

HW 11 due on wed
 HW 12 due next wed
 Off day 11:30-12:30
 wed 2:30-4

16: CORRELATION AND MATRIX APPROACH

Larsen & Marx 11.4; Rice 14.3; 14.4
 Prof Amanda Luby

1 Covariance and Correlation

When we started linear regression, we began with the simplest scenario from a statistical standpoint – the case where each (x_i, y_i) are just constants with no probabilistic structure. When we moved into inference for this setting, we treated x_i as constant and Y_i as a random variable. We’ll now move into the next layer of complexity: assuming both X_i and Y_i are random variables.

Covariance

Let X and Y be two random variables. The *covariance* of X and Y is given by:

$$\text{Cov}(X, Y) = E(XY) - E(X)E(Y)$$

Let X and Y be two random variables with finite variances. Then,

$$\text{Var}(aX + bY) = a^2\text{Var}(X) + b^2\text{Var}(Y) + 2ab\text{Cov}(X, Y)$$

x_1, x_2, \dots, x_n
 $\sim F_x$
 "independent"

If X and Y are independent:

$$\begin{aligned} f_{X,Y} &= f_X f_Y \\ E(X \cdot Y) &= E(X)E(Y) \\ \text{Cov}(X, Y) &= 0 \end{aligned}$$

all of these are if and only if
 statements \rightarrow can show independence
 w/ any property

The covariance of two random variables gives us a sense of how/what direction they are “related”, but it also depends on the scale of the mean/variance for each RV. The *correlation coefficient* gives us a similar measure that is comparable across all RV’s:

Correlation coefficient

Let X and Y be two random variables. The correlation coefficient of X and Y is given by:

“rho”

$$\rho(X, Y) = \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y} = \text{Cov}(X^*, Y^*)$$

where
$$X^* = \frac{X - \mu_X}{\sigma_X} \quad Y^* = \frac{Y - \mu_Y}{\sigma_Y}$$

ρ = population
 parameter

Note: $|\rho(X, Y)| \leq 1$:

$$\begin{aligned} 0 &\leq \text{Var}(X^* \pm Y^*) = 1 + 1 \pm 2\text{Cov}(X^*, Y^*) \\ &= 2 \pm 2 \cdot \rho(X, Y) \\ &= 2[1 \pm \rho(X, Y)] \\ 0 &\leq 1 \pm \rho(X, Y) \\ 1 &\quad \pm \rho(X, Y) \leq 1 \end{aligned}$$

Example: Suppose the correlation coefficient between X and Y is unknown, but we have observed n measurements $(X_1, Y_1), (X_2, Y_2), \dots, (X_n, Y_n)$. How could we use this data to estimate ρ ?

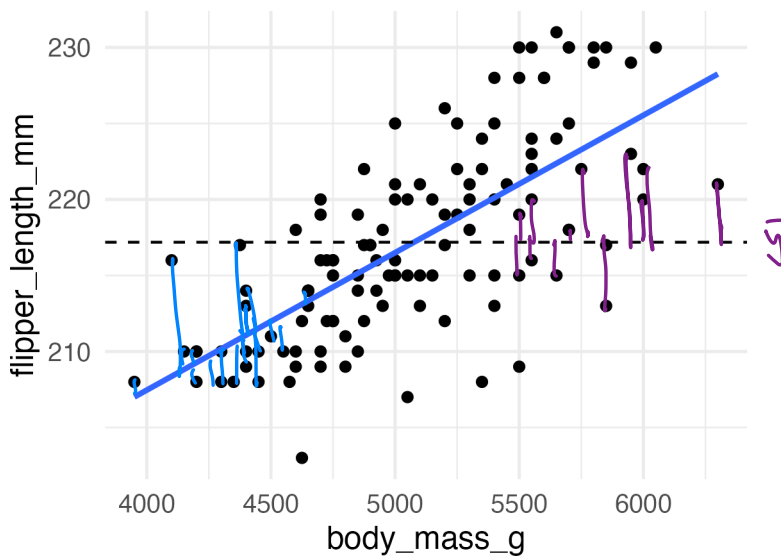
$$\rho(x, y) = \frac{E(XY) - E(X)E(Y)}{\sqrt{\text{var}(X)}\sqrt{\text{var}(Y)}} \quad \left. \begin{array}{l} \text{function of theoretical moments of } X \text{ \& } Y \\ \text{idea: plug in the sample moments} \end{array} \right\}$$

