



# Spatial Gesture Semantics

## 1. Introduction: Visuo-Spatial Level of Meaning

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## **Basic Information**

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## Outline of course

1. Introduction: Visuo-spatial Level of Meaning
2. Spatial Gesture Semantics
3. Exemplification and Informational Evaluation
4. AI and Gesture Detection
5. Frame-based Speech–Gesture Integration

# Instructors

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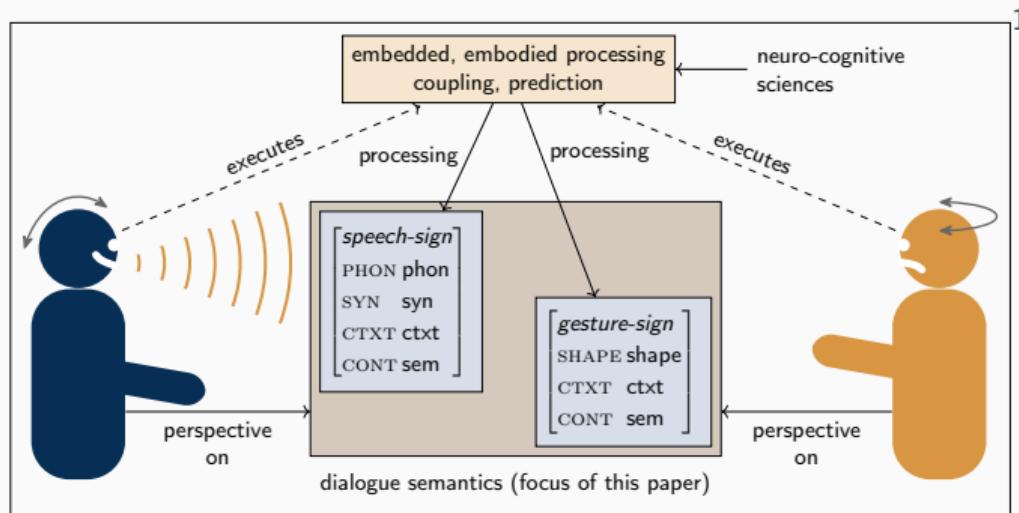
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# Multimodal Dialogue



Dialogue: research topic  
*sui generis*

- interaction
- “polyphony”
- alignment
- verbal and non-verbal signals

<sup>1</sup> A. Lücking and J. Ginzburg (2023). “Leading voices: Dialogue semantics, cognitive science, and the polyphonic structure of multimodal interaction”. In: *Language and Cognition* 15, 148–172

## Overview of nonverbal communication means<sup>2</sup>

- paralinguistic signals / speech phonation
- laughter, sighing / non-speech phonation
- manual gesture (our focus)
- facial expressions
- gaze
- proxemics: spatio-social behavior connected to the interpersonal distances of interlocutors.
- tactile codes
- time behaviour (“chronemics”): length of laughter, respiratory pauses; “kairemics”: at the right moment
- Others, hitherto not much studied: clothing, smelling, ...

<sup>2</sup>From A. Lücking and T. Pfeiffer (2012). "Framing Multimodal Technical Communication. With Focal Points in Speech-Gesture-Integration and Gaze Recognition". In: **Handbook of Technical Communication**. Ed. by A. Mehler and L. Romary. In collab. with D. Gibbon, 591–644

# Why gesture?

- Gesture can add meaning:



- “Ich g[laube das sollen TREP]pen sein” /

*I think that should be staircases*

(Capitalization indicates main stress of the first syllable  
of the noun *Treppen* ‘staircases’, square brackets  
indicate the temporal alignment of speech and gesture)

- Obligatory pointing gestures: *I want to have this!*

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<sup>3</sup> P. Schlenker (2018). “Gesture projection and cosuppositions”. In: *Linguistics and Philosophy* 41, 295–365, 296

# Why gesture?

- Gesture can add meaning:



- "Ich g[laube das [REDACTED] sollen TREP]pen sein" /  
*I think that should be staircases*  
(Capitalization indicates main stress of the first syllable  
of the noun *Treppen* 'staircases', square brackets  
indicate the temporal alignment of speech and gesture)
- Obligatory pointing gestures: *I want to have  
this!*

- But what exactly is the semantic contribution of a gesture?
- Semantic lacuna: "It should be emphasized that we will not seek to explain how a gesture [...] comes to have the content that it does."<sup>3</sup>
  - ➔ truth-conditional visuo-spatial meaning
  - ➔ theoretically challenging:  
informational evaluation  
(exemplification)

<sup>3</sup> P. Schlenker (2018). "Gesture projection and cosuppositions". In: *Linguistics and Philosophy* 41, 295–365, 296

# Eclecticism<sup>4</sup>

- Gesture studies
- Dynamic semantics
- Grammar theory
- Computer Science
- Model-theoretic semantics
- Philosophy of language
- Cognitive Science / Psychophysics

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<sup>4</sup> A. Lücking (11, 2013). [Eclectic Semantics for Non-Verbal Signs](#). Talk at the Conference on Investigating Semantics: Empirical and Philosophical Approaches, Bochum

## On gestures and gestures

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## Ex: Wheel

(1) Stewart Robson on *ESPN FC Extra Time*

(first gesture):

*You know when they go on that wheel*



*and throw the dagger would you  
ever like to see that go wrong?*

⇒ the wheel has a circular layout

([https://www.youtube.com/watch?v=CiVS5\\_HKFY8&t=0h1m18s](https://www.youtube.com/watch?v=CiVS5_HKFY8&t=0h1m18s))

## Ex: Wheel

(1) Stewart Robson on *ESPN FC Extra Time*

(first gesture):

*You know when they go on that wheel*



↝ Hand is drawing a shape

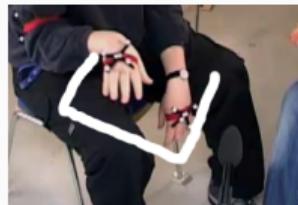
*and throw the dagger would you  
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## Ex: Like this

- (2) SaGA dialogue V11, starting at 2:32:  
dann ist das Haus halt so: / *then the house is*

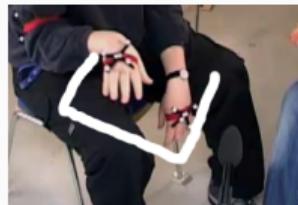


*like this:*

⇒ the house has a rectangular, U-shaped layout.

