

/home/alsarmi/udacity
_ws/src/3D-MAV-Path-Planner
/pointcloud_publisher/include
/pointcloud_publisher.h

```
graph TD; A["/home/alsarmi/udacity_ws/src/3D-MAV-Path-Planner/pointcloud_publisher/include/pointcloud_publisher.h"] --> B["ros/ros.h"]; A --> C["sensor_msgs/PointCloud2.h"]; A --> D["string"];
```

ros/ros.h

sensor_msgs/PointCloud2.h

string