

Invariant Surfaces in \mathbb{S}^3 Based on Generalized Elastic Curves

Álvaro Pámpano Llarena

*63rd Texas Geometry and Topology Conference
(Texas Tech University)*

Lubbock, April 24-26 (2020)

Historical Background: Elastic Curves in \mathbb{R}^2

Historical Background: Elastic Curves in \mathbb{R}^2

- 1691: J. Bernoulli.

Proposed the problem of determining the **shape** of **elastic rods** (**bending deformations** of rods).

Historical Background: Elastic Curves in \mathbb{R}^2

- **1691: J. Bernoulli.**

Proposed the problem of determining the **shape** of elastic rods
(**bending deformations** of rods).

- **1742: D. Bernoulli.**

In a letter to L. Euler suggested to study **elasticae** as
minimizers (**critical points**) of the **bending energy**.

Historical Background: Elastic Curves in \mathbb{R}^2

- **1691: J. Bernoulli.**

Proposed the problem of determining the **shape** of **elastic rods** (**bending deformations** of rods).

- **1742: D. Bernoulli.**

In a letter to L. Euler suggested to study **elasticae** as **minimizers** (**critical points**) of the **bending energy**.

In modern terminology:

$$\mathcal{E}(\gamma) := \int_{\gamma} \kappa^2 \, ds .$$

Historical Background: Elastic Curves in \mathbb{R}^2

- **1691: J. Bernoulli.**

Proposed the problem of determining the **shape** of **elastic rods** (**bending deformations** of rods).

- **1742: D. Bernoulli.**

In a letter to L. Euler suggested to study **elasticae** as **minimizers** (**critical points**) of the **bending energy**.

In modern terminology:

$$\mathcal{E}(\gamma) := \int_{\gamma} \kappa^2 \, ds .$$

- **1744: L. Euler.**

Described the shape of **planar elasticae** (with **constraint** on the length).

Partially solved by J. Bernoulli, 1692-1694.

Historical Background: Elastic Curves in \mathbb{S}^2

Historical Background: Elastic Curves in \mathbb{S}^2

- 1986: R. Bryant & P. Griffiths.

Extended the notion of *elasticae* to Riemannian manifolds
(different approach).

Historical Background: Elastic Curves in \mathbb{S}^2

- **1986: R. Bryant & P. Griffiths.**

Extended the notion of **elasticae** to Riemannian manifolds
(different approach).

- **1987: J. Langer & D. A. Singer.**

Consider **elasticae** in Riemannian manifolds (in particular, in
the **2-sphere $\mathbb{S}^2(\rho)$**).

We follow here this approach.

Historical Background: Elastic Curves in \mathbb{S}^2

- 1986: R. Bryant & P. Griffiths.

Extended the notion of *elasticae* to Riemannian manifolds (different approach).

- 1987: J. Langer & D. A. Singer.

Consider *elasticae* in Riemannian manifolds (in particular, in the **2-sphere** $\mathbb{S}^2(\rho)$).

We follow here this approach.

1985: U. Pinkall

Link between **Willmore** surfaces and *elastica*.

Scheme

Scheme

1. Part I. Generalized Elastic Curves

Scheme

1. **Part I.** Generalized Elastic Curves
2. **Part II.** Binormal Evolution

Scheme

1. **Part I.** Generalized Elastic Curves
2. **Part II.** Binormal Evolution
3. **Part III.** Vertical Lifts

Part I

Generalized Elastic Curves

Generalized Elastic Curves

Generalized Elastic Curves

For **fixed** real constants $\mu, p \in \mathbb{R}$, we consider the biparametric family of **curvature energy functionals**

$$\Theta(\gamma) \equiv \Theta_{\mu,p}(\gamma) := \int_{\gamma} (\kappa - \mu)^p = \int_0^L (\kappa(s) - \mu)^p ds .$$

Generalized Elastic Curves

For **fixed** real constants $\mu, p \in \mathbb{R}$, we consider the biparametric family of **curvature energy functionals**

$$\Theta(\gamma) \equiv \Theta_{\mu,p}(\gamma) := \int_{\gamma} (\kappa - \mu)^p = \int_0^L (\kappa(s) - \mu)^p ds.$$

- We assume that Θ acts on the space of **smooth immersed curves** of $\mathbb{S}^2(\rho)$ joining two points of it, $\Omega_{p_0 p_1}$, verifying $\kappa - \mu > 0$ (when necessary).

Generalized Elastic Curves

For **fixed** real constants $\mu, p \in \mathbb{R}$, we consider the biparametric family of **curvature energy functionals**

$$\Theta(\gamma) \equiv \Theta_{\mu,p}(\gamma) := \int_{\gamma} (\kappa - \mu)^p = \int_0^L (\kappa(s) - \mu)^p ds.$$

- We assume that Θ acts on the space of **smooth immersed curves** of $\mathbb{S}^2(\rho)$ joining two points of it, $\Omega_{p_0 p_1}$, verifying $\kappa - \mu > 0$ (when necessary).
- We are mainly interested on the space of **closed curves**.

Classical Energies

The biparametric family of functionals

$$\Theta_{\mu,p}(\gamma) = \int_{\gamma} (\kappa - \mu)^p \, ds$$

includes the following [classical energies](#):

Classical Energies

The biparametric family of functionals

$$\Theta_{\mu,p}(\gamma) = \int_{\gamma} (\kappa - \mu)^p \, ds$$

includes the following **classical energies**:

- If $p = 0$, Θ is nothing but the **length functional**.

Classical Energies

The biparametric family of functionals

$$\Theta_{\mu,p}(\gamma) = \int_{\gamma} (\kappa - \mu)^p \, ds$$

includes the following classical energies:

- If $p = 0$, Θ is nothing but the length functional.
- If $p = 1$ and $\mu = 0$, we get the total curvature functional.

Classical Energies

The biparametric family of functionals

$$\Theta_{\mu,p}(\gamma) = \int_{\gamma} (\kappa - \mu)^p \, ds$$

includes the following classical energies:

- If $p = 0$, Θ is nothing but the length functional.
- If $p = 1$ and $\mu = 0$, we get the total curvature functional.
- If $p = 2$ and $\mu = 0$, we recover the classical bending energy.

Classical Energies

The biparametric family of functionals

$$\Theta_{\mu,p}(\gamma) = \int_{\gamma} (\kappa - \mu)^p \, ds$$

includes the following **classical energies**:

- If $p = 0$, Θ is nothing but the **length functional**.
- If $p = 1$ and $\mu = 0$, we get the **total curvature functional**.
- If $p = 2$ and $\mu = 0$, we recover the classical **bending energy**.
- If $p = 2$ and $\mu \neq 0$, Θ is the **bending energy** (circular at rest).

Classical Energies

The biparametric family of functionals

$$\Theta_{\mu,p}(\gamma) = \int_{\gamma} (\kappa - \mu)^p \, ds$$

includes the following classical energies:

- If $p = 0$, Θ is nothing but the length functional.
- If $p = 1$ and $\mu = 0$, we get the total curvature functional.
- If $p = 2$ and $\mu = 0$, we recover the classical bending energy.
- If $p = 2$ and $\mu \neq 0$, Θ is the bending energy (circular at rest).
- If $p = 1/2$, we obtain an extension of an energy studied by Blaschke in 1930.

Variational Problem

Variational Problem

For simplicity we denote $P(\kappa) := (\kappa - \mu)^P$. Then,

Euler-Lagrange Equation

Regardless of the boundary conditions, a **critical curve** γ in $\mathbb{S}^2(\rho)$ satisfies

$$\dot{P}_{ss} + \dot{P} (\kappa^2 + \rho) - \kappa P = 0. \quad \left(\dot{P} \equiv \frac{dP}{d\kappa} \right)$$

Variational Problem

For simplicity we denote $P(\kappa) := (\kappa - \mu)^P$. Then,

Euler-Lagrange Equation

Regardless of the boundary conditions, a **critical curve** γ in $\mathbb{S}^2(\rho)$ satisfies

$$\dot{P}_{ss} + \dot{P} (\kappa^2 + \rho) - \kappa P = 0. \quad \left(\dot{P} \equiv \frac{dP}{d\kappa} \right)$$

Vector Fields Along Critical Curves

Consider $\mathbb{S}^2(\rho)$ embedded as a **totally geodesic** surface of $\mathbb{S}^3(\rho)$. Then, we have

$$\mathcal{J} = (\kappa \dot{P} - P) T + \dot{P}_s N, \quad \mathcal{I} = \dot{P} B$$

where $\{T, N, B\}$ denotes the **Frenet frame** of γ in $\mathbb{S}^3(\rho)$.