## Ex: Like this

- (2) SaGA dialogue V11, starting at 2:32:  
dann ist das Haus halt so: / *then the house is*



*like this:*

⇒ the house has a rectangular, U-shaped layout.

~~ Again, shape drawing

## Ex: Right

- (3) SaGA dialogue V5, starting at 6:48  
und da musst du sofort, scharfer rechter



Winkel, rechts rein /  
*and you must enter immediately on the right,  
at an acute right angle*  
⇒ the path of the movement runs straight to  
the right

## Ex: Right

- (3) SaGA dialogue V5, starting at 6:48

und da musst du sofort, scharfer rechter



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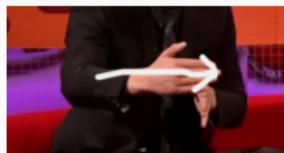
~~> pointing/drawing a direction

*and you must enter immediately on the right,  
at an acute right angle*

⇒ the path of the movement runs straight to  
the right

## Ex: Pull out

- (4) Keanu Reeves at the *Graham Norton Show*:



*a car pulled out in front of me*  
⇒ the car pulled out in a straight line from  
the right

([https://www.youtube.com/watch?v=6VxnceG\\_eh4&t=0h13m39s](https://www.youtube.com/watch?v=6VxnceG_eh4&t=0h13m39s))

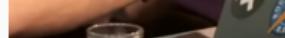
~~ Hand draws movement  
trajectory, from speaker's  
perspective + represents car

## Ex: Tubes

(5) Etienne Gardet:

Was mich wundert is, es gibt ja beim Tennis



so Röhren , ich weiß nich ob  
ihr die kennt / *What surprises me is that there  
are such tubes in tennis, I don't know if you  
know them*

(<https://www.youtube.com/watch?v=1xLPdMU91F8&t=1h23m42s>)

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~~ Hands holding/sculpturing a  
cylindric volume

## Ex: Dagger

- (6) Stewart Robson on *ESPN FC Extra Time*  
(second gesture):

*You know when they go on that wheel and*



*throw [the dagger] would you ever  
like to see that go wrong?*

⇒ throwing exhibits a certain handshape and  
movement trajectory

([https://www.youtube.com/watch?v=CiVS5\\_HKFY8&t=0h1m18s](https://www.youtube.com/watch?v=CiVS5_HKFY8&t=0h1m18s))

## Ex: Dagger

- (6) Stewart Robson on *ESPN FC Extra Time*  
(second gesture):

*You know when they go on that wheel and*



*throw [the dagger] would you ever ↗ Speaker mimes throwing action like to see that go wrong?*

⇒ throwing exhibits a certain handshape and movement trajectory

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## Ex: Hit

- (7) Keanu Reeves at the *Graham Norton Show*:



*no one could hit*

⇒ fist and straight movement path away from speaker's body

([https://www.youtube.com/watch?v=6VxnceG\\_eh4&t=0h1m6s](https://www.youtube.com/watch?v=6VxnceG_eh4&t=0h1m6s))

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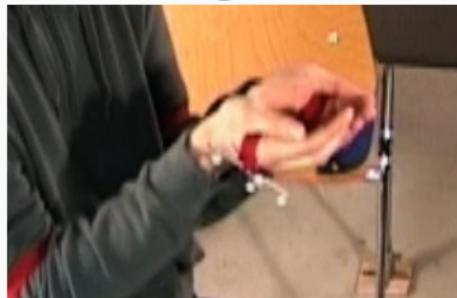
~~> Speaker mimes hitting action

⇒ fist and straight movement path away from  
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([https://www.youtube.com/watch?v=6VxnceG\\_eh4&t=0h1m6s](https://www.youtube.com/watch?v=6VxnceG_eh4&t=0h1m6s))

## Ex: Bowl

- (8) SaGA dialogue V21, starting at 4:38:



und 'ne kleinere Schale obendrauf /

*and a smaller bowl on top*

⇒ layout of hands represents main axis of  
bowl object

## Ex: Bowl

- (8) SaGA dialogue V21, starting at 4:38:



↝ Hands represent object talked about

und 'ne kleinere Schale obendrauf /  
*and a smaller bowl on top*  
⇒ layout of hands represents main axis of  
bowl object

## Ex: Two towers

(9) SaGA dialogue V24, 6:25:



die rechte Kirche die hat zwei spitze Türme /  
*the church to the right it has two pointed  
towers*

⇒ Church towers are stretched vertically

## Ex: Two towers

(9) SaGA dialogue V24, 6:25:



~~> Each index finger represents a church tower

die rechte Kirche die hat zwei spitze Türme /  
*the church to the right it has two pointed towers*

⇒ Church towers are stretched vertically

## Ex: Some ...some

(10) Daniel Levitin, *Ted talk*:



*some of them are obvious*

*some of them are not so obvious*



⇒ *on the one hand...on the other hand* figure

(<https://www.youtube.com/watch?v=8jPQjjsBbIc&t=0h3m55s>)

## Ex: Some ...some

(10) Daniel Levitin, *Ted talk*:



*some of them are obvious*

*some of them are not so obvious*



~~ Hands engage in discourse structuring

⇒ *on the one hand...on the other hand* figure

(<https://www.youtube.com/watch?v=8jPQjjsBbIc&t=0h3m55s>)

## Ex: So then

(11) Kathy Griffin:<sup>5</sup>



/

*Anyway um .. so so then*

*decided to promote my own shows*

⇒ palm up open hand gesture towards Colbert (host on the right) shows “re-engagement with main discourse” (*op. cit.*, p. 177f)

([https:](https://www.youtube.com/watch?v=UWKI1jRfltM&t=0h7m17s)

