

The Vector Convention

Cédric HT

2017

Abstract

We introduce a convention that aims to make array notations shorter. In a nutshell, it revolves around the following: $\vec{x} = x_1, \dots, x_n$. When handling numerical vectors, the boldface $\mathbf{v} \in \mathbb{R}^k$ is often used. Here, we favour the arrow notation as it is rather seldom, unlikely to conflict with an already existing notation, more flexible as we will see, as well as to leave the boldface available for other meanings. We also extend this notation in a functional programming's apply fashion.

1 Indexation

Generalities. For X a set, let \vec{x} denote a finite array of elements in X :

$$\vec{x} = x_1, \dots, x_n,$$

where n is implicit. The reversed sequence is denoted by

$$\overleftarrow{x} = x_n, \dots, x_1.$$

Examples. • The statement $x_1, \dots, x_n \in X$ can be shortened as $\vec{x} \in X$.

- Identifying sequences and tuples, a real (or complex) valued vector is naturally denoted with an arrow: $\vec{v} \in \mathbb{R}^k$.

Multiple indexes. We consider an array of arrays of elements of X an array of elements of X itself, by implicit concatenation. This allows the following notation:

$$\begin{aligned} \overrightarrow{\vec{x}} &= \vec{x}_1, \dots, \vec{x}_n \\ &= x_{1,1}, \dots, x_{m_1,1}, x_{1,2}, \dots, x_{m_2,2}, \dots, x_{1,n}, \dots, x_{m_n,n}, \end{aligned}$$

with \vec{m} and n implicit. Notice how the indexes are written from the inner-most (corresponding to the lower arrow) to the outer-most (corresponding to the upper arrow), so that the arrows are expanded from top to bottom. If x is instead k -indexed, then it should be written with k arrows over it.

Examples. • The notation $\overrightarrow{\vec{x}} = \vec{y}$ means that \vec{x} is a partition of \vec{y} in subsequences of consecutive elements:

$$x_{1,1}, \dots, x_{m_1,1}, \dots, x_{1,n}, \dots, x_{m_n,n} = y_1, \dots, y_k.$$

In particular, $\sum \vec{m} = k$.

Over-indexing. For $a \in X$, let

$$\overrightarrow{a} = a, a, \dots, a,$$

where the length of the list is implicit. In particular, if $\vec{x} \in X$ is an array of elements of X , then

$$\overrightarrow{\vec{x}} = \vec{x}, \dots, \vec{x} = x_1, \dots, x_n, \dots, x_1, \dots, x_n.$$

2 Operations

Formulas. If f is any kind of mathematical statement (e.g. a function, logical formula, quantification) taking an elements of X as argument, and $\vec{x} \in X$, then let

$$\overrightarrow{f(\vec{x})} = f(x_1), \dots, f(x_n).$$

If there is no ambiguity, the notation $f(\vec{x})$ can also be used, but it is in general less clear. If \square is any kind of index-based notation (e.g. \sum , \prod), let

$$\square \vec{x} = \square_{i=1}^n x_i.$$

Examples. • For $\vec{\phi}$ a sequence of formulas, their logical conjunction is given by $\bigwedge \vec{\phi}$, which is equivalent to $\neg \bigvee \neg \vec{\phi}$. For the sake of shorter arrows, the latter formula can be rewritten as $\neg \bigvee \neg \vec{\phi}$.

- Let \vec{r} be the invariant factors of a finite abelian group G . Then $G \cong \bigoplus \mathbb{Z}/r = \bigoplus \mathbb{Z}/\vec{r}$.
- If Y is a subset or an element of X , let χ_Y be the associated characteristic function. Then for $\vec{x} \in X$ we have $\sum \overrightarrow{\chi_x} = \chi_{\{\vec{x}\}}$.

Operations with multiple sequences. If \vec{x} and \vec{y} are two sequences of elements of X , then their concatenation is written as

$$\vec{x} \vec{y} = x_1, \dots, x_n, y_1, \dots, y_m.$$

If $n = m$, and if f is any kind of mathematical statement, then let

$$\overrightarrow{f(x, y)} = f(x_1, y_1), f(x_2, y_2), \dots, f(x_n, y_n).$$

Of course, this can be extended to more than two sequences.

