

# Concurrent programming in C++11

## Computer Architecture

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- 1 Introduction to concurrency in C++
- 2 Library overview
- 3 Class `thread`
- 4 Mutex objects and condition variables
- 5 Conclusion

# Motivation

- C++11 (ISO/IEC 14882:2011) offers its own concurrency model.
  - Minor revisions in C++14.
  - More expected for C++17.
- Any compliant implementation must supply it.
  - Solves inherent problems from **PThreads**.
  - Portable concurrent code: **Windows**, **POSIX**, ...
- **Implications:**
  - Changes in the **language**.
  - Changes in the **standard library**.
- Influence on C11 (ISO/IEC 9899:2011).
- **Important:** Concurrency and parallelism are two **related** but **distinct** concepts.

# Structure

- C++ **language offers**:
  - A new **memory model**.
  - **thread\_local** variables.
- C++ **standard library offers**:
  - **Atomic types**.
    - Useful for portable **lock free programming**.
  - **Portable abstractions** for concurrency.
    - **thread**.
    - **mutex**.
    - **lock**.
    - **packaged\_task**.
    - **future**.

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## 2 Library overview

- Threads
- Access to shared data
- Waiting
- Asynchronous execution

# Thread launching

- A **thread** represented by class **std::thread**.
  - Usually represents an OS thread.

## Launching a thread from a function

```
void f1();  
void f2();  
  
void g() {  
    thread t1{f1}; // Launches thread executing f1()  
    thread t2{f2}; // Launches thread executing f2()  
  
    t1.join(); // Waits until t1 terminates.  
    t2.join(); // Waits until t2 terminates.  
}
```

# Shared objects

- Two threads may access to a **shared object**.
- Possibility for **data races**.

## Access to shared variables

```
int x = 42;

void f() { ++x; }
void g() { x=0; }
void h() { cout << "Hello" << endl; }
void i() { cout << "Bye" << endl; }

void race() {
    thread t1{f}; thread t2{g};
    t1.join (); t2.join ();

    thread t3{h}; thread t4{i};
    t3.join (); t4.join ();
}
```



# Argument passing

- **Simplified argument passing** without needing any **casts**.

## Argument passing

```
void f1(int x);  
void f2(double x, double y);  
  
void g() {  
    thread t1{f1, 10}; // Runs f1(10)  
    thread t2{f1}; // Error  
    thread t3{f2, 1.0} // Error  
    thread t4{f2, 1.0, 1.0}; // Runs f2(1.0,1.0)  
    // ...  
    // Thread joins
```

# Threads and function objects

- **Function object**: Object that can be invoked as a function.
- **operator ()** *overload/redefinition*.

## Function object in a thread

```
struct myfunc {  
    myfunc(int val) : x{val} {} // Constructor. Initializes object.  
    void operator()() { do_something(x); } // Redefine operator()  
    int x;  
};  
  
void g() {  
    myfunc f1{10}; // Constructs object f1  
    f1(); // Invokes call operator f1.operator()  
    thread t1{f1}; // Runs f1() in a thread  
    thread t2{myfunc{20}}; // Construct temporal and invokes it  
    // ...  
    // Threads joins
```

## 2 Library overview

- Threads
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# Mutual exclusion

- **mutex** allows to control access with **mutual exclusion to a resource**.
  - **lock()**: **Acquires** associated lock.
  - **unlock()**: **Releases** associated lock.

## Use of mutex

```
mutex m;  
int x = 0;  
  
void f() {  
    m.lock();  
    ++x;  
    m.unlock();  
}
```

## Launching threads

```
void g() {  
    thread t1(f);  
    thread t2(f);  
    t1.join();  
    t2.join();  
    cout << x << endl;  
}
```

# Problems with `lock()`/`unlock()`

## ■ Possible problems:

- Forgetting to **release a lock**.

- **Exceptions**.

## ■ Solution: **`unique_lock`**.

- **Pattern**: **RAII** (Resource Acquisition Is Initialization).

