

%To find the Z-transform of a given discrete-time signal x[n]

```
clear all; close all; clc;
n = -35:1:35; % Time range for the signal
length_of_sqn = length(n);
x_n = zeros(1, length_of_sqn); % Initialize i.p signal

% Choose and uncomment the desired signal:
% Unit step signal
for ii = 1 : length_of_sqn
    if (n(ii) < 0)
        x_n(ii) = 0;
    else
        x_n(ii) = 1;
    end end
% Ramp signal
% for ii = 1 : length_of_sqn
%     if (n(ii) < 0)
%         x_n(ii) = 0;
%     else
%         x_n(ii) = n(ii);
%     end end

% Exponential signal
% for ii = 1 : length_of_sqn
%     if (n(ii) >= 0)
%         x_n(ii) = 0.5.^n(ii);
%     else
%         x_n(ii) = 0;
%     end end
% Double-sided exponential signal
% for ii = 1 : length_of_sqn
%     if (n(ii) >= 0)
%         x_n(ii) = 0.5.^n(ii);
%     else
%         x_n(ii) = 0.8.^n(ii);
%     end end

% Plotting the input signal
subplot(2,2,1);
stem(n, x_n, 'filled');
title('Input Signal');
xlabel('n');
ylabel('x[n]');

omega = linspace(-pi, pi, 100);
z = [];
% Generate Z values
for r = linspace(0, 3, 100)
    z = [z; r .* exp(1j .* omega)];
end
Xtemp = [];
X = [];
XFinal = [];
% Compute Z-transform
for c = 1:length(z)
    for b = 1:length(z)
        temp = 0;
        for a = 1:length(n)
            temp = temp + (x_n(a) .* (z(c,b) .^ (-n(a))));
        end
        Xtemp = [Xtemp, temp];
    end
    X = [X; Xtemp];
    Xtemp = [];
end
XFinal = X;
```

```
% Plot Z-transform result
```

```
subplot(2,2,3:4);
```

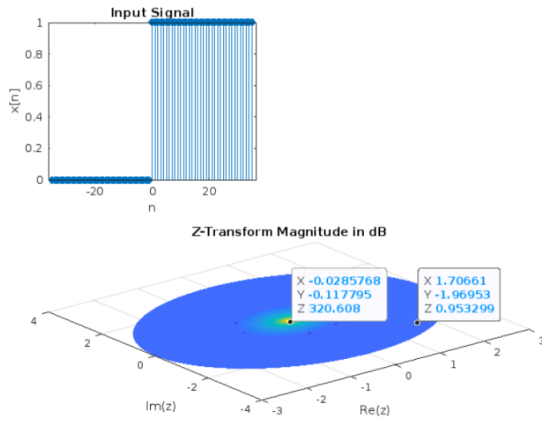
```
surf(real(z), imag(z), 10*log10(abs(XFinal)),  
'linestyle', 'none');
```

```
title('Z-Transform Magnitude in dB');
```

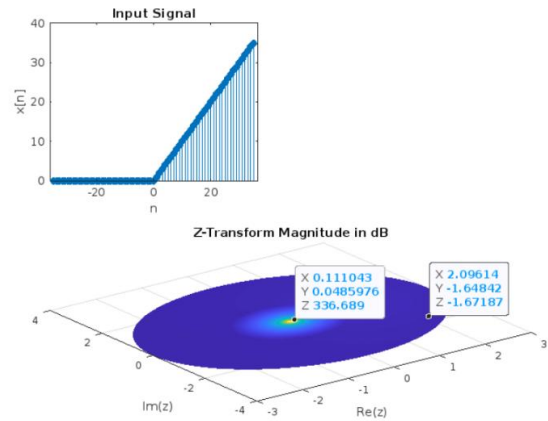
```
xlabel('Re(z)');
```

```
ylabel('Im(z)');
```