[//www.youtube.com/watch?v=UWKI1jRfltM&t=0h7m17s](https://www.youtube.com/watch?v=UWKI1jRfltM&t=0h7m17s))

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<sup>5</sup>Slightly simplified from S. Laparle (2022). “The shape of discourse: how gesture structures conversation”. PhD thesis. University of California, Berkeley, p. 177

# Thumbs Up

(12)



Male Hand Giving Thumbs Up Sign by  
freebie.photography, CC BY 3.0 Unported.  
⇒ emblem: *good/like*

# Thumbs Up



(12)

Male Hand Giving Thumbs Up Sign by  
freebie.photography, CC BY 3.0 Unported.  
⇒ emblem: *good/like*

~~> Conventionalized response item

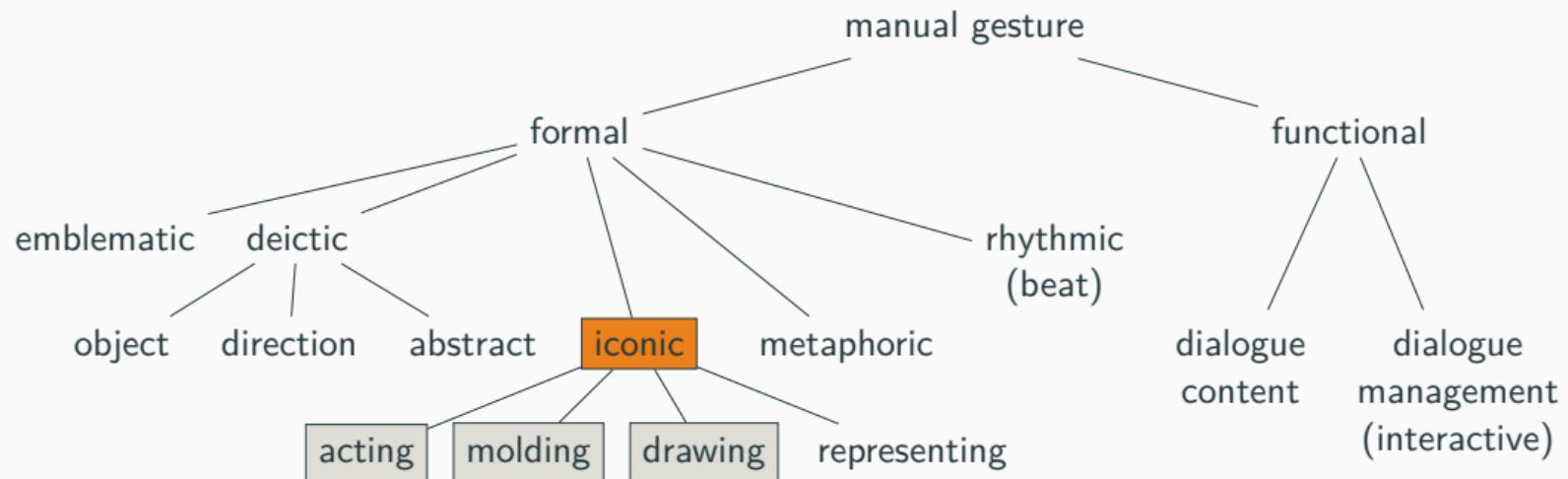
Different iconic  
motivations of  
gestures

## Acting, molding, drawing, representing

"Müller [...] has distinguished four modes of representation: **acting**, **molding**, **drawing**, and **representing**. In the **acting** mode, the hands are used to mime or reenact actual manual activities, such as grasping, holding, giving, receiving, opening a window, turning off a radiator, or pulling an old-fashioned gear shift; in the **molding** mode, the hands mold or shape a transient sculpture, such as a picture frame or a bowl; in the **drawing** mode, the hand(s) outline(s) the contour or the form of objects or the path of movements in space; and in the **representing** mode, the hand embodies an object as a whole, a kind of manual 'sculpture', when, for example, a flat open hand represents a piece of paper and the extended index finger represents the pen used to make notes on that paper." (p. 1691)<sup>6</sup>

<sup>6</sup> C. Müller (2014). "Gestural modes of representation as techniques of depiction". In: **Body – Language – Communication**. Ed. by C. Müller et al. Vol. 2, 1687–1702

# Dimensions of classifying gestures



## Kendon's Continuum<sup>7</sup>, modified



- To the right: increasing degree of conventionalization, decreasing language dependency
- We are concerned with Gesticulation and recurrent gestures
- Problem: no lexicon (as exist for emblems and sign language)

<sup>7</sup> D. McNeill (1992). *Hand and Mind. What Gestures Reveal about Thought.* Cambridge UP, 37

- A gesture attaches to a “docking point” in speech, the **affiliate**<sup>8</sup>
- Hints: Temporal alignment, stressed intonation/information structure, semantic constraints (' indicates secondary stress)
- Affiliate is a lexical item in about 70% of cases<sup>9</sup>

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<sup>8</sup> E. A. Schegloff (1984). “On some Gestures’ Relation to Talk”. In: **Structures of Social Action. Studies in Conversational Analysis**. Ed. by J. M. Atkinson and J. Heritage, 266–296

<sup>9</sup> A. Mehler and A. Lücking (2012). “Pathways of Alignment between Gesture and Speech: Assessing Information Transmission in Multimodal Ensembles”. In: **Proc. of the International Workshop on Formal and Computational Approaches to Multimodal Communication under the auspices of ESSLLI 2012, Opole, Poland, 6-10 August**

## Scope of spatial gesture semantics

- There are various kinds/uses of gestures
- lack of “gestionary” (gesture lexicon) → we need a way to interpret a gesture('s form) “online”
- Gestures integrate with (lexical) affiliate
- There is no presupposition that a spatial semantics captures all of them (alike)
- Stroke is assumed to be the semantically relevant gesture phase

## Gesture phases



- By 'gesture', we usually refer to the stroke phase
- Preparation often anticipates/precedes the gesture's affiliate → interesting from a production perspective
- typical alignment: co-speech

