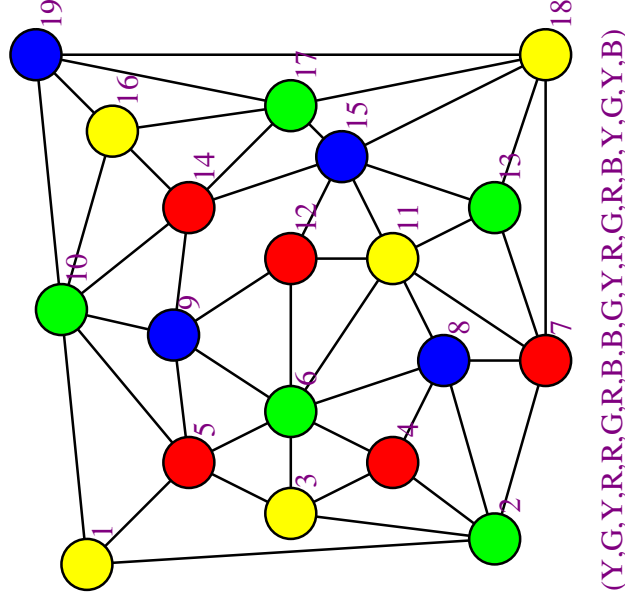


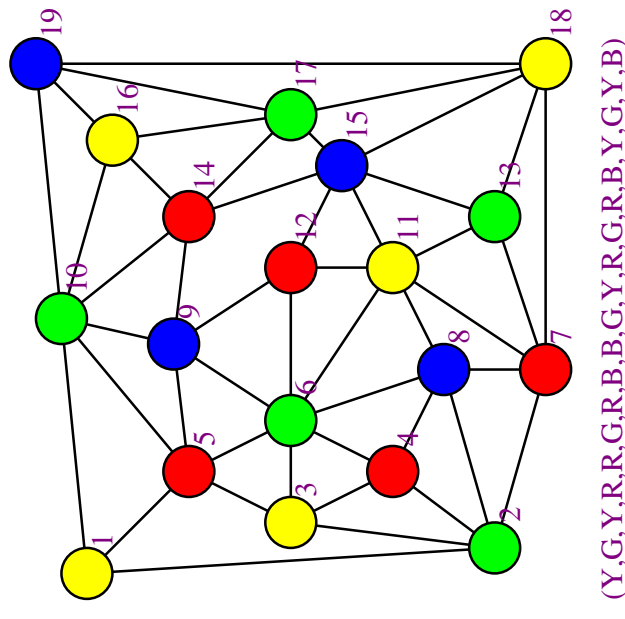
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- Many problems have very simple, natural representations as a string
- Graph colouring is an example of this
- We can use standard string based mutation and crossover operators on these natural representation



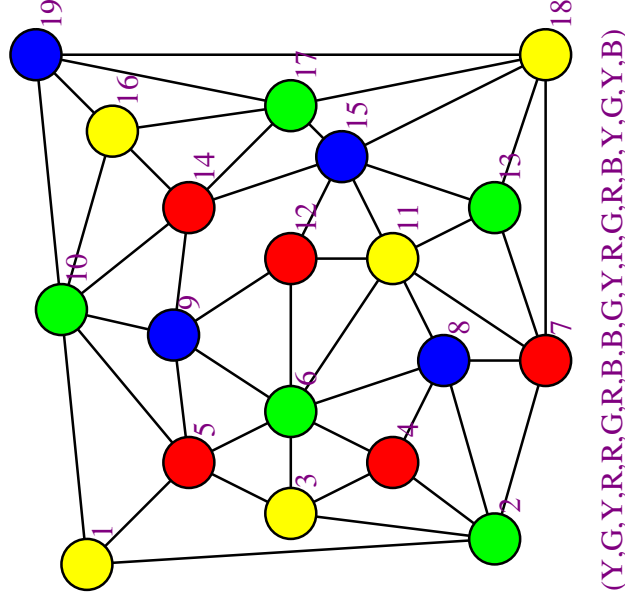
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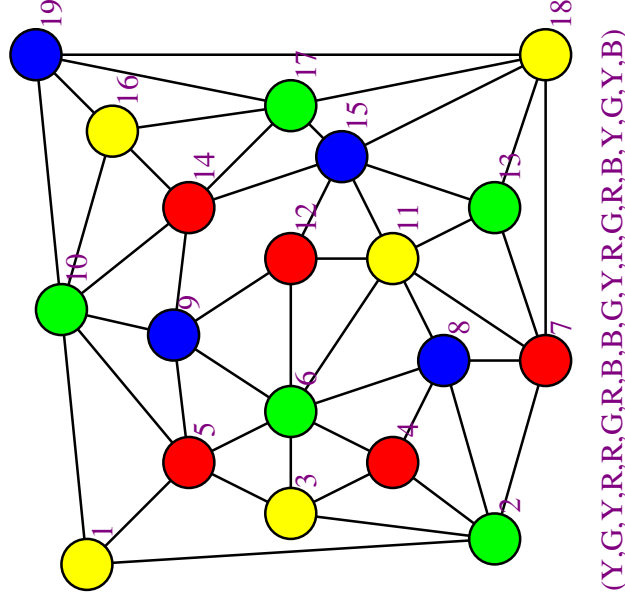
