

```
graph BT; A["/home/alsarmi/udacity_ws/src/3D-MAV-Path-Planner/path_planner/include/ib_rrt_star_planner.h"] --> B["/home/alsarmi/udacity_ws/src/3D-MAV-Path-Planner/path_planner/include/path_planner_node.h"]; B --> C["/home/alsarmi/udacity_ws/src/3D-MAV-Path-Planner/path_planner/src/path_planner_node.cpp"]
```

/home/alsarmi/udacity
_ws/src/3D-MAV-Path-Planner
/path_planner/include/ib
_rrt_star_planner.h

/home/alsarmi/udacity
_ws/src/3D-MAV-Path-Planner
/path_planner/include/path
_planner_node.h

/home/alsarmi/udacity
_ws/src/3D-MAV-Path-Planner
/path_planner/src/path_planner
_node.cpp