$$r = \frac{\frac{1}{n} \sum X_i Y_i - \frac{1}{n} \sum X_i \frac{1}{n} \sum Y_i}{\sqrt{\frac{1}{n} \sum (X_i - \bar{X})^2} \sqrt{\frac{1}{n} \sum (Y_i - \bar{Y})^2}} = \frac{n \sum X_i Y_i - \sum X_i \sum Y_i}{\sqrt{n \sum X_i^2 - (\sum X_i)^2} \sqrt{n \sum Y_i^2 - (\sum Y_i)^2}}$$

* nice relationship between r & $\hat{\beta}$, (thw, yay!)

If we square the (estimated) correlation coefficient, we can simplify to: $\hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i$

$$R^2 = r^2 = \frac{\sum (y_i - \bar{y})^2 - \sum (y_i - \hat{y}_i)^2}{\sum (y_i - \bar{y})^2}$$



$\sum (y_i - \bar{y})^2$: total variability in y 's (SS_{total})

$\sum (y_i - \hat{y}_i)^2$: total variability "left over" after fitting regression model (SS_{resid})

Interpretation of R^2 :

proportion of total variability in the y 's that is explained by the linear regression on x .

$$R^2 = \frac{\text{variability in } y\text{'s that are explained by regression}}{\text{total variability in the } y\text{'s}}$$

$r = .6 \rightarrow R^2 = .36 \rightarrow 36\%$ of the variability in y is explained by the regression on x (and therefore 64% is due to other factors)

correlation

```
cor(gentoo$body_mass_g, gentoo$flipper_length_mm, use = "complete.obs")
```

r= [1] 0.7026665

Deals w/ missing data

y ~ x

```
gentoo_lm = lm(flipper_length_mm ~ body_mass_g, data = gentoo)
summary(gentoo_lm)
```

Call:

```
lm(formula = flipper_length_mm ~ body_mass_g, data = gentoo)
```

Residuals:

Min	1Q	Median	3Q	Max
-12.0194	-2.7401	0.1781	2.9859	8.9806

Coefficients:

	Estimate	Std. Error	t value	Pr(> t)
(Intercept)	1.713e+02	4.244e+00	40.36	<2e-16 ***
body_mass_g	9.039e-03	8.321e-04	10.86	<2e-16 ***

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 4.633 on 121 degrees of freedom
(1 observation deleted due to missingness)

Multiple R-squared: 0.4937, Adjusted R-squared: 0.4896

F-statistic: 118 on 1 and 121 DF, p-value: < 2.2e-16

Not important
until we
have > 1
X variable

12/6

HW 11 due today
OK 2:30-3:45

Final project
Comments up

2 Matrix Approach to Least Squares

2.1 Deriving the least squares solutions for 1 variable case

Define:

$$X = \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \quad Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

$$\hat{Y} = X\beta$$

$$n \times 2 \cdot 2 \times 1 = n \times 1$$

$$\begin{bmatrix} \beta_0 + \beta_1 x_1 \\ \beta_0 + \beta_1 x_2 \\ \vdots \\ \beta_0 + \beta_1 x_n \end{bmatrix}$$

$$\beta = \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} \quad \hat{\beta} = \begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{bmatrix}$$

$$X^T = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ x_1 & x_2 & x_3 & \dots & x_n \end{bmatrix}$$