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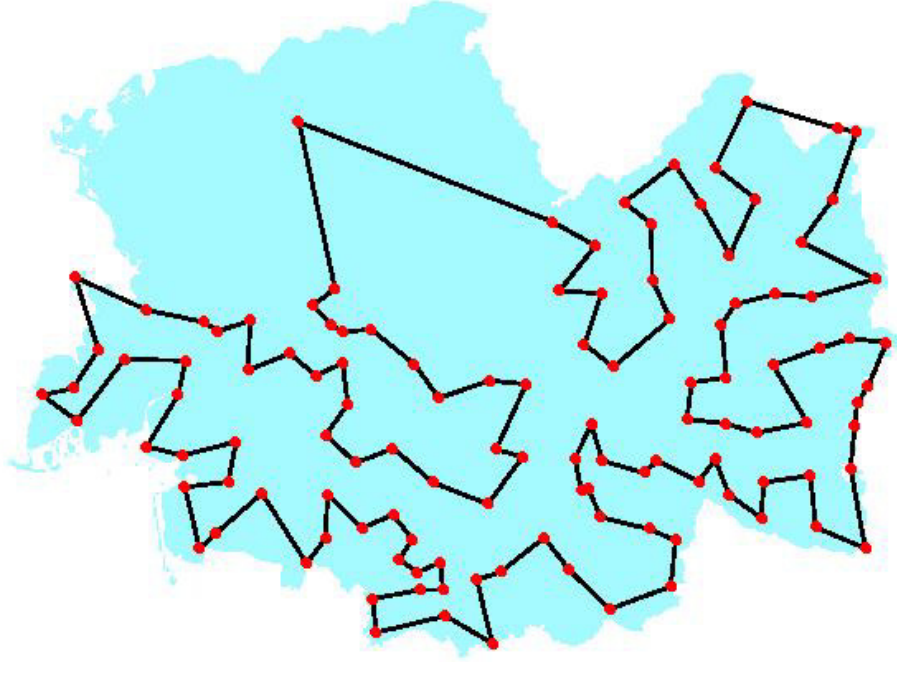
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- In TSP there is not a natural string representation
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$(1, 2, 3, 4)$  *point mutation*  $\longrightarrow (1, 2, 1, 4)$

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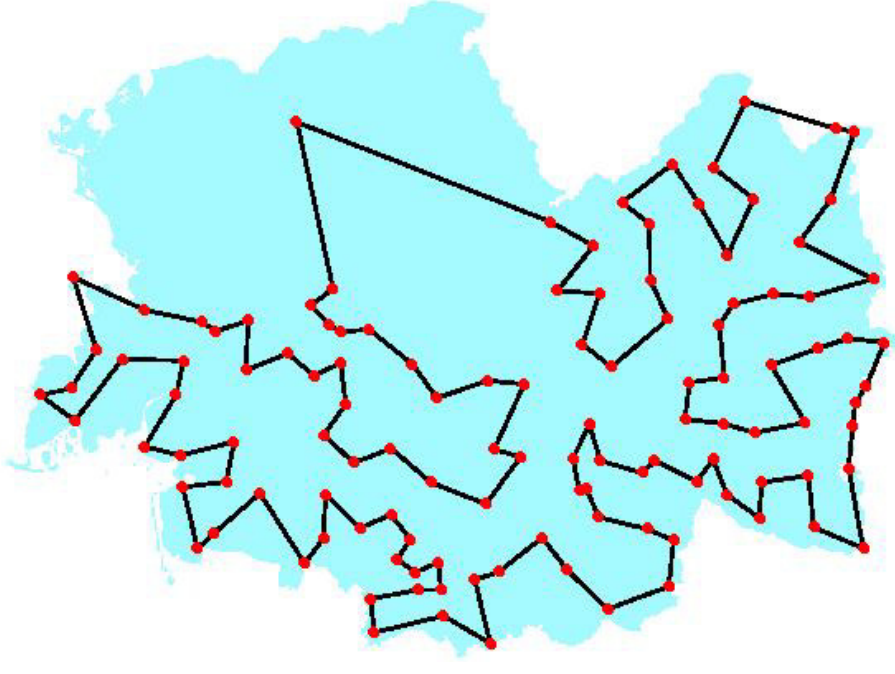
