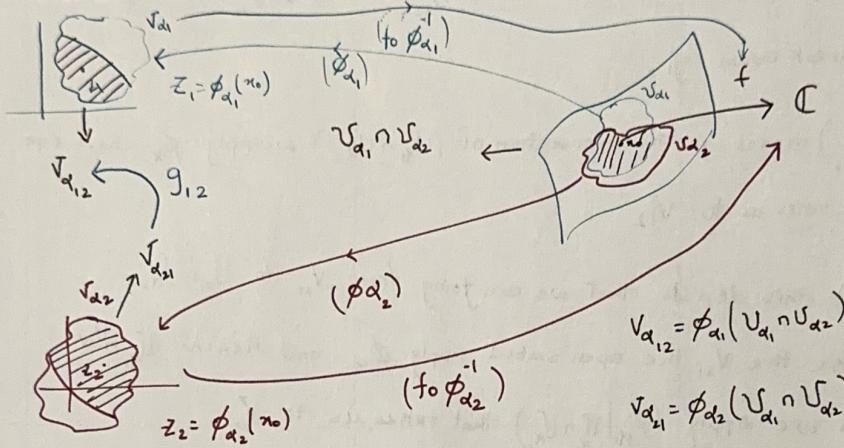
$f \circ \phi_{\alpha_2}^{-1}$   $\alpha_2$  is the chart selected

One thing we can do is equate them. But still it don't make much sense. Since the chart are arbitrary.



then the idea of a function i.e. holomorphic should be intrinsic to the function

To ensure we define things independent of chart



→ To ensure the holomorphicity of a function using various charts happens and to make holomorphicity an intrinsic property of the function lets define

$$g_{12} = (\phi_{\alpha_1}|_{U_{\alpha_1} \cap U_{\alpha_2}})^{-1} \circ (\phi_{\alpha_2}|_{V_{\alpha_2} \cap U_{\alpha_2}}) \circ V_{\alpha_2} \rightarrow V_{\alpha_1}$$

we want  $g_{12}$  to be defined as above this ensures it is and it is an homeomorphism. Since  $(\phi_{\alpha_1}|_{U_{\alpha_1} \cap U_{\alpha_2}})^{-1}$  is a open subset

$(\phi_{\alpha_2}|_{V_{\alpha_2} \cap U_{\alpha_2}})$  is again open subset

Requiring  $g_{12}$  to be holomorphic should also make it into a holomorphic isomorphism.

Intersection  $U_{\alpha_1} \cap U_{\alpha_2} \Rightarrow (U_{\alpha_1} \cap U_{\alpha_2})$  now lets apply  $\phi_{\alpha_1}$  to intersection.

that takes us to  $V_{\alpha_{21}}$

Similarly we apply  $\phi_{\alpha_2}$  to the intersection landing up on  $V_{\alpha_{12}}$

$$(U_{\alpha_1} \cap U_{\alpha_2})$$

Now let's understand what happens in  $g_{12}$

$$g_{12} = (\phi_{\alpha_1}|_{V_{\alpha_1} \cap V_{\alpha_2}}) \circ (\phi_{\alpha_2}^{-1}|_{V_{\alpha_2}}) : V_{\alpha_1} \rightarrow V_{\alpha_2}$$

Now let's Break Down  $g_{12}$

$(\phi_{\alpha_1}|_{V_{\alpha_1} \cap V_{\alpha_2}})$  means in the intersection of  $(U_{\alpha_1} \cap U_{\alpha_2})$  we apply  $\phi_{\alpha_1}$  chart one that ~~this~~ takes us to  $V_{12}$

$(\phi_{\alpha_2}^{-1}|_{V_{\alpha_2}})$  this depicts that we are going from  $V_{21}$  to  $V_{\alpha_1} \cap V_{\alpha_2}$  we take the  $V_{21}$  the open subset apply  $\phi_{\alpha_2}^{-1}$  and Reach  $V_{\alpha_1} \cap V_{\alpha_2}$  and then we apply  $(\phi_{\alpha_1}|_{V_{\alpha_1} \cap V_{\alpha_2}})$  that takes us to  $V_{12}$

So we can define  $\boxed{g_{12} : V_{21} \rightarrow V_{12}}$

we were able to define  $g_{12} : V_{21} \rightarrow V_{12}$  as homeomorphism since  $g_{12}$  is a map from open subset  $U$  to  $V$  so  $g_{12}$  is homeomorphism.

Now since we were able to tell that  $g_{12}$  is homeomorphic now we want it holomorphic! (This means its injective)

→ Requiring  $g_{12}$  to be holomorphic should also make it into a holomorphic isomorphism.

$$\boxed{f \circ \phi_{\alpha_1}^{-1} \circ g_{12}} = \boxed{f \circ \phi_{\alpha_2}^{-1}}$$

The above equation tells us that  $f \circ \phi_{\alpha_1}^{-1}$  is holo iff  $f \circ \phi_{\alpha_2}^{-1}$  is

Definition:

If we want that the function  $g_{12}$  (transition functions) to be holo whenever  $(U_{\alpha_1} \cap U_{\alpha_2} \neq \emptyset)$  we get a compatible collections of charts which gives a Riemann Surface structure on "X".

Summarizing on Riemann Surface.

→ Started with Complex analysis on Surface in  $\mathbb{R}^3$

→ we define complex coordinates charts.

$$\{(U_\alpha, \phi_\alpha) \mid \alpha \in I\}$$

I = indexed charts.  
 $\alpha$  = one of the arbitrary chart.

→ Charts should cover the whole open set

→ Problem comes when multiple chart can represent the same things  
so to avoid the ambiguity. we define a transition function

$g_{12}$  to be holomorphic (whenever  $U_{\alpha_1} \cap U_{\alpha_2} \neq \emptyset$ ) this gives us  
Compatible collections of charts that gives Riemann structure on X

$$f \circ \phi_{\alpha_1}^{-1} \circ g_{12} = f \circ \phi_{\alpha_2}^{-1}$$

$\hookrightarrow g_{12}$  is holomorphic.