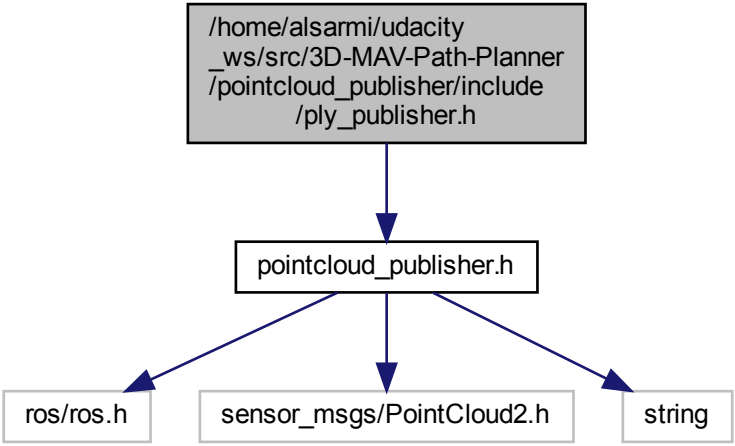


/home/alsarmi/udacity
_ws/src/3D-MAV-Path-Planner
/pointcloud_publisher/include
/ply_publisher.h



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pointcloud_publisher.h

ros/ros.h

sensor_msgs/PointCloud2.h

string