

# Computational Geometry

## Chapter 3

### Polygons and Triangulation



13.

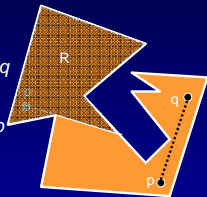
## On the Agenda

- The Art Gallery Problem
- Polygon Triangulation

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## Art Gallery Problem

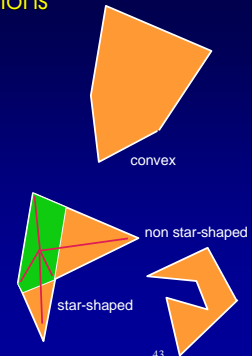
- Given a simple polygon  $P$ , say that two points  $p$  and  $q$  can see each other if the open segment  $pq$  lies entirely within  $P$ .
- A point *guards* a region  $R \subseteq P$  if  $p$  sees all  $q \in R$ .
- Given a polygon  $P$ , what is the minimal number of guards required to guard  $P$ , and what are their locations?



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## Observations

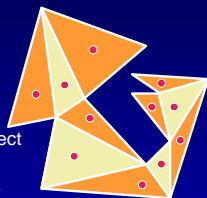
- The *entire* interior of a convex polygon is visible from *any* interior point.
- A *star-shaped* polygon requires only one guard located in its *kernel*. (actually this is the definition of a star-shape polygon)



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## Art Gallery Problem – Easy Upper Bound

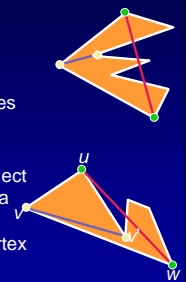
- $n-2$  guards suffice:
  - Subdivide the polygon into  $n-2$  triangles (triangulation)
  - (we will show that this is the correct number of triangles)
  - Place one guard in each triangle.
- **Theorem:** Any simple planar polygon with  $n$  vertices has a triangulation of size  $n-2$ .



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## Diagonals in Polygons

- A *diagonal* of a polygon  $P$  is a line segment connecting two non-adjacent vertices, which lies entirely within  $P$ .
- **Theorem:** Any polygon with  $n > 3$  vertices has a diagonal, which may be found in  $O(n)$  time.
- **Proof:** Find the leftmost vertex  $v$ . Connect its two neighbors  $u$  and  $w$ . If this is not a diagonal there are other vertices inside the triangle  $uvw$ . Connect  $v$  to the vertex  $v'$  furthest from the (line containing the) segment  $uw$ .



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## $O(n^2)$ Polygon Triangulation

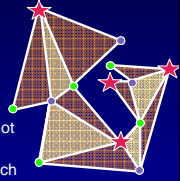
- **Theorem:** Every simple polygon with  $n$  vertices has a triangulation consisting of  $n-3$  diagonals and  $n-2$  triangles.
- **Proof:** By induction on  $n$ : **Basis:** A triangle ( $n=3$ ) has a triangulation (itself) with no diagonals and one triangle.
- **Induction:** for a  $n+1$  vertex polygon, construct a diagonal dividing the polygon into two polygons with  $n_1$  and  $n_2$  vertices such that  $n_1+n_2=n$ . Triangulate the two parts of the polygon. There are now  $n_1-3+n_2-3+1=n-3$  diagonals and  $n_1-2+n_2-2=n-2$  triangles.



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## Art Gallery Problem – Upper Bound

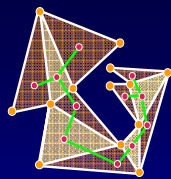
- **Claim:**  $\lfloor n/3 \rfloor$  guards are enough
- Color the vertices of the triangulated polygon with three colors, such that there is no edge between two vertices with the same color. (will show that this doable)
- Pick a color which is least used. This color cannot appear more than  $\lfloor n/3 \rfloor$  times.
- Place a guard on each vertex with this color. Each triangle has only one guarded vertex, but this guard covers all triangles incident on the vertex.
- $\Rightarrow$  New upper bound:  $\lfloor n/3 \rfloor$



83.

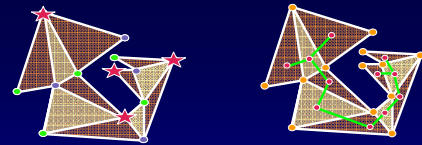
## 3-Coloring

- **Theorem:** Every triangulated polygon has an *ear* (a triangle containing two boundary edges).
- **Proof:** Consider the *dual* to the triangulation.
  - Every triangle  $\rightarrow$  vertex.
  - Two neighboring triangles  $\rightarrow$  an edge.
  - Since any diagonal disconnects the polygon, the dual is a tree.
  - The vertex degrees are bounded by 3.
  - Ears correspond to leaves in the dual.