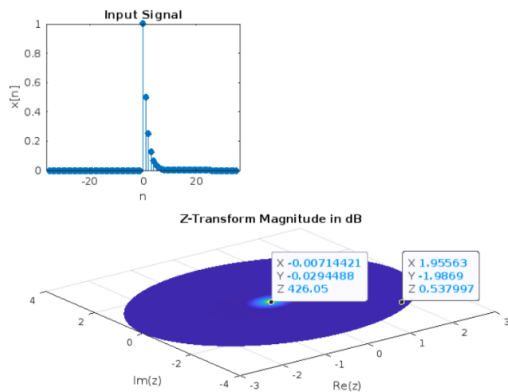
```
zlabel('Magnitude (dB)');
```



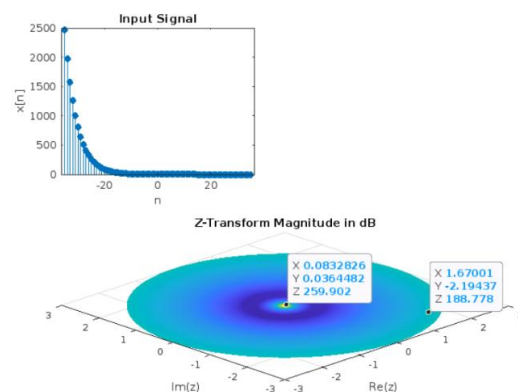
Unit step signal



Unit ramp signal



One sided exponential signal



Double sided exponential signal

% 10 a: Visualization of Z plane

```
clear all;close all; clc;
```

```
% Define the frequency range
```

```
w = linspace(-pi, pi, 1001); % Frequency range
```

```
% Initialize arrays for Z and H values
```

```
Z = []; % Initialize Z values
```

```
H = []; % Initialize H values
```

```
% Generate Z values for radius from 0 to 3
```

```
for r = linspace(0, 3, 1001)
```

```
    Z = [Z; r .* exp(1j * w)]; % Create Z values for each radius
```

```
end
```

```
% Calculate the transfer function H(z)
```

```
H = (2 .* Z) ./ (2 .* Z - 1); % H(z) formula
```

```
% Plotting the 3D mesh of H(z) in the Z plane
```

```
mesh(real(Z), imag(Z), abs(H)); % Plot mesh
```

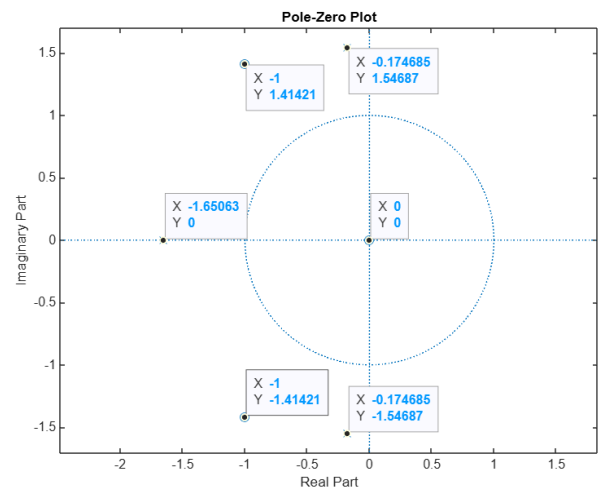
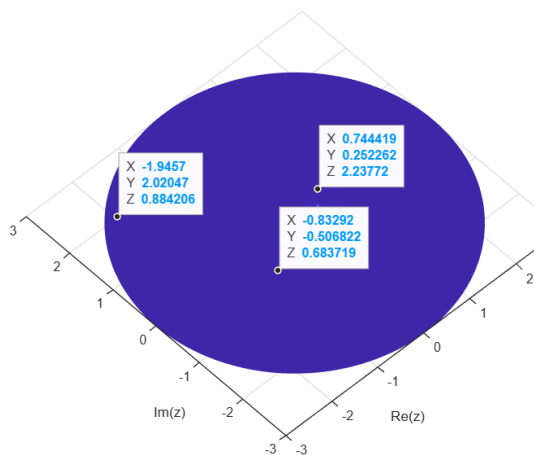
```
grid on;
```

```
% Add labels to the plot
```

```
xlabel('Re(z)'); % Real part of Z
```

```
ylabel('Im(z)'); % Imaginary part of Z
```

```
zlabel('H(z)'); % Magnitude of H(z)
```



%10 b: Z-plane plot (Pole-Zero Plot)

```
clear all; close all; clc;
```

```
% Pole-Zero plot using zplane function
```

```
zplane([1 2 3], [1 2 3 4]);
```