Parametrization of Critical Curves

Parametrization of Critical Curves

1. If $\kappa(s) = \kappa_o$ is constant, the critical curve is a circle.

Parametrization of Critical Curves

1. If $\kappa(s) = \kappa_o$ is constant, the critical curve is a **circle**.
2. If $\kappa(s)$ is not constant, then: **first integral** of the Euler-Lagrange equation

$$\langle \mathcal{J}, \mathcal{J} \rangle + \rho \langle \mathcal{I}, \mathcal{I} \rangle = d > 0.$$

Parametrization of Critical Curves

1. If $\kappa(s) = \kappa_o$ is constant, the critical curve is a circle.
2. If $\kappa(s)$ is not constant, then: first integral of the Euler-Lagrange equation

$$\langle \mathcal{J}, \mathcal{J} \rangle + \rho \langle \mathcal{I}, \mathcal{I} \rangle = d > 0.$$

3. In this case, using spherical coordinates in $\mathbb{S}^2(\rho) \subset \mathbb{R}^3$, we get the following parametrization of the critical curves:

$$\gamma(s) = \frac{1}{\sqrt{\rho d}} \left(\sqrt{\rho} \dot{P}, \sqrt{d - \rho \dot{P}^2} \sin \Psi(s), \sqrt{d - \rho \dot{P}^2} \cos \Psi(s) \right)$$

where

$$\Psi(s) = \sqrt{\rho d} \int \frac{\kappa \dot{P} - P}{d - \rho \dot{P}^2} ds.$$

Closure Condition

Let $\gamma(s)$ be a critical curve with non-constant curvature $\kappa(s)$.

Closure Condition

Let $\gamma(s)$ be a critical curve with non-constant curvature $\kappa(s)$.

- A necessary, but not sufficient, condition for γ to close up is that the curvature $\kappa(s)$ is periodic.

Closure Condition

Let $\gamma(s)$ be a critical curve with non-constant curvature $\kappa(s)$.

- A necessary, but not sufficient, condition for γ to close up is that the curvature $\kappa(s)$ is periodic.
- Assume $\kappa(s)$ is periodic (of period ϱ). Then,

Closure Condition

The critical curve $\gamma(s)$ in $\mathbb{S}^2(\rho)$ is closed, if and only if,

$$\Lambda(d) = \sqrt{\rho d} \int_0^\varrho \frac{\kappa \dot{P} - P}{d - \rho \dot{P}^2} ds = 2 \frac{n}{m} \pi,$$

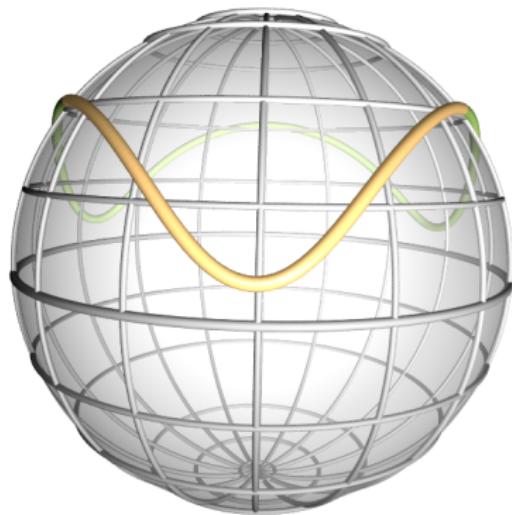
for any integers n and m .

Geometric Description (1)

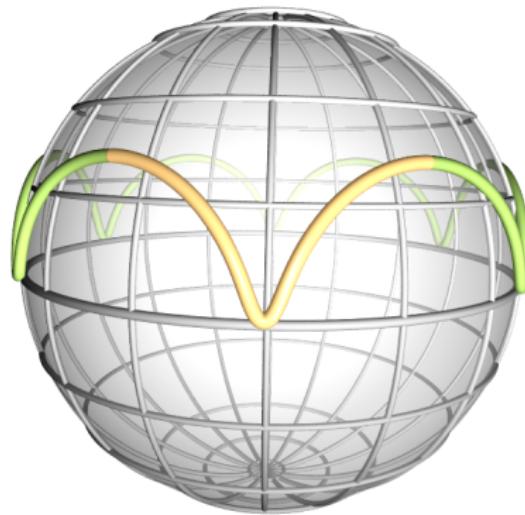
We fix $p = 1/2$ (i.e. the extended Blaschke's curvature energy).

Geometric Description (1)

We fix $p = 1/2$ (i.e. the extended Blaschke's curvature energy).

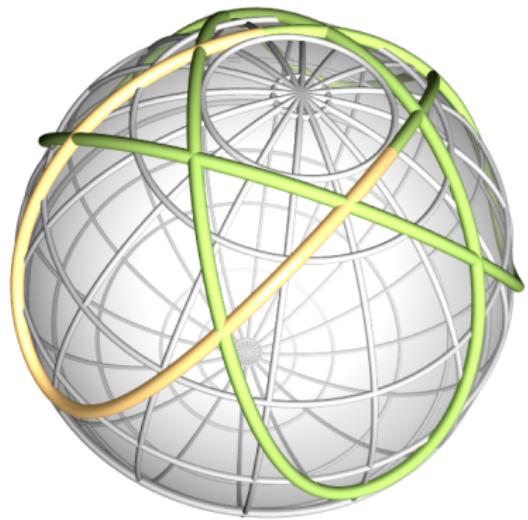


(c) $\mu = -1$



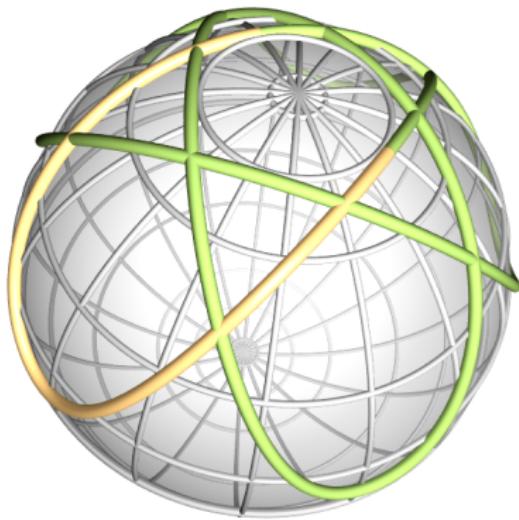
(d) $\mu = -2$

Geometric Description (2)

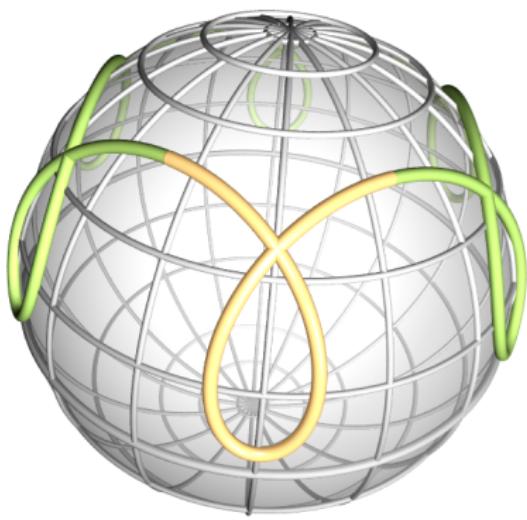


(E) $\mu = -0.1$

Geometric Description (2)



(G) $\mu = -0.1$



(H) $\mu = 1$

Geometric Description (3)



Geometric Description (3)



- They **never cut** the axis $x_1 = 0$ (the **equator**), since $\dot{P} = \frac{1}{2\sqrt{\kappa-\mu}} > 0$.

Part II

Binormal Evolution

Killing Vector Fields

A vector field W along γ , which infinitesimally preserves unit speed parametrization is said to be a Killing vector field along γ if it evolves in the direction of W without changing shape, only position. That is, the following equations hold

$$W(v) = W(\kappa) = 0$$

along γ . (Langer & Singer, 1984)

Killing Vector Fields

A vector field W along γ , which infinitesimally preserves unit speed parametrization is said to be a Killing vector field along γ if it evolves in the direction of W without changing shape, only position. That is, the following equations hold

$$W(v) = W(\kappa) = 0$$

along γ . (Langer & Singer, 1984)

Proposition (Langer & Singer, 1984)

The vector fields \mathcal{I} and \mathcal{J} are Killing vector fields along critical curves.

(We are mainly interested in \mathcal{I} .)

Killing Vector Fields

A vector field W along γ , which infinitesimally preserves unit speed parametrization is said to be a Killing vector field along γ if it evolves in the direction of W without changing shape, only position. That is, the following equations hold

$$W(v) = W(\kappa) = 0$$

along γ . (Langer & Singer, 1984)

Proposition (Langer & Singer, 1984)

The vector fields \mathcal{I} and \mathcal{J} are Killing vector fields along critical curves.

(We are mainly interested in \mathcal{I} .)

- Killing vector fields along γ can be extended to Killing vector fields on the whole $\mathbb{S}^3(\rho)$. The extension is unique.

Binormal Evolution Surfaces

Let $\gamma(s) \subset \mathbb{S}^2(\rho)$ be any generalized elastic curve. (We consider $\mathbb{S}^2(\rho) \subset \mathbb{S}^3(\rho)$ and γ being planar, i.e. $\tau = 0$.)

Binormal Evolution Surfaces

Let $\gamma(s) \subset \mathbb{S}^2(\rho)$ be any **generalized elastic curve**. (We consider $\mathbb{S}^2(\rho) \subset \mathbb{S}^3(\rho)$ and γ being **planar**, i.e. $\tau = 0$.)

