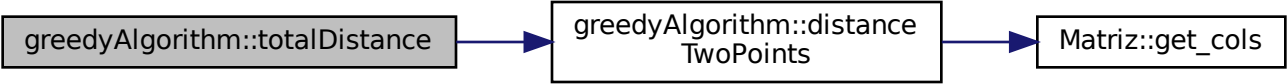


greedyAlgorithm::totalDistance



```
graph LR; A[greedyAlgorithm::totalDistance] --> B[greedyAlgorithm::distanceTwoPoints]; B --> C[Matriz::get_cols];
```

greedyAlgorithm::distance
TwoPoints

Matriz::get_cols