

Using Neural Networks to Classify 3D Scans of Museum Artifacts

Capstone Project in Machine Learning, 2021

Alvaro Ortiz Troncoso



<https://www.epfl.ch/>

Research Question A

Introduction



*Barbara Piccinotti Violin Maker
(Image: Roberto Cavagnoli, CC BY-SA)*



*Glenn Casamassa, Regional Forester, USDA
Forest Service (Image: Kevin Beasley, U.S.
Forest Service, Pacific Northwest Region, CC0)*

A metaphor:
What knowledge about forest engineering is required to make a violin?

Research Question A

How much math is necessary to apply Machine Learning (M.L.) in practice?



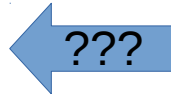
Michael Minovitch **solved** the "3 Body Problem" at NASA in 1961, using a computer simulation. *

(Image: © 2003 Dr. Michael A. Minovitch)



Henri Poincaré proved in 1890 that the "3 Body Problem" **cannot be solved**.

(Image: public domain)



* Minovitch, M., 1961. Alternative method for determination of elliptic and hyperbolic trajectories. *Jet Propulsion Laboratory, Technical Memo*, pp.312-118.

3D-digitalization of archaeological or natural history artifacts



Automated 3D scanning at Museum für Naturkunde Berlin, using the CultLab3D system developed by Fraunhofer institute (Photo: Carola Radke, MfN)

Research Question B

Given the current state of digitization of cultural artifacts,
what results can be expected?



Until 2021

Digitizing an artifact can take several hours
(including post-processing), therefore
digitization reserved for
the most prestigious items in the collection

After 2021

Cost-efficient and timely mass-digitization of
all
the artifacts in a collection
(Fraunhofer IGD, MfN)

Data Sources



University of Virginia, Charlottesville, USA



Musée Art & Histoire, Bruxelles, BE



INSTITUTE OF ARCHAEOLOGY OF CAS, Prague, CS



Global Digital Heritage, USA / IT / ES (non-profit)

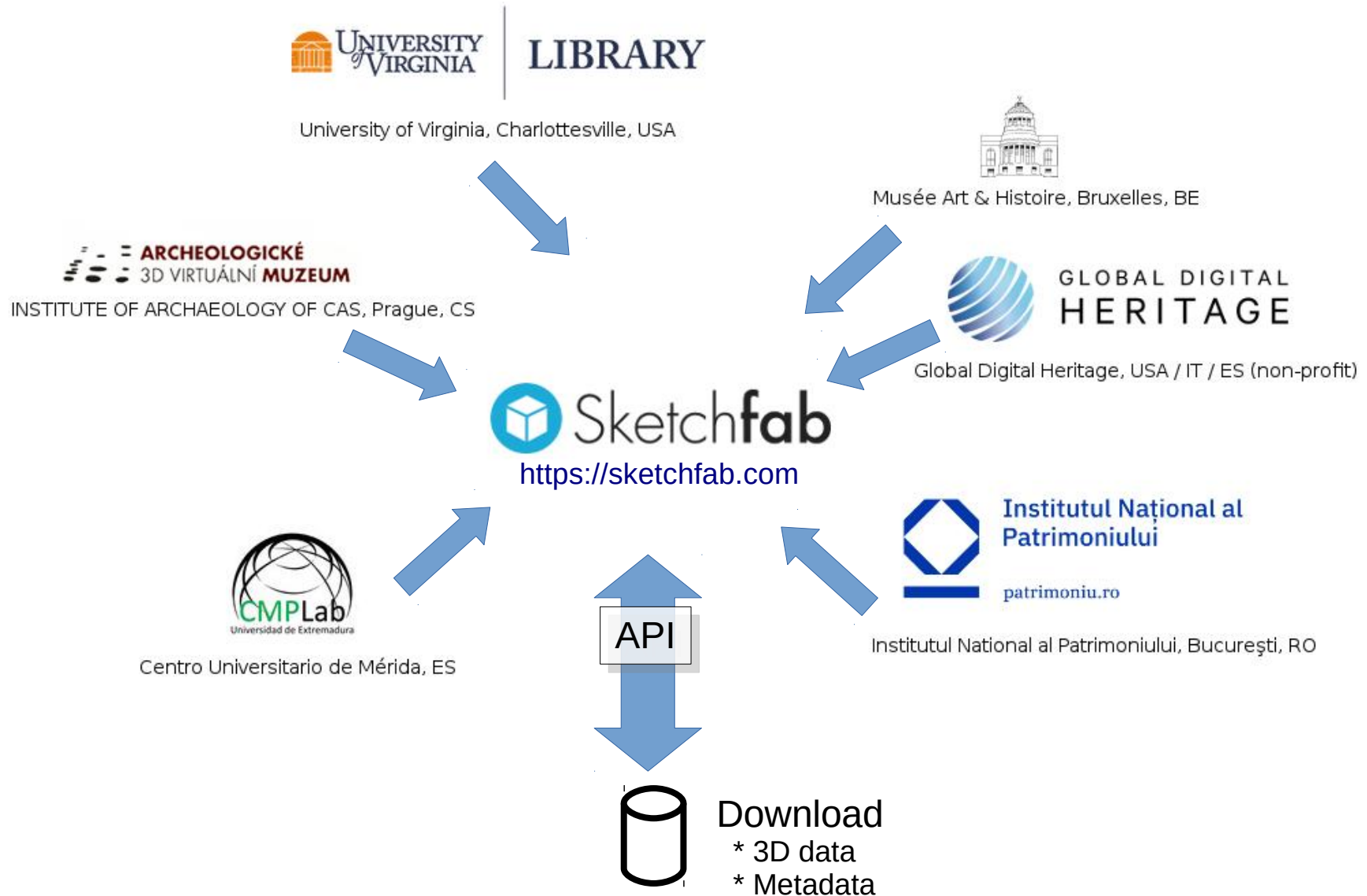


Centro Universitario de Mérida, ES



Institutul National al Patrimoniului, București, RO

Data Sources



Downloaded data: Metadata

- 1) the name of the 3D model
- 2) ideally a textual description of the object, written by a museum curator
- 3) the API-URI where the 3D-model file can be downloaded
- 4) a link to the 3D-model's preview page on Sketchfab
- 5) the name of the museum, institution or organization that provided the digitized object
- 6) a link to the providers page on Sketchfab
- 7) the license of the 3D-model
- 8) the number of vertices in the 3D-model
- 9) tags added by the provider of the 3D-model describing the object (json)