1. Consider the **Killing vector field along γ** in the direction of the **(constant)** binormal vector field:

$$\mathcal{I} = \dot{P}(\kappa)B. \quad (P(\kappa) := (\kappa - \mu)^p)$$

Binormal Evolution Surfaces

Let $\gamma(s) \subset \mathbb{S}^2(\rho)$ be any generalized elastic curve. (We consider $\mathbb{S}^2(\rho) \subset \mathbb{S}^3(\rho)$ and γ being planar, i.e. $\tau = 0$.)

1. Consider the Killing vector field along γ in the direction of the (constant) binormal vector field:

$$\mathcal{I} = \dot{P}(\kappa)B. \quad (P(\kappa) := (\kappa - \mu)^p)$$

2. Let's denote by ξ the (unique) extension to a Killing vector field of $\mathbb{S}^3(\rho)$. (It can be assumed to be: $\xi = \lambda_1 X_1 + \lambda_2 X_2$.)

Binormal Evolution Surfaces

Let $\gamma(s) \subset \mathbb{S}^2(\rho)$ be any generalized elastic curve. (We consider $\mathbb{S}^2(\rho) \subset \mathbb{S}^3(\rho)$ and γ being planar, i.e. $\tau = 0$.)

1. Consider the Killing vector field along γ in the direction of the (constant) binormal vector field:

$$\mathcal{I} = \dot{P}(\kappa)B. \quad (P(\kappa) := (\kappa - \mu)^p)$$

2. Let's denote by ξ the (unique) extension to a Killing vector field of $\mathbb{S}^3(\rho)$. (It can be assumed to be: $\xi = \lambda_1 X_1 + \lambda_2 X_2$.)
3. Since $\mathbb{S}^3(\rho)$ is complete, the one-parameter group of isometries determined by ξ is $\{\phi_t, t \in \mathbb{R}\}$.

Binormal Evolution Surfaces

Let $\gamma(s) \subset \mathbb{S}^2(\rho)$ be any generalized elastic curve. (We consider $\mathbb{S}^2(\rho) \subset \mathbb{S}^3(\rho)$ and γ being planar, i.e. $\tau = 0$.)

1. Consider the Killing vector field along γ in the direction of the (constant) binormal vector field:

$$\mathcal{I} = \dot{P}(\kappa)B. \quad (P(\kappa) := (\kappa - \mu)^p)$$

2. Let's denote by ξ the (unique) extension to a Killing vector field of $\mathbb{S}^3(\rho)$. (It can be assumed to be: $\xi = \lambda_1 X_1 + \lambda_2 X_2$.)
3. Since $\mathbb{S}^3(\rho)$ is complete, the one-parameter group of isometries determined by ξ is $\{\phi_t, t \in \mathbb{R}\}$.
4. We construct the binormal evolution surface (Garay & —, 2016)

$$S_\gamma := \{x(s, t) := \phi_t(\gamma(s))\}.$$

Geometric Properties

Geometric Properties

By construction S_γ is a ξ -invariant surface.

Geometric Properties

By construction S_γ is a ξ -invariant surface. Moreover, it verifies:

- Since $\gamma(s) \subset \mathbb{S}^2(\rho)$ (γ is planar),

Geometric Properties

By construction S_γ is a ξ -invariant surface. Moreover, it verifies:

- Since $\gamma(s) \subset \mathbb{S}^2(\rho)$ (γ is planar),

Theorem (Arroyo, Garay & —, 2017)

The binormal evolution surface S_γ is either a flat isoparametric surface (when $\kappa(s) = \kappa_o$ is constant); or, it is a rotational surface (when $\kappa(s)$ is not constant).

Geometric Properties

By construction S_γ is a ξ -invariant surface. Moreover, it verifies:

- Since $\gamma(s) \subset \mathbb{S}^2(\rho)$ (γ is planar),

Theorem (Arroyo, Garay & —, 2017)

The binormal evolution surface S_γ is either a flat isoparametric surface (when $\kappa(s) = \kappa_o$ is constant); or, it is a rotational surface (when $\kappa(s)$ is not constant).

- Since $\gamma(s)$ is a generalized elastic curve,

Geometric Properties

By construction S_γ is a ξ -invariant surface. Moreover, it verifies:

- Since $\gamma(s) \subset \mathbb{S}^2(\rho)$ (γ is planar),

Theorem (Arroyo, Garay & —, 2017)

The binormal evolution surface S_γ is either a flat isoparametric surface (when $\kappa(s) = \kappa_o$ is constant); or, it is a rotational surface (when $\kappa(s)$ is not constant).

- Since $\gamma(s)$ is a generalized elastic curve,

Theorem (—, 2018)

The binormal evolution surface S_γ is a linear Weingarten surface.

It verifies:

$$\kappa_1 = a\kappa_2 + b, \quad (\kappa_i \text{ principal curvatures})$$

for $a = p/(p - 1)$ and $b = -\mu/(p - 1)$.

Weingarten Surfaces

A Weingarten surface in $\mathbb{S}^3(\rho)$ is a surface where the two principal curvatures (κ_1 and κ_2) satisfy a certain relation $\Phi(\kappa_1, \kappa_2) = 0$.

Weingarten Surfaces

A Weingarten surface in $\mathbb{S}^3(\rho)$ is a surface where the two principal curvatures (κ_1 and κ_2) satisfy a certain relation $\Phi(\kappa_1, \kappa_2) = 0$. Here, we consider the linear relation

$$\kappa_1 = a\kappa_2 + b$$

where $a, b \in \mathbb{R}$ and $a \neq 0$.

Weingarten Surfaces

A Weingarten surface in $\mathbb{S}^3(\rho)$ is a surface where the two principal curvatures (κ_1 and κ_2) satisfy a certain relation $\Phi(\kappa_1, \kappa_2) = 0$. Here, we consider the linear relation

$$\kappa_1 = a\kappa_2 + b$$

where $a, b \in \mathbb{R}$ and $a \neq 0$.

Well known families of linear Weingarten surfaces are:

- Totally Umbilical Surfaces (Spheres \mathbb{S}^2)

Weingarten Surfaces

A Weingarten surface in $\mathbb{S}^3(\rho)$ is a surface where the two principal curvatures (κ_1 and κ_2) satisfy a certain relation $\Phi(\kappa_1, \kappa_2) = 0$. Here, we consider the linear relation

$$\kappa_1 = a\kappa_2 + b$$

where $a, b \in \mathbb{R}$ and $a \neq 0$.

Well known families of linear Weingarten surfaces are:

- Totally Umbilical Surfaces (Spheres \mathbb{S}^2)
- Isoparametric Surfaces (Tori $\mathbb{S}^1 \times \mathbb{S}^1$)

Weingarten Surfaces

A Weingarten surface in $\mathbb{S}^3(\rho)$ is a surface where the two principal curvatures (κ_1 and κ_2) satisfy a certain relation $\Phi(\kappa_1, \kappa_2) = 0$. Here, we consider the linear relation

$$\kappa_1 = a\kappa_2 + b$$

where $a, b \in \mathbb{R}$ and $a \neq 0$.

Well known families of linear Weingarten surfaces are:

- Totally Umbilical Surfaces (Spheres \mathbb{S}^2)
- Isoparametric Surfaces (Tori $\mathbb{S}^1 \times \mathbb{S}^1$)
- Constant Mean Curvature Surfaces
(Rotational: Delaunay Surfaces in $\mathbb{S}^3(\rho)$)

Characterization of Profile Curves

Let M be a **rotational linear Weingarten surface** of $\mathbb{S}^3(\rho)$.

Characterization of Profile Curves

Let M be a **rotational** linear Weingarten surface of $\mathbb{S}^3(\rho)$. Since it is rotational, it can be described (**locally**) as

$$M \equiv S_\gamma := \{x(s, t) = \phi_t(\gamma(s))\}$$

where

1. ϕ_t is a **rotation**, and
2. $\gamma(s)$ is the **profile curve** (everywhere orthogonal to the orbits of ϕ_t).

Characterization of Profile Curves

Let M be a **rotational linear Weingarten surface** of $\mathbb{S}^3(\rho)$. Since it is rotational, it can be described (**locally**) as

$$M \equiv S_\gamma := \{x(s, t) = \phi_t(\gamma(s))\}$$

where

1. ϕ_t is a **rotation**, and
2. $\gamma(s)$ is the **profile curve** (everywhere orthogonal to the orbits of ϕ_t).

Theorem (—, 2018)

The **profile curve** γ of a rotational linear Weingarten surface of $\mathbb{S}^3(\rho)$ (for $a \neq 1$) is a **planar** ($\gamma(s) \subset \mathbb{S}^2(\rho)$) **generalized elastic curve** for $\mu = -b/(a-1)$ and $p = a/(a-1)$.

Characterization of Profile Curves

Let M be a **rotational linear Weingarten surface** of $\mathbb{S}^3(\rho)$. Since it is rotational, it can be described (**locally**) as

$$M \equiv S_\gamma := \{x(s, t) = \phi_t(\gamma(s))\}$$

where

1. ϕ_t is a **rotation**, and
2. $\gamma(s)$ is the **profile curve** (everywhere orthogonal to the orbits of ϕ_t).