### Automatic lock

```
mutex m;  
int x = 0;  
  
void f() {  
    // Acquires lock  
    unique_lock<mutex> l{m};  
    ++x;  
} // Releases lock
```

### Launching threads

```
void g() {  
    thread t1(f);  
    thread t2(f);  
    t1.join();  
    t2.join();  
  
    cout << x << endl;  
}
```

# Acquiring multiple `mutex`

- **`lock()`** allows for acquiring simultaneously several **`mutex`**.
  - Acquires all or none.
  - If some is blocked it waits releasing all of them.

## Multiple acquisition

```
mutex m1, m2, m3;
```

```
void f() {  
    lock(m1, m2, m3);
```

```
    // Access to shared data
```

```
    // Beware: Locks are not released
```

```
    m1.unlock();  
    m2.unlock();  
    m3.unlock()
```

```
}
```

# Acquiring multiple `mutex`

- Specially useful in cooperation with `unique_lock`

## Multiple automatic acquisition

```
void f() {  
    unique_lock l1{m1, defer_lock};  
    unique_lock l2{m2, defer_lock};  
    unique_lock l3{m3, defer_lock};  
  
    lock(l1, l2, l3);  
    // Access to shared data  
  
} // Automatic release
```



## 2 Library overview

- Threads
- Access to shared data
- **Waiting**
- Asynchronous execution



# Timed waiting

## ■ Access to clock:

```
using namespace std::chrono;  
auto t1 = high_resolution_clock::now();
```

## ■ Time difference:

```
auto dif = duration_cast<nanoseconds>(t2-t1);  
cout << dif.count() << endl;
```

## ■ Specifying a wait:

```
this_thread::sleep_for(microseconds{500});
```

# Condition variables

- Mechanism to synchronize threads when accessing shared resources.
  - **wait()**: Wait on a **mutex**.
  - **notify\_one()**: Awakens a waiting thread.
  - **notify\_all()**: Awakens all waiting threads.

## Producer/Consumer

```
class request;  
  
queue<request> q; // Requests queue  
condition_variable cv; //  
mutex m;  
  
void producer();  
void consumer();
```

## Consumer

```
void consumer() {  
    for (;;) {  
        unique_lock<mutex> l{m};  
  
        while (q.empty()) {  
            cv.wait(l);  
        }  
  
        auto r = q.front();  
        q.pop();  
        l.unlock();  
  
        process(r);  
    }  
}
```

### ■ Effect of **wait**:

- 1 Releases lock and waits a notification.
- 2 Acquires the lock when awoken.

## Producer

```
void producer() {  
    for (;;) {  
        request r = generate();  
  
        unique_lock<mutex> l{m};  
        q.push(r);  
  
        cv.notify_one();  
    }  
}
```

- Effects of **notify\_one()**:
  - 1 Awakes to one thread waiting on the condition.



## 2 Library overview

- Threads
- Access to shared data
- Waiting
- Asynchronous execution

# Asynchronous execution and futures

- An asynchronous task allows simple launching of a task execution:
  - In a different thread of execution.
  - As a deferred task.
  
- A **future** is an object allowing that a thread can return a value to the code section that invoked it.

## Asynchronous tasks invocation

```
#include <future>
#include <iostream>

int main() {
    std::future<int> r = std::async(task, 1, 10);
    other_task();
    std::cout << "Result= " << r.get() << std::endl;
    return 0;
}
```

# Using futures

## ■ General idea:

- When a thread needs to pass a value to another thread it sets the value into a **promise**.
- Implementation takes care that the value is available in the corresponding **future**.

## ■ Access to the **future** through **f.get()**:

- If a value has been assigned → it gets that value.
- In other case → calling thread blocks until it is available.
- Allows to transparently transfer exceptions among threads.



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# Class `thread`

- Abstraction of a *thread* represented through class **thread**.
- One-to-one correspondence with operating system thread.
- All threads in an application run in the same address space.
- Each thread has its own stack.
- **Dangers:**
  - Pass a pointer or a non-const reference to another thread.
  - Pass a reference through capture in lambda expressions.
- **thread** represents a link to a system thread.
  - Cannot be copied.
  - They can be moved.

# Thread construction

- A thread is constructed from a function and arguments that must be passed to that function.
  - Template with variable number of arguments.
  - Type safe.