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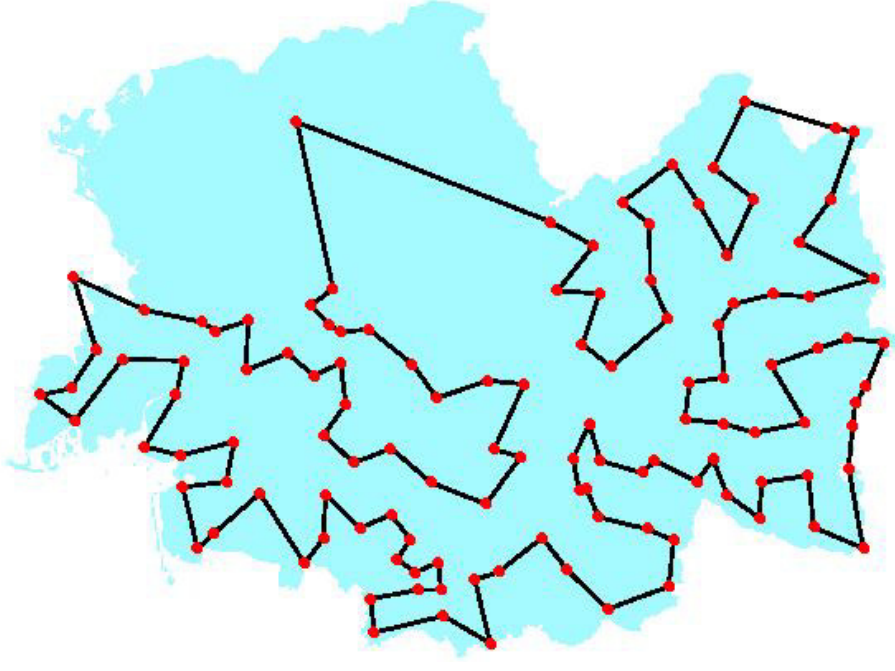


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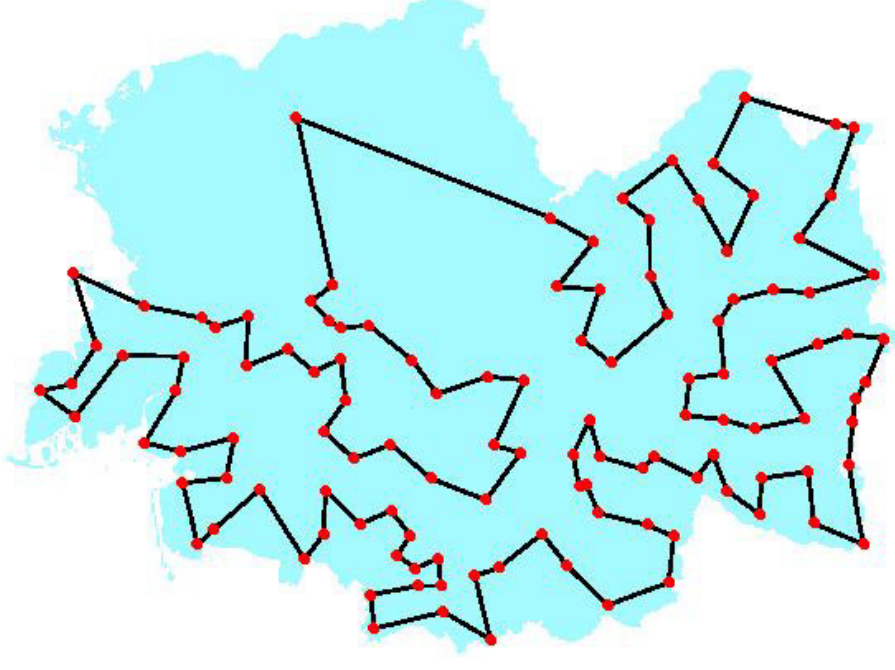
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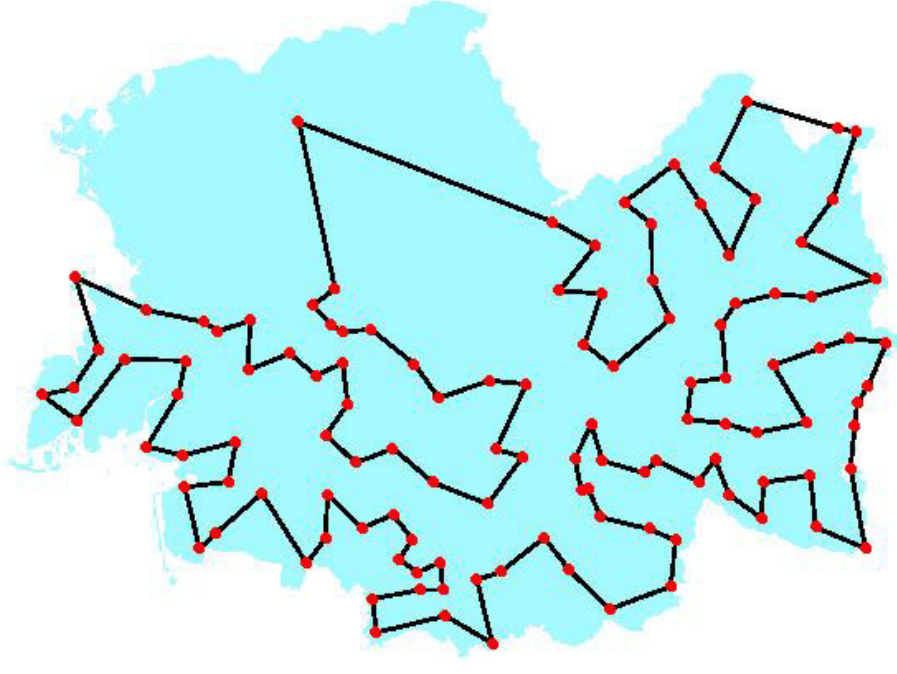


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**not legal tours!**



# Changing the Representation

- A number of different representations for the