## Multilayer Perceptron

Legend :

 $\left(a_0^{l_0}
ight)$ 

Input n°0 of layer n°0

 $(b^{l_0})$ 

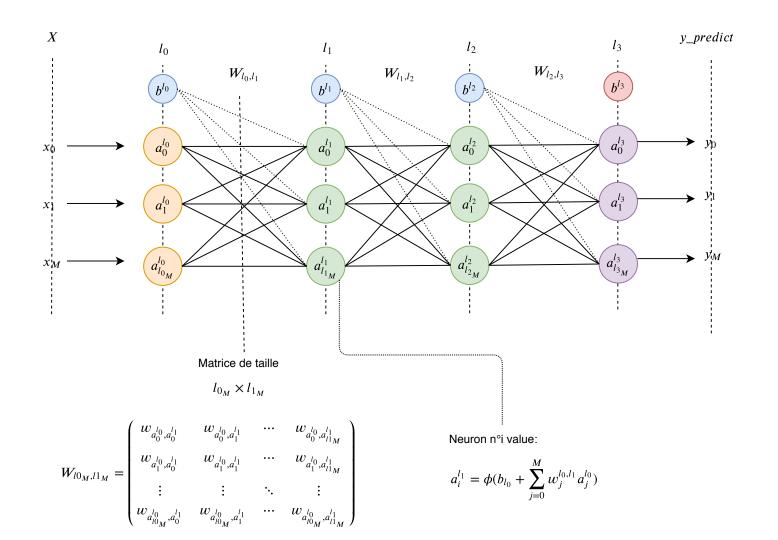
Bias of layer n°0

 $W_{l_0,l_1}$  Matrix of weights beetwen layer n°0 and layer n°1

 $x_0$  First feature of the input vector

y<sub>0</sub> Probability that the input vector is of class n°0

M is used to mean length



## Description of backward propagation learning

$$y_{l_0,l_1} = \phi(X \cdot W_{l_0,l_1} + bias_{l_0,l_1}) \qquad y_{l_1,l_2} = \phi(y_{l_0,l_1} \cdot W_{l_1,l_2} + bias_{l_1,l_2}) \qquad y\_predict = \phi(y_{l_1,l_2} \cdot W_{l_2,l_3} + bias_{l_2,l_3})$$

$$\downarrow \qquad \qquad \downarrow \qquad$$

$$X \longrightarrow W_{l_0,l_1} \longrightarrow \phi(r) \longrightarrow W_{l_1,l_2} \longrightarrow \phi(r) \longrightarrow W_{l_2,l_3} \longrightarrow \phi(r) \longrightarrow y\_predict$$

$$\epsilon_{0,1} = \delta_{1,2} \cdot W_{l_0,l_1} \qquad \epsilon_{1,2} = \delta_{2,3} \cdot W_{l_1,l_2} \qquad \epsilon_{2,3} = \delta_{3,4} \cdot W_{l_2,l_3}$$

$$\delta_{0,1} = \epsilon_{0,1} \cdot \frac{\partial \phi}{\partial y}(X) \qquad \delta_{1,2} = \epsilon_{1,2} \cdot \frac{\partial \phi}{\partial y}(y_{l_0,l_1}) \qquad \delta_{2,3} = \epsilon_{2,3} \cdot \frac{\partial \phi}{\partial y}(y_{l_1,l_2}) \qquad \delta_{3,4} = \frac{\partial C(y,y\_predict)}{\partial y}$$

$$W_{l_0,l_1} += \delta_{0,1} \cdot X \cdot \mu \qquad \longrightarrow \qquad W_{l_1,l_2} += \delta_{1,2} \cdot y_{l_0,l_1} \cdot \mu \qquad \longrightarrow \qquad W_{l_2,l_3} += \delta_{2,3} \cdot y_{l_1,l_2} \cdot \mu$$

$$b_{l_0,l_1} += \delta_{0,1} \cdot \mu \qquad \qquad b_{l_2,l_3} += \delta_{2,3} \cdot \mu$$

FORWARD PROPAGATION

BACKWARD PROPAGATION

*y\_predict* Output vector

X Input vector  $\int \phi(r_0)$ 

 $\phi(\vec{r})$  Activation function  $\phi(r) = \begin{bmatrix} \phi(r_1) \\ \dots \\ \vdots \\ \phi(r_n) \end{bmatrix}$ 

 $\mu$  Learning rate

 $C(y, y_p redict)$  Error function

## MLP project architecture