## Example

```
void f();  
void g(int, double);  
  
thread t1{f}; // OK  
thread t2{f, 1}; // Error: Too many arguments  
  
thread t3{g, 1, 0.5}; // OK  
thread t4{g}; // Error: Missing arguments  
thread t5{g, 1, "Hello"}; // Error: Wrong types
```

# Construction and references

- Constructor of **thread** is a template with variable number of arguments.

```
template <class F, class ...Args>  
explicit thread(F&& f, Args&&... args);
```

- Arguments passing to a thread is by value.
- To force passing by reference:
  - Use a helper function for **reference\_wrapper**.
  - Use lambdas and reference captures.

```
void f(record & r);  
  
void g(record & s) {  
    thread t1{f,s}; // Error if f takes a reference  
    thread t2{f, ref(s)}; // OK. Reference to s  
    thread t3{[&] { f(s); }}; // Reference to s  
}
```

# Two-phase construction

- Construction includes thread launching.
  - There is no separate operation to *start* execution.

## Producer/Consumer

```
struct producer {  
    producer(queue<request> & q);  
    void operator()();  
    // ...  
};  
  
struct consumer {  
    consumer(queue<request> & q);  
    void operator()();  
    // ...  
};
```

## Stages

```
void f() {  
    // Stage 1: Construction  
    queue<request> q;  
    producer prod{q};  
    consumer cons{q};  
  
    // Stage 2: Launching  
    thread tp{prod};  
    thread tc{cons};  
  
    // ...  
}
```

# Empty thread

- Default constructor creates a thread without associated execution task.

```
thread() noexcept;
```

- Useful in combination with move constructor.

```
thread(thread &&) noexcept;
```

- An execution takes can be moved from a thread to another thread.

- Original thread remains without associated execution task.

```
thread create_task();  
thread t1 = create_task();  
thread t2 = move(t1); // t1 is empty now
```

# Thread identity

- Each thread has a unique identifier.
  - Type: `thread::id`.
  - If the `thread` is not associated with a thread `get_id()` returns `id{}`.
  - Current thread identifier is obtained with `this_thread::get_id()`.
  
- `t.get_id()` returns `id{}` if:
  - An execution task has not been assigned to it.
  - It has finished.
  - Task has been moved to another `thread`.
  - It has been detached (`detach()`).

# Operations on `thread::id`

- Is an implementation dependent type, but it must allow:
  - Copying.
  - Comparison operators (`==`, `<`, ...).
  - Output to streams through operator `<<`.
  - *hash* transformation through specialization `hash<thread::id>`.

## Example

```
void print_id(thread & t) {  
    if (t.get_id() == id{})  
        cout << "Invalid thread" << endl;  
    else {  
        cout << "Current thread: " << this_thread::get_id() << endl;  
        cout << "Received thread: " << t.get_id() << endl;  
    }  
}
```



# Joining

- When a thread wants to wait for other thread termination, it may use operation **join()**.
  - **t.join()** → waits until **t** has finished.

## Example

```
void f() {  
    vector<thread> vt;  
    for (int i=0; i< 8; ++i) {  
        vt.push_back(thread(f,i));  
    }  
  
    for (auto &t : vt) { // Waits until all threads have finished  
        t.join();  
    }  
}
```

# Periodic tasks

## Initial idea

```
void update_bar() {  
    while (!task_has_finished()) {  
        this_thread::sleep_for(chrono::seconds(1))  
        update_progress();  
    }  
}  
  
void f() {  
    thread t{update_bar};  
    t.join();  
}
```

## ■ Problems?

# What if I forget `join`?

- When scope where thread was defined is exited, its destructor is invoked.
- **Problem:**
  - Link with operating system thread might be lost.
  - System thread goes on running but cannot be accessed.
- If `join()` was not called, destructor invokes `terminate()`.

## Example

```
void update() {  
    for (;;) {  
        show_clock(steady_clock::now());  
        this_thread::sleep_for(second{1});  
    }  
}  
  
void f() {  
    thread t{update};  
}
```

- `terminate()` is called when exiting `f()`.

# Destruction

- **Goal:** Avoid a thread to survive its **thread** object.
- **Solution:** If a **thread** is *joinable* its destructor invokes **terminate()**.
  - A **thread** is joinable if it is linked to a system thread.