TSP have been proposed so that point mutation and one or two-point crossover work
- Unfortunately, such representations don't lead to good GAs
- More commonly a crossover is introduced which takes half the tour from one parent and takes as much of the tour as possible from the second parent but **repairs** the tour where necessary
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- Since it is the edges which determines the cost it seems sensible to build operators to preserve as many edges as possible
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- These are slight variants on this strategy, but they all try to construct a child using as many edges of the parents as possible

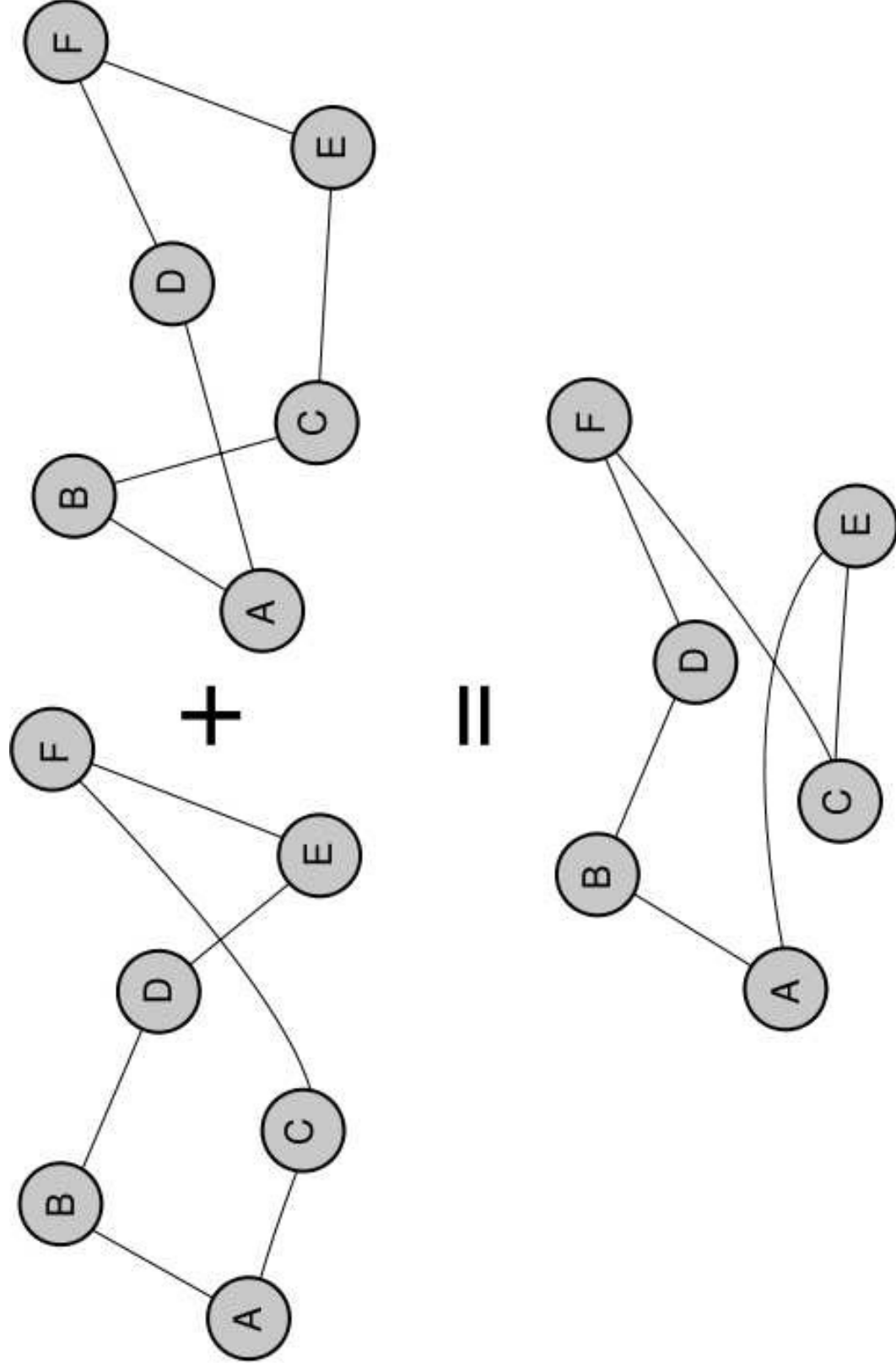
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- Point mutations make no sense

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$$(1, 2, 3, 4, 5, 6) \xrightarrow{\text{swap mutation}} (1, 5, 3, 4, 2, 6)$$

