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```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%
% Ian Landwehr, Sam Alvares, and Sam Ridgley
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%
% ME480: Machine Component Design
% Dr. Constans
% Spring 2021
%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%

clc
close all
clear variables
```

## Basic Level

```
define constants

x1 = 1.032 ; % inches
x2 = 0 ; % inches
x3 = 2.825 ; % inches
x4 = 9.0625 ; % inches
y1 = 5.936 ; % inches
y2 = 0 ; % inches
y3 = 1.16 ; % inches
y4 = 7.9375; % inches
pin_diameter = 0.25 ; % inches
theta = 20.577 * (pi/180) ; % (refers to the theta (in radians)
    calculated using Pythagorean theorem)
w = 0.712; % inches
t = 0.09 ; % since values for arm and link are the same for simplicity
Force = 20 ; % lbf (refers to half the force applied to the handle due
    to symmetry)
FOS = 1.8 ; % (refers to the Factor of Safety required)
alpha = 0;

% solve for reaction forces
F1 = Force * (sin(alpha)*y4 + cos(alpha)*x4) / (sin(theta)*y3 +
    cos(theta)*x3) ;
F3 = Force * (sin(alpha)*y4 + cos(alpha)*x4) / (sin(theta)*y3 +
    cos(theta)*x3) ;
```

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```

F2_x = -(Force)*(sin(alpha)*sin(theta)*y3 - sin(alpha)*sin(theta)*y4 +
    sin(alpha)*cos(theta)*x3 - sin(theta)*cos(alpha)*x4) / (sin(theta)*y3
    + cos(theta)*x3) ; % x-component of the force present at rivet 2
F2_y = -(Force)*(sin(alpha)*cos(theta)*y4 - sin(theta)*cos(alpha)*y3 -
    cos(alpha)*cos(theta)*x3 + cos(alpha)*cos(theta)*x4) / (sin(theta)*y3
    + cos(theta)*x3) ; % y-component of the force present at rivet 2
F2 = sqrt( (F2_x).^2 + (F2_y).^2 ) ;
Flink = F1;

% print reactions
fprintf('----- Basic Level (alpha=0) -----\n')
fprintf('Reaction forces:\n')
fprintf('F1 = %4.4f\n',F1)
fprintf('F2x = %4.4f\n',F2_x)
fprintf('F2y = %4.4f\n',F2_y)
fprintf('F2 = %4.4f\n',F2)
fprintf('F3 = %4.4f\n',F3)

% rivet strength - direct shear
pin_radius_outer = 1/8 ; % inches
pin_thickness = 1/16 ; % inches
pin_radius_inner = pin_radius_outer - pin_thickness ; % inches
pin_inner_area = pi * pin_radius_inner^2 ; % inches^2
pin_outer_area = pi * pin_radius_outer^2 ; % inches^2
Area_Pin = pin_outer_area - pin_inner_area; % inches^2
Tau_Pin_1_Shear = F1 / Area_Pin; % psi
Tau_Pin_2_Shear = F2 / Area_Pin; % psi
Tau_Pin_3_Shear = F3 / Area_Pin; % psi
tau_rivet_critical = Tau_Pin_1_Shear;
Sy_yield_rivet = FOS*2*tau_rivet_critical;

% link strength - normal stress (axial)
Aaxial = t*(w-pin_diameter);
sigma_axial = Flink/Aaxial;
Sy_yield_axial = FOS*sigma_axial;

% link strenght - normal stress (bearing)
Abearing = t*pin_diameter;
sigma_bearing = Flink/Abearing;
Sy_yield_bearing = FOS*sigma_bearing;

% link strength
l = sqrt((w/2)^2-(pin_diameter/2)^2);
Atearout = 2*l*t;
tau_tearout = Flink/Atearout;
Sy_yield_tearout = FOS*2*tau_tearout;

% print yield strengths
fprintf('\nYield strengths:\n')
fprintf('Sy_yield_rivet = %4.4f\n',Sy_yield_rivet)
fprintf('Sy_yield_axial = %4.4f\n',Sy_yield_axial)
fprintf('Sy_yield_bearing = %4.4f\n',Sy_yield_bearing)
fprintf('Sy_yield_tearout = %4.4f\n',Sy_yield_tearout)

