Actividad 2 - II Unidad: Interpolación de Newton

1- EJERCICIO

2- EJERCICIO

```
1ejercicio1.py
                  2ejercicio2.py X
3ejercicio.py
                                                      4ejercicio.py
                                                                       5ejercicio.py
 2ejercicio2.py > ...
      #EJERCICIO 2
       import numpy as np
       def newton_interpolation(x_data, y_data, x):
          n = len(x_data)
          coef = np.copy(y_data).astype(float)
          for j in range(1, n):
               coef[j:n] = (coef[j:n] - coef[j-1:n-1]) / (x_data[j:n] - x_data[0:n-j])
          result = coef[-1]
           for k in range(n-2, -1, -1):
               result = result * (x - x_data[k]) + coef[k]
           return result, coef
      x points = np.array([0, 1, 2])
       y_points = np.array([1, 4, 9])
       val, coef = newton_interpolation(x_points, y_points, 1.5)
       print("Coeficientes:", coef)
       print("P(1.5) =", val)
PROBLEMS
          OUTPUT PORTS POSTMAN CONSOLE
TERMINAL
PS C:\Users\pc-\modelado\semana10> & C:/Users/pc-/AppData/Local/Programs/Python/Python313/
o2.py
Coeficientes: [1. 3. 1.]
 P(1.5) = 6.25
PS C:\Users\pc-\modelado\semana10>
```

3- EJERCICIO

```
🕽 3ejercicio.py > 😭 newton_interp
      import numpy as np
      import math
     x points = np.array([0, 1, 2])
      y points = np.array([math.e**x for x in x points])
      def newton_interp(x_data, y_data, x):
          n = len(x_data)
          coef = np.copy(y_data)
          for j in range(1, n):
              coef[j:n] = (coef[j:n] - coef[j-1:n-1]) / (x_data[j:n] - x_data[0:n-j])
          result = coef[-1]
          for k in range(n-2, -1, -1):
              result = result * (x - x data[k]) + coef[k]
          return result
      print("P(1.5) =", newton_interp(x_points, y_points, 1.5))
PROBLEMS
TERMINAL
PS C:\Users\pc-\modelado\semana10> & C:/Users/pc-/AppData/Local/Programs/Python/Python313/
o.py
P(1.5) = 4.684607408443277
PS C:\Users\pc-\modelado\semana10>
```

4- EJERCICIO

```
4ejercicio.py > ...
      # EJERCICIO 4
      import numpy as np
      import math
     x_points = np.array([0, math.pi/4, math.pi/2])
      y_points = np.sin(x_points)
     def newton_interp(x_data, y_data, x):
          n = len(x_data)
          coef = np.copy(y_data)
         for j in range(1, n):
              coef[j:n] = (coef[j:n] - coef[j-1:n-1]) / (x_data[j:n] - x_data[0:n-j])
          result = coef[-1]
          for k in range(n-2, -1, -1):
              result = result * (x - x_data[k]) + coef[k]
          return result
     x_eval = math.pi / 3
      print("P(pi/3) =", newton_interp(x_points, y_points, x_eval))
      print("Valor real =", math.sin(x_eval))
PROBLEMS
                  PORTS POSTMAN CONSOLE DEBUG CONSOLE
TERMINAL
PS C:\Users\pc-\modelado\semana10> & C:\Users/pc-/AppData/Local/Programs/Python/Python313/
o.py
P(pi/3) = 0.8507615832769311
Valor real = 0.8660254037844386
PS C:\Users\pc-\modelado\semana10>
```