	Data Provider	Object Count
1	Archaeological 3D virtual museum	369
2	The Royal Museums of Art and History	343
3	Global Digital Heritage	180
4	Institutul Național al Patrimoniului	22
5	CMPLab	11
6	UVA3D	10
7	Other (less than 10 models each)	85

Downloaded data: Classes



2812170

57 0 2



Mi_81_1

94 0 2



Bowl on foot - PG.2000.1388

16 0 0



Visigothic Ceramic, Castilla-La Mancha, Spain

6 0 0



Olpe with Satyrs

1.2k 1 43

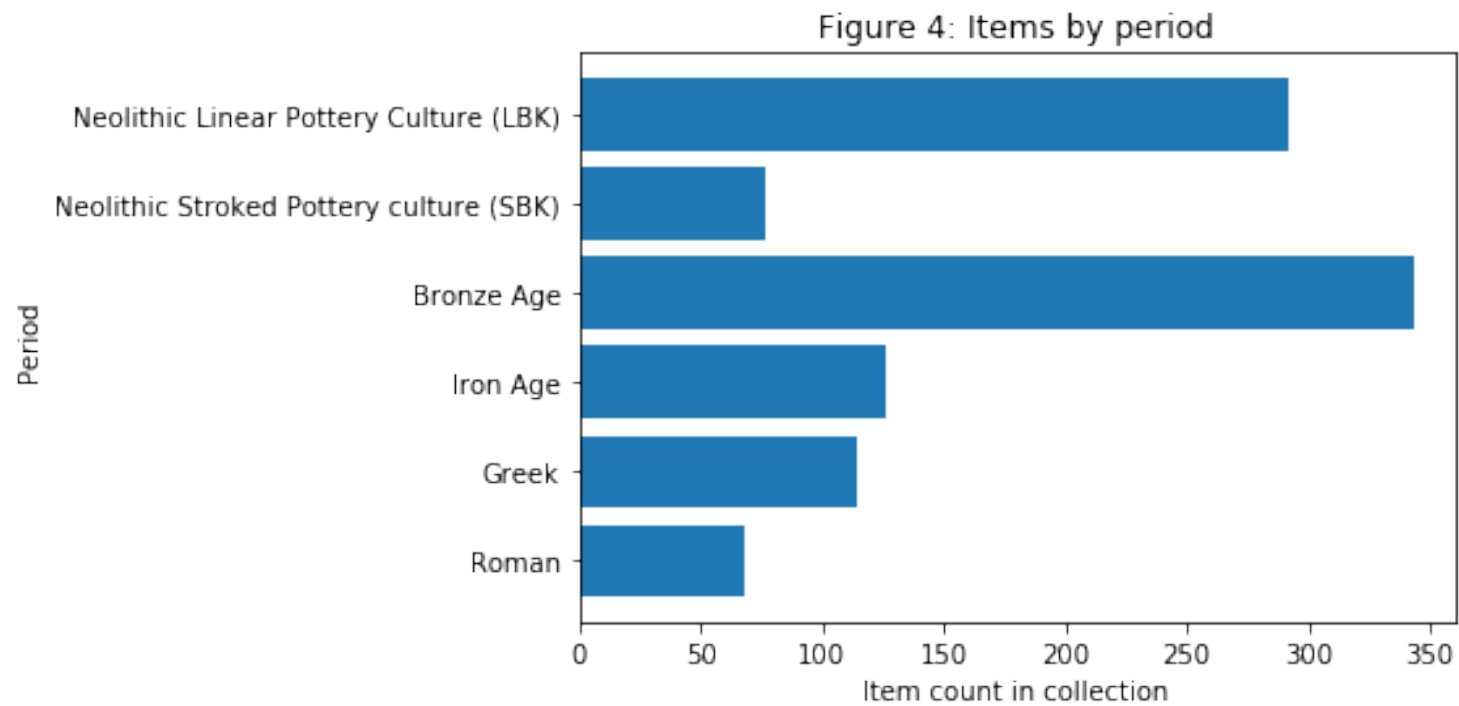


"Terra sigillata" vessel

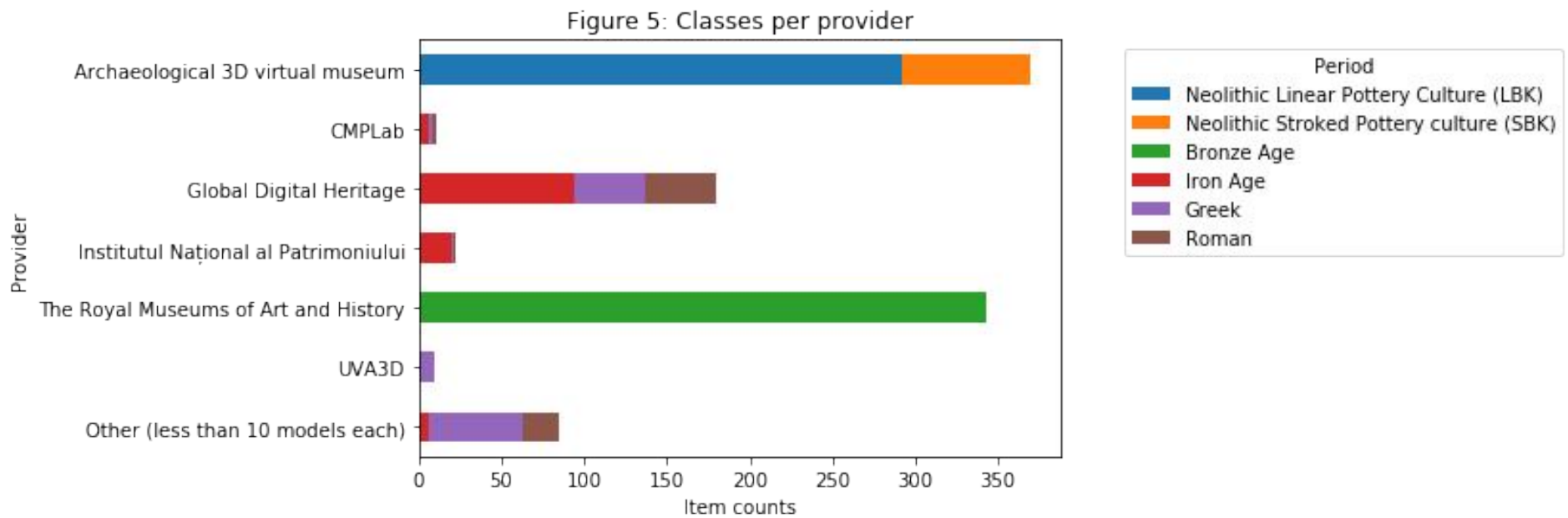
267 0 14

Various types of pots in the data set: Neolithic LBK vessel, Neolithic SBK mortar, Bronze Age bowl on foot, Iron Age -Visigoth- bottle, Greek Jug, Roman cup (screenshot from the Sketchfab website).