# Co/Pro/Post/Pre<sup>10</sup>

- Co:  
I think that should be staircases
- Pre:  
I think that should be staircases



- Pro:  
I think that should be

- Post:  
I think that should be staircases



<sup>10</sup> P. Schlenker (2018). "Gesture projection and cosuppositions". In: *Linguistics and Philosophy* 41, 295–365; T. Slama-Cazacu (1976). "Nonverbal Components in Message Sequence: 'Mixed Syntax'". In: *Language and Man. Anthropological Issues*. Ed. by W. C. McCormick and S. A. Wurm, 217–227

- Co seems to be natural, Pro and Post presumably intentionally produced → pragmatic effects
- Conjecture: Pro works the better the more right on Kendon's continuum (conventionalization)
- Pre found with word elicitation difficulties<sup>a</sup>

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<sup>a</sup> M. L. Rose (2013). "Releasing the Constraints on Aphasia Therapy: The Positive Impact of Gesture and Multimodality Treatments". In: *American Journal of Speech-Language Pathology* 22, 227–239

# Meaning

- Sometimes gestures add meaning.
- Often, speech and gesture have seemingly identical meanings.
- “Yet they express this meanings in completely different ways.” (McNeill 1992:11)<sup>11</sup>

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<sup>11</sup> D. McNeill (1992). *Hand and Mind. What Gestures Reveal about Thought*. Cambridge UP

## A visuo-spatial level of meaning

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# Teasing apart verbal and gestural meaning

[Talking about an entrance door]



zwei .. äh .. Stangen mit nem  
drüber halt

*(two .. uh .. poles with a roof over them )*

- Intuitively, the gesture just depicts what is said (*over them*)
- **IF** gestures contribute meaning like words do, we would expect that meaning to be addressable.

## Interlude: Parallelism constraint

- Clarification request:  
categorical and phonological  
parallelism with their source<sup>12</sup>
  - A: Do you fear him? B:  
Fear? / #Afraid?
  - A: I phoned him. B: Him?  
/ #He?
  - A: Were you cycling  
yesterday? B: Cycling? /  
#Cycled?

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<sup>12</sup> J. Ginzburg and R. Cooper (2004). "Clarification, Ellipsis, and the Nature of Contextual Updates in Dialogue". In: *Linguistics and Philosophy* 27, 297–365

<sup>13</sup> J. Ginzburg and A. Lücking (2021). "Requesting clarifications with speech and gestures". In: *Proc. of the 1st Workshop on Multimodal Semantic Representations*, 21–31

## Interlude: Parallelism constraint

- Clarification request: categorical and phonological parallelism with their source<sup>12</sup>
  - A: Do you fear him? B: Fear? / #Afraid?
  - A: I phoned him. B: Him? / #He?
  - A: Were you cycling yesterday? B: Cycling? / #Cycled?

- Parallelism constraint generalizes multimodally<sup>13</sup>
  - B: You have to move your legs like this [*moves right hand up and down in a wave-like manner*]. A: [*moves right hand up and down in a wave-like manner, raises eye-brows*] (constructed from a kids TV show)
  - A: I hear you're busy ⟨laughter⟩ [= little giggle]. B: ⟨laughter⟩? (= low arousal laughter with rising contour). (attested example)

<sup>12</sup> J. Ginzburg and R. Cooper (2004). "Clarification, Ellipsis, and the Nature of Contextual Updates in Dialogue". In: *Linguistics and Philosophy* 27, 297–365

<sup>13</sup> J. Ginzburg and A. Lücking (2021). "Requesting clarifications with speech and gestures". In: *Proc. of the 1st Workshop on Multimodal Semantic Representations*, 21–31

## Interlude: Parallelism constraint

- Repair: Repetition of (delayed) reparandum<sup>14</sup>
  - A: I think I'll wear my green dress. Can you bring it to me please?
  - B: OK [leaves to go get dress].
  - Wait, did I say **green**? / #blue? Sorry, I meant my red dress.

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<sup>14</sup> A. Lücking and J. Ginzburg (2022). "How to repair a slip of the tongue?" In: **Proc. of SemDial 2022**, 35–46

## Denial i



(13) [...] with a [redacted] roof over them

- a. ?No, that's [?] not true. The roof (i) is  
not ⟨\*⟩ / (ii) actually is ⟨\*⟩
- b. ?Wait a minute. The roof (i) is not ⟨\*⟩ /  
actually is ⟨\*⟩

## Denial i

(13) [...] with a  roof over them

- a. ?No, that's [?] not true. The roof (i) is not <\*> / (ii) actually is <\*>
- b. ?Wait a minute. The roof (i) is not <\*> / actually is <\*>

- What is *that* referring to? It does not seem to be able to pick out the gesture
- What can be said in the places marked with the wildcard “<\*>”? Any verbal answer would violate the parallelism constraint!
  - ➔ No gesture meaning accessible

## Denial ii

(14) [...] with a  roof over them

a. No, that's not true, the roof (i) is not



/ (ii) actually is



- Multimodal repair is possible: categorical parallelism is preserved.  
→ gestures can respond to gestures

# Establishing a linguistic interpretation

- (15) a. A: [...] with a roof over them



- b. B: By [redacted], do you mean that (i) the roof is a flat one / (ii) extends to the right?
- c. A: Yes.
- d. B: But that's not true. The roof (i) is not flat / (ii) does not extend to the right.



- If interlocutors agree on a linguistic interpretation of a gesture, then this interpretation can finally be questioned.
- “The Linguistic Interpretation of Non-emblematic Gestures Must be agreed in Dialogue”<sup>15</sup>

<sup>15</sup> A. Lücking, A. Mehler, and A. Henlein (2024). “The Linguistic Interpretation of Non-emblematic Gestures Must be agreed in Dialogue: Combining Perceptual Classifiers and Grounding/Clarification Mechanisms”. In: *Proc. of the 28th Workshop on The Semantics and Pragmatics of Dialogue*

## Anaphoric potential



- (16) [...] two poles with a roof over them
- a. They (= two poles) stand firm.
  - b. It (= roof) was covered in moss.
  - c. #It (= *gesture*) extends to the right.

