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1. Assuming **A** and $\mathbf{A} + \mathbf{u}\mathbf{v}^{\mathrm{T}}$ are nonsingular, prove

$$(\mathbf{A} + \mathbf{u}\mathbf{v}^{\mathrm{T}})^{-1} = \mathbf{A}^{-1} - \frac{\mathbf{A}^{-1}\mathbf{u}\mathbf{v}^{\mathrm{T}}\mathbf{A}^{-1}}{(1 + \mathbf{v}^{\mathrm{T}}\mathbf{A}^{-1}\mathbf{u})}$$
(1)

Proof. Since $\mathbf{A} + \mathbf{u}\mathbf{v}^{\mathrm{T}}$ is nonsingular, then the inverse of its inverse exists. And using the fact that

$$(\mathbf{A} + \mathbf{u}\mathbf{v}^{\mathrm{T}})^{-1}(\mathbf{A} + \mathbf{u}\mathbf{v}^{\mathrm{T}}) = \mathbf{I},$$
(2)

then we want to show that

$$\left[\mathbf{A}^{-1} - \frac{\mathbf{A}^{-1}\mathbf{u}\mathbf{v}^{\mathrm{T}}\mathbf{A}^{-1}}{(1 + \mathbf{v}^{\mathrm{T}}\mathbf{A}^{-1}\mathbf{u})}\right](\mathbf{A} + \mathbf{u}\mathbf{v}^{\mathrm{T}}) = \mathbf{I}.$$
 (3)

Simpliying this leads to the following

$$\mathbf{A}^{-1}(\mathbf{A} + \mathbf{u}\mathbf{v}^{\mathrm{T}}) - \frac{\mathbf{A}^{-1}\mathbf{u}\mathbf{v}^{\mathrm{T}}\mathbf{A}^{-1}}{(1 + \mathbf{v}^{\mathrm{T}}\mathbf{A}^{-1}\mathbf{u})}(\mathbf{A} + \mathbf{u}\mathbf{v}^{\mathrm{T}}) \stackrel{?}{=} \mathbf{I}$$
(4)

$$\mathbf{I} + \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}} - \frac{\mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}} + \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}} \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}}}{(1 + \mathbf{v}^{\mathrm{T}} \mathbf{A}^{-1} \mathbf{u})} \stackrel{?}{=} \mathbf{I}$$
 (5)

For brevity, let the scalar $(1 + \mathbf{v}^T \mathbf{A}^{-1} \mathbf{u})$ factor be α . Then

$$\mathbf{I} + \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}} - \frac{\mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}} + \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}} \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}}}{\alpha} \stackrel{?}{=} \mathbf{I}$$
 (6)

Note that $\mathbf{v}^{\mathrm{T}}\mathbf{A}^{-1}\mathbf{u}$ is a scalar, then

$$\mathbf{I} + \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}} - \frac{\mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}} + (\mathbf{v}^{\mathrm{T}} \mathbf{A}^{-1} \mathbf{u}) \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}}}{\alpha} \stackrel{?}{=} \mathbf{I}$$
 (7)

$$\mathbf{I} + \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}} - \frac{[1 + (\mathbf{v}^{\mathrm{T}} \mathbf{A}^{-1} \mathbf{u})] \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}}}{\alpha} \stackrel{?}{=} \mathbf{I}$$
 (8)

$$\mathbf{I} + \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}} - \frac{\alpha \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^{\mathrm{T}}}{\alpha} \stackrel{\checkmark}{=} \mathbf{I}$$
 (9)

2. Rayleigh's quotient.

Assume $\mathbf{S} \geq \mathbf{0}$ in \mathbb{R}_n^n with eigenvalues $\lambda_1 \geq \cdots \geq \lambda_n$ and corresponding eigenvectors $\mathbf{x}_1, \cdots, \mathbf{x}_n$. Prove:

(a) $\lambda_n \le \frac{\mathbf{x}^{\mathrm{T}} \mathbf{S} \mathbf{x}}{\mathbf{x}^{\mathrm{T}} \mathbf{x}} \le \lambda_1, \quad \forall \mathbf{x} \ne \mathbf{0}.$ (10)

(b) For any fixed $j = 2, \dots, n$,

$$\frac{\mathbf{x}^{\mathrm{T}}\mathbf{S}\mathbf{x}}{\mathbf{x}^{\mathrm{T}}\mathbf{x}} \le \lambda_{j}, \quad \forall \mathbf{x} \ne \mathbf{0}$$
 (11)

such that $\langle \mathbf{x}, \mathbf{x}_1 \rangle = \cdots = \langle \mathbf{x}, \mathbf{x}_{i-1} \rangle = 0$.