## Example

```
void check() {  
    for (;;) {  
        check_state();  
        this_thread::sleep_for(second{10});  
    }  
}  
  
void f() {  
    thread t{check};  
} // Destruction without join() -> Invokes terminate()
```

# Problems with destruction

## Example

```
void f();  
void g();  
  
void example() {  
    thread t1{f}; // Thread running task f  
    thread t2; // Empty thread  
  
    if (mode == mode1) {  
        thread tg {g};  
        // ...  
        t2 = move(tg); // tg empty, t2 running g()  
    }  
  
    vector<int> v{10000}; // Might throw exceptions  
    t1.join();  
    t2.join();  
}
```

- What if constructor of **v** throws an exception?
- What if end of example is reached with **mode==mode1**?

# Automatic thread

- RAII pattern can be used.
  - Resource Acquisition Is Initialization.

## A joining thread

```
struct auto_thread : thread {  
    using thread::thread; // All thread constructors  
    ~auto_thread() {  
        if (joinable()) join();  
    }  
};
```

- Constructor acquires resource.
- Destructor releases resource.
- Avoids resource leakage.

# Simplifying with RAI

- Simpler code and higher safety.

## Example

```
void example() {  
    auto_thread t1{f}; // Thread running task f  
    auto_thread t2; // Empty thread  
  
    if (modo == mode1) {  
        auto_thread tg {g};  
        // ...  
        t2 = move(tg); // tg empty, t2 running g()  
    }  
  
    vector<int> v{10000}; // Might throw exceptions  
}
```

# Detached threads

- A thread can be specified to go on running after destructor, with **detach()**.
- Useful for task running as daemons.

## Example

```
void update() {  
    for (;;) {  
        show_clock(steady_clock::now());  
        this_thread::sleep_for(second{1});  
    }  
}  
  
void f() {  
    thread t{update};  
    t.detach();  
}
```



# Problems with detached threads

## ■ Drawbacks:

- Control of active threads is lost.
- Uncertain whether the result generated by a thread can be used.
- Uncertain whether a thread has released its resources.
- Access to objects that might have already been destroyed.

## ■ Recommendations:

- Avoid using detached threads.
- Move threads to other scope (via return value).
- Move threads to a container in a larger scope.

# A hard to catch bug

- **Problem:** Access to local variables from a detached thread after destruction.

## Example

```
void g() {  
    double x = 0;  
    thread t{[&x]{ f1(); x = f2(); }}; // If g has finished -> Problem  
    t.detach();  
}
```

# Operations on current thread

- Operations on current thread as global functions in name subspace **`this_thread`**.
  - **`get_id()`**: Gets identifier from current thread.
  - **`yield()`**: Allows potential selection of another thread for execution.
  - **`sleep_until(t)`**: Wait until a certain point in time.
  - **`sleep_for(d)`**: Wait for a given duration of time.
- Timed waits:
  - If clock can be modified, **`wait_until()`** is affected.
  - If clock can be modified, **`wait_for()`** is **not** affected.

# Thread local variables

- Alternative to **static** as storage specifier: **thread\_local**.
  - A variable **static** has a single shared copy for all threads.
  - A variable **thread\_local** has a per thread copy.
- Lifetime: *thread storage duration*.
  - Starts before its first usage in thread.
  - Destroyed upon thread exit.
- Reasons to use thread local storage:
  - Transform data from static storage to thread local storage.
  - Keep data caches to be thread local (exclusive access).
    - Important in machines with separate caches and coherence protocols.

## A function with computation caching

```
thread_local map<int, int> cache;

int compute_key(int x) {
    auto i = cache.find(x);
    if (i != cache.end()) return i->second;
    return cache[arg] = slow_and_complex_algorithm(arg);
}

vector<int> generate_list(vector<int> v) {
    vector<int> r;
    for (auto x : v) {
        r.push_back(compute_key(x));
    }
}
```

- Avoids need for synchronization.
- Some computations might be repeated in multiple threads.

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## 4 Mutex objects and condition variables

- Mutex objects

- Condition variables

# *mutex* classification

- Represent exclusive access to a resource.
  - **mutex**: Basic non-recursive *mutex*.
  - **recursive\_mutex**: A *mutex* that can be acquired more than once from the same thread.
  - **timed\_mutex**: Non-recursive *mutex* with timed operations.
  - **recursive\_timed\_mutex**: Recursive *mutex* with timed operations.
- Only a thread can own a *mutex* at a given time.
  - Acquire a *mutex* → Get exclusive access to object.
    - Blocking operation.
  - Release a *mutex* → Release exclusive access to object.
    - Allows another thread to get access.