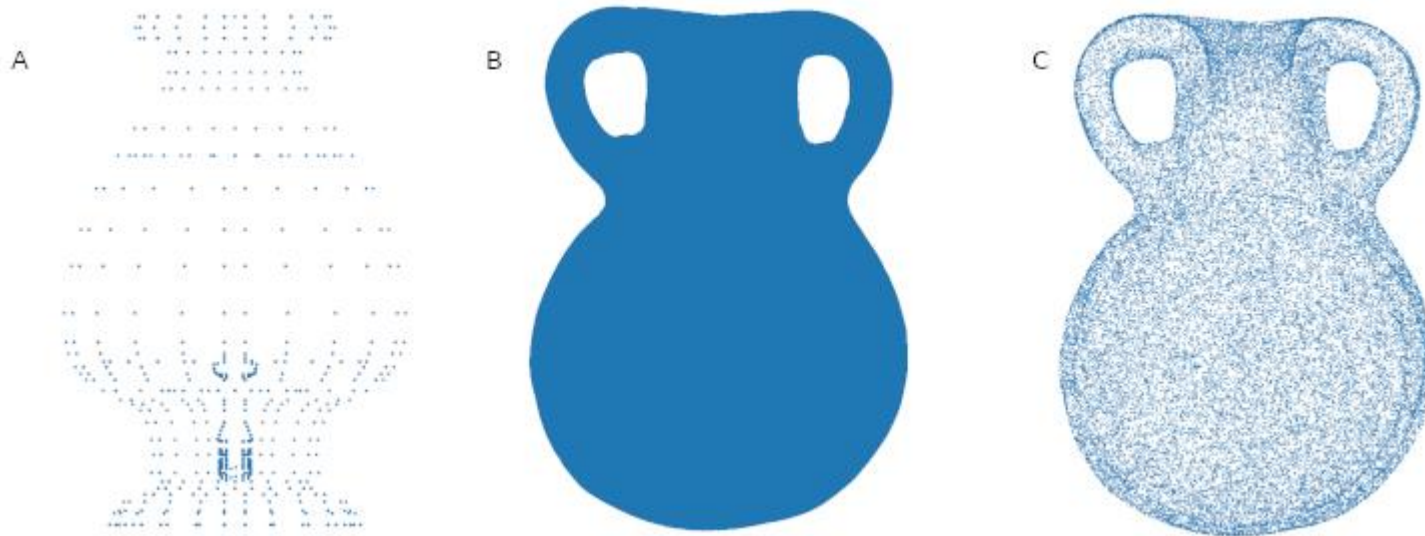
Caveat 1: Data is imbalanced by source



Caveat 2: Data is imbalanced by class

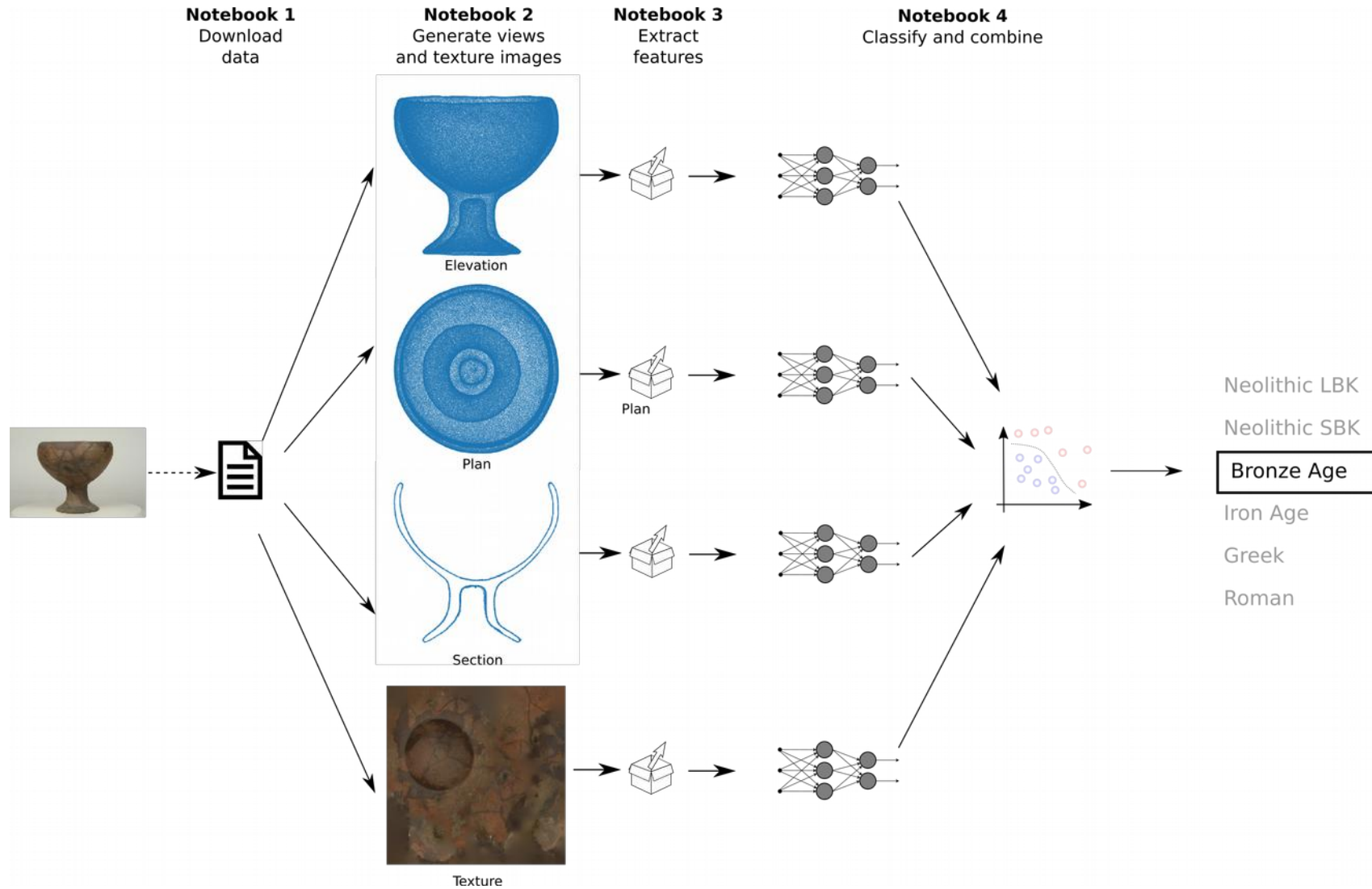


Caveat 3: Downloaded 3D models are not homogeneous



*The 3D-model with the least vertices (A), with the most vertices (B),
the model with the most vertices sub-sampled to 37532 vertices (C)*

Machine learning setup



Preprocess 3D-models



A Greek jug (A), its 3D point cloud (B), its texture image (C).