3. Given a bivariate copula d.f. $C(t_1, t_2)$, two measures of association are Spearman's ρ and Kendall's τ ,

$$\rho = 12 \int_{[0,1]^2} t_1 t_2 dC(t_1, t_2) - 3, \tag{12}$$

$$\tau = 4 \int_{[0,1]^2} C(t_1, t_2) dC(t_1, t_2) - 1, \tag{13}$$

 $|\rho| \le 1$ and $|\tau| \le 1$. Now, let $|\alpha| < 1/3$ in the bivariate Morgenstern copula

$$C(t_1, t_2) = t_1 t_2 [1 + 3\alpha(1 - t_1)(1 - t_2)]. \tag{14}$$

Verify this copula is parameterized by Spearman's meausre, or

$$\alpha = 12 \int_{[0,1]^2} t_1 t_2 dC(t_1, t_2) - 3.$$
 (15)

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Proof. Consider the following differentiation,

$$\begin{split} \frac{\mathrm{d}^2}{\mathrm{d}t_1 \mathrm{d}t_2} C(t_1, t_2) &= \frac{\mathrm{d}^2}{\mathrm{d}t_1 \mathrm{d}t_2} (t_1 t_2 + 3\alpha t_1 t_2 - 3\alpha t_1 t_2^2 - 3\alpha t_1^2 t_2 + 3\alpha t_1^2 t_2^2) \\ &= \frac{\mathrm{d}}{\mathrm{d}t_2} (t_2 + 3\alpha t_2 - 3\alpha t_2^2 - 6\alpha t_1 t_2 + 6\alpha t_1 t_2^2) \\ &= 1 + 3\alpha - 6\alpha t_2 - 6\alpha t_1 + 12\alpha t_1 t_2. \end{split}$$

We want to show that $\rho = \alpha$. So that

$$\begin{split} \rho &= 12 \int_{[0,1]^2} t_1 t_2 \mathrm{d}C(t_1,t_2) - 3 \\ &= 12 \int_{[0,1]} \int_{[0,1]} t_1 t_2 \mathrm{d}^2 C(t_1,t_2) - 3 \\ &= 12 \int_{[0,1]} \int_{[0,1]} t_1 t_2 \frac{\mathrm{d}^2}{\mathrm{d}t_1 \mathrm{d}t_2} C(t_1,t_2) \mathrm{d}t_1 \mathrm{d}t_2 - 3 \\ &= 12 \int_{[0,1]} \int_{[0,1]} t_1 t_2 (1 + 3\alpha - 6\alpha t_2 - 6\alpha t_1 + 12\alpha t_1 t_2) \mathrm{d}t_1 \mathrm{d}t_2 - 3 \\ &= 12 \int_{[0,1]} \int_{[0,1]} (t_1 t_2 + 3\alpha t_1 t_2 - 6\alpha t_1 t_2^2 - 6\alpha t_1^2 t_2 + 12\alpha t_1^2 t_2^2) \mathrm{d}t_1 \mathrm{d}t_2 - 3 \\ &= 12 \int_{[0,1]} \left(\frac{t_1^2}{2} t_2 + 3\alpha \frac{t_1^2}{2} t_2 - 3\alpha t_1^2 t_2^2 - 2\alpha t_1^3 t_2 + 4\alpha t_1^3 t_2^2 \right) \Big|_{t_1 = 0}^{t_1 = 1} \mathrm{d}t_2 - 3 \\ &= 12 \int_{[0,1]} \left(\frac{1}{2} t_2 + 3\alpha \frac{1}{2} t_2 - 3\alpha t_2^2 - 2\alpha t_2 + 4\alpha t_2^2 \right) \mathrm{d}t_2 - 3 \\ &= 12 \left(\frac{1}{4} t_2^2 + 3\alpha \frac{1}{4} t_2^2 - \alpha t_2^3 - \alpha t_2^2 + \frac{4}{3} \alpha t_2^3 \right) \Big|_0^1 - 3 \\ &= 12 \left(\frac{1}{4} + 3\alpha \frac{1}{4} - 2\alpha + \frac{4}{3} \alpha \right) - 3 \\ &= 3 + 9\alpha - 24\alpha + 16\alpha - 3 = \alpha \end{split}$$