# Operations

- Construction and destruction:
  - Can be default constructed.
  - Cannot be neither copied nor moved.
  - Destructor may lead to undefined behavior if *mutex* is not free.
- Acquire and release:
  - **m.lock()**: Acquires *mutex* in a blocking mode.
  - **m.unlock()**: Releases *mutex*.
  - **r = m.try\_lock()**: Tries to acquire *mutex*, returning success indication.
- Others:
  - **h = m.native\_handle()**: Returns platform dependent identifier of type **native\_handle\_type**.

# Example

## Exclusive access

```
mutex mutex_output;
```

```
void print(int x) {  
    mutex_output.lock();  
    cout << x << endl;  
    mutex_output.unlock();  
}
```

```
void print(double x) {  
    mutex_output.lock();  
    cout << x << endl;  
    mutex_output.unlock();  
}
```

## Threads launch

```
void f() {  
    thread t1{ print , 10};  
    thread t2{ print , 5.5};  
    thread t3{ print , 3};  
  
    t1.join();  
    t2.join();  
    t3.join();  
}
```

# Errors in mutual exclusion

- In case of error exception **system\_error** is thrown.
- Error codes:
  - **resource\_deadlock\_would\_occur.**
  - **resource\_unavailable\_try\_again.**
  - **operation\_not\_permitted.**
  - **device\_or\_resource\_busy.**
  - **invalid\_argument.**

```
mutex m;  
try {  
    m.lock();  
    //  
    m.lock();  
}  
catch (system_error & e) {  
    cerr << e.what() << endl;  
    cerr << e.code() << endl;  
}
```

# Deadlines

- Operations supported by **timed\_mutex** and **recursive\_timed\_mutex**.
- Add acquire operations with indication of deadlines.
  - **`r = m.try_lock_for(d)`**: Try to acquire *mutex* for a duration **d**, returning success indication.
  - **`r = m.try_lock_until(t)`**: Try to acquire *mutex* until a point in time returning success indication.

## 4 Mutex objects and condition variables

- Mutex objects

- Condition variables

# Condition variables

- Synchronizing operations among threads.
- Optimized for class **mutex** (alternative **condition\_variable\_any**)).
- Construction and destruction:
  - **condition\_variable c{}**: Creates a condition variable
    - Might throw **system\_error**.
  - Destructor: Destroys condition variable.
    - Requires no thread is waiting on condition.
  - Cannot be neither copied nor moved.
  - Before destruction all threads blocked in variable need to be notified.
    - Or they could be blocked forever.

# Notification/waiting operations

- Notification:
  - **c.notify\_one()**: Wakes up one of waiting threads.
  - **c.notify\_all()**: Wakes up all waiting threads.
- Unconditional waiting (**l** of type **unique\_lock<mutex>**):
  - **c.wait(l)**: Blocks until it gets to acquire lock **l**.
  - **c.wait\_until(l,t)**: Blocks until it gets to acquire lock **l** or time **t** is reached.
  - **c.wait\_for(l,t)**: Blocks until it gets to acquire lock **l** or duration **d** elapses.
- Waiting with predicates.
  - Takes as additional arguments a predicate that must be satisfied.

# Revisiting producer/consumer

## Predicate injection in wait

```
void consumer() {  
    for (;;) {  
        unique_lock<mutex> l{m};  
  
        cv.wait(l, [this]{ return !q.empty();});  
  
        auto r = q.front();  
        q.pop();  
        l.unlock();  
  
        process(r);  
    };  
}
```





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# Summary

- C++ offers a concurrency model through a combination of language and library.
- Class **thread** abstracts an OS thread.
- Synchronization through a combination of **mutex** and **condition\_variable**.
- **std::async** offers a high-level mechanism to run threads.
- **std::future** allows result and exceptions transfer among threads.
- **thread\_local** offer portable support for thread local storage.

# References

- *C++ Concurrency in Action. Practical multithreading.*  
Anthony Williams.  
Chapters 2, 3, and 4.

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## Computer Architecture

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