```
view_frames Result

Recorded at time: 1727889058.6532104
```

```
world
```
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
roboball_cylinder_link
```
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
arm_base_rail_link
```
Broadcaster: default_authority
Average rate: 56.25
Buffer length: 4.64
Most recent transform: 24.013
Oldest transform: 19.373

```
arm_mid_rail_link
```
Broadcaster: default_authority
Average rate: 56.25
Buffer length: 4.64
Most recent transform: 24.013
Oldest transform: 19.373

```
arm_base_car_link
```

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
arm_base_link    box_four_link    box_one_link    box_three_link    box_two_link
```

Broadcaster: default_authority
Average rate: 56.25
Buffer length: 4.64
Most recent transform: 24.013
Oldest transform: 19.373

```
base_plate_link
```
Broadcaster: default_authority
Average rate: 56.25
Buffer length: 4.64
Most recent transform: 24.013
Oldest transform: 19.373

```
forward_drive_arm_link
```
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
elbow_link
```
Broadcaster: default_authority
Average rate: 56.25
Buffer length: 4.64
Most recent transform: 24.013
Oldest transform: 19.373

```
horizontal_arm_link
```
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
wrist_link
```
Broadcaster: default_authority
Average rate: 56.25
Buffer length: 4.64
Most recent transform: 24.013
Oldest transform: 19.373

```
claw_support_link
```

Broadcaster: default_authority
Average rate: 56.25
Buffer length: 4.64
Most recent transform: 24.013
Oldest transform: 19.373

Broadcaster: default_authority
Average rate: 56.25
Buffer length: 4.64
Most recent transform: 24.013
Oldest transform: 19.373

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
gripper_left_link    gripper_right_link    arm_rgb_camera_optical_link
```

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
arm_rgb_camera_link
```