```

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----- Basic Level (alpha=0) -----

Reaction forces:

F1 = 59.3782

F2x = 20.8694

F2y = -35.5899

F2 = 41.2574

F3 = 59.3782

Yield strengths:

Sy\_yield\_rivet = 5806.2847

Sy\_yield\_axial = 2570.4846

Sy\_yield\_bearing = 4750.2555

Sy\_yield\_tearout = 3562.6934

## Medium Level

```
fprintf('\n----- Medium Level (alpha = 10 deg) -----\n')
```

```
alpha = 10*pi/180; %rad
```

```
% solve for reaction forces
```

```
F1 = Force * (sin(alpha)*y4 + cos(alpha)*x4) / (sin(theta)*y3 +  
cos(theta)*x3) ;
```

```
F3 = Force * (sin(alpha)*y4 + cos(alpha)*x4) / (sin(theta)*y3 +  
cos(theta)*x3) ;
```

```
F2_x = -(Force)*(sin(alpha)*sin(theta)*y3 - sin(alpha)*sin(theta)*y4 +  
sin(alpha)*cos(theta)*x3 - sin(theta)*cos(alpha)*x4) / (sin(theta)*y3  
+ cos(theta)*x3) ; % x-component of the force present at rivet 2
```

```
F2_y = -(Force)*(sin(alpha)*cos(theta)*y4 - sin(theta)*cos(alpha)*y3 -  
cos(alpha)*cos(theta)*x3 + cos(alpha)*cos(theta)*x4) / (sin(theta)*y3  
+ cos(theta)*x3) ; % y-component of the force present at rivet 2
```

```
F2 = sqrt( (F2_x).^2 + (F2_y).^2 ) ;
```

```
Flink = F1;
```

```
% print reactions
```

```
fprintf('Reaction forces:\n')
```

```
fprintf('F1 = %4.4f\n',F1)
```

```
fprintf('F2x = %4.4f\n',F2_x)
```

```
fprintf('F2y = %4.4f\n',F2_y)
```

```
fprintf('F2 = %4.4f\n',F2)
```

```
fprintf('F3 = %4.4f\n',F3)
```

```
% rivet strength - direct shear
```

```
pin_radius_outer = 1/8 ; % inches
```

```
pin_thickness = 1/16 ; % inches
```

```
pin_radius_inner = pin_radius_outer - pin_thickness ; % inches
```

```
pin_inner_area = pi * pin_radius_inner^2 ; % inches^2
```

```
pin_outer_area = pi * pin_radius_outer^2 ; % inches^2
```

```
Area_Pin = pin_outer_area - pin_inner_area; % inches^2
```

```
Tau_Pin_1_Shear = F1 / Area_Pin ; % psi
```

```
Tau_Pin_2_Shear = F2 / Area_Pin ; % psi
```

```
Tau_Pin_3_Shear = F3 / Area_Pin ; % psi
```

```
tau_rivet_critical = Tau_Pin_1_Shear;
```

```
Sy_yield_rivet = FOS*2*tau_rivet_critical;
```

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```

% link strength - normal stress (axial)
Aaxial = t*(w-pin_diameter);
sigma_axial = Flink/Aaxial;
Sy_yield_axial = FOS*sigma_axial;

% link strenght - normal stress (bearing)
Abearing = t*pin_diameter;
sigma_bearing = Flink/Abearing;
Sy_yield_bearing = FOS*sigma_bearing;

% link strength
l = sqrt((w/2)^2-(pin_diameter/2)^2);
Atearout = 2*l*t;
tau_tearout = Flink/Atearout;
Sy_yield_tearout = FOS*2*tau_tearout;

% print yield strengths
fprintf('\nYield strengths:\n')
fprintf('Sy_yield_rivet = %4.4f\n',Sy_yield_rivet)
fprintf('Sy_yield_axial = %4.4f\n',Sy_yield_axial)
fprintf('Sy_yield_bearing = %4.4f\n',Sy_yield_bearing)
fprintf('Sy_yield_tearout = %4.4f\n',Sy_yield_tearout)