- Noun phrases can be picked out by pronouns
- The gesture does not appear to be anaphorically accessible

## Interim conclusion

- The linguistic and visual meanings are not on a par and one cannot simply switch from one to the other.
- Accordingly, it is important to keep the two dimensions apart when trying to formalize the semantic integration of speech and gesture.

## **Visuo-spatial models**

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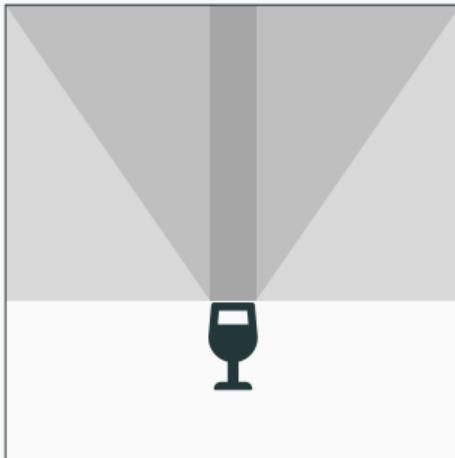
## “Visual truth-functions”

- There are at least quite clear semantic intuitions about the circumstances under which a multimodal utterance is true that can guide semantic theorizing.
  - Informally, the multimodal PP is true of the modified NP if the extension  $\llbracket \text{NP} \rrbracket^e$  of the NP in situation e has a roof and the roof “looks like” the gesture.
- The only thing left to do: specify what “look like a gesture” means.

[...] two poles with a roof over them



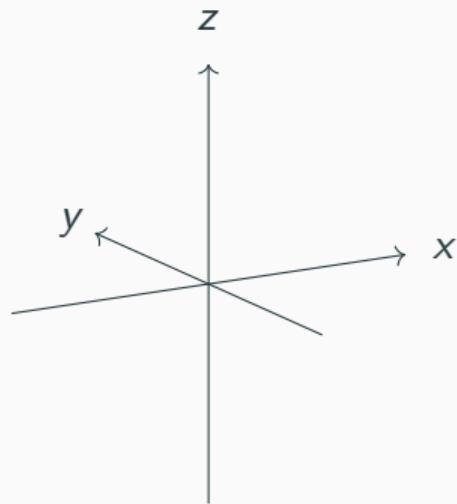
# Spatial prepositions



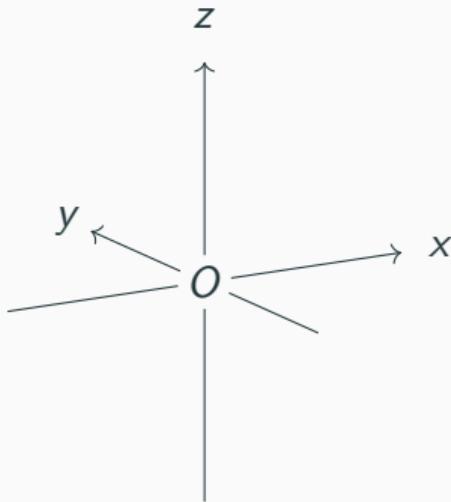
- Three different readings of *above*
  - Each is a sub-region within the space surrounding the reference object
- (Three-dimensional, Euclidean) **Vector Space Semantics**<sup>16</sup>

<sup>16</sup> J. Zwarts (1997). "Vectors as Relative Positions: A Compositional Semantics of Modified PPs". In: *J. of Semantics* 14, 57–86

## Euclidean space, idea

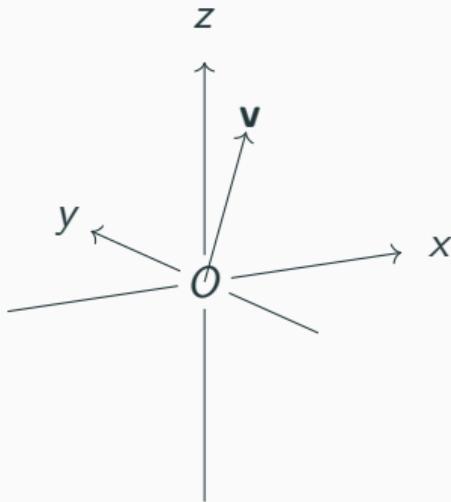


## Euclidean space, idea



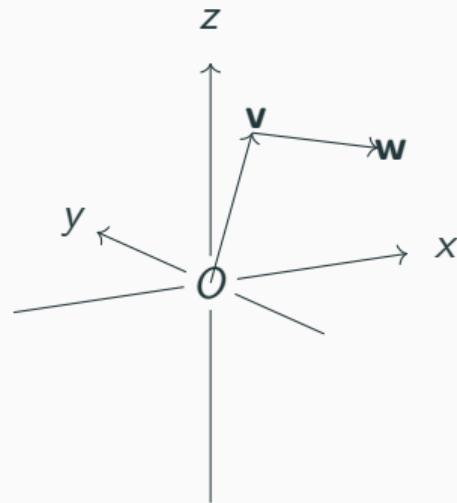
- $O$ : Origin

## Euclidean space, idea



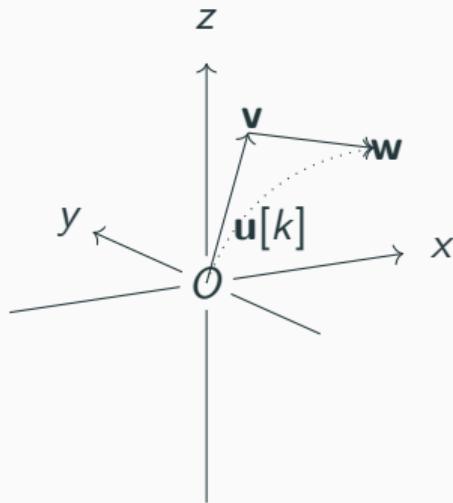
- $O$ : Origin
- $\mathbf{v}$ : Vector

## Euclidean space, idea



- $O$ : Origin
- $\mathbf{v}$ : Vector
- $\mathbf{w}$ : Vector
- $\mathbf{vw}$ : Sequence of (two) vectors

