

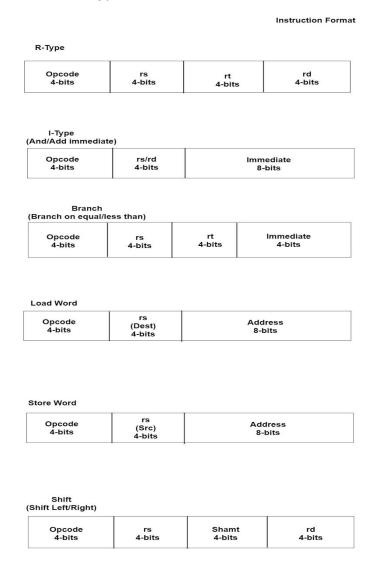
Team Nova

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Overview

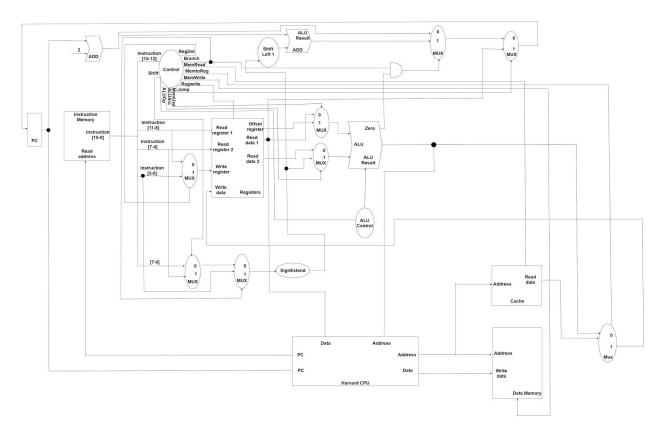
We implemented our architecture with specific features that help in drawing out the best performance possible according to our project proposal choices. Our architecture is implemented with reference to Harvard architecture where we can access both data and instruction memories simultaneously. The size of both data and instruction memories is 1024*16-bit. The total number of registers used is 16 registers, where all of them are general-purpose registers except that there is the zero register (\$0) is used as an offset in Load word and Store word instructions. We implemented the instruction set 2. In order to implement instruction set 2, we had to create a new instruction format that suits our architecture implementation approach. Each Instruction size is 16 bits, and according to the type of the instruction, it goes through the datapath differently. The following table shows the different types of instructions and how we divide the instructions according to its type:



A side note is that the 8-bit immediate part in the I-type and branch instructions, also the 8-bit address part in load word and store word instructions are written as binary signed 2's complement.

We have created a cache in the data memory. The cache uses the direct-mapped organization, thus the replacement policy is built-in which means we did not have to use a specific replacement policy.

Then, for our datapath it goes as follows:



We can see from the graphical representation above that all the required components which are Instruction Memory, Data Memory + Cache, Register File, Program Counter, Arithmetic Logic Unit, Control Unit exist in the datapath. We added a new component however which is the Harvard CPU component which manages reading/writing data from/to data memory and its cache and setting the program counter value.

Finally, for our code structure, The code contains two packages (Components & Stages) and the main class (Computer). (Components) package has all the modules, And (Stages)

has all the stages (InstructionFetch - InstructionDecode - Execute - MemoryAccess - WriteBack). The program begins as an ArrayList of instructions which is passed to a run method in the main class (Computer). The run method loads the program to the instruction memory, then a run helper method is called which performs pipelining. Each instruction has to pass through all five stages. The program terminates after the last instruction to be executed goes through the (WriteBack) stage.

Our output is something like the following after loading a certain set of instructions