----- Medium Level (alpha = 10 deg) -----
Reaction forces:
F1 = 67.5070
F2x = 20.2535
F2y = -43.5040
F2 = 47.9875
F3 = 67.5070

Yield strengths:
Sy_yield_rivet = 6601.1627
Sy_yield_axial = 2922.3829
Sy_yield_bearing = 5400.5636
Sy_yield_tearout = 4050.4247

```

## Advanced Level

```

fprintf("\n----- Advanced Level (variable alpha) ----- \n")

alpha_deg = (-15:75).';
alpha = alpha_deg*(pi/180); %rad

% solve for reaction forces
F1 = Force * (sin(alpha)*y4 + cos(alpha)*x4) / (sin(theta)*y3 +
cos(theta)*x3) ;
F3 = Force * (sin(alpha)*y4 + cos(alpha)*x4) / (sin(theta)*y3 +
cos(theta)*x3) ;
F2_x = -(Force)*(sin(alpha)*sin(theta)*y3 - sin(alpha)*sin(theta)*y4 +
sin(alpha)*cos(theta)*x3 - sin(theta)*cos(alpha)*x4) / (sin(theta)*y3
+ cos(theta)*x3) ; % x-component of the force present at rivet 2

```

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```

F2_y = -(Force)*(sin(alpha)*cos(theta)*y4 - sin(theta)*cos(alpha)*y3 -
    cos(alpha)*cos(theta)*x3 + cos(alpha)*cos(theta)*x4) / (sin(theta)*y3
    + cos(theta)*x3) ; % y-component of the force present at rivet 2
F2 = sqrt( (F2_x).^2 + (F2_y).^2 ) ;
Flink = F1;

% rivet strength - direct shear
pin_radius_outer = 1/8 ; % inches
pin_thickness = 1/16 ; % inches
pin_radius_inner = pin_radius_outer - pin_thickness ; % inches
pin_inner_area = pi * pin_radius_inner^2 ; % inches^2
pin_outer_area = pi * pin_radius_outer^2 ; % inches^2
Area_Pin = pin_outer_area - pin_inner_area; % inches^2
Tau_Pin_1_Shear = F1 / Area_Pin ; % psi
Tau_Pin_2_Shear = F2 / Area_Pin ; % psi
Tau_Pin_3_Shear = F3 / Area_Pin ; % psi
tau_rivet_critical = Tau_Pin_1_Shear;
Sy_yield_rivet = FOS*2*tau_rivet_critical;

% link strength - normal stress (axial)
Aaxial = t*(w-pin_diameter);
sigma_axial = Flink/Aaxial;
Sy_yield_axial = FOS*sigma_axial;

% link strength - normal stress (bearing)
Abearing = t*pin_diameter;
sigma_bearing = Flink/Abearing;
Sy_yield_bearing = FOS*sigma_bearing;

% link strength
Rlink = w/2;
Rrivet = pin_diameter/2;
l = sqrt((Rlink)^2-(Rrivet)^2);
Atearout = 2*l*t;
tau_tearout = Flink/Atearout;
Sy_yield_tearout = FOS*2*tau_tearout;

% plot required strengths
figure(1)

plot(alpha_deg, Sy_yield_axial, '.b') ;
hold on
plot(alpha_deg, Sy_yield_bearing, '.g') ;
hold on
plot(alpha_deg, Sy_yield_tearout, '.r') ;
xlabel('Alpha [degrees]') ;
ylabel('Required Strength of Link [psi]') ;
legend('S_{y,axial}', 'S_{y,bearing}', 'S_{y,tearout}', 'Location', 'NORTHWEST')

figure(2)
plot(alpha_deg, Sy_yield_rivet, '.k') ;
xlabel('Alpha [degrees]') ;
ylabel('Required Strength of Rivet [psi]') ;

