

Stochastic Backpropagation

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Exponential Families

$$p(x|\eta) = h(x)g(\eta)\exp\{\eta^T u(x)\}$$

Maximum Likelihood Estimation

$$p(X|\eta) = \int h(x)g(\eta)\exp\{\eta^T u(x)\}$$

Differentiating, we get

$$\begin{aligned}\frac{\partial p(X|\eta)}{\partial \eta} &= \nabla g(\eta) \int h(x) \exp\{\eta^T u(x)\} dx \\ &\quad + g(\eta) \int h(x) \exp\{\eta^T u(x)\} u(x) dx\end{aligned}$$

Exponential Families

Alternatively, $\eta = \eta(\theta)$,

$$p(x|\eta) = h(x)\exp\{\eta^T u(x) - A(\eta)\}$$

A is the *log-partition function*.

Exponential Families

Theorem

The log-partition function $\theta \rightarrow A(\theta)$ is infinitely differentiable on its open domain $D := \{\theta \in \mathbb{R}^d : A(\theta) < \infty\}$. Moreover, A is convex.

Proof.

For convexity, let $\theta_\lambda = \lambda\theta_1 + (1 - \lambda)\theta_2$, where $\theta_1, \theta_2 \in D$. Then, $\frac{1}{\lambda} \geq 1$ and $\frac{1}{1-\lambda} \geq 1$, and Holder's inequality is applicable. (Since the coefficients are conjugate exponents). We get,

$$\begin{aligned} & \log \int h(x) \exp(\langle \theta_\lambda, u(x) \rangle) dx \\ &= \log \int h(x) \exp(\langle \theta_1, u(x) \rangle)^\lambda \exp(\langle \theta_2, u(x) \rangle)^{1-\lambda} dx \\ &\leq \log \left(\int h(x) \exp(\langle \theta_1, u(x) \rangle)^\lambda dx \right)^\lambda \left(\int \exp(\langle \theta_2, u(x) \rangle)^{\frac{1-\lambda}{1-\lambda}} dx \right)^{1-\lambda} \end{aligned}$$

Exponential Distribution

Proof (Cont.)

$$= \lambda \log \int h(x) \exp(\langle \theta_1, u(x) \rangle) dx + (1 - \lambda) \log \int h(x) \exp(\langle \theta_2, u(x) \rangle) dx$$



Exponential Distribution

Convexity makes estimation in exponential families substantially easier. Indeed, given a sample X_1, \dots, X_n assume that we estimate θ by maximizing likelihood (equivalently, minimizing the log loss):

$$\min_{\theta} \sum_{i=1}^n \log \frac{1}{p_{\theta}(X_i)} = \sum_{i=1}^n [-\langle \theta, u(X_i) \rangle + A(\theta)]$$

which is convex in θ .

Stochastic Backpropagation

Gradient descent methods in latent variable models require computations

$$\nabla_{\theta} \mathbb{E}_{q_{\theta}}[f(x)]$$

$$\theta \sim q_{\theta}(\cdot)$$

f = loss function

Quantity is difficult to compute:

1. expectation is unknown
2. indirect dependency on q

Bonnet's Theorem

Let $f(x): \mathbb{R}^d \rightarrow \mathbb{R}$ be a integrable and twice differentiable function. The gradient of the expectation of $f(x)$ under a Gaussian distribution $\mathcal{N}(x|\mu, \Sigma)$ with respect to the mean μ can be expressed as the expectation of the gradient of $f(x)$.

$$\nabla_{\mu_i} \mathbb{E}_{\mathcal{N}(\mu, \Sigma)}[f(x)] = \mathbb{E}_{\mathcal{N}(\mu, \Sigma)}[\nabla_{x_i} f(x)]$$

Price's Theorem

Let $f(x): \mathbb{R}^d \rightarrow \mathbb{R}$ be a integrable and twice differentiable function. The gradient of the expectation of $f(x)$ under a Gaussian distribution $\mathcal{N}(x|\mu, \Sigma)$ with respect to the covariance Σ can be expressed in terms of the expectation of the Hessian of $f(x)$ as:

$$\nabla_{\Sigma_{i,j}} \mathbb{E}_{\mathcal{N}(\mu, \Sigma)}[f(x)] = \frac{1}{2} \mathbb{E}_{\mathcal{N}(\mu, \Sigma)}[\nabla_{x_i, x_j}^2 f(x)]$$

Backpropagation

By applying chain rule, we get:

$$\nabla_{\theta} \mathbb{E}_{\mathcal{N}(\mu, \Sigma)}[f(x)] = \mathbb{E}_{\mathcal{N}(\mu, \Sigma)} \left[\mathbf{g}^T \frac{\partial \mu}{\partial \theta} + \frac{1}{2} \text{Tr} \left(H \frac{\partial \Sigma}{\partial \theta} \right) \right]$$