4. Corollary 3.2 (Marginal Dirichlet) If $\mathbf{x}_1 = (x_{i_1}, \dots, x_{i_K})^{\mathrm{T}}$ denotes any subset of the coordinates, then $\mathbf{x}_1 \sim \mathcal{D}_K(\mathbf{p}_1, q)$ with $\mathbf{p}_1 = (p_{i_1}, \dots, p_{i_K})^{\mathrm{T}}$ and $p = q + \sum_{i=1}^K p_{i_i}$.

Proof. Let $\mathbf{y} \sim \mathcal{D}_{n-1}(\mathbf{p}, p_n)$ where $\mathbf{p} = (p_1, \cdots, p_{n-1})^{\mathrm{T}}, p_i > 0, i = 1, \cdots, n$. Suppose $\mathbf{y} = (x_1, \cdots, x_n)^{\mathrm{T}}$ where $x_n = 1 - \sum_{j=1}^{n-1} x_j$, then \mathbf{y} forms the vector coordinates of the probability simplex such that $\sum_{i=1}^{n} x_i = 1$. If $\mathbf{x}_1 = (x_{i_1}, \cdots, x_{i_K})^{\mathrm{T}}$ is any subset of the coordinate vector \mathbf{y} , then it should be understood that K < n (for example, if the probability simplex has n = 3 dimension, then the plane $x_1 x_2$ forms another simplex on K = 2 dimensional space). Recall that the Dirichlet distribution is mathematically given by:

$$\mathbb{P}(\mathbf{y}|\boldsymbol{\alpha}) \triangleq \frac{\Gamma(\mathfrak{S})}{\prod_{i=1}^{n} \Gamma(\alpha_i)} \prod_{i=1}^{n} x_i^{\alpha_i - 1}$$
(16)

$$= \frac{\Gamma(\alpha_1 + \dots + \alpha_n)}{\Gamma(\alpha_1) \times \dots \times \Gamma(\alpha_n)}$$
(17)

$$\times x_1^{\alpha_1 - 1} \times \dots \times x_{n-1}^{\alpha_{n-1} - 1} \left[1 - \sum_{j=1}^{n-1} x_j^{\alpha_j - 1} \right]^{\alpha_n - 1}$$
 (18)

The marginal distribution of \mathbf{x}_1 is done by integrating out $x_{i_l^*}$ variables such that $i_l^* \neq i_k, \forall k = 1, \dots, K$ and $\forall l = 1, \dots, n-1-K$. That is,

$$\mathbb{P}(\mathbf{x}_1) = \int \int \cdots \int \mathbb{P}(x_{i_1}, \cdots, x_{i_K}, x_{i_1^{\star}}, \cdots, x_{i_{n-1-K}^{\star}}) \mathrm{d}x_{i_1^{\star}} \mathrm{d}x_{i_2^{\star}} \cdots \mathrm{d}x_{i_{n-1-K}^{\star}}$$