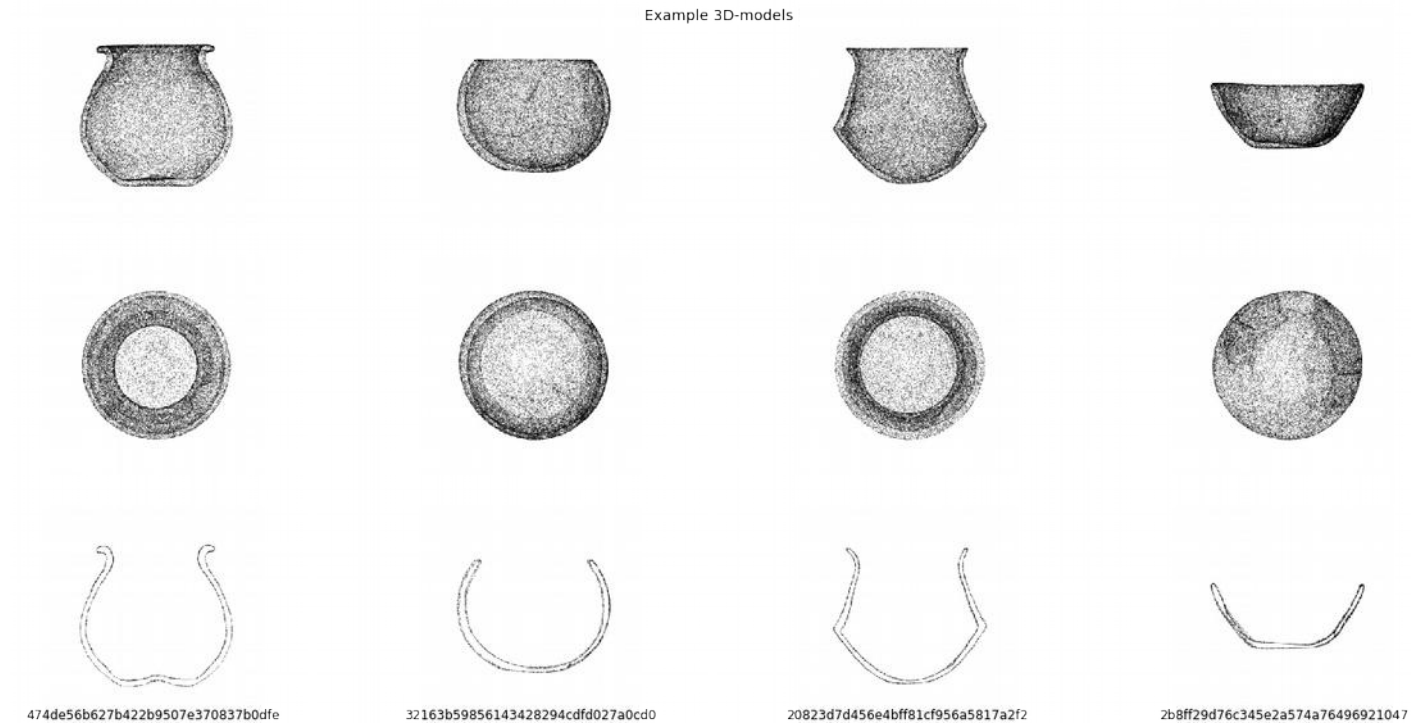
Point clouds

- 1) sub sample point cloud data so that the number of vertices is the number computed in the EDA in notebook 1, i.e. 37838 vertices
- 2) rotate the point cloud to generate an elevation (side) view
- 3) generate plan (top) and cross-section views by rotating the elevation view
- 4) render the views as images
- 5) save the pixel data of the flattened images into a npz file

Textures

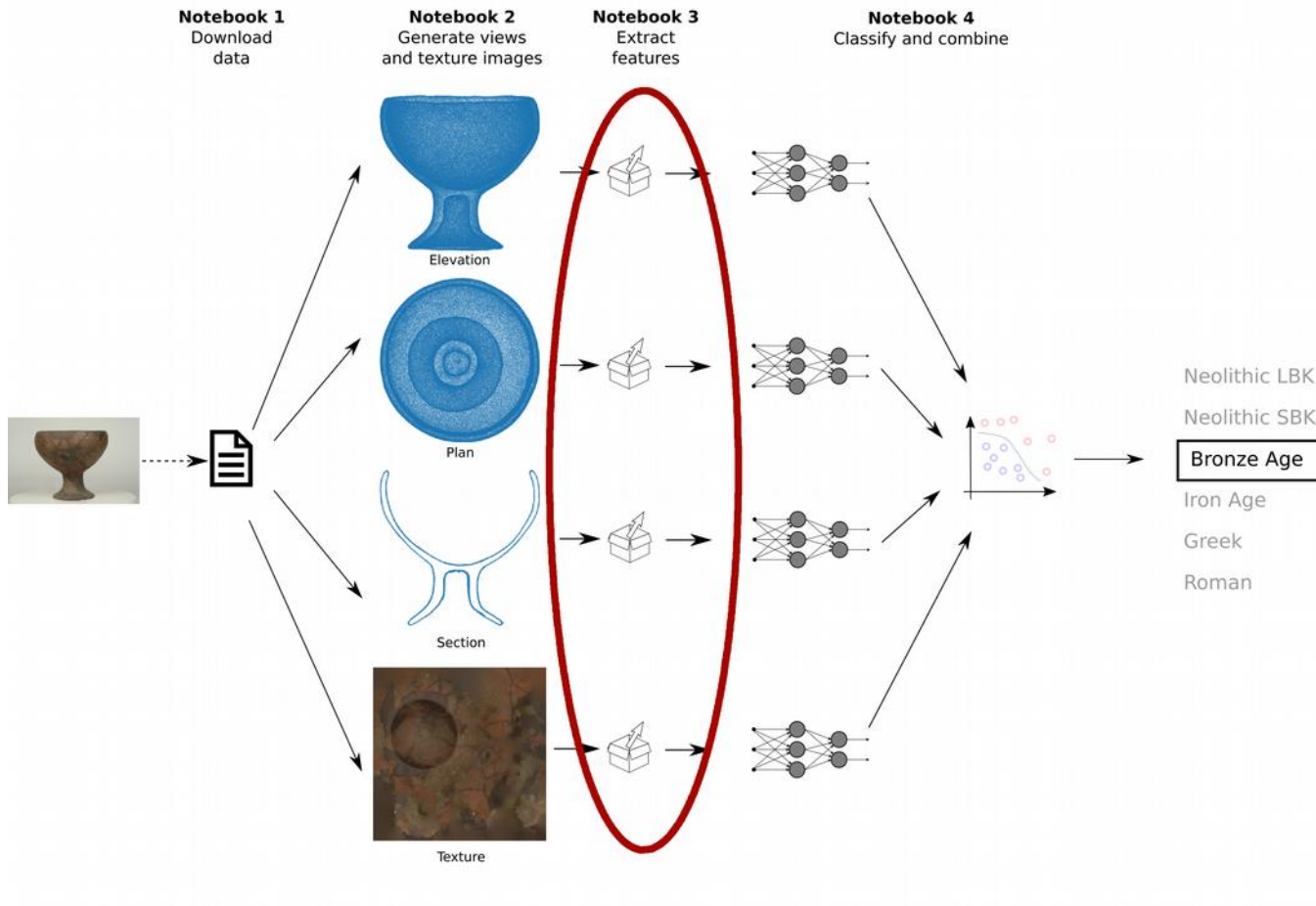
- 6) resize the texture image to the size expected by the data extraction model, i.e. 299x299 pixels RGB
- 7) save the textures as flattened images into a npz file