Theorem (—, 2018)

The **profile curve** γ of a rotational linear Weingarten surface of $\mathbb{S}^3(\rho)$ (for $a \neq 1$) is a **planar** ($\gamma(s) \subset \mathbb{S}^2(\rho)$) **generalized elastic curve** for $\mu = -b/(a-1)$ and $p = a/(a-1)$.

- The case $a = 1$; rotational surfaces with **constant skew curvature**. (López & —, 2020)

Particular Case 1: CMC

Particular Case 1: CMC

Specializing previous characterization we get

Theorem (Arroyo, Garay & —, 2018)

A **rotational** surface with **constant mean curvature** H of $\mathbb{S}^3(\rho)$ is, locally, a **binormal evolution surface** with initial condition a **generalized elastic curve** in $\mathbb{S}^2(\rho)$ for $p = 1/2$ and $\mu = -H$, i.e. for the **extended Blaschke's energy**

$$\Theta(\gamma) \equiv \Theta_{\mu,1/2}(\gamma) = \int_{\gamma} \sqrt{\kappa - \mu}$$

where $\mu = -H$.

Particular Case 1: CMC

Specializing previous characterization we get

Theorem (Arroyo, Garay & —, 2018)

A **rotational** surface with **constant mean curvature** H of $\mathbb{S}^3(\rho)$ is, locally, a **binormal evolution surface** with initial condition a **generalized elastic curve** in $\mathbb{S}^2(\rho)$ for $p = 1/2$ and $\mu = -H$, i.e. for the **extended Blaschke's energy**

$$\Theta(\gamma) \equiv \Theta_{\mu,1/2}(\gamma) = \int_{\gamma} \sqrt{\kappa - \mu}$$

where $\mu = -H$.

Basically, we need to understand these critical curves:

- If $\kappa = \mu$, we have **global minima** (acting on the space L^1).

Local Classification

Local Classification

Theorem (Arroyo, Garay & —, 2019)

Rotational surfaces with constant mean curvature H in $\mathbb{S}^3(\rho)$ are locally congruent to a piece of

Local Classification

Theorem (Arroyo, Garay & —, 2019)

Rotational surfaces with constant mean curvature H in $\mathbb{S}^3(\rho)$ are locally congruent to a piece of

1. The equator $\mathbb{S}^2(\rho)$; if $\kappa(s) = H = 0$.

Local Classification

Theorem (Arroyo, Garay & —, 2019)

Rotational surfaces with constant mean curvature H in $\mathbb{S}^3(\rho)$ are locally congruent to a piece of

1. The equator $\mathbb{S}^2(\rho)$; if $\kappa(s) = H = 0$.
2. A totally umbilical sphere; if $\kappa(s) = |H| \neq 0$.

Local Classification

Theorem (Arroyo, Garay & —, 2019)

Rotational surfaces with constant mean curvature H in $\mathbb{S}^3(\rho)$ are locally congruent to a piece of

1. The equator $\mathbb{S}^2(\rho)$; if $\kappa(s) = H = 0$.
2. A totally umbilical sphere; if $\kappa(s) = |H| \neq 0$.
3. A Hopf torus

$$\mathbb{S}^1\left(\sqrt{\rho + \kappa_o^2}\right) \times \mathbb{S}^1\left(\frac{\sqrt{\rho}}{\kappa_o}\sqrt{\rho + \kappa_o^2}\right)$$

if $\kappa(s) = \kappa_o = -|H| + \sqrt{\rho + H^2}$.

Local Classification

Theorem (Arroyo, Garay & —, 2019)

Rotational surfaces with constant mean curvature H in $\mathbb{S}^3(\rho)$ are locally congruent to a piece of

1. The equator $\mathbb{S}^2(\rho)$; if $\kappa(s) = H = 0$.
2. A totally umbilical sphere; if $\kappa(s) = |H| \neq 0$.
3. A Hopf torus

$$\mathbb{S}^1\left(\sqrt{\rho + \kappa_o^2}\right) \times \mathbb{S}^1\left(\frac{\sqrt{\rho}}{\kappa_o}\sqrt{\rho + \kappa_o^2}\right)$$

if $\kappa(s) = \kappa_o = -|H| + \sqrt{\rho + H^2}$.

4. A binormal evolution surface shaped on γ (planar critical curve of extended Blaschke's energy for $|\mu| = |H|$ with non-constant curvature).

Illustration (1)

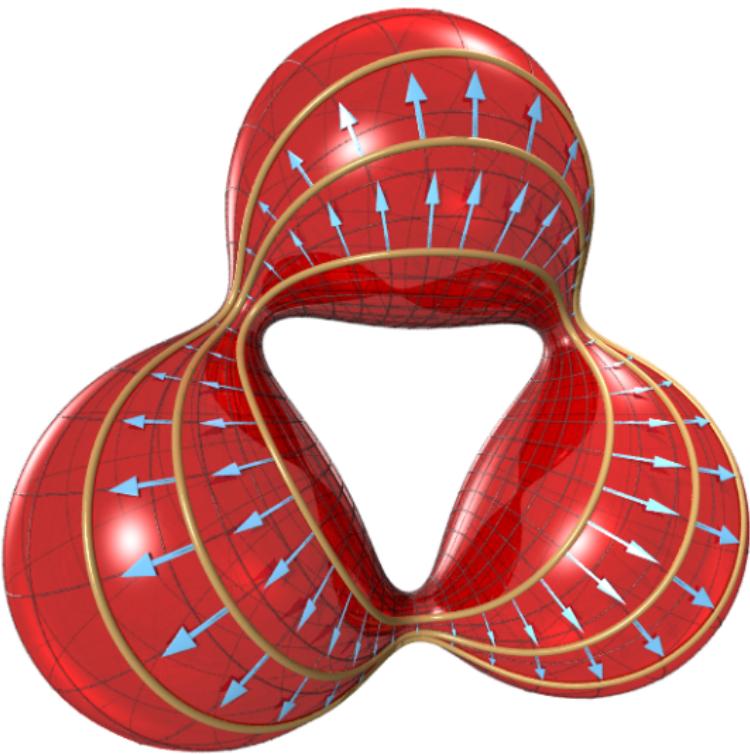
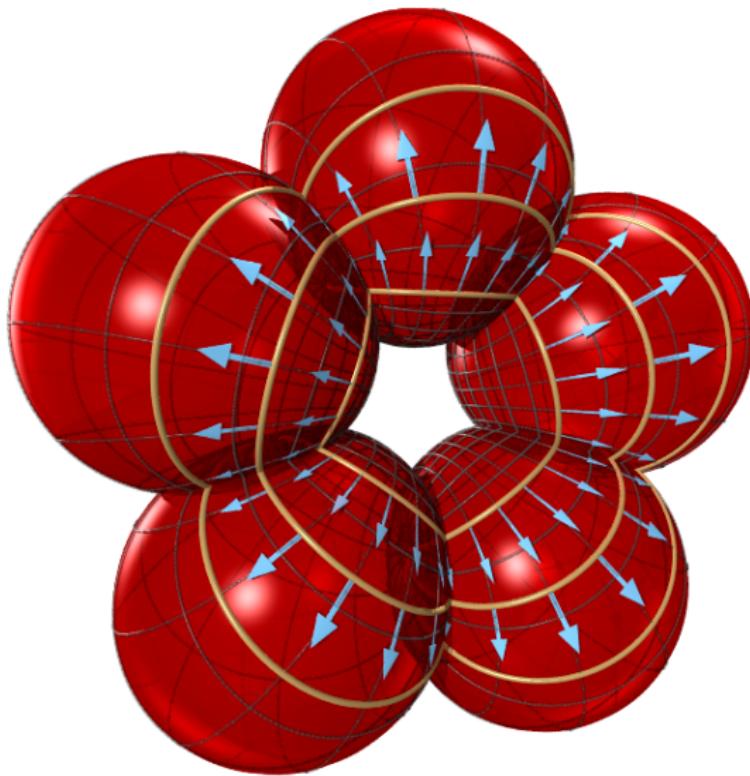


Illustration (2)



Global Results

Global Results

Binormal evolution surfaces S_γ of Point 4 depend greatly on γ (critical curves have always periodic curvature).

Global Results

Binormal evolution surfaces S_γ of Point 4 depend greatly on γ (critical curves have always periodic curvature).

1. If γ is closed, then S_γ is a torus.

Global Results

Binormal evolution surfaces S_γ of Point 4 depend greatly on γ (critical curves have always periodic curvature).

1. If γ is closed, then S_γ is a torus.

Theorem (Arroyo, Garay & —, 2019)

For any $\mu \in \mathbb{R}$, there exist closed critical curves.

Global Results

Binormal evolution surfaces S_γ of Point 4 depend greatly on γ (critical curves have always periodic curvature).

1. If γ is closed, then S_γ is a torus.

Theorem (Arroyo, Garay & —, 2019)

For any $\mu \in \mathbb{R}$, there exist closed critical curves.