disrupts four edges 1–5, 5–3, 4–2 and 2–6

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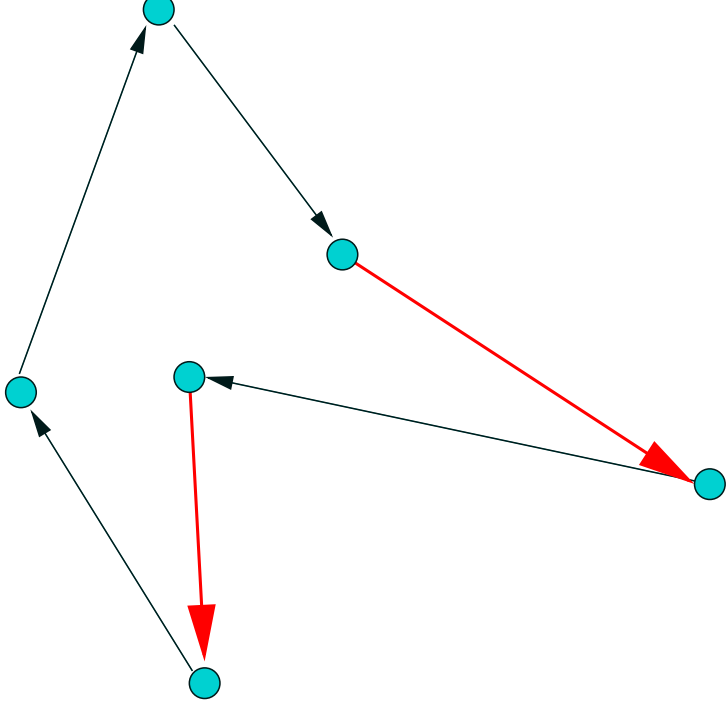
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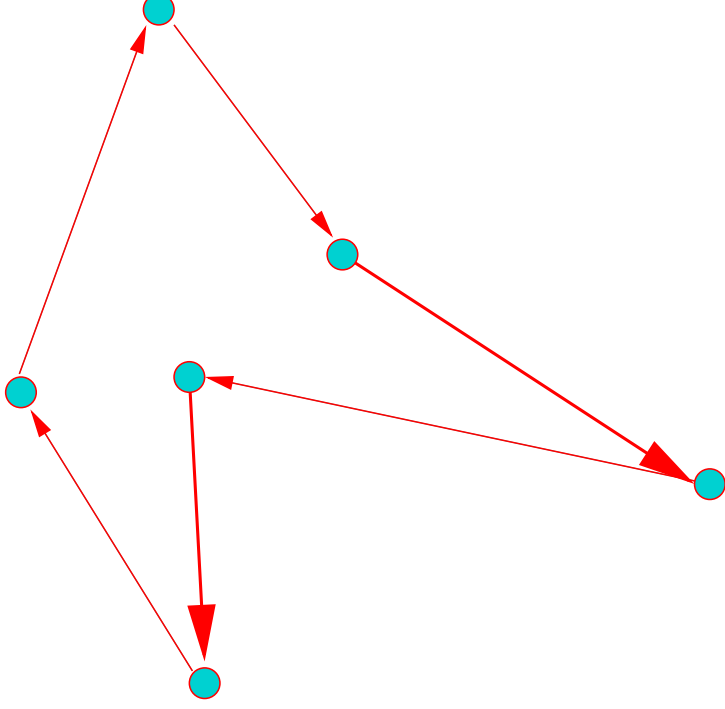
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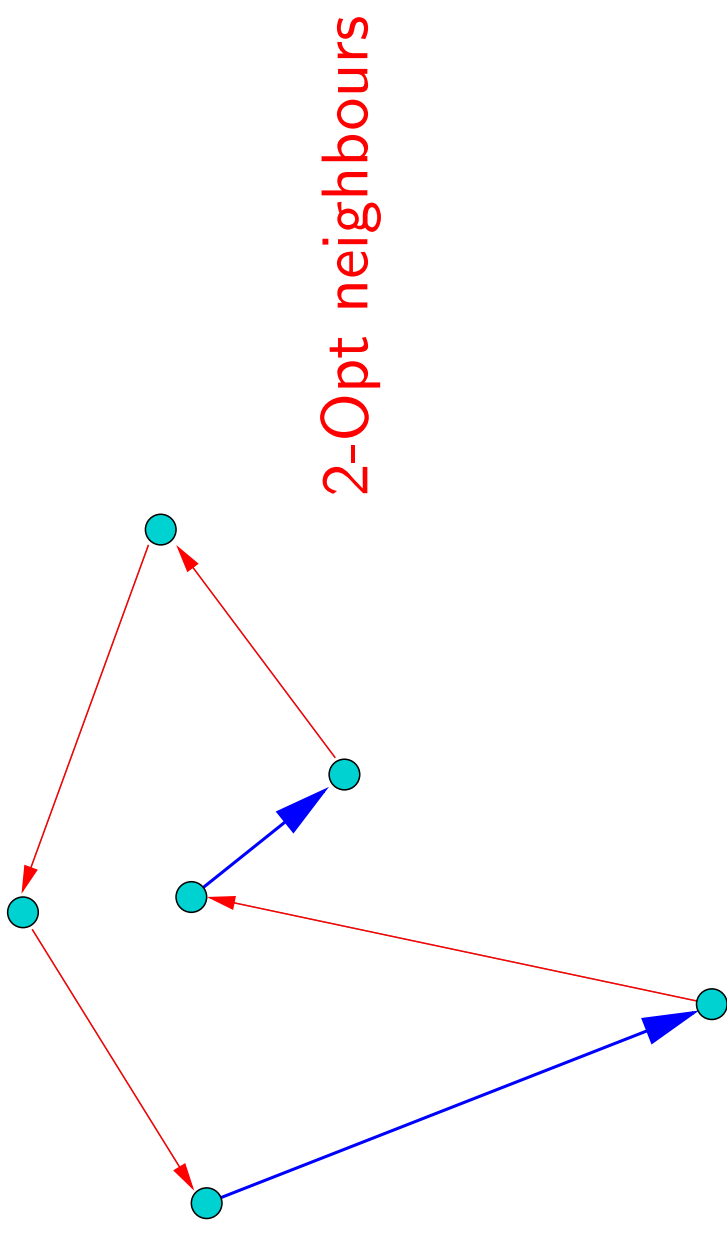
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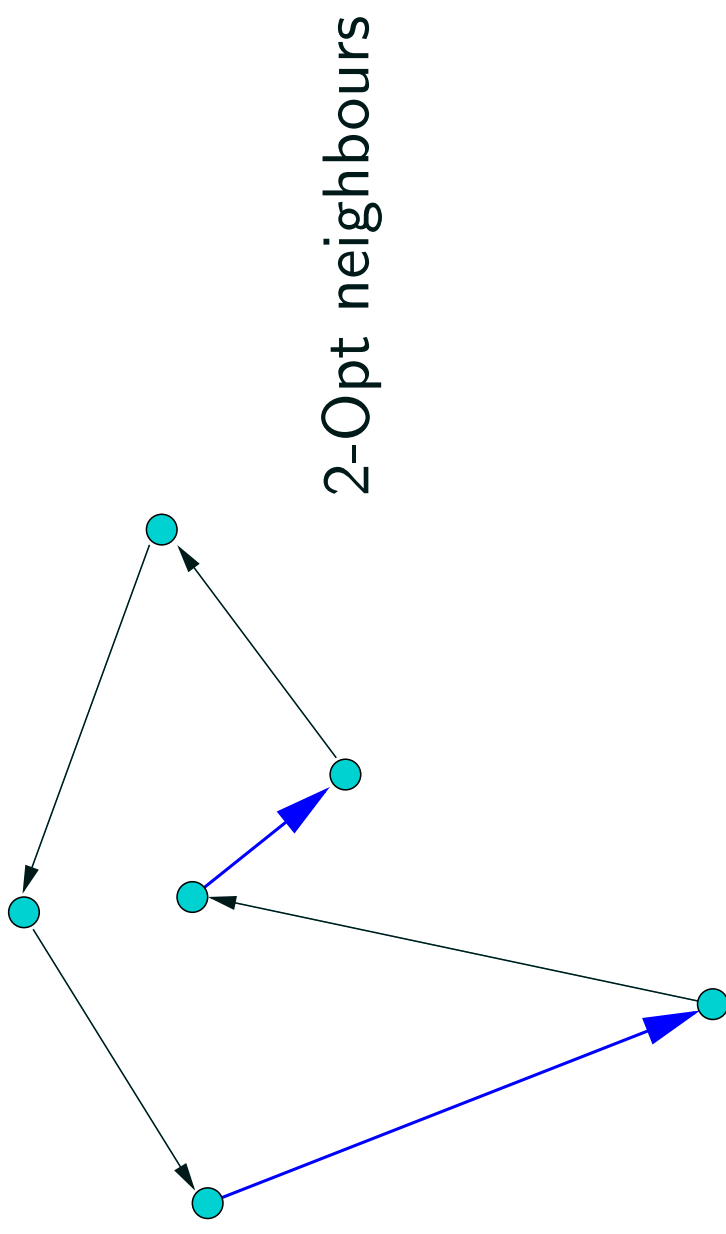