Split data into "train", "validate" and "test" datasets

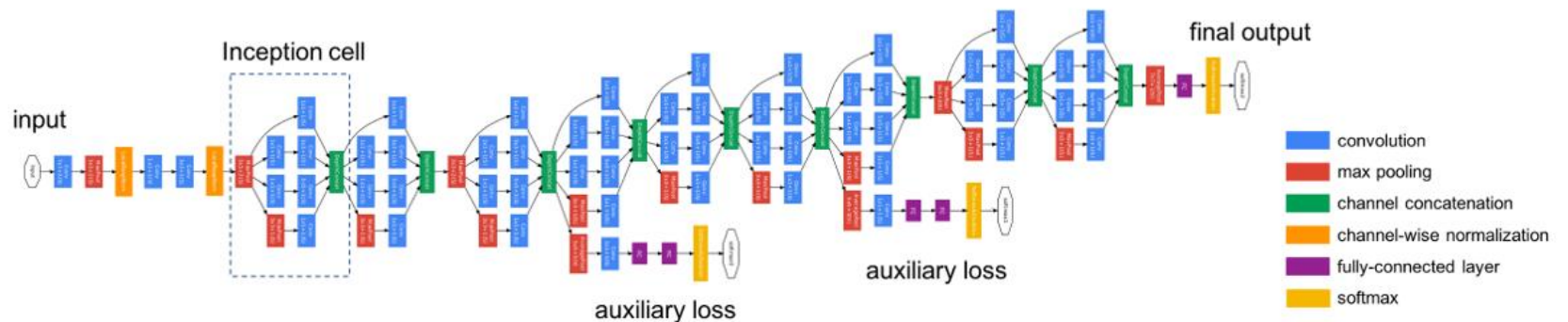
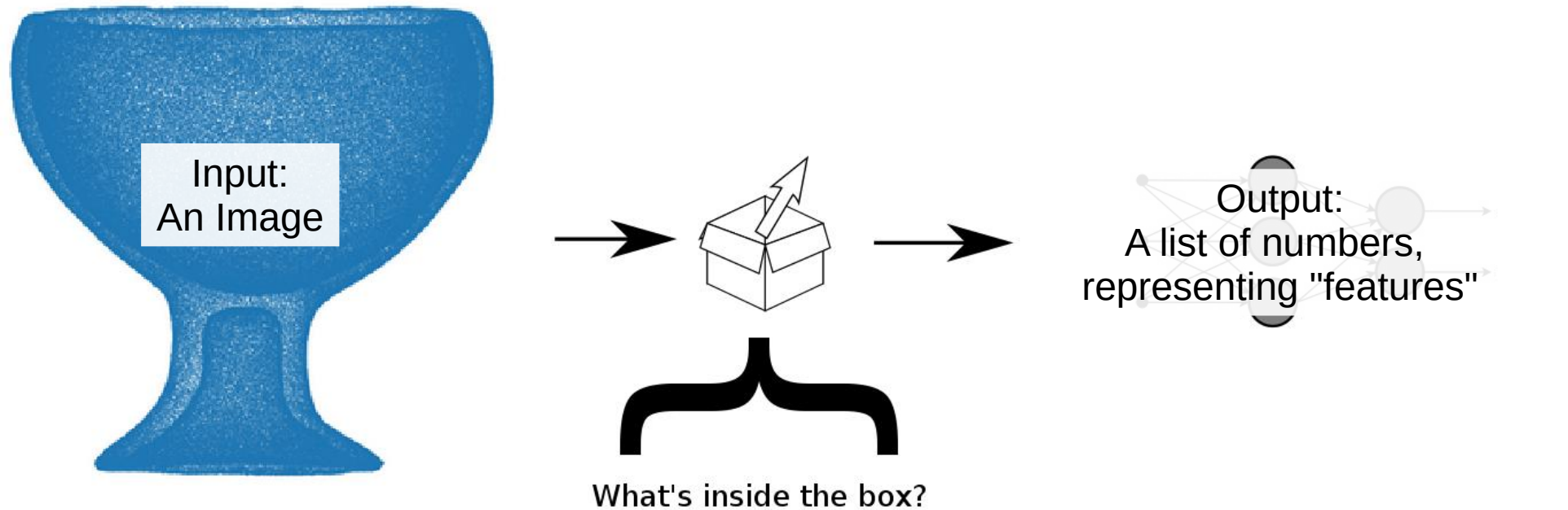


- Training dataset (70%)
- Validation dataset (20%)
- Test dataset (10%)