Note that for purpose of generalization, the $x_{i_l^*}$ s are not necessarily in a particular order or sequence so long as $\sum_{i=1}^n x_i = \sum_{k=1}^K x_{i_k} + \sum_{l=1}^{n-K} x_{i_l^*} = 1$. So that

$$\mathbb{P}(\mathbf{x}_{1}) = \frac{\Gamma(\alpha_{i_{1}} + \dots + \alpha_{i_{n-K}^{\star}})}{\Gamma(\alpha_{i_{1}}) \times \dots \times \Gamma(\alpha_{i_{n-K}^{\star}})} x_{i_{1}}^{\alpha_{i_{1}} - 1} \times \dots \times x_{i_{K}}^{\alpha_{i_{K}} - 1}$$

$$\times \int \dots \int x_{i_{1}^{\star}}^{\alpha_{i_{1}^{\star}} - 1} \times \dots \times x_{i_{n-1-K}^{\star}}^{\alpha_{i_{n-1}-K}^{\star} - 1}$$

$$\times \left[1 - \sum_{k=1}^{K} x_{i_{k}} - \sum_{l=1}^{n-2-K} x_{i_{l}^{\star}} - x_{i_{n-1-K}^{\star}} \right]^{\alpha_{i_{n-K}^{\star}}^{\star} - 1} dx_{i_{n-1-K}^{\star}} \dots dx_{i_{1}^{\star}}^{\star}$$

Now we want to prove by induction that for all l, the marginal distribution of \mathbf{x}_1 is a Dirichlet distribution. In particular, for l = n - 1 - K: let $x_{i_{n-1}-K}^{\star} = \left[1 - \sum_{k=1}^{K} x_{i_k} - \sum_{l=1}^{n-2-K} x_{i_l^{\star}}\right] u$. Then evaluating the first

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integration with respect to $x_{i_{n-1-K}^{\star}}$ gives:

$$\int \frac{\Gamma(\alpha_{i_{1}} + \dots + \alpha_{i_{n-K}})}{\Gamma(\alpha_{i_{1}}) \times \dots \times \Gamma(\alpha_{i_{n-K}})} x_{i_{1}}^{\alpha_{i_{1}}-1} \times \dots \times x_{i_{K}}^{\alpha_{i_{K}}-1}$$

$$\times x_{i_{1}^{*}}^{\alpha_{i_{1}^{*}}-1} \times \dots \times \left\{ \left[1 - \sum_{k=1}^{K} x_{i_{k}} - \sum_{l=1}^{n-2-K} x_{i_{l}^{*}} \right] u \right\}^{\alpha_{i_{n-1}-K}}^{\alpha_{i_{n-1}-K}-1}$$

$$\times \left\{ (1-u) \left[1 - \sum_{k=1}^{K} x_{i_{k}} - \sum_{l=1}^{n-2-K} x_{i_{l}^{*}} \right] \right\}^{\alpha_{i_{n-K}}^{*}-1} dx_{i_{n-1-K}^{*}}^{*}$$

$$= \frac{\Gamma(\alpha_{i_{1}} + \dots + \alpha_{i_{n-K}^{*}})}{\Gamma(\alpha_{i_{1}}) \times \dots \times \Gamma(\alpha_{i_{n-K}^{*}})} x_{i_{1}}^{\alpha_{i_{1}}-1} \times \dots \times x_{i_{K}^{*}}^{\alpha_{i_{K}}-1}$$

$$\times x_{i_{1}^{*}}^{\alpha_{i_{1}^{*}}-1} \dots \left\{ \left[1 - \sum_{k=1}^{K} x_{i_{k}} - \sum_{l=1}^{n-2-K} x_{i_{l}^{*}} \right] \right\}^{\alpha_{i_{n-1-K}}^{*}+\alpha_{i_{n-K}^{*}}-1}$$

$$\times \int u^{\alpha_{i_{n-1-K}}^{*}-1} (1-u)^{\alpha_{i_{n-K}}^{*}} - 1 dx_{i_{n-1-K}^{*}} \dots dx_{i_{1}^{*}}^{*}$$

$$\times \int u^{\alpha_{i_{n-1-K}}^{*}-1} (1-u)^{\alpha_{i_{n-K}}^{*}} dx_{i_{n-1}^{*}}^{*} \times \dots \times x_{i_{K}^{*}}^{*}$$