% 10 d Effect of distance of poles from the unit circle on |mag| and p.h spectrum

```

clear all; close all; clc;

w = linspace(-pi, pi, 1001); % Frequency range

r = 1; % Assuming r = 1 (you can change this as
needed)

z = r .* exp(1j * w); % Compute Z values

%% First Transfer Function H = z / (z - 0.5)
% H1 = z ./ (z - 0.5);

%% Second Transfer Function H = z / (z - 0.99)
% H2 = z ./ (z - 0.99);

%% Third Transfer Function H = z / (z - 0.1)
% H3 = z ./ (z - 0.1);

% Plot the magnitude of the first transfer function
subplot(3,1,1);
plot(w, abs(H1)); % Magnitude of H1
xlabel('\omega');
ylabel('|H(\omega)| at z = 0.5');

grid on;

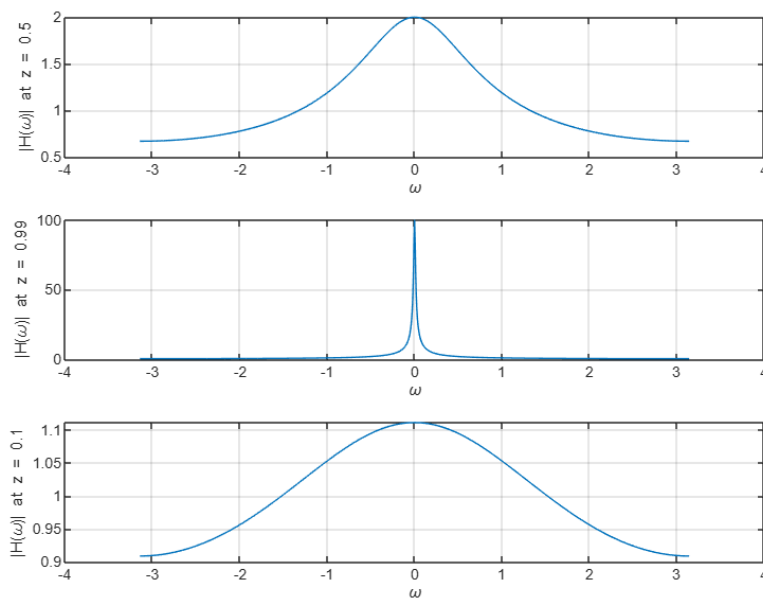
% Plot the magnitude of the second transfer
function
subplot(3,1,2);
plot(w, abs(H2)); % Magnitude of H2
xlabel('\omega');
ylabel('|H(\omega)| at z = 0.99');

grid on;

% Plot the magnitude of the third transfer
function
subplot(3,1,3);
plot(w, abs(H3)); % Magnitude of H3
xlabel('\omega');
ylabel('|H(\omega)| at z = 0.1');

grid on;

```



%10 c: Magnitude and Phase of a System

```
clear all; close all; clc;

w = linspace(-pi, pi, 1001); % Frequency range
r = 1; % Radius for the Z-plane
z = r .* exp(1j * w); % Z values

% Define the transfer function H(z)
H = ((6 .* z) .* (7 .* z - 3)) ./ ((2.8 .* z - 1) .* (3 .* z - 1));

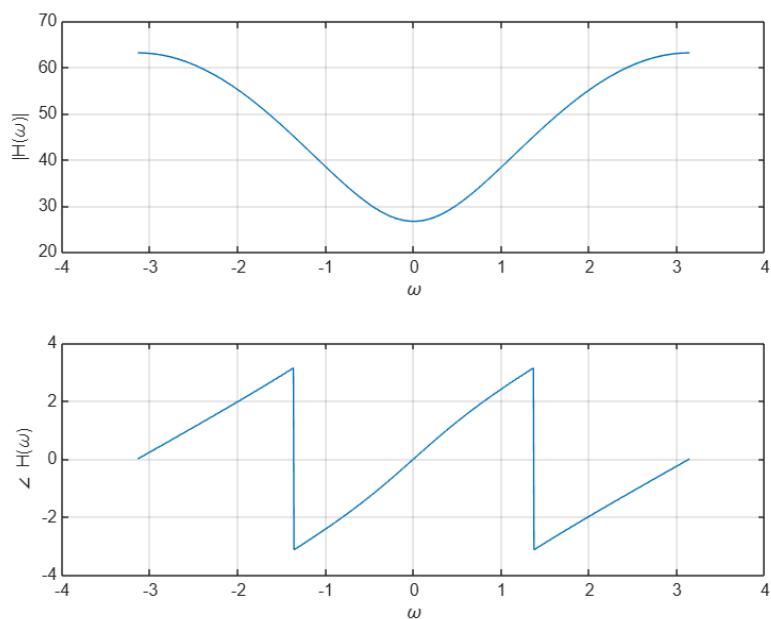
%% Plot the magnitude and phase of H(z)
figure;

% Plot magnitude of H(z)
subplot(2,1,1);

plot(w, abs(H)); % Absolute value of H(z)
xlabel('\omega');
ylabel('|H(\omega)|');
grid on;

% Plot phase of H(z)
subplot(2,1,2);

plot(w, angle(H));
xlabel('\omega');
ylabel('\angle H(\omega)');
grid on;
```