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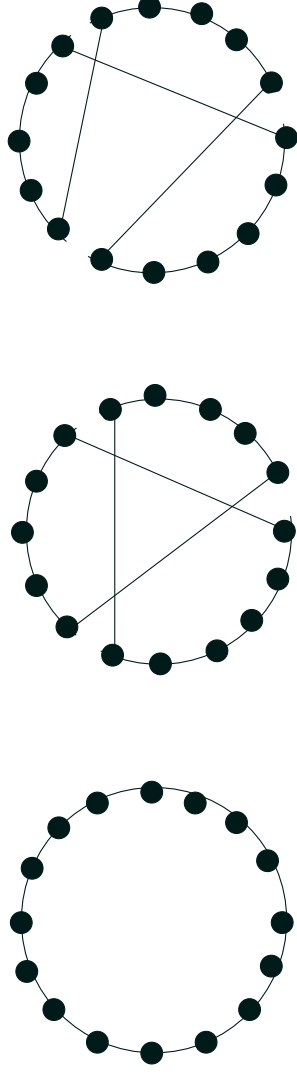
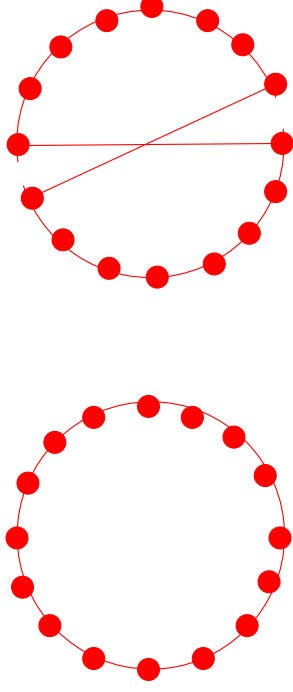
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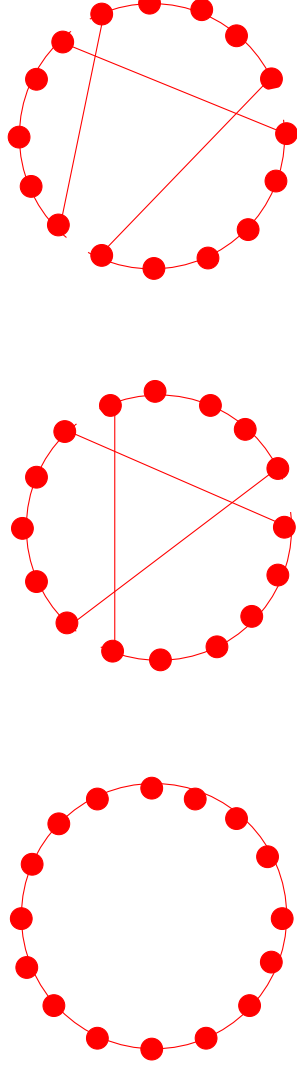
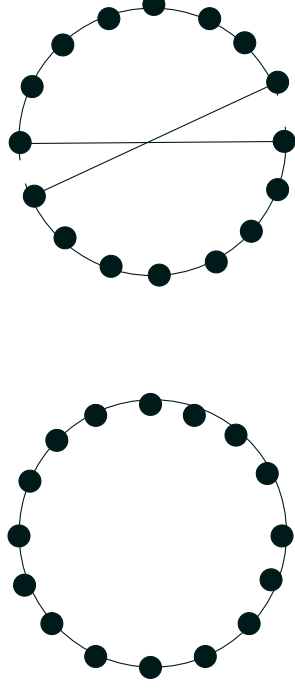
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# Neighbourhood Search

- Using 2-Opt and 3-Opt provides a fast neighbourhood search
- Neighbourhood search is fast because it is relatively cheap to recompute the cost after performing a 2-Opt or 3-Opt move
- The classic search method for TSP is the *Lin-Kernighan method* which uses 2-Opt, 3-Opt and a specialised 4-Opt which combines two 2-Opt
- The best heuristic to date for finding good solutions for TSP is *Iterated Lin-Kernighan*
- For any GA to be competitive with the state-of-the-art it has to include a fast neighbourhood search