## Euclidean space, idea



- $O$ : Origin
- $\mathbf{v}$ : Vector
- $\mathbf{w}$ : Vector
- $\mathbf{vw}$ : Sequence of (two) vectors
- $\mathbf{u}[k]$ : Path: Sequence of  $k$  vectors

## Model-theory

- Model:  $\langle V, D_e, D_s \rangle$ , with
  - $V$ : Interpretation function
  - $D_e$ : Domain of entities
  - $D_s$ : Domain of situations/events

## Extending the domain of semantic model<sup>17</sup>

- The domain of points:  $D_p = V$  (each point is defined by a vector's endpoint)
- The domain of vectors:  $D_v = V \times V$  (the Cartesian product of  $V$ )

Vector space population: For each element (“point”)  $w \in D_p$  there is a vector space  $V_w \subseteq D_v$  ( $w$  is the zero-vector, or origin of  $V_w$ ).

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<sup>17</sup> J. Zwarts and Y. Winter (2000). “Vector Space Semantics: A Model-Theoretic Analysis of Locative Prepositions”. In: *Journal of Logic, Language, and Information* 9, 169–211

## Connecting the extending domain<sup>18</sup>

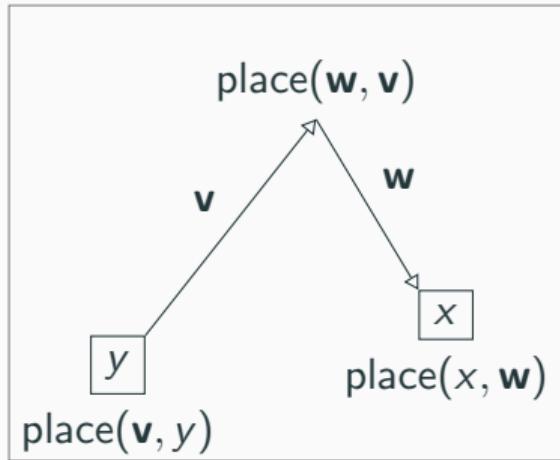
$D_e$  (entities),  $D_s$  (events) and  $D_v$  (vector sequences) are related by a couple of functions:

- The vector space located at a concrete object denoted by an NP  $\alpha$  is given by ‘space( $[\![\alpha]\!]^e$ )’.
- Place and axis vectors determine spatial relationships:
  - $\text{place}(x, \mathbf{v})$ :  $x$  is placed at the end of  $\mathbf{v}$ ;  $\text{place}(\mathbf{v}, x)$ : the starting point of  $\mathbf{v}$  is placed at  $x$ ;  $\text{place}(\mathbf{u}, \mathbf{v})$ : the starting point of  $\mathbf{u}$  is placed at the end of  $\mathbf{v}$ .
  - $\text{axis}(x, \mathbf{v})$  object  $x$  has an axis  $\mathbf{v}$ .

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<sup>18</sup> J. Zwarts (2003). “Vectors Across Spatial Domains: From Place to Size, Orientation, Shape, and Parts”. In: [Representing Direction in Language and Space](#). Ed. by E. van der Zee and J. Slack, 39–68, frame

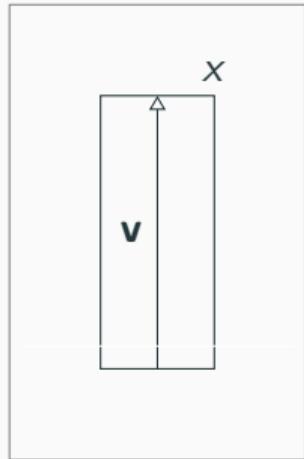
# Place



*The car is in front of the house.  
The spoon is near the fork.*

...

# Axis



*The bar is straight.  
The tower is wide.*

...

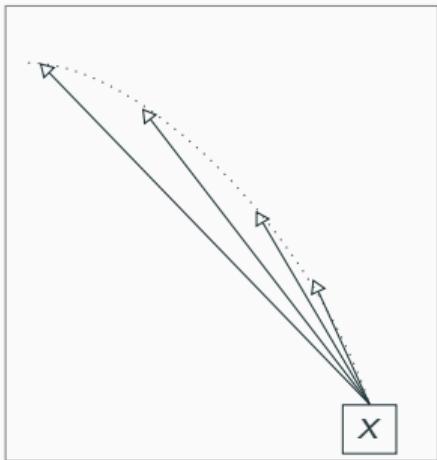
(Very simple model, the use of subsidiary axes would lead to much more detailed object shapes.)

## Paths

- Paths: sequences of axis or place vectors. Paths are defined as  $n$ -tuples of points,  $n > 2$ .
- Paths are notated as  $\mathbf{v}[k]$ .
- We use the letters  $a$  and  $z$  to denote the first and the last element of the tuple, respectively. The start of a path is indexed as  $\mathbf{v}[a]$ , its end point as  $\mathbf{v}[z]$ .
- Paths can be constructed for axis and for place vectors, giving rise to axis-paths and place-paths, respectively.
- Note that paths are non-temporal entities. They receive a temporal interpretation only if index  $k$  is mapped to points or intervals in time.

Note: Paths can be implemented in terms of a vector plus one or more transformation matrices.

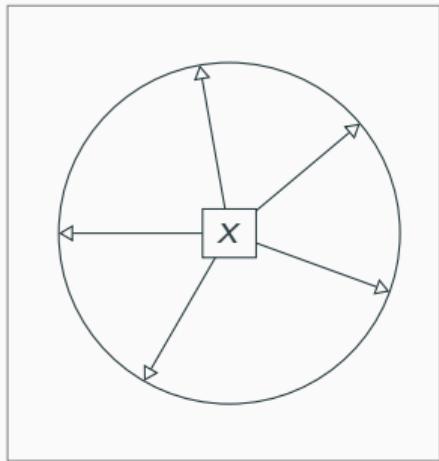
## Place path



*The road bends to the left.  
She travels along the river bend.*

...