%ASSIGNMENT: Z-plane plot (Pole-Zero Plot)

```
%H(z) = z(z-0.5cos(\pi/4)) / 2*(z - e^{-j\pi/4}/2)(z - e^{j\pi/4}/2)
```

```
clear all; close all; clc;
```

```
% Define zeros
```

```
z1 = 0;
```

```
z2 = sqrt(2)/4;
```

```
zeros = [z1, z2];
```

```
% Define poles (conjugate complex)
```

```
p1 = (1/2)*exp(1j*pi/4);
```

```
p2 = (1/2)*exp(-1j*pi/4);
```

```
poles = [p1, p2];
```

```
% Get numerator and denominator coefficients
```

```
num = poly(zeros); % z*(z - sqrt(2)/4)
```

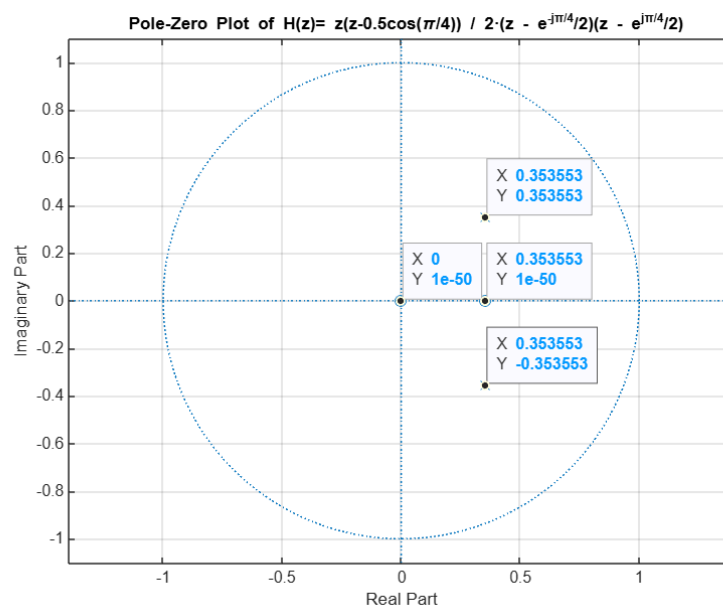
```
den = 2 * poly(poles); % 2*(z - e^{j\pi/4}/2)*(z - e^{-j\pi/4}/2)
```

```
% Plot pole-zero plot
```

```
zplane(num, den);
```

```
title(' Pole-Zero Plot of H(z)= z(z-0.5cos(\pi/4)) / 2*(z - e^{-j\pi/4}/2)(z - e^{j\pi/4}/2)');
```

```
grid on;
```



%ASSIGNMENT: Z-plane plot (Pole-Zero Plot)

```
%H(z) = z·sin(\pi/4) / 2·(z - e^{-j\pi/4}/2)(z - e^{j\pi/4}/2)

clear all; close all; clc;

% Numerator zero

z0 = 0; % zero at origin

gain = sin(pi/4); % gain from numerator

% Poles (complex conjugates)

p1 = (1/2) * exp(1j * pi/4);
p2 = (1/2) * exp(-1j * pi/4);

% Get coefficients

num = gain * poly([z0]); % z * sin(pi/4)

den = 2 * poly([p1, p2]); % 2 * (z - e^{-j\pi/4}/2)(z - e^{j\pi/4}/2)

% Plot pole-zero plot

zplane(num, den);

title('Pole-Zero Plot of H(z) = z·sin(\pi/4) / 2·(z - e^{-j\pi/4}/2)(z - e^{j\pi/4}/2)');

grid on;
```