$$= \frac{\Gamma(\alpha_{i_{1}} + \dots + \alpha_{i_{n-K}^{*}})}{\Gamma(\alpha_{i_{1}}) \times \dots \times \Gamma(\alpha_{i_{n-K}^{*}})} x_{i_{1}}^{\alpha_{i_{1}}-1} \times \dots \times x_{i_{K}^{*}}^{*}$$

$$\times x_{i_{1}^{*}}^{*} \dots \left\{ \left[1 - \sum_{k=1}^{K} x_{i_{k}} - \sum_{l=1}^{n-2-K} x_{i_{l}^{*}} \right] \right\}^{\alpha_{i_{n-1-K}}^{*}+\alpha_{i_{n-K}}^{*}-1}$$

$$\frac{\Gamma(\alpha_{i_{n-1-K}}^{*})\Gamma(\alpha_{i_{n-K}^{*}})}{\Gamma(\alpha_{i_{n-1-K}}^{*})\Gamma(\alpha_{i_{n-K}^{*}})} dx_{i_{n-2-K}}^{*} \dots dx_{i_{1}^{*}}.$$

Ignoring for now other remaining integrals returns the marginal distribution for the remaining variables $x_{i_1}, \dots, x_{i_K}, x_{i_1^*}, \dots, x_{i_{n-2-K}^*}$ and is given by

$$\frac{\Gamma(\alpha_{i_1} + \dots + \alpha_{i_{n-K}^*})}{\Gamma(\alpha_{i_1}) \times \dots \times \Gamma(\alpha_{i_{n-1-K}^*} + \alpha_{i_{n-K}^*})} x_{i_1}^{\alpha_{i_1} - 1} \times \dots \times x_{i_K}^{\alpha_{i_K} - 1} x_{i_1^*}^{\alpha_{i_1^*} - 1} \\
\times \dots x_{i_{n-2-K}^*}^{\alpha_{i_{n-1-K}^*} - 1} \left\{ \left[1 - \sum_{k=1}^K x_{i_k} - \sum_{l=1}^{n-2-K} x_{i_l^*} \right] \right\}^{\alpha_{i_{n-1-K}^*} + \alpha_{i_{n-K}^*} - 1} . (19)$$

Hence the distribution of the subset coordinate $\mathbf{x}_1^{(1)} \triangleq (x_{i_1}, \cdots, x_{i_K}, x_{i_1^*}, \cdots, x_{i_{n-2-K}})^{\mathrm{T}}$ is Dirichlet distribution with parameters $(\mathbf{p}_1^{(1)}, q^{(1)})$ where $\mathbf{p}_1^{(1)} = (\alpha_{i_1}, \cdots, \alpha_{i_K}, \alpha_{i_1^*}, \cdots, \alpha_{i_{n-2-K}})^{\mathrm{T}}$ and $q^{(1)} = \alpha_{i_{n-1-K}^*} + \alpha_{i_{n-K}^*}$. Equivalently, since \mathbf{x}_1 is arbitrary then $\mathbf{x}_1^{(1)}$ is one possible vector of \mathbf{x}_1 with parameters $\mathbf{p}_1 = \mathbf{p}_1^{(1)}$ and if we let $p \triangleq \sum_{i=1}^n \alpha_i = \sum_{k=1}^K \alpha_{i_k} + \sum_{l=1}^{n-K} \alpha_{i_l^*}$ then $q^{(1)} = p - \mathbf{1}^{\mathrm{T}} \mathbf{p}_1^{(1)} = p - \sum_{k=1}^K \alpha_{i_k} - \sum_{l=1}^{n-2-K} \alpha_{i_l^*}$.