## Axis path

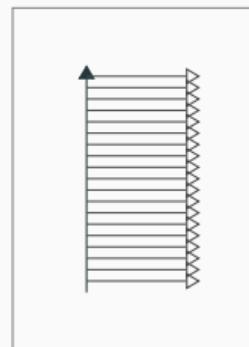


*A round disk.  
A cylindric cup.*

...

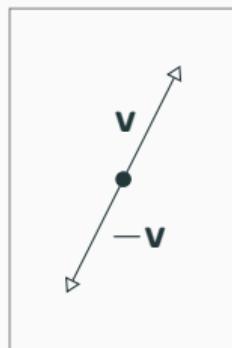
# Level

Vectors pointing in the same direction constitute a **level**.



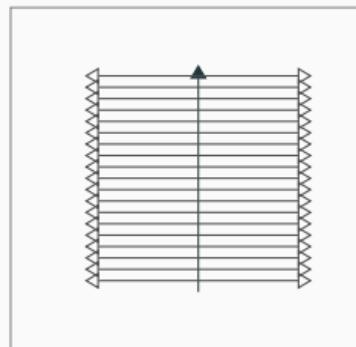
## Invers

The **inverse**  $-\mathbf{v}$  of a vector  $\mathbf{v}$   
points in the opposite direction of  
 $\mathbf{v}$ .



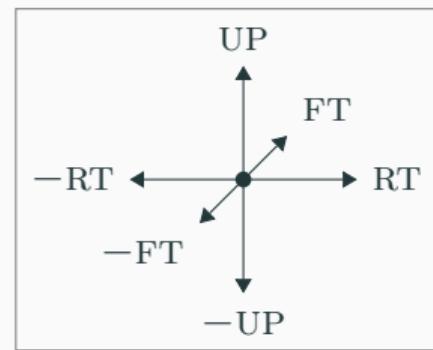
# Plane

The set of vectors varying only in the direction of one of their three dimensions (i.e., vectors + their inverses) make up a **plane**.



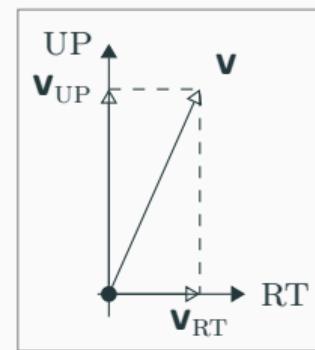
# Oriented Vector Space

Each vector space  $V$  provides three, mutually perpendicular **orienting levels**. Intuitively, these levels correspond to the directions *up* (UP), *forward* or *front* (FT), and *right* (RT). These levels in addition to their corresponding inverses, give rise to an **oriented vector space**.

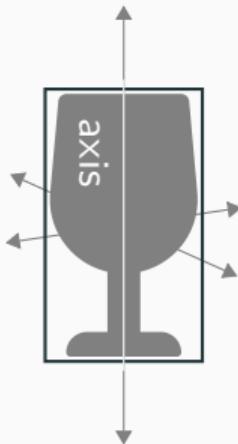


# Projections

Given orienting levels  $A$  and  $A'$ , a vector  $\mathbf{v}$  can be decomposed into its [projections](#) onto the levels,  $\mathbf{v}_A$  and  $\mathbf{v}'_A$ . The figure shows the orthogonal components of  $\mathbf{v}$  on the UP and the RT levels.

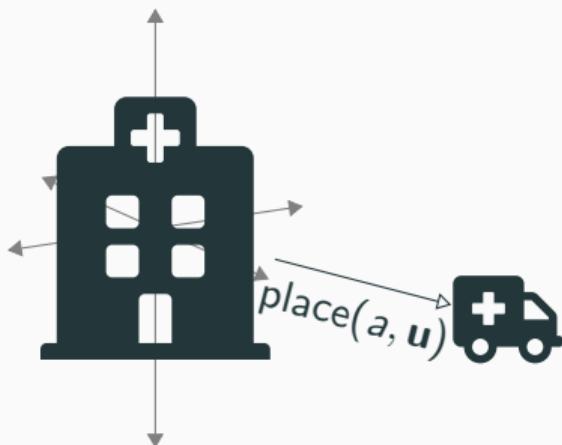


## Ex.: Wine glass



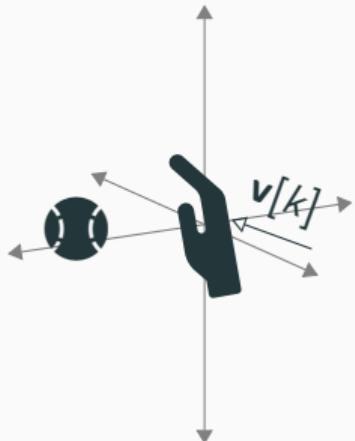
Spatial projection of a wine glass. The glass is located at the center of a vector space, and has a main axis.

## Ex.: Near



Spatial projection of two objects being spatially related. The ambulance  $a$  is near the hospital if the length of  $\mathbf{u}$  is below some threshold  $\tau$ .

## Ex.: Throwing



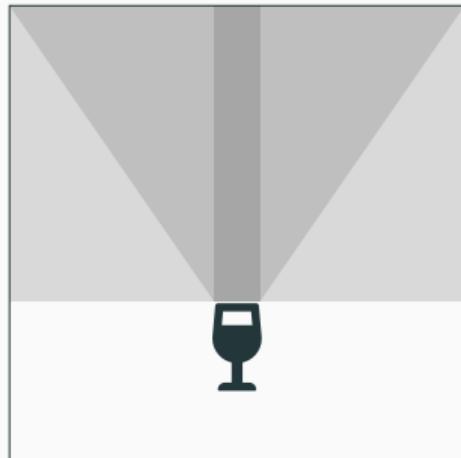
Spatial projection of a throwing event. The movement of the hand “leaves” a place path vector sequence in the domain.

(We will address the issues of handshapes soon.)