```

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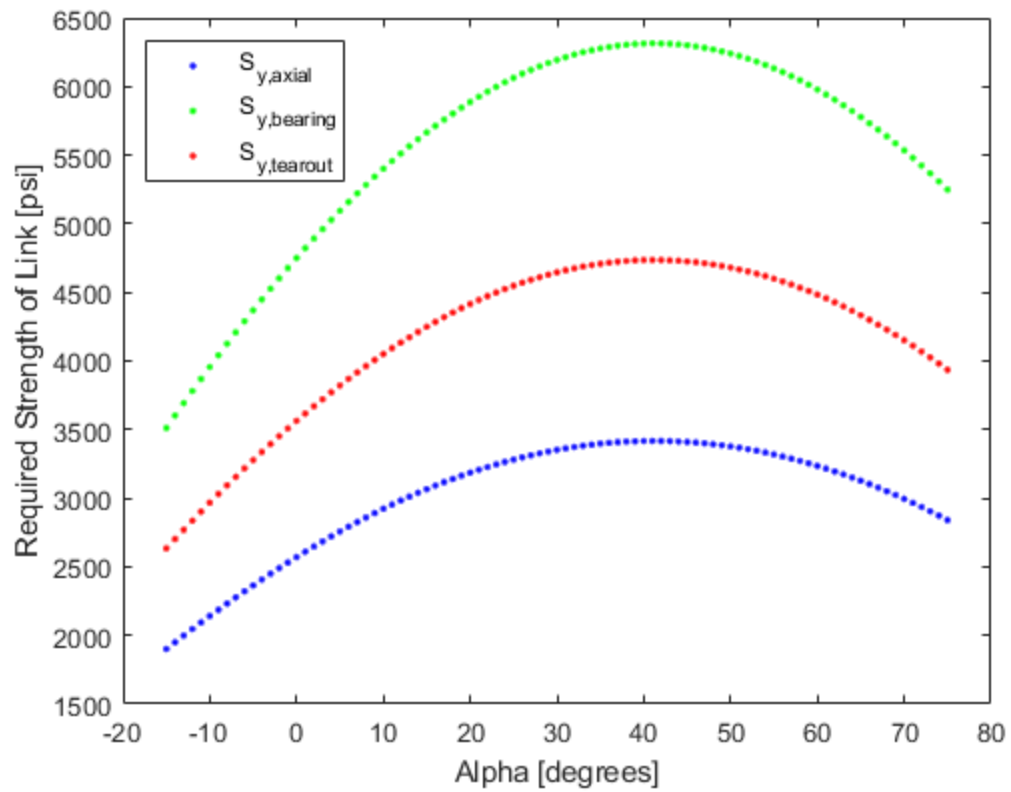
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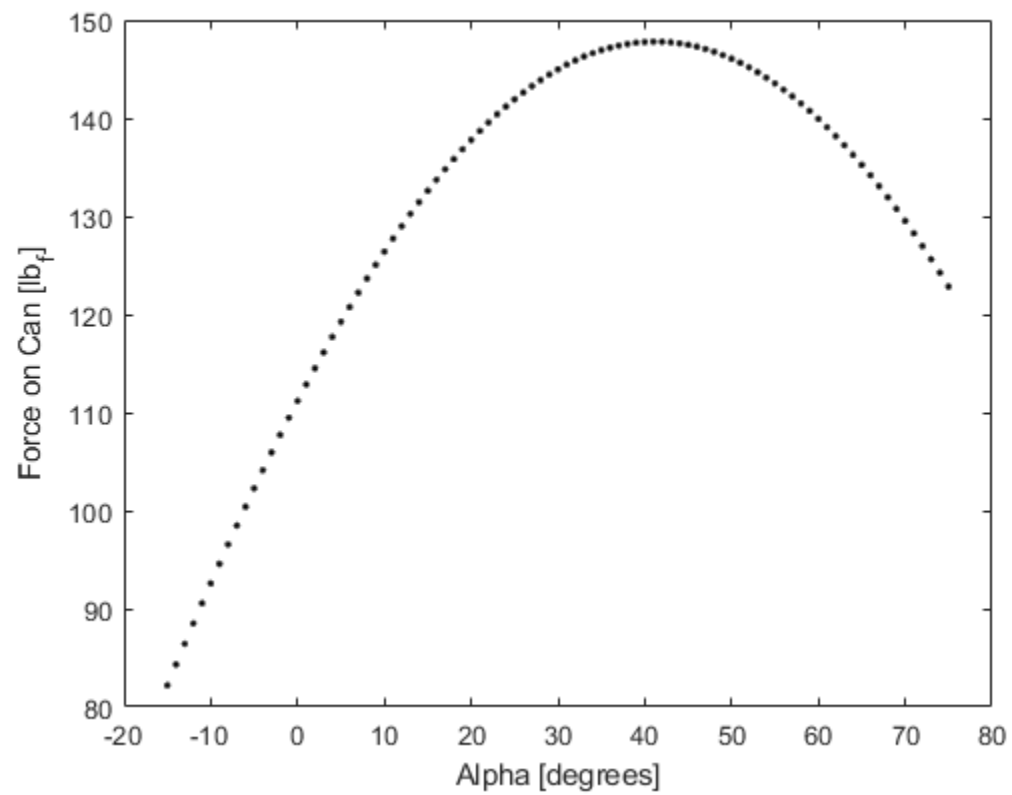
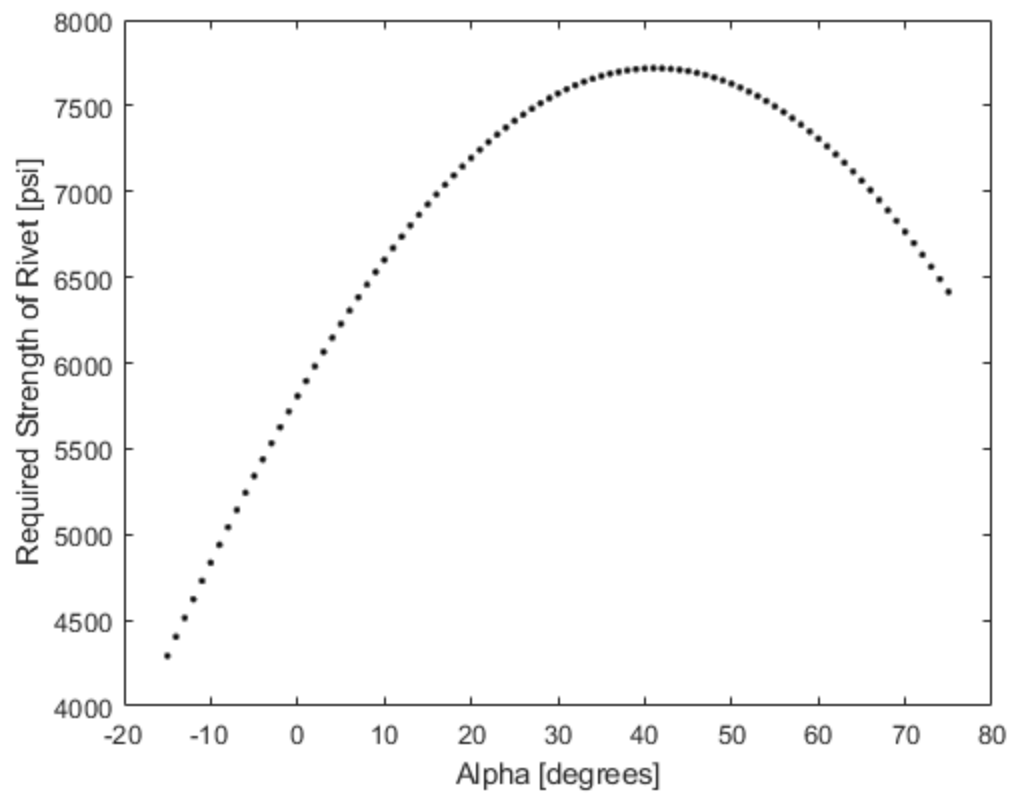
```

% plot crushing force
figure(3)
F_can = 2*F1.*cos(theta);
plot(alpha_deg,F_can,'.k');
xlabel('Alpha [degrees]')
ylabel('Force on Can [lb_{f}]')

% calculate max crushing forces angle
[maxF,I] = max(F_can);
alphaMaxF = alpha_deg(I);

```





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