If we continue with the remaining integration this time with respect to $x_{i_{n-2-K}^*}$, the marginal distribution is still Dirichlet distribution but with parameters $(\mathbf{p}_1^{(2)},q^{(2)})$ where $\mathbf{p}_1^{(2)}=(\alpha_{i_1},\cdots,\alpha_{i_K},\alpha_{i_1^*},\cdots,\alpha_{i_{n-3-K}})^{\mathrm{T}}$ and $q^{(2)}=\alpha_{i_{n-2-K}^*}+\alpha_{i_{n-1-K}^*}+\alpha_{i_{n-K}^*}=p-\mathbf{1}^{\mathrm{T}}\mathbf{p}_1^{(2)}=p-\sum_{k=1}^K\alpha_{i_k}-\sum_{l=1}^{n-3-K}\alpha_{i_l^*}$. To see this, apply the change variable technique, that is for l=n-2-K: let $x_{i_{n-2-K}^*}=\left[1-\sum_{k=1}^Kx_{i_k}-\sum_{l=1}^{n-3-K}x_{i_l^*}\right]u$. Then with a little algebra aiming for the kernel of Beta distribution, this time with parameters $\alpha_{i_{n-2-K}^*}$ and $\alpha_{i_{n-1-K}^*}+\alpha_{i_{n-K}^*}$, one will obtain the said marginal distribution.

Therefore in general, for any subset coordinate vector \mathbf{x}_1 , the distribution of \mathbf{x}_1 is Dirichlet with parameters stated in the Corollary that is now verified to be true.

5. Corollary 3.4 If $S = \mathbf{x}^T \mathbf{1} = \sum_{i=1}^n x_i$ and again $\mathbf{x}_1 = (x_{i_1}, \dots, x_{i_K})^T, K < n$ is any subset, let $\mathbf{w}_1 \stackrel{d}{=} \frac{1}{S} \mathbf{x}_1$. We find $\mathbf{w}_1 \sim \mathcal{D}_K(\mathbf{p}_1; r)$ with $\mathbf{p}_1 = (p_{i_1}, \dots, p_{i_K})^T$ as before but this time, $p - p_{n+1} = r + \sum_{j=1}^K p_{i_j}$.

Proof. From Corollary 3.2, we proved that $\mathbf{x}_1 \sim \mathcal{D}_k(\mathbf{p}_1, q)$ and $p = q + \sum_{i=1}^K p_{i_i}$. Then

$$\mathbb{P}(\mathbf{x}_1|\mathbf{p},q) \triangleq \frac{\Gamma(\mathfrak{S})}{\prod_{i=1}^{n-K} \Gamma(\alpha_i)\Gamma(q)} \prod_{i=1}^{n-K-1} x_i^{\alpha_i-1} \left(1 - \sum_{j=1}^{n-K-1} x_i^{\alpha_i-1}\right)^{q-1}$$
(20)

where $\mathfrak{S} = \sum_{i=1}^{n-K} \alpha_i$. To show that $\mathbf{w}_1 \stackrel{d}{=} \frac{1}{S} \mathbf{x}_1$, we have to consider

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Jacobian transformation. That is,

$$\mathbf{x}_{1} \stackrel{d}{=} S\mathbf{w}_{1} \quad \text{or} \quad \begin{bmatrix} x_{i_{1}} \\ x_{i_{2}} \\ \vdots \\ x_{i_{K}} \end{bmatrix} \stackrel{d}{=} \begin{bmatrix} Sw_{1} \\ Sw_{2} \\ \vdots \\ S \end{bmatrix}. \tag{21}$$

Now using vector differentiation and noting that $x_{i_K} = S(1 - \sum_{k=1}^{K-1} x_{i_k})$, we have

$$\frac{\partial \mathbf{x}_1}{\partial \mathbf{w}_1} = \begin{pmatrix} \frac{\partial x_{i_1}}{\partial w_1} & \frac{\partial x_{i_1}}{\partial w_2} & \cdots & \frac{\partial x_{i_1}}{\partial w_K} \\ \frac{\partial x_{i_2}}{\partial w_1} & \frac{\partial x_{i_2}}{\partial w_2} & \cdots & \frac{\partial x_{i_2}}{\partial w_K} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x_{i_K}}{\partial w_1} & \frac{\partial x_{i_K}}{\partial w_2} & \cdots & \frac{\partial x_{i_K}}{\partial w_K} \end{pmatrix}$$

The rest of the proof is analogous to the proof of Proposition 3.1. Hence, following the proof of the said Proposition, Corollary 3.4 then follows. \Box