2. If γ is also simple, then S_γ is an embedded torus.

Global Results

Binormal evolution surfaces S_γ of Point 4 depend greatly on γ (critical curves have always periodic curvature).

1. If γ is closed, then S_γ is a torus.

Theorem (Arroyo, Garay & —, 2019)

For any $\mu \in \mathbb{R}$, there exist closed critical curves.

2. If γ is also simple, then S_γ is an embedded torus.

Theorem (Arroyo, Garay & —, 2019)

If the closed critical curve is simple, then $\mu \neq -\sqrt{\rho/3}$ is negative.

Global Results

Binormal evolution surfaces S_γ of Point 4 depend greatly on γ (critical curves have always periodic curvature).

1. If γ is closed, then S_γ is a torus.

Theorem (Arroyo, Garay & —, 2019)

For any $\mu \in \mathbb{R}$, there exist closed critical curves.

2. If γ is also simple, then S_γ is an embedded torus.

Theorem (Arroyo, Garay & —, 2019)

If the closed critical curve is simple, then $\mu \neq -\sqrt{\rho/3}$ is negative.

- For this last theorem, we need to consider $n = 1$ in the closure condition of critical curves, which yields to an already known condition.

Embedded CMC Tori in $\mathbb{S}^3(\rho)$

Theorem (Perdomo, 2010)

For any $m > 1$ and any H such that

$$|H| \in \left(\sqrt{\rho} \cot \frac{\pi}{m}, \sqrt{\rho} \frac{m^2 - 2}{2\sqrt{m^2 - 1}} \right)$$

there exists a non-isoparametric embedded constant mean curvature rotational tori.

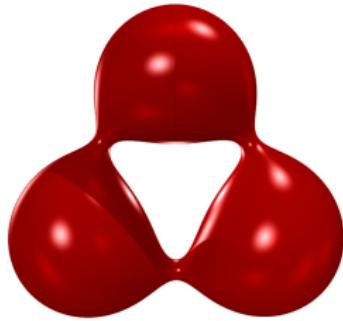
Embedded CMC Tori in $\mathbb{S}^3(\rho)$

Theorem (Perdomo, 2010)

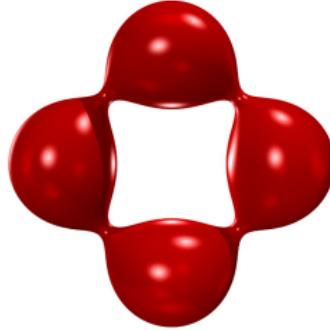
For any $m > 1$ and any H such that

$$|H| \in \left(\sqrt{\rho} \cot \frac{\pi}{m}, \sqrt{\rho} \frac{m^2 - 2}{2\sqrt{m^2 - 1}} \right)$$

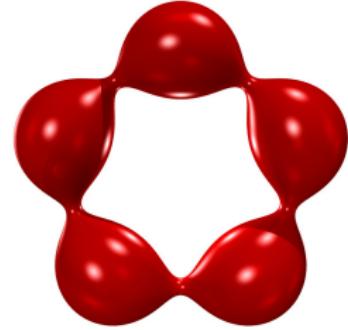
there exists a non-isoparametric embedded constant mean curvature rotational tori.



(L) $m = 3$



(M) $m = 4$



(N) $m = 5$

Relation with Famous Conjectures

Relation with Famous Conjectures

Pinkall-Sterling's Conjecture (Pinkall & Sterling, 1989)

Any constant mean curvature tori embedded in $\mathbb{S}^3(\rho)$ must be rotationally symmetric. (Recently proved in [Andrews & Li, 2015].)

Relation with Famous Conjectures

Pinkall-Sterling's Conjecture (Pinkall & Sterling, 1989)

Any constant mean curvature tori embedded in $\mathbb{S}^3(\rho)$ must be rotationally symmetric. (Recently proved in [Andrews & Li, 2015].)

- Once we fix H , for each $m > 1$, there exists at most one embedded non-isoparametric tori of constant mean curvature.

Relation with Famous Conjectures

Pinkall-Sterling's Conjecture (Pinkall & Sterling, 1989)

Any constant mean curvature tori embedded in $\mathbb{S}^3(\rho)$ must be rotationally symmetric. (Recently proved in [Andrews & Li, 2015].)

- Once we fix H , for each $m > 1$, there exists at most one embedded non-isoparametric tori of constant mean curvature.
- Ripoll's Theorem** (Ripoll, 1986). For any $H \neq 0, \pm\sqrt{\rho/3}$, there exists a non-isoparametric torus of constant mean curvature.

Relation with Famous Conjectures

Pinkall-Sterling's Conjecture (Pinkall & Sterling, 1989)

Any constant mean curvature tori embedded in $\mathbb{S}^3(\rho)$ must be rotationally symmetric. (Recently proved in [Andrews & Li, 2015].)

- Once we fix H , for each $m > 1$, there exists at most one embedded non-isoparametric tori of constant mean curvature.
- Ripoll's Theorem** (Ripoll, 1986). For any $H \neq 0, \pm\sqrt{\rho/3}$, there exists a non-isoparametric torus of constant mean curvature.
- The only minimal tori is $\mathbb{S}^1(\sqrt{2\rho}) \times \mathbb{S}^1(\sqrt{2\rho})$.

Relation with Famous Conjectures

Pinkall-Sterling's Conjecture (Pinkall & Sterling, 1989)

Any constant mean curvature tori embedded in $\mathbb{S}^3(\rho)$ must be rotationally symmetric. (Recently proved in [Andrews & Li, 2015].)

- Once we fix H , for each $m > 1$, there exists at most one embedded non-isoparametric tori of constant mean curvature.
- Ripoll's Theorem** (Ripoll, 1986). For any $H \neq 0, \pm\sqrt{\rho/3}$, there exists a non-isoparametric torus of constant mean curvature.
- The only minimal tori is $\mathbb{S}^1(\sqrt{2\rho}) \times \mathbb{S}^1(\sqrt{2\rho})$.

Lawson's Conjecture (Lawson, 1970)

The only embedded minimal tori in $\mathbb{S}^3(\rho)$ is the Clifford torus. (Recently proved in [Brendle, 2013].)

Particular Case 2: Biconservative Surfaces

Particular Case 2: Biconservative Surfaces

Here, we use the work [Caddeo, Montaldo, Oniciuc & Piu, 2014] (among others) to define them.

Definition

A surface $S \subset \mathbb{S}^3(\rho)$ is said to be **biconservative** if it satisfies

$$A_\eta(\text{grad}H) + H \text{grad}H = 0$$

where η is the unit normal to S and A_η is the shape operator.

Particular Case 2: Biconservative Surfaces

Here, we use the work [Caddeo, Montaldo, Oniciuc & Piu, 2014] (among others) to define them.

Definition

A surface $S \subset \mathbb{S}^3(\rho)$ is said to be **biconservative** if it satisfies

$$A_\eta (\text{grad}H) + H \text{grad}H = 0$$

where η is the unit normal to S and A_η is the shape operator.

Theorem (Caddeo, Montaldo, Oniciuc & Piu, 2014)

A biconservative surface of $\mathbb{S}^3(\rho)$ is either a **constant mean curvature** surface or a **rotational surface**.

Particular Case 2: Biconservative Surfaces

Here, we use the work [Caddeo, Montaldo, Oniciuc & Piu, 2014] (among others) to define them.

Definition

A surface $S \subset \mathbb{S}^3(\rho)$ is said to be **biconservative** if it satisfies

$$A_\eta(\text{grad}H) + H \text{grad}H = 0$$

where η is the unit normal to S and A_η is the shape operator.

Theorem (Caddeo, Montaldo, Oniciuc & Piu, 2014)

A biconservative surface of $\mathbb{S}^3(\rho)$ is either a constant mean curvature surface or a **rotational surface**.

- Non-CMC biconservative surfaces are **rotational linear Weingarten** surfaces for

$$3\kappa_1 + \kappa_2 = 0.$$

Characterization and Global Results

Theorem (Montaldo & —, submitted)

All non-CMC biconservative surfaces of $\mathbb{S}^3(\rho)$ are, locally, binormal evolution surfaces with the initial condition critical for

$$\Theta(\gamma) \equiv \Theta_{0,1/4}(\gamma) = \int_{\gamma} \kappa^{1/4}$$

in $\mathbb{S}^2(\rho)$.

Characterization and Global Results

Theorem (Montaldo & —, submitted)

All non-CMC biconservative surfaces of $\mathbb{S}^3(\rho)$ are, locally, binormal evolution surfaces with the initial condition critical for

$$\Theta(\gamma) \equiv \Theta_{0,1/4}(\gamma) = \int_\gamma \kappa^{1/4}$$

in $\mathbb{S}^2(\rho)$.

- All critical curves have periodic curvature.

Characterization and Global Results

Theorem (Montaldo & —, submitted)

All non-CMC biconservative surfaces of $\mathbb{S}^3(\rho)$ are, locally, binormal evolution surfaces with the initial condition critical for

$$\Theta(\gamma) \equiv \Theta_{0,1/4}(\gamma) = \int_{\gamma} \kappa^{1/4}$$

in $\mathbb{S}^2(\rho)$.