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- **Rembrandt Theorem:** The vertices of the (triangulated) polygon may be 3-colored, so the colors of the vertices of each edge are different.
- **Proof:** By induction on  $n$ :
  - Basis: Trivial if  $n=3$ .
  - Induction: Cut off an ear.
    - 3-color the  $n-1$  vertex remainder.
    - Color the  $n$ 'th vertex with the third color different from the two on its supporting edge.



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## $\lfloor n/3 \rfloor$ - Tight Bound

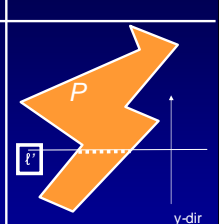
- There exists a polygon with  $n$  vertices, for which  $n/3$  guards are necessary.



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## $O(n \log n)$ -Time Polygon Triangulation

- A simple (no holes) polygon  $P$  is called *monotone* with respect to a direction  $\ell$  if for any line  $\ell'$  perpendicular to  $\ell$  the intersection of  $P$  with  $\ell'$  is connected.
- A polygon is called *monotone* if there exists any such direction  $\ell$ .
- A polygon that is monotone with respect to both the  $x$  and  $y$ -axis is called *x/y-monotone*.



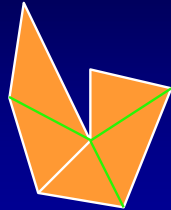
**Question:** How can we check in  $O(n)$  time whether a polygon is  $y$ -monotone?

$y$ -monotone but not  $x$ -monotone polygon

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## Triangulation Algorithm – cont.

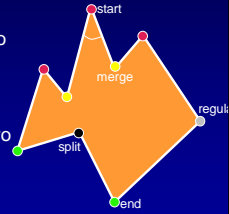
- 1) Partition the polygon into  $y$ -monotone pieces.
- 2) Triangulate each  $y$ -monotone piece separately.



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## Classifying the vertices of $Y$ -Monotone Polygons

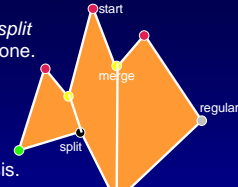
- A **start** (resp., **end**) vertex is one whose interior angle is  $\leq \pi$  and its two neighboring vertices both lie below (resp., above) it.
- A **split** (resp., **merge**) vertex is one whose interior angle is  $\geq \pi$  and its two neighboring vertices both lie below (resp., above) it.
- All other vertices are **regular**.



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## $Y$ -Monotone Polygons

- **Theorem:** A polygon without *split* and *merge* vertices is  $y$ -monotone.
- **Proof:** Since there are only start/end/regular vertices, the polygon must consist of two  $y$ -monotone chains. Alternatively, do a case analysis.

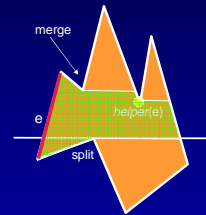


- To partition a polygon to monotone pieces, eliminate split (merge) vertices by adding diagonals upward (downward) from the vertex. Naturally, the diagonals must not intersect!

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## Monotone Partitioning

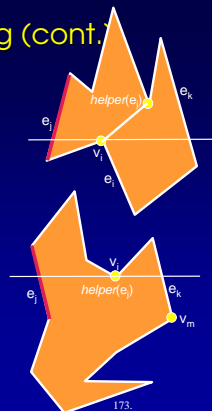
- Classify all vertices.
- Sweep  $P$  (with a line) from top to bottom.
- Maintain the edges intersected by the sweep line in a *sweep line status* (SLS sorted by  $x$  coordinate).
- Maintain vertex events in an event queue (EQ sorted by  $y$  coordinate).
- Eliminate split/merge vertices by connecting them to other vertices, as follow:
- For each edge  $e$ , define *helper(e)* as the lowest vertex (seen so far) above the sweep line **vertically visible** to the right of the edge.
- *helper(e)* is initialized to the upper endpoint of  $e$ .



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## Monotone Partitioning (cont.)

- A split vertex may be connected to the helper vertex of the edge immediately to its left (along the sweep line).
  - Question: Why this connection does not intersect previously-made connections?
- However, a merge vertex should be connected to a vertex which has not yet been processed!
- Clever idea: Every merge vertex is the helper of some edge, and will be handled when this edge "terminates".



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## Monotone Partitioning Algorithm

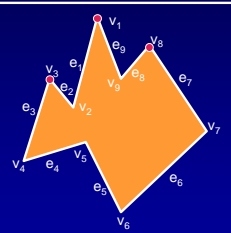
- Input: A counterclockwise ordered list of vertices of  $P$ .
  - /\* Notation: The edge  $e_i$  immediately follows the vertex  $v_i$  CCK\*/
- Construct an EQ (*events queue*) on the vertices of  $P$  using  $y$ -coordinates.
- Initialize SLS (*sweep line status*) to be empty.
- While EQ is not empty:
  - Pop vertex  $v_i$ ;
  - Handle  $v_i$ .
 (No new events are generated during execution.)
- Idea: No split/merge vertex remains unhandled!

