## **Continuous Optimization**

Spring 2025

# Exercise 6: Newton's method

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## Problem 1 (Affine invariance property of Newton's method):

Consider a function  $f: \mathbb{R}^d \to \mathbb{R}$  and a non-singular matrix  $\mathbf{A} \in \mathbb{R}^{d \times d}$ . Let  $\mathbf{x} = \mathbf{A}\mathbf{y}$  and  $g(\mathbf{y}) = f(\mathbf{A}\mathbf{y})$ .

1. Show that the per-step update of Newton's method that minimizes  $g(\mathbf{y})$  is equal to

$$\mathbf{y}^+ = \mathbf{y} - \mathbf{A}^{-1} (\nabla^2 f(\mathbf{A}\mathbf{y}))^{-1} \nabla f(\mathbf{A}\mathbf{y}).$$

2. Show that

$$\mathbf{x}^+ = \mathbf{x} - (\nabla^2 f(\mathbf{x}))^{-1} \nabla f(\mathbf{x}).$$

3. What conclusion can you draw from the previous equation?

Hint: Given a composition of functions  $g = f(h(\mathbf{y}))$ , where  $h : \mathbb{R}^d \to \mathbb{R}^p$  and  $f : \mathbb{R}^p \to \mathbb{R}$ , and such that  $\frac{\partial^2 h}{\partial y_i \partial y_j} = 0$ , then

$$\nabla^2 g = \mathbf{J}_h^{\mathsf{T}} \mathbf{H}_f \mathbf{J}_h, \tag{1}$$

where  $\mathbf{J}_h$  is the Jacobian matrix of h, and  $\mathbf{H}_q$  is the Hessian matrix of g.

## Problem 2 (Quadratic convergence of Newton's method):

1. Recall the following theorem derived in class.

**Theorem 1** (Undamped). Assume that  $f(\cdot)$  satisfies the Assumptions seen in class and that  $\|\mathbf{x}_k - \mathbf{x}^*\| \leq \frac{2\mu}{3L}$ , then

$$\|\mathbf{x}_{k+1} - \mathbf{x}^*\| \le \frac{3L}{2\mu} \|\mathbf{x}_k - \mathbf{x}^*\|^2.$$
 (2)

Using the above theorem, provide a bound on  $\|\mathbf{x}_{k+s} - \mathbf{x}^*\|$ .

- 2. Assuming  $\|\mathbf{x}_0 \mathbf{x}^*\| \leq \frac{\mu}{3L}$ , prove that  $\|\mathbf{x}_k \mathbf{x}^*\| \leq \left(\frac{1}{2}\right)^{2^k 1} \cdot \frac{\mu}{3L}$ .
- 3. Assuming  $\|\mathbf{x}_0 \mathbf{x}^*\| \leq \frac{\mu}{3L}$ , prove that the Hessian satisfies the following relative error bound:

$$\frac{\|\nabla f^2(\mathbf{x}_k) - \nabla f^2(\mathbf{x}^*)\|}{\|\nabla f^2(\mathbf{x}^*)\|} \le 2\left(\frac{1}{3}\right)^{2^k - 1}.$$

### Problem 3 (Convergence in terms of gradient norm):

We optimize a function  $f: \mathbb{R}^d \to \mathbb{R}$  using Newton's method that produces the iterates:

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \mathbf{p}_k,\tag{3}$$

where  $\mathbf{p}_k := [\nabla^2 f(\mathbf{x}_k)]^{-1} \nabla f(\mathbf{x}_k)$ .

1. Using the relation  $\nabla f(\mathbf{x}_k) + \nabla^2 f(\mathbf{x}_k) \mathbf{p}_k = 0$ , prove that

$$\|\nabla f(\mathbf{x}_{k+1})\| \le \int_0^1 \|\nabla^2 f(\mathbf{x}_k + t\mathbf{p}_k) - \nabla^2 f(\mathbf{x}_k)\| \|\mathbf{p}_k\| \, \mathrm{d}t.$$

2. Since  $\nabla^2 f$  is non-singular and Lipschitz continuous, there is a radius r > 0 such that  $\|\nabla^2 f(\mathbf{x}_k)^{-1}\| \le 2\|\nabla^2 f(\mathbf{x}^*)^{-1}\|$  for all  $\mathbf{x}_k$  such that  $\|\mathbf{x}_k - \mathbf{x}^*\| \le r$ . Use this result to prove that

$$\|\nabla f(\mathbf{x}_{k+1})\| \le 2L \|[\nabla^2 f(\mathbf{x}^*)]^{-1}\|^2 \|\nabla f(\mathbf{x}_{k+1})\|^2 \quad \text{if } \|\mathbf{x}_k - \mathbf{x}^*\| \le r,$$

i.e. the gradient norm converges to zero quadratically.