- All critical curves have periodic curvature.
- Using closure conditions, we get

Theorem (Montaldo & —, submitted)

For $m < 2n < \sqrt{2}m$, there exists a biparametric family of closed biconservative surfaces.

Characterization and Global Results

Theorem (Montaldo & —, submitted)

All non-CMC biconservative surfaces of $\mathbb{S}^3(\rho)$ are, locally, binormal evolution surfaces with the initial condition critical for

$$\Theta(\gamma) \equiv \Theta_{0,1/4}(\gamma) = \int_{\gamma} \kappa^{1/4}$$

in $\mathbb{S}^2(\rho)$.

- All critical curves have periodic curvature.
- Using closure conditions, we get

Theorem (Montaldo & —, submitted)

For $m < 2n < \sqrt{2}m$, there exists a biparametric family of closed biconservative surfaces. (None of them is embedded.)

Part III

Vertical Lifts

Hopf Tori

We denote by $\tilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho)$ the (classical) **Hopf fibration**.

Hopf Tori

We denote by $\tilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho)$ the (classical) Hopf fibration.

1. Let γ be an immersed curve in $\mathbb{S}^2(4\rho)$.

Hopf Tori

We denote by $\tilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho)$ the (classical) Hopf fibration.

1. Let γ be an immersed curve in $\mathbb{S}^2(4\rho)$.
2. The surface $\tilde{S}_\gamma := \tilde{\pi}^{-1}(\gamma)$ is an isometrically immersed surface in $\mathbb{S}^3(\rho)$.

Hopf Tori

We denote by $\tilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho)$ the (classical) Hopf fibration.

1. Let γ be an immersed curve in $\mathbb{S}^2(4\rho)$.
2. The surface $\tilde{S}_\gamma := \tilde{\pi}^{-1}(\gamma)$ is an isometrically immersed surface in $\mathbb{S}^3(\rho)$.

It is usually called Hopf tube based on γ .

Hopf Tori

We denote by $\tilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho)$ the (classical) Hopf fibration.

1. Let γ be an immersed curve in $\mathbb{S}^2(4\rho)$.
2. The surface $\tilde{S}_\gamma := \tilde{\pi}^{-1}(\gamma)$ is an isometrically immersed surface in $\mathbb{S}^3(\rho)$.
It is usually called Hopf tube based on γ .
3. Moreover, \tilde{S}_γ is invariant under ξ (the vertical Killing vector field).

Hopf Tori

We denote by $\tilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho)$ the (classical) Hopf fibration.

1. Let γ be an immersed curve in $\mathbb{S}^2(4\rho)$.
2. The surface $\tilde{S}_\gamma := \tilde{\pi}^{-1}(\gamma)$ is an isometrically immersed surface in $\mathbb{S}^3(\rho)$.
It is usually called Hopf tube based on γ .
3. Moreover, \tilde{S}_γ is invariant under $\tilde{\xi}$ (the vertical Killing vector field). All $\tilde{\xi}$ -invariant surfaces of $\mathbb{S}^3(\rho)$ can be seen as vertical lifts of curves.

Hopf Tori

We denote by $\tilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho)$ the (classical) Hopf fibration.

1. Let γ be an immersed curve in $\mathbb{S}^2(4\rho)$.
2. The surface $\tilde{S}_\gamma := \tilde{\pi}^{-1}(\gamma)$ is an isometrically immersed surface in $\mathbb{S}^3(\rho)$.
It is usually called Hopf tube based on γ .
3. Moreover, \tilde{S}_γ is invariant under $\tilde{\xi}$ (the vertical Killing vector field). All $\tilde{\xi}$ -invariant surfaces of $\mathbb{S}^3(\rho)$ can be seen as vertical lifts of curves.
4. If γ is closed, then \tilde{S}_γ is a (flat) torus.

Hopf Tori

We denote by $\tilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho)$ the (classical) Hopf fibration.

1. Let γ be an immersed curve in $\mathbb{S}^2(4\rho)$.
2. The surface $\tilde{S}_\gamma := \tilde{\pi}^{-1}(\gamma)$ is an isometrically immersed surface in $\mathbb{S}^3(\rho)$.
It is usually called Hopf tube based on γ .
3. Moreover, \tilde{S}_γ is invariant under $\tilde{\xi}$ (the vertical Killing vector field). All $\tilde{\xi}$ -invariant surfaces of $\mathbb{S}^3(\rho)$ can be seen as vertical lifts of curves.
4. If γ is closed, then \tilde{S}_γ is a (flat) torus. However, the horizontal lift of γ may not be closed.

Hopf Tori

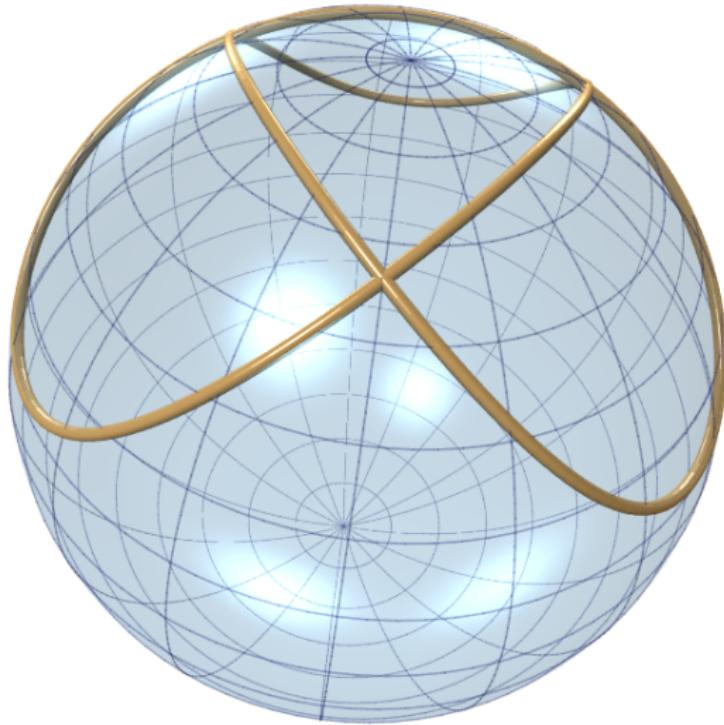
We denote by $\tilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho)$ the (classical) Hopf fibration.

1. Let γ be an immersed curve in $\mathbb{S}^2(4\rho)$.
2. The surface $\tilde{S}_\gamma := \tilde{\pi}^{-1}(\gamma)$ is an isometrically immersed surface in $\mathbb{S}^3(\rho)$.

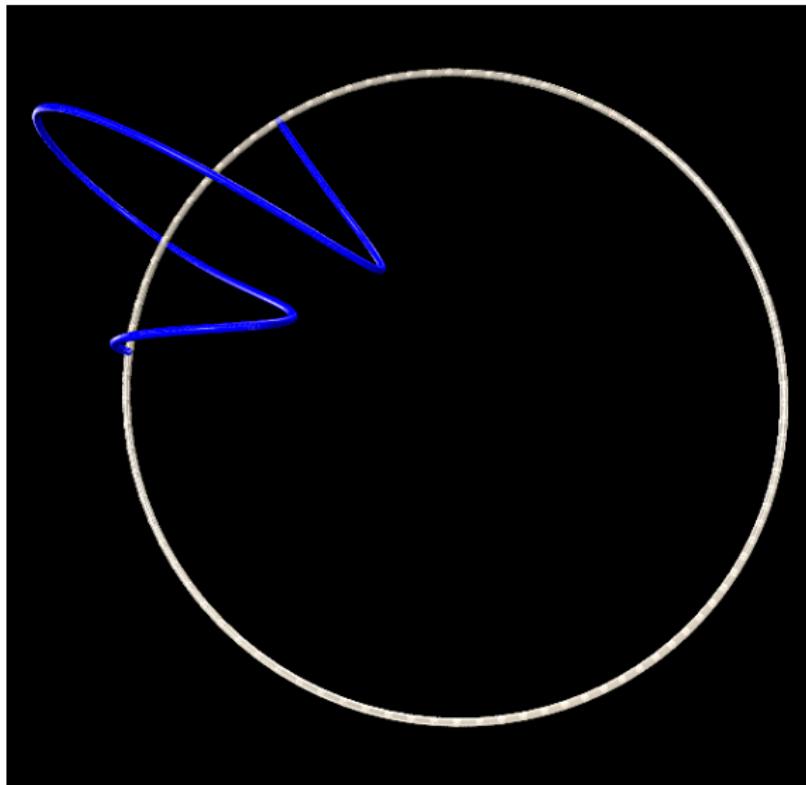
It is usually called Hopf tube based on γ .

3. Moreover, \tilde{S}_γ is invariant under $\tilde{\xi}$ (the vertical Killing vector field). All $\tilde{\xi}$ -invariant surfaces of $\mathbb{S}^3(\rho)$ can be seen as vertical lifts of curves.
4. If γ is closed, then \tilde{S}_γ is a (flat) torus. However, the horizontal lift of γ may not be closed.
(A condition on the enclosed area is essential, (Arroyo, Barros & Garay, 2000).)