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## Monotone Partitioning

### Handling a *start* vertex ( $v_i$ ):

- Add  $e_i$  to SLS
- $helper(e_i) := v_i$

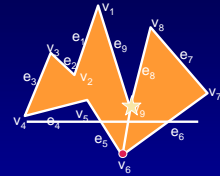


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## Monotone Partitioning

### Handling an *end* vertex ( $v_i$ ):

- If  $helper(e_{i-1})$  is a merge vertex, then connect  $v_i$  to  $helper(e_{i-1})$
- Else don't connect  $v_i$
- Remove  $e_{i-1}$  from SLS

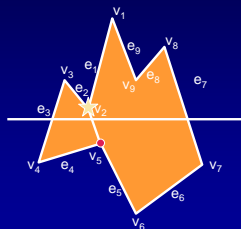


203.

## Monotone Partitioning

### Handling a *split* vertex ( $v_i$ ):

- Find in SLS the edge  $e_j$  directly to the left of  $v_i$
- Connect  $v_i$  to  $helper(e_j)$
- $helper(e_i) := v_i$
- Insert  $e_i$  into SLS
- $helper(e_i) := v_i$

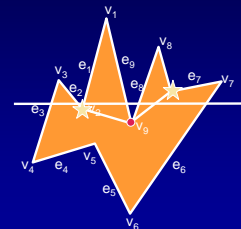


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## Monotone Partitioning

### Handling a *merge* vertex ( $v_i$ ):

- If  $helper(e_{i-1})$  is a merge vertex, then connect  $v_i$  to  $helper(e_{i-1})$
- Remove  $e_{i-1}$  from SLS
- Find in SLS the edge  $e_j$  directly to the left of  $v_i$
- If  $helper(e_j)$  is a merge vertex, then connect  $v_i$  to  $helper(e_j)$
- $helper(e_i) := v_i$

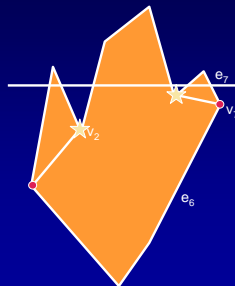


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## Monotone Partitioning

### Handling a *regular* vertex ( $v_i$ ):

- If the polygon's interior lies to the left of  $v_i$  then:
  - Find in SLS the edge  $e_j$  directly to the left of  $v_i$
  - If  $helper(e_j)$  is a merge vertex, then connect  $v_i$  to  $helper(e_j)$
  - $helper(e_i) := v_i$
- Else:
  - If  $helper(e_{i-1})$  is a merge vertex, then connect  $v_i$  to  $helper(e_{i-1})$
  - Remove  $e_{i-1}$  from SLS
  - Insert  $e_i$  into SLS
  - $helper(e_i) := v_i$



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## Triangulating a Y-monotone Polygon-warm-ups

Recall – must consist of a left chain and right chain

Def: Convex vertex – interior angle  $\leq \pi$ .  
Otherwise called reflex vertex.

Convex chain – consecutive part of the chain consisting of convex vertices.

Very easy to triangulate a chain of convex vertices greedily connect them to a vertex on the other side, or between themselves

Preference to connect left chain to right, but sometimes must connect within the same chain.



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## Triangulating a Y-monotone Polygon

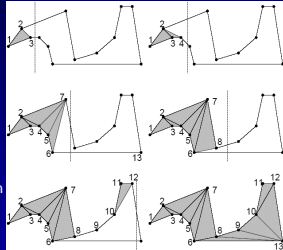
Sweep the polygon from top to bottom.

Greeditly triangulate anything possible above the sweep line, and then forget about this region. (order irrelevant)

- When we process a vertex  $v$ , the unhandled region above it always has a simple structure:  
Two y-monotone (left and right) chains, each containing at least one edge. If a chain consists of two or more edges, it is *reflex*, and the other chain consists of a single edge whose bottom endpoint has not been handled yet.

- Each diagonal is added in  $O(1)$  time – only constant number of checks

A chain consists of both polygon edges and diagonals (connecting left-left or right-right)



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## Triangulating a Y-monotone Polygon

- Continue sweeping while one chain contains only one edge, while the other edges are reflex.
- When a “convex edge” appears in the concave chain (or a second edge appears in the other one), triangulate as much as possible using a “fan”.
- Time complexity:  $O(n)$ , where  $n$  is the complexity of the polygon.



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