## Vector spaces in truth-conditional action

- Clear motivation for vectors from modified spatial prepositions such as *3cm above X*.
- But it is reasonable to assume that vectors should extend truth-condition of many more constructions.

Ex.: *above*



- Three readings of *above(wineglass)*:
- $\{\mathbf{v} \in \text{space}([\![\text{wineglass}]\!]^e) \mid$ 
  1.  $|\mathbf{v}_{\text{UP}}| = |\mathbf{v}|\}$  [dark gray]
  2.  $|\mathbf{v}_{\text{UP}}| > |\mathbf{v}_{\text{RT}/-\text{RT}}|\}$  [medium gray]
  3.  $|\mathbf{v}_{\text{UP}}| > 0\}$  [light gray]

$|\mathbf{v}|$ : length of vector  $\mathbf{v}$ .

$$|\mathbf{v}| = \sqrt{v_1^2 + v_2^2 + v_3^2}$$

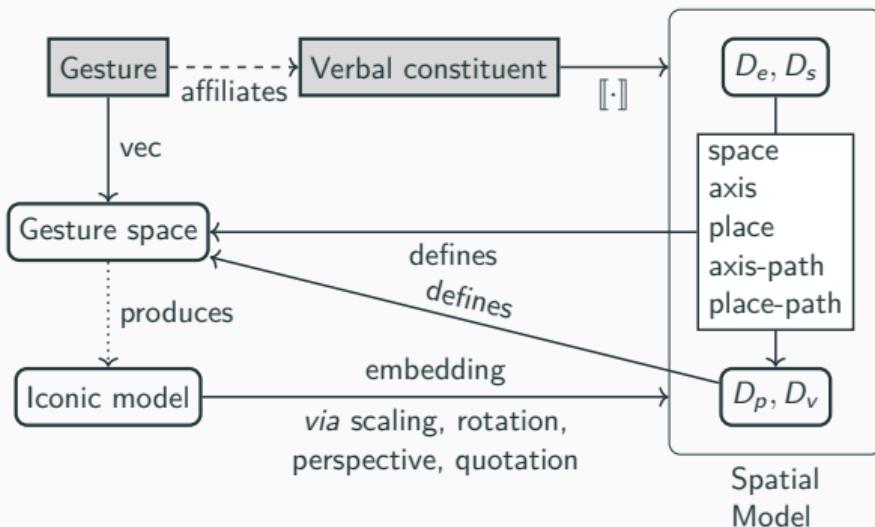
Vectors are not normalized.

## Ex.: Walk



- $\lambda x. \lambda e [\text{walk}(e) \wedge \text{ag}(e) = x \wedge \exists v [\text{path}(e, v)]]$ .
- “Mary walked the shortest route from the university to the capitol.” is true if there is an  $e$  and an  $x$  such that the above holds, and there is no  $w$  which is shorter than  $v$ .

# Architecture of spatial gesture semantics



Spatial models relate entities ( $D_e$ ) and events ( $D_s$ ) onto points ( $D_p$ ) and vectors ( $D_v$ ) in terms of vector spaces, axes, places, and paths. The latter are used to define vectorial gesture spaces. Gestures are translated into these gesture spaces, producing formal iconic models that – eventually modified by the operations of scaling, rotation, perspective, or quotation – impose constraints on the spatial domain in which their affiliated verbal expressions are evaluated.

## Very Basic Vector Math

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- A vector  $\mathbf{v}$  is a collection of numbers:  
 $\mathbf{v} = [x_0, x_1, x_2, \dots, x_{d-1}]$ .
- $d$  is the dimensionality of a vector (note that indexing usually starts with “0”).
- Ex.:  $\mathbf{v} = [0, 4, 6]$  is a three-dimensional vector.
- Vectors can be “stretched” by multiplying them with a scalar  $a$  (a number).  
 $a\mathbf{v} = [ax_0, ax_1, ax_2, \dots, ax_{d-1}]$
- Vectors of the same dimension can be added together by adding their elements (“superposition”).  
 $\mathbf{v} + \mathbf{w} = [x_0 + y_0, x_1 + y_1, x_2 + y_2, \dots, x_{d-1} + y_{d-1}]$

## Length and Norm

- The length of a vector is the square root of the sum of the squares of its elements.

- $|\mathbf{v}| = \sqrt{x_0^2 + x_1^2 + x_2^2 + \dots + x_{d-1}^2}$   
(also written  $\|\mathbf{v}\|$ )

- Normalized or unit vectors are vectors of length 1.
- The unit vector of a vector  $\mathbf{v}$  is obtained by dividing  $\mathbf{v}$  by  $|\mathbf{v}|$ .
- $\hat{\mathbf{v}} = \frac{\mathbf{v}}{|\mathbf{v}|} = \left[ \frac{x_0}{|\mathbf{v}|}, \frac{x_1}{|\mathbf{v}|}, \frac{x_2}{|\mathbf{v}|}, \dots, \frac{x_{d-1}}{|\mathbf{v}|} \right]$

# Linear Transformations

- A linear mapping of a vector is defined in terms of a set of vectors collected in a matrix.

- A  $2 \times 2$ -dimensional matrix is

$$\mathbf{M} = \begin{bmatrix} m_{1,1} & m_{1,2} \\ m_{2,1} & m_{2,2} \end{bmatrix}$$

- A linear transformation of a two-dimensional

vector  $\mathbf{v}$  is  $\begin{bmatrix} y_0 \\ y_1 \end{bmatrix} = \begin{bmatrix} m_{1,1} & m_{1,2} \\ m_{2,1} & m_{2,2} \end{bmatrix} \cdot \begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$

- $\mathbf{Mv} = \begin{bmatrix} m_{1,1} & m_{1,2} \\ m_{2,1} & m_{2,2} \end{bmatrix} \cdot \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} m_{1,1}x_0 + m_{1,2}x_1 \\ m_{2,1}x_0 + m_{2,2}x_1 \end{bmatrix}$

- Ex.: Counterclockwise rotation by  $\theta^\circ$ .

- $\mathbf{M} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$