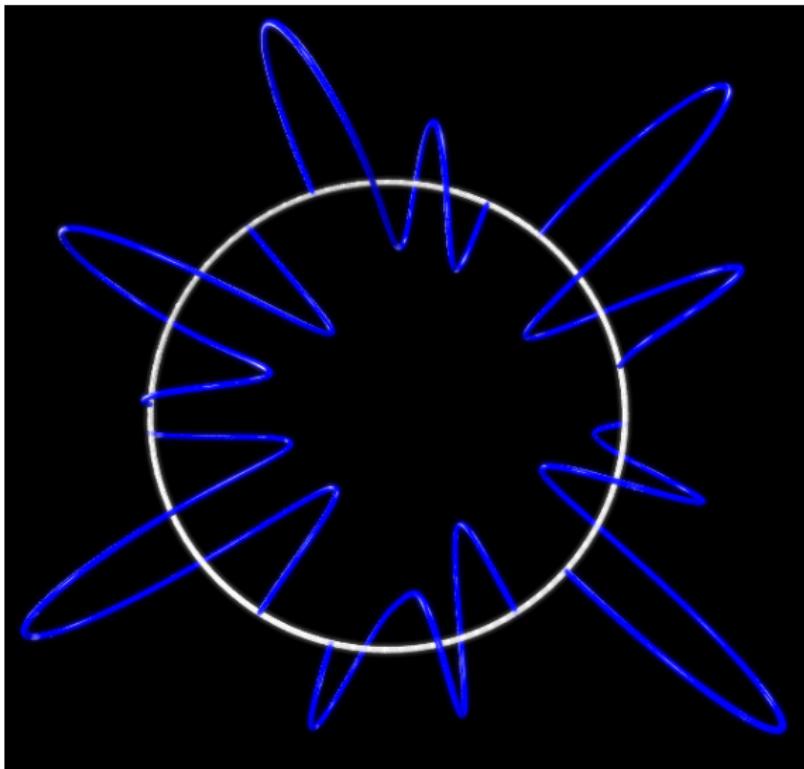
Horizontal Lift (Base Curve)



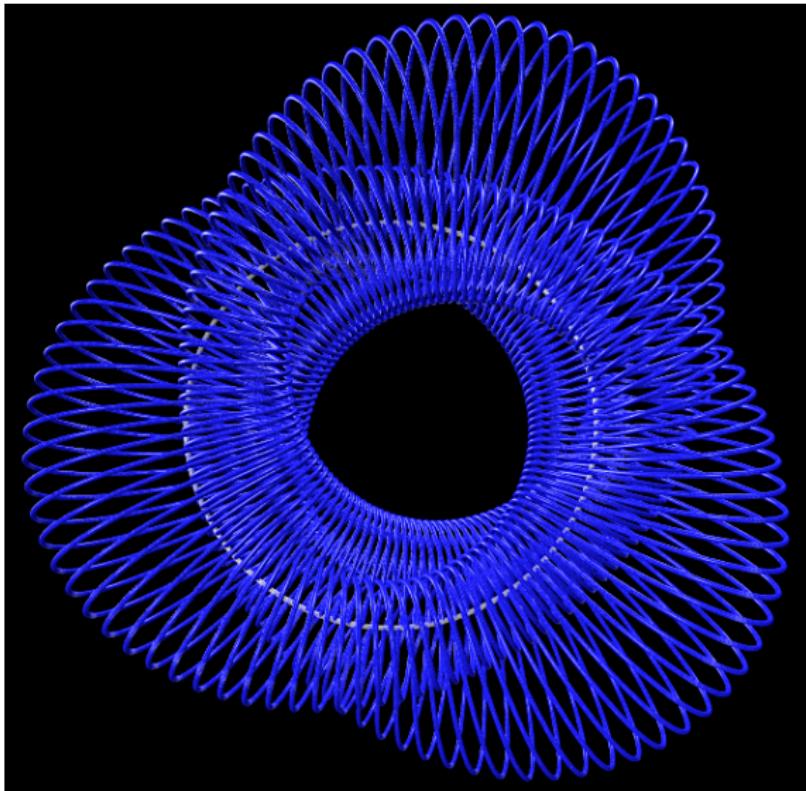
Horizontal Lift (One Lift)



Horizontal Lift (Six Lifts)



Horizontal Lift (One Hundred Lifts)



Surface Energies

Surface Energies

Consider the biparametric family of energies

$$\mathcal{F}_{\lambda,p}(S) \equiv \mathcal{F}(S) := \int_S (H - \lambda)^p \ dA$$

defined on the space of surface immersions in $\mathbb{S}^3(\rho)$.

Surface Energies

Consider the biparametric family of energies

$$\mathcal{F}_{\lambda,p}(S) \equiv \mathcal{F}(S) := \int_S (H - \lambda)^p \ dA$$

defined on the space of surface immersions in $\mathbb{S}^3(\rho)$.

- These energies are kind of p -Willmore energies, (Gruber, Toda & Tran, 2019).

Surface Energies

Consider the biparametric family of energies

$$\mathcal{F}_{\lambda,p}(S) \equiv \mathcal{F}(S) := \int_S (H - \lambda)^p \ dA$$

defined on the space of surface immersions in $\mathbb{S}^3(\rho)$.

- These energies are kind of p -Willmore energies, (Gruber, Toda & Tran, 2019).
- We introduce the notation $P(H) := (H - \lambda)^p$.

Euler-Lagrange Equation

A critical point of $\mathcal{F}(S)$ in $\mathbb{S}^3(\rho)$ satisfies

$$\Delta P' + 2P' (2H^2 - K + 2\rho) - 4PH = 0$$

where $P' \equiv dP/dH$.

Critical p -Willmore Hopf Tori

Critical p -Willmore Hopf Tori

For a Hopf tori \widetilde{S}_γ , the mean curvature is given by

$$H = \frac{1}{2} (\kappa \circ \widetilde{\pi}) \quad (\widetilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho))$$

where κ is the curvature of γ in $\mathbb{S}^2(4\rho)$.

Critical p -Willmore Hopf Tori

For a Hopf tori \widetilde{S}_γ , the mean curvature is given by

$$H = \frac{1}{2} (\kappa \circ \widetilde{\pi}) \quad (\widetilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho))$$

where κ is the curvature of γ in $\mathbb{S}^2(4\rho)$.

- Let γ be a closed curve in $\mathbb{S}^2(4\rho)$.

Critical p -Willmore Hopf Tori

For a Hopf tori \widetilde{S}_γ , the mean curvature is given by

$$H = \frac{1}{2} (\kappa \circ \widetilde{\pi}) \quad (\widetilde{\pi} : \mathbb{S}^3(\rho) \rightarrow \mathbb{S}^2(4\rho))$$

where κ is the curvature of γ in $\mathbb{S}^2(4\rho)$.

- Let γ be a closed curve in $\mathbb{S}^2(4\rho)$.
- Using H and the Symmetric Criticality Principle of Palais (Palais, 1979), we get

Theorem (—, submitted)

The Hopf torus $\widetilde{S}_\gamma = \widetilde{\pi}^{-1}(\gamma)$ based on γ is a critical point of $\mathcal{F}(S)$ if and only if γ is a generalized elastic curve in $\mathbb{S}^2(4\rho)$ with $\mu = \lambda/2$, i.e.,

$$\Theta(\gamma) = \int_\gamma (\kappa - \mu)^p .$$

Correspondence Result

Correspondence Result

Theorem (—, submitted)

The Hopf torus \tilde{S}_γ based on γ is critical for

$$\mathcal{F}(S) = \int_S (H - \lambda)^p \, dA$$

in $\mathbb{S}^3(\rho)$ if and only if the binormal evolution torus S_γ generated by evolving γ under its associated binormal flow is a (rotational) linear Weingarten torus in $\mathbb{S}^3(4\rho)$, i.e. it satisfies

$$\kappa_1 = a\kappa_2 + b$$

between its principal curvatures κ_i .

Correspondence Result

Theorem (—, submitted)

The Hopf torus \tilde{S}_γ based on γ is critical for

$$\mathcal{F}(S) = \int_S (H - \lambda)^p \, dA$$

in $\mathbb{S}^3(\rho)$ if and only if the binormal evolution torus S_γ generated by evolving γ under its associated binormal flow is a (rotational) linear Weingarten torus in $\mathbb{S}^3(4\rho)$, i.e. it satisfies

$$\kappa_1 = a\kappa_2 + b$$

between its principal curvatures κ_i .

- There exists a correspondence between (rotational) linear Weingarten tori and critical p -Willmore Hopf tori in \mathbb{S}^3 .

Illustration of a Particular Case

We recover the Blaschke's curvature energy ($p = 1/2$ and $\mu = 0$):

$$\Theta(\gamma) \equiv \Theta_{0,1/2}(\gamma) = \int_{\gamma} \sqrt{\kappa}$$

in $\mathbb{S}^2(4\rho)$.