Example. Take $\vec{x}, \vec{y} \in \mathbb{R}^k$. Their sum can be naturally written as $\vec{x} + \vec{y}$. Their inner product is given by $\sum \vec{x} \cdot \vec{y}$.

3 Comparative examples

- Let $\vec{x} \in X$. We have

$$\begin{aligned} \vec{x} &= x_1, \dots, x_n, \\ \overrightarrow{\vec{x}} &= \vec{x}, \dots, \vec{x}, \\ x &\text{ doesn't make sense.} \end{aligned}$$

- Let $\vec{x}, \vec{y} \in X$. We have

$$\begin{aligned} \vec{x} \vec{y} &= x_1, \dots, x_n, y_1, \dots, y_m, \\ \overrightarrow{\vec{x} \vec{y}} &= x_1, \dots, x_n, \vec{y}, \dots, \vec{y}, \\ \overrightarrow{\vec{x}} \vec{y} &= \vec{x} \vec{y}, \dots, \vec{x} \vec{y}, \\ \overrightarrow{\vec{x}} \overrightarrow{\vec{y}} &= \vec{x}, \dots, \vec{x}, \vec{y}, \dots, \vec{y}. \end{aligned}$$

- Let $\vec{x}, \vec{y} \in X$ and f be any kind of mathematical statement. We have

$$\begin{aligned} \overrightarrow{f(x, y)} &= f(x_1, y_1), f(x_2, y_2), \dots, f(x_n, y_n), \\ f(\vec{x}, \vec{y}) &= f((x_1, \dots, x_n), (y_1, \dots, y_n)), \\ \overrightarrow{f(x, \vec{y})} &= f(x_1, \vec{y}), \dots, f(x_n, \vec{y}), \\ \overrightarrow{f(\vec{x}, \vec{y})} &= f(\vec{x}, \vec{y}), f(\vec{x}, \vec{y}), \dots, f(\vec{x}, \vec{y}). \end{aligned}$$

- Let $\vec{x} \in X$ be doubly indexed, and \bigcirc, \square be any kind of index-based notation. We have

$$\begin{aligned}\square \vec{x} &= \square_{i=1}^n \vec{x}_i, \\ \overline{\square} \vec{x} &= \left(\square_{j=1}^{m_1} x_{j,1} \right), \left(\square_{j=1}^{m_2} x_{j,2} \right), \dots, \left(\square_{j=1}^{m_n} x_{j,n} \right), \\ \bigcirc \overline{\square} \vec{x} &= \bigcirc_{i=1}^n \left(\square \vec{x} \right)_i = \bigcirc_{i=1}^n \square_{j=1}^{m_i} x_{j,i}.\end{aligned}$$

4 Danger zone

The following conventions should be used with caution, or not at all.

Explicit index. A sequence \vec{x} may also be written as \vec{x}_i . The benefit is that the explicit index can be reused. It is of course unadvised to mix explicit and implicit index notations.

- Examples.**
- A polynomial $P = \lambda_0 + \lambda_1 t + \lambda_2 t^2 + \dots$ can be rewritten as $\sum \overline{\lambda_i t^i}$, and $\overline{\lambda_i t^i}$ are the monomials of P . We mention that in this case, the Einstein summation convention is even shorter: $P = \lambda_i t^i$.
 - The symmetric group \mathfrak{S}_n acts on X^n by $\sigma \vec{x}_i = \overline{x_{\sigma(i)}}$.

Words. If the context leaves no ambiguity, we propose that a sequence $\vec{x} \in X$ can be identified with the word $x_1 \cdots x_n \in X^{<\omega}$.

- Examples.**
- For \vec{f} a sequence of function of the following form

$$\bullet \xrightarrow{f_1} \bullet \xrightarrow{f_2} \bullet \cdots \bullet \xrightarrow{f_n} \bullet,$$

their composite can be written as \overleftarrow{f} .

- We present a case where identifying arrays and words is ambiguous. Consider $\vec{x} \in X^{<\omega}$. If the notation is expanded as $x_1, \dots, x_n \in X^{<\omega}$, then the x_i 's are words over x . If the notation is expanded as $x_1 \cdots x_n \in X^{<\omega}$, then the x_i 's are elements of X .