Extract features by transfer learning



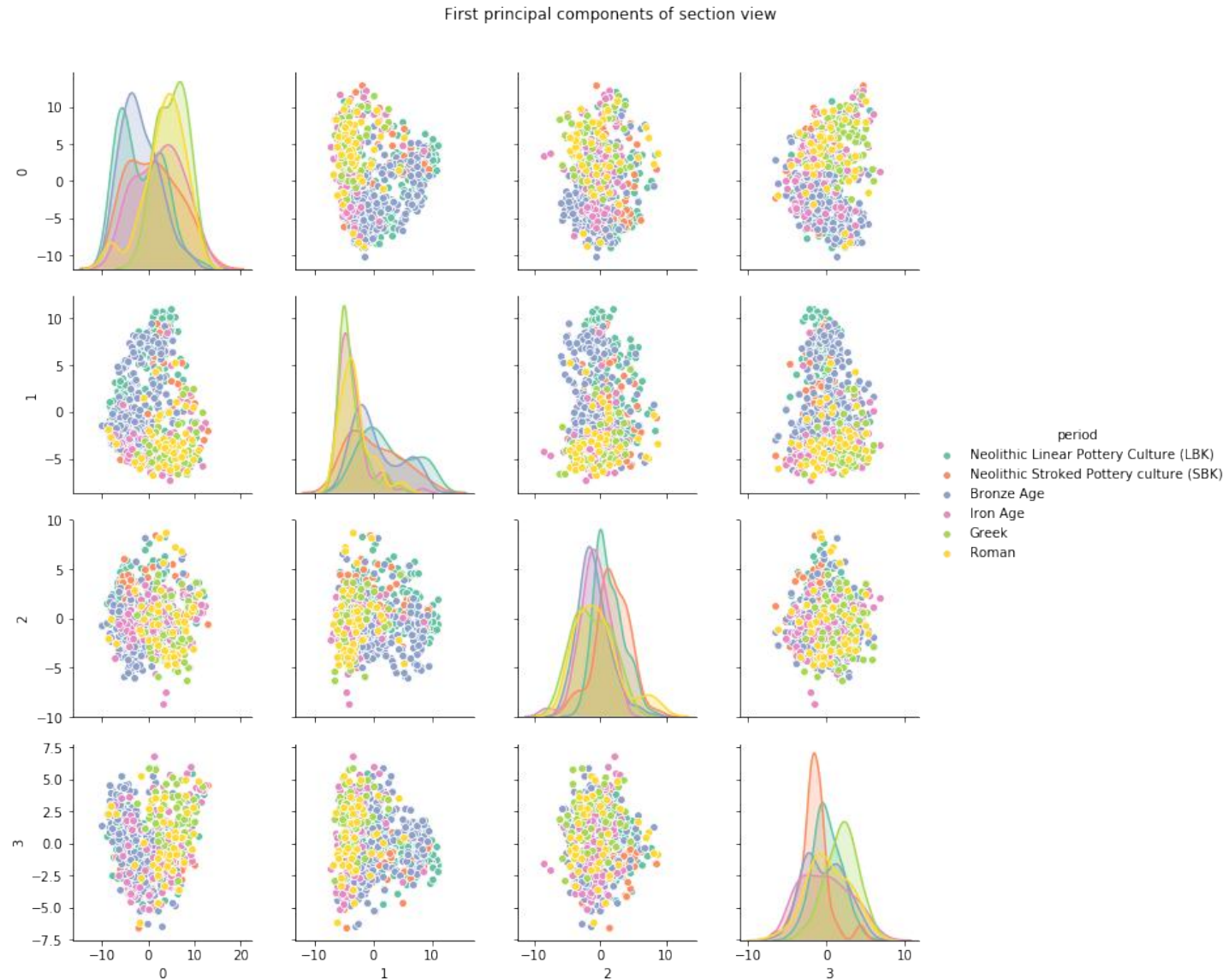
Extract features by transfer learning