Illustration of a Particular Case

We recover the Blaschke's curvature energy ($p = 1/2$ and $\mu = 0$):

$$\Theta(\gamma) \equiv \Theta_{0,1/2}(\gamma) = \int_{\gamma} \sqrt{\kappa}$$

in $\mathbb{S}^2(4\rho)$.

1. Let γ be a closed critical curve.

Illustration of a Particular Case

We recover the Blaschke's curvature energy ($p = 1/2$ and $\mu = 0$):

$$\Theta(\gamma) \equiv \Theta_{0,1/2}(\gamma) = \int_{\gamma} \sqrt{\kappa}$$

in $\mathbb{S}^2(4\rho)$.

1. Let γ be a closed critical curve.
2. The parameters n and m in the closure condition satisfy:

$$m < 2n < \sqrt{2} m.$$

Illustration of a Particular Case

We recover the Blaschke's curvature energy ($p = 1/2$ and $\mu = 0$):

$$\Theta(\gamma) \equiv \Theta_{0,1/2}(\gamma) = \int_{\gamma} \sqrt{\kappa}$$

in $\mathbb{S}^2(4\rho)$.

1. Let γ be a closed critical curve.
2. The parameters n and m in the closure condition satisfy:

$$m < 2n < \sqrt{2} m .$$

3. There are no simple closed critical curves ($n \neq 1$).

Illustration of a Particular Case

We recover the Blaschke's curvature energy ($p = 1/2$ and $\mu = 0$):

$$\Theta(\gamma) \equiv \Theta_{0,1/2}(\gamma) = \int_{\gamma} \sqrt{\kappa}$$

in $\mathbb{S}^2(4\rho)$.

1. Let γ be a closed critical curve.
2. The parameters n and m in the closure condition satisfy:

$$m < 2n < \sqrt{2} m .$$

3. There are no simple closed critical curves ($n \neq 1$).
4. The choices of smallest n and m is: $n = 2$ and $m = 3$.

Illustration of a Particular Case

We recover the Blaschke's curvature energy ($p = 1/2$ and $\mu = 0$):

$$\Theta(\gamma) \equiv \Theta_{0,1/2}(\gamma) = \int_{\gamma} \sqrt{\kappa}$$

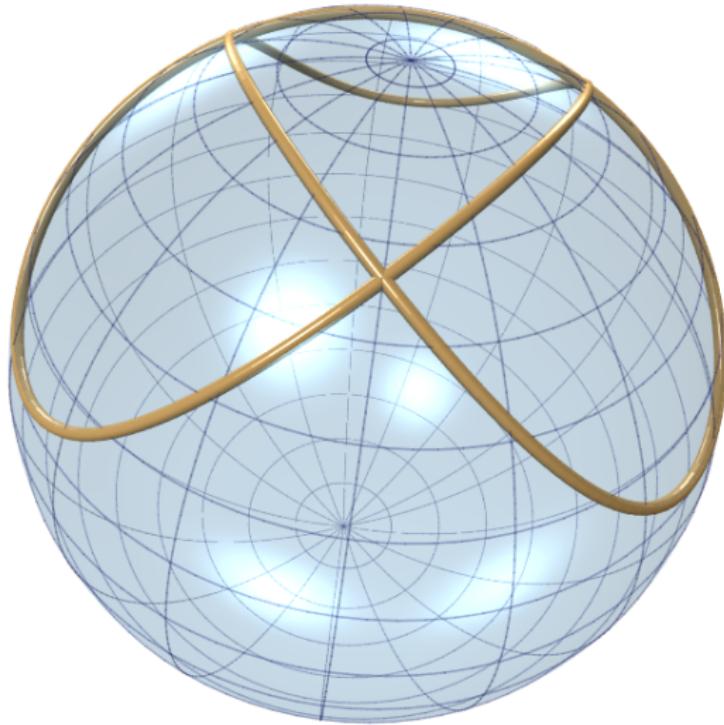
in $\mathbb{S}^2(4\rho)$.

1. Let γ be a closed critical curve.
2. The parameters n and m in the closure condition satisfy:

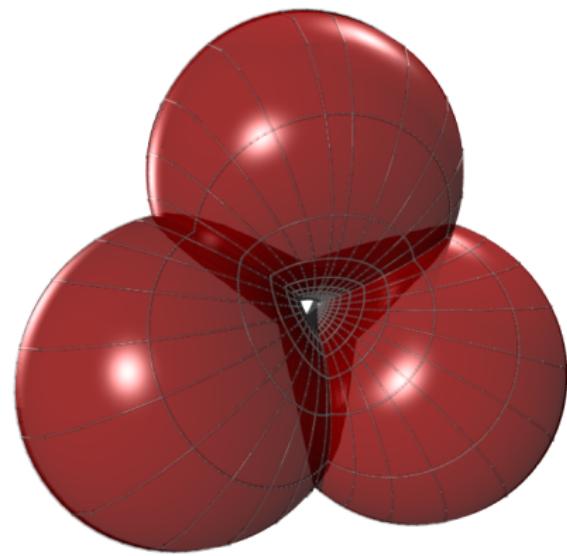
$$m < 2n < \sqrt{2} m .$$

3. There are no simple closed critical curves ($n \neq 1$).
4. The choices of smallest n and m is: $n = 2$ and $m = 3$.
5. We consider this critical curve, $\gamma_{2,3}$.

Critical Curve $\gamma_{2,3}$

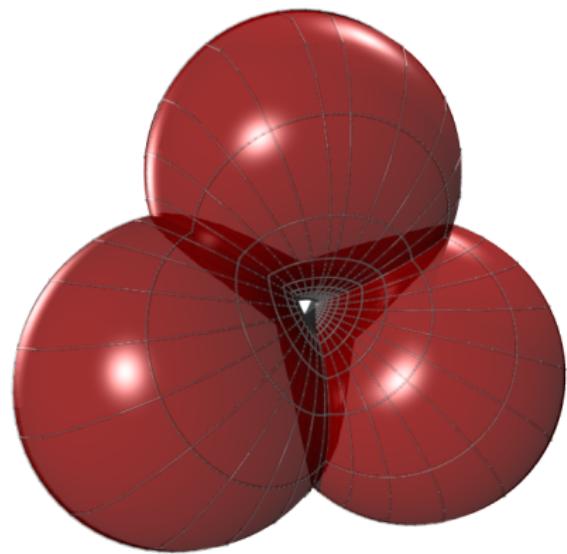


Invariant Surfaces Associated to $\gamma_{2,3}$

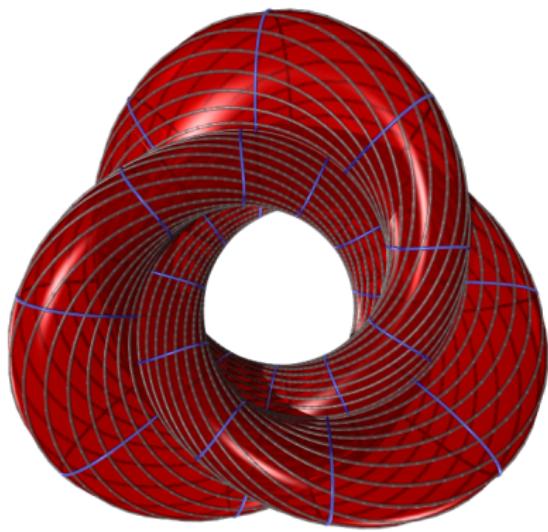


(o) Minimal (Rotational) Torus

Invariant Surfaces Associated to $\gamma_{2,3}$



(Q) Minimal (Rotational) Torus



(R) Hopf Torus

Consequences

Corollary

The Hopf torus \tilde{S}_γ based on $\gamma_{2,3}$ is critical for

$$\mathcal{F}(S) = \int_S \sqrt{H} dA$$

in $\mathbb{S}^3(\rho)$. (1/2-Willmore.)

Consequences

Corollary

The Hopf torus \tilde{S}_γ based on $\gamma_{2,3}$ is critical for

$$\mathcal{F}(S) = \int_S \sqrt{H} dA$$

in $\mathbb{S}^3(\rho)$. (1/2-Willmore.)

Furthermore,

- For any $m < 2n < \sqrt{2}m$, there exists a biparametric family of Hopf tori critical for $\mathcal{F}(S)$, i.e. 1/2-Willmore.

Consequences

Corollary

The Hopf torus \tilde{S}_γ based on $\gamma_{2,3}$ is critical for

$$\mathcal{F}(S) = \int_S \sqrt{H} dA$$

in $\mathbb{S}^3(\rho)$. (1/2-Willmore.)

Furthermore,

- For any $m < 2n < \sqrt{2}m$, there exists a biparametric family of Hopf tori critical for $\mathcal{F}(S)$, i.e. 1/2-Willmore.
- There is a correspondence between minimal tori and 1/2-Willmore Hopf tori in \mathbb{S}^3 .

THE END

Thank You!

Acknowledgements: Research partially supported by MINECO-FEDER,
PGC2018-098409-B-100 and by Gobierno Vasco, IT1094-16.