Note: $\|\vec{u}\|^2 = \sum u_i^2$

The least squares problem is to find $\hat{\beta}$ to minimize $L = \sum (y_i - (\beta_0 + \beta_1 x_i))^2$.

$$= \|Y - X\beta\|^2$$

$$= \|Y - \hat{Y}\|^2$$

$$Y - \hat{Y} = \begin{bmatrix} y_1 - \hat{y}_1 \\ y_2 - \hat{y}_2 \\ \vdots \\ y_n - \hat{y}_n \end{bmatrix}$$

In Notes 14, we should that the least squares estimates satisfy:

$$\frac{\partial L}{\partial \beta_0} = \sum (y_i - (\beta_0 + \beta_1 x_i)) = 0$$

$$\frac{\partial L}{\partial \beta_1} = \sum (y_i - (\beta_0 + \beta_1 x_i)) x_i = 0$$

$$\begin{aligned} \sum y_i &= \sum (\beta_0 + \beta_1 x_i) \\ &= n\beta_0 + \beta_1 \sum x_i \\ \sum x_i y_i &= \beta_0 \sum x_i + \beta_1 \sum x_i^2 \end{aligned}$$

In matrix form, these equations are equivalent to:

$$X^T X \hat{\beta} = X^T Y$$

equivalent

$$X^T Y = \begin{bmatrix} y_1 + y_2 + \dots + y_n \\ x_1 y_1 + x_2 y_2 + \dots + x_n y_n \end{bmatrix} = \begin{bmatrix} \sum y_i \\ \sum x_i y_i \end{bmatrix}$$

$$\begin{bmatrix} n\hat{\beta}_0 + \hat{\beta}_1 \sum x_i \\ \hat{\beta}_0 \sum x_i + \hat{\beta}_1 \sum x_i^2 \end{bmatrix} = \begin{bmatrix} \sum y_i \\ \sum x_i y_i \end{bmatrix}$$

$$X^T X = \begin{bmatrix} 1+1+\dots+1 & x_1+x_2+\dots+x_n \\ x_1+x_2+\dots+x_n & x_1^2+x_2^2+\dots+x_n^2 \end{bmatrix} = \begin{bmatrix} n & \sum x_i \\ \sum x_i & \sum x_i^2 \end{bmatrix}$$

$$X^T X \hat{\beta} = \begin{bmatrix} n\hat{\beta}_0 + \hat{\beta}_1 \sum x_i \\ \hat{\beta}_0 \sum x_i + \hat{\beta}_1 \sum x_i^2 \end{bmatrix}$$

$$\hat{\beta} = \begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{bmatrix}$$

$$X^T X \hat{\beta} = X^T Y$$

$$(X^T X)^{-1} X^T X \hat{\beta} = (X^T X)^{-1} X^T Y$$

$$\hat{\beta} = (X^T X)^{-1} X^T Y$$

$$X^T X = \begin{bmatrix} n & \sum x_i \\ \sum x_i & \sum x_i^2 \end{bmatrix}$$

Which means that the least squares solution is (assuming $(X^T X)$ invertible)

$$\hat{\beta} = (X^T X)^{-1} X^T Y$$

$$(X^T X)^{-1} = \frac{1}{n \sum x_i^2 - (\sum x_i)^2} \begin{bmatrix} \sum x_i^2 & -\sum x_i \\ -\sum x_i & n \end{bmatrix}$$

$$(X^T X)^{-1} X^T Y = \frac{1}{n \sum x_i^2 - (\sum x_i)^2} \begin{bmatrix} \sum x_i^2 & -\sum x_i \\ -\sum x_i & n \end{bmatrix} \begin{bmatrix} \sum y_i \\ \sum x_i y_i \end{bmatrix}$$

$$\hat{\beta} = \frac{1}{n \sum x_i^2 - (\sum x_i)^2} \begin{bmatrix} \sum y_i \sum x_i^2 - \sum x_i \sum x_i y_i \\ -\sum x_i \sum y_i + n \sum x_i y_i \end{bmatrix}$$