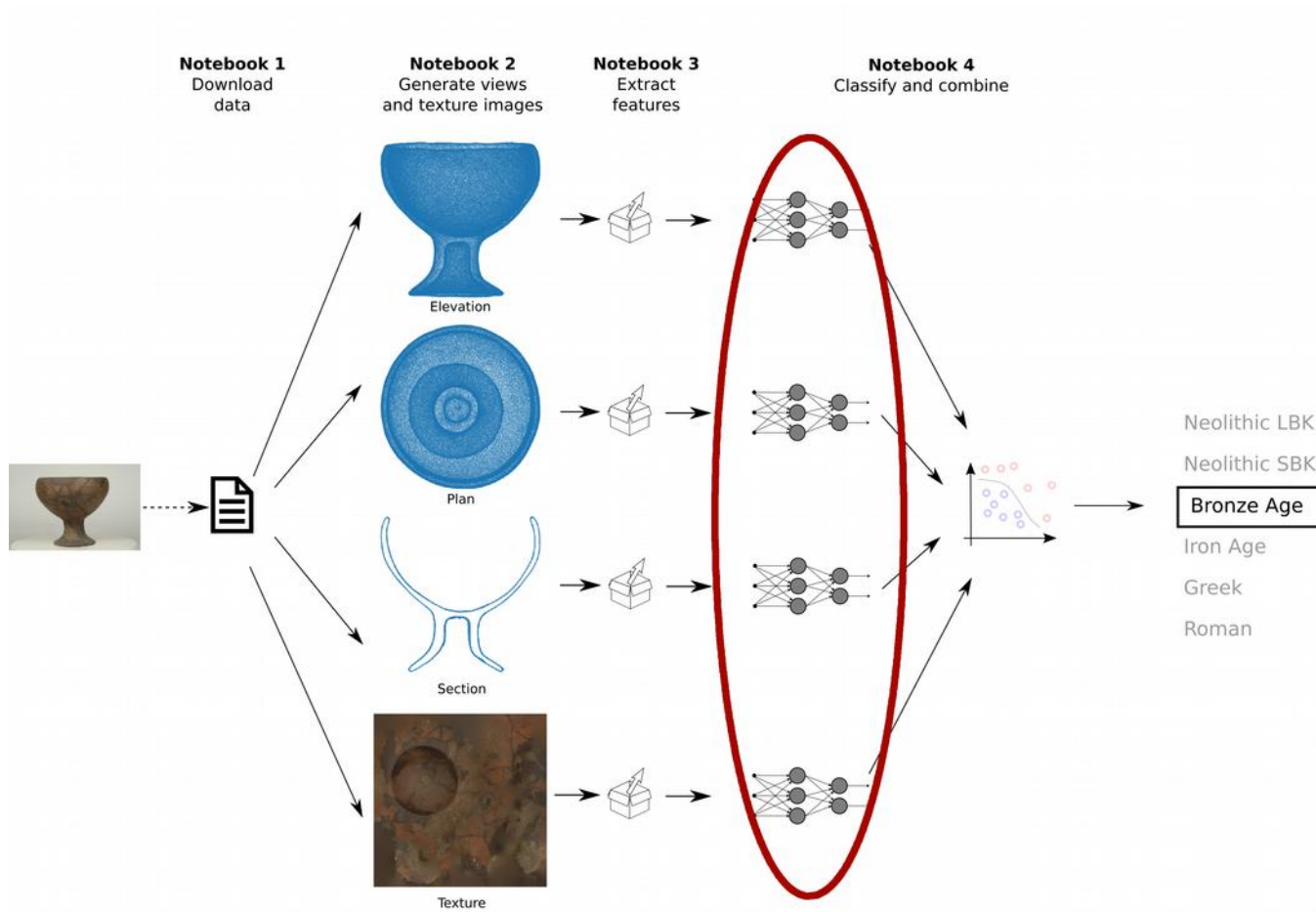
Inception v3 model, trained on "ImageNet" dataset (14.197.122 images) on Google Cloud