\mathbf{g} : gradient

H : hessian

For General Distributions

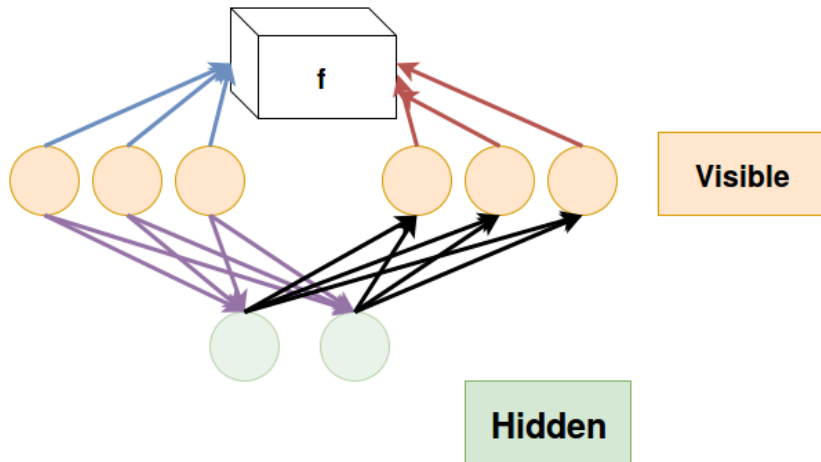
$$\nabla_{\theta} \mathbb{E}_p[f(x)] = \mathbb{E}_{p(x|\theta)}[B(x) \nabla_x f(x)]$$

where B is a non-linear function.

For exponential distributions:

$$B(x) = \frac{[\nabla_{\theta} \eta u(x) - \nabla_{\theta} A]}{[\nabla_x \log[h(x)] + \eta^T \nabla_x u(x)]}$$

Relation to RBM



Energy Function

$$E(\mathbf{v}, \mathbf{h}) = \sum_{i=1}^V \frac{(v_i - b_i)^2}{2\sigma_i^2} - \mathbf{c}^T \mathbf{h} - \sum_{j=1}^V \sum_{i=1}^H \frac{v_i}{\sigma_i} h_j w_{ij}$$

Probability

$$P(\mathbf{v}) = \sum_{\mathbf{h}} \frac{1}{Z} e^{-E(\mathbf{v}, \mathbf{h})} = \sum_{\mathbf{h}} \frac{1}{Z} e^{-\sum_{i=1}^V \frac{(v_i - b_i)^2}{2\sigma_i^2} + \mathbf{c}^T \mathbf{h} + \sum_{j=1}^V \sum_{i=1}^H \frac{v_i}{\sigma_i} h_j w_{ij}}$$

$$P(\mathbf{v}) = \frac{1}{Z} e^{-F(\mathbf{v})}$$

where $F(\mathbf{v})$ is free energy

GB-RBM

Free Energy

$$F(v) = -\log\left(\sum_{\mathbf{h}} e^{-\sum_{i=1}^V \frac{(v_i - b_i)^2}{2\sigma_i^2} + \mathbf{c}_{\mathbf{h}}^T \mathbf{h} + \sum_{j=1}^H \sum_{i=1}^V \frac{v_i}{\sigma_i} h_j w_{ij}}\right)$$

Simplifying the term within the \log

$$\begin{aligned} & \sum_{\mathbf{h}} e^{-\sum_{i=1}^V \frac{(v_i - b_i)^2}{2\sigma_i^2} + \mathbf{c}_{\mathbf{h}}^T \mathbf{h} + \sum_{j=1}^H \sum_{i=1}^V \frac{v_i}{\sigma_i} h_j w_{ij}} \\ &= e^{-\sum_{i=1}^V \frac{(v_i - b_i)^2}{2\sigma_i^2}} \times \prod_j (e^{c_j + \sum_{i=1}^V \frac{v_i}{\sigma_i} w_{ij}} + 1) \end{aligned}$$

Substituting, we get

$$F(v) = \sum_{i=1}^V \frac{(v_i - b_i)^2}{2\sigma_i^2} - \sum_j \log(e^{c_j + \sum_{i=1}^V \frac{v_i}{\sigma_i} w_{ij}} + 1)$$

Conditional Probability

$$\begin{aligned}P(\mathbf{h}|\mathbf{v}) &= \frac{\prod_j e^{(c_j h_j + \sum_{i=1}^V v_i w_{ij} h_j)}}{\prod_j \sum_{h_j} e^{(c_j h_j + \sum_{i=1}^V v_i w_{ij} h_j)}} \\&= \prod_j \frac{e^{(c_j h_j + \sum_{i=1}^V v_i w_{ij} h_j)}}{\sum_{h_j} e^{(c_j h_j + \sum_{i=1}^V v_i w_{ij} h_j)}} \\&= \prod_j P(h_j|\mathbf{v})\end{aligned}$$

Conclusions

Stochastic Backpropagation possible as shown above.

References I



Danilo Jimenez Rezende, Shakir Mohamed, Daan Wierstra
Stochastic Backpropagation and Approximate Inference in
Deep Generative Models