$$\hat{\beta}_0 = \frac{\sum y_i \sum x_i^2 - \sum x_i \sum x_i y_i}{n \sum x_i^2 - (\sum x_i)^2} \leftarrow \bar{y} - \hat{\beta}_1 \bar{x} \dots \text{algebra :)}$$

$$\hat{\beta}_1 = \frac{n \sum x_i y_i - \sum x_i \sum y_i}{n \sum x_i^2 - (\sum x_i)^2} \leftarrow \text{matches form of } \hat{\beta}_1 \text{ from Notes 14}$$

2.2 Mean and Covariance of Vector-Valued RV's

Let Y be a random vector where $E(Y_i) = \mu_i$ and $Cov(Y_i, Y_j) = \sigma_{ij}$

$$Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

Not identical
if $\sigma_{ij} \neq 0$, not independent

$$E(\vec{Y}) = \vec{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_n \end{bmatrix}$$

$$\Sigma_Y = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \dots & \sigma_{1n} \\ \sigma_{21} & \sigma_{22} & \dots & \sigma_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{n1} & \sigma_{n2} & \dots & \sigma_{nn} \end{bmatrix}$$

each (i, j) element is covariance

identically distributed independent

$$Y_1, Y_2, \dots, Y_n \stackrel{d}{\sim} N(\mu, \sigma^2)$$

↓ extend to multivariate case

$$\vec{Y} \sim MVN(\vec{\mu}, \Sigma_Y)$$

Linear functions of random variables

Let $Z = c + AY$. Then

$$E(Z) = c + AE(Y) \text{ and } \Sigma_Z = A \Sigma_Y A^T$$

c = vector of constants $(n \times 1)$

A = matrix of constants $(n \times n)$

→ kind of equivalent to $V(a + bX) = b^2 V(X)$

2.3 Mean and Covariance of Least Squares Estimates

Let $Y_i = \beta_0 + \beta_1 X_i + \epsilon_i$, where:

$$Y_i \sim N(\beta_0 + \beta_1 X_i, \sigma^2)$$

$$\epsilon_i \sim N(0, \sigma^2)$$

$$I = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}$$

$$E(\epsilon_i) = 0$$

$$V(\epsilon_i) = \sigma^2$$

$$\text{Cov}(\epsilon_i, \epsilon_j) = 0 \text{ for } i \neq j$$

$$\Sigma_{\epsilon} = \begin{bmatrix} \sigma^2 & 0 & \dots & 0 \\ 0 & \sigma^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma^2 \end{bmatrix} = \sigma^2 \cdot I$$

Matrix form: $\epsilon_i \sim \text{MVN} \left(\begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \sigma^2 I \right)$

$$\begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix} \sim \text{MVN} (X\beta, \sigma^2 I)$$

Mean and covariance of LS estimates (Matrix Form)

$$E(\hat{\beta}) = \beta$$

$$\Sigma_{\hat{\beta}} = \sigma^2 (X^T X)^{-1}$$

$$\hat{\beta} = (X^T X)^{-1} X^T y$$

$$= (X^T X)^{-1} X^T (X\beta + \epsilon)$$

$$= (X^T X)^{-1} X^T X\beta + (X^T X)^{-1} X^T \epsilon$$

$$= \beta + (X^T X)^{-1} X^T \epsilon$$

$$E(\hat{\beta}) = \beta + (X^T X)^{-1} X^T E(\epsilon)$$

$$= \beta$$

$\hat{\beta}_0$ and $\hat{\beta}_1$ (and $\hat{\beta}_2, \hat{\beta}_3, \dots, \hat{\beta}_p$) are all unbiased for $\beta_0, \beta_1, \dots, \beta_p$

true even if ϵ_i 's are dependent/not constant variance!

(even if we have weird residual props, $\hat{\beta}$ still unbiased as long as $E(\epsilon) = \vec{0}$)