*Christian Szegedy, Vincent Vanhoucke, Sergey Ioffe, Jonathon Shlens, Zbigniew Wojna:
"Rethinking the Inception Architecture for Computer Vision", 2015.*

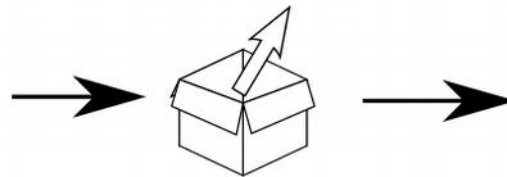
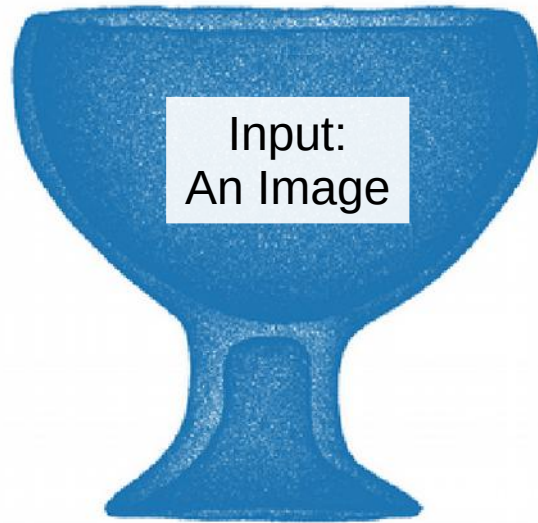
Principal component analysis



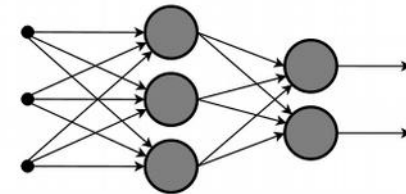
Classify



Classify



Intermediate result:
A list of numbers,
representing "features"



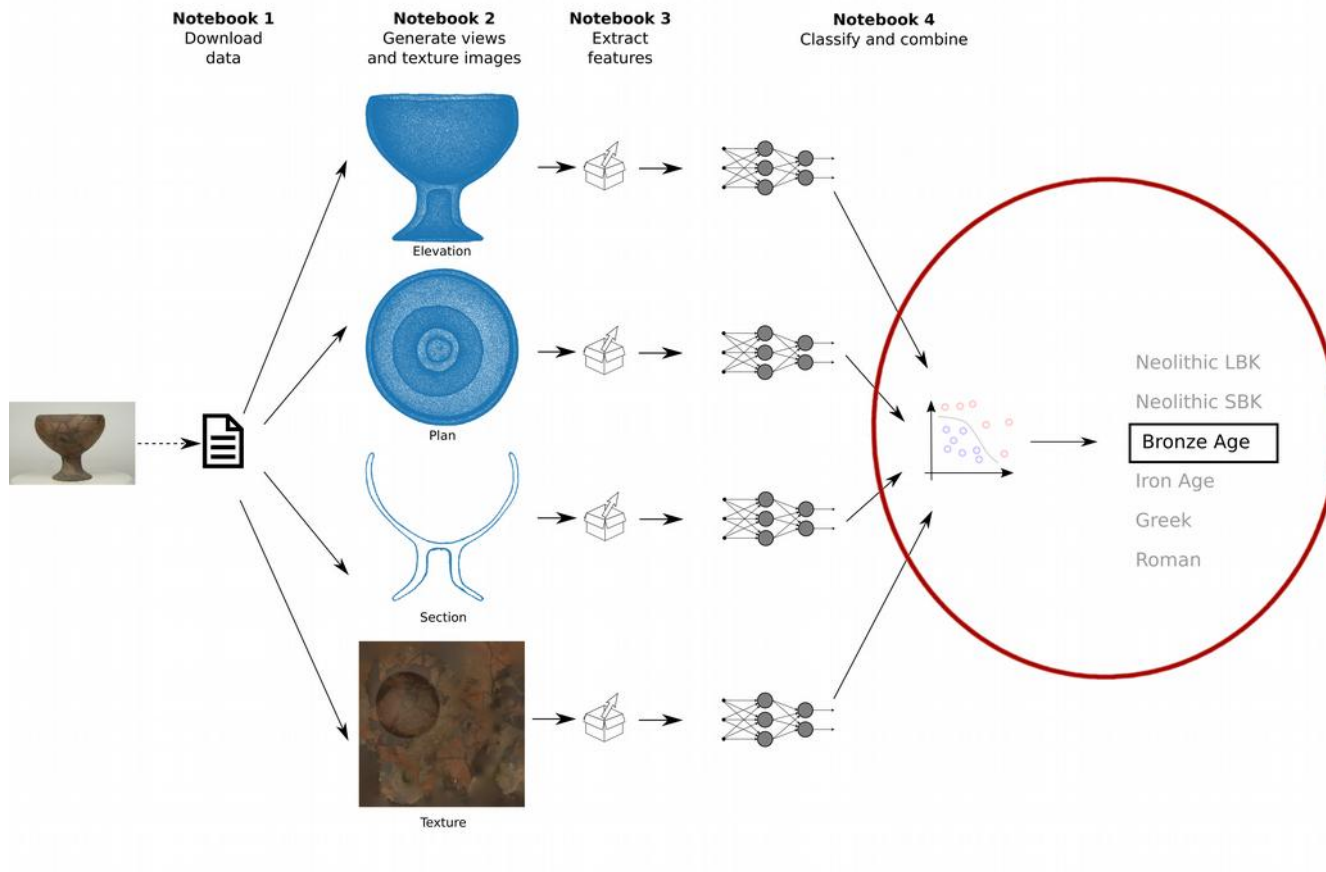
Output:
Probability that the artifact
belongs to each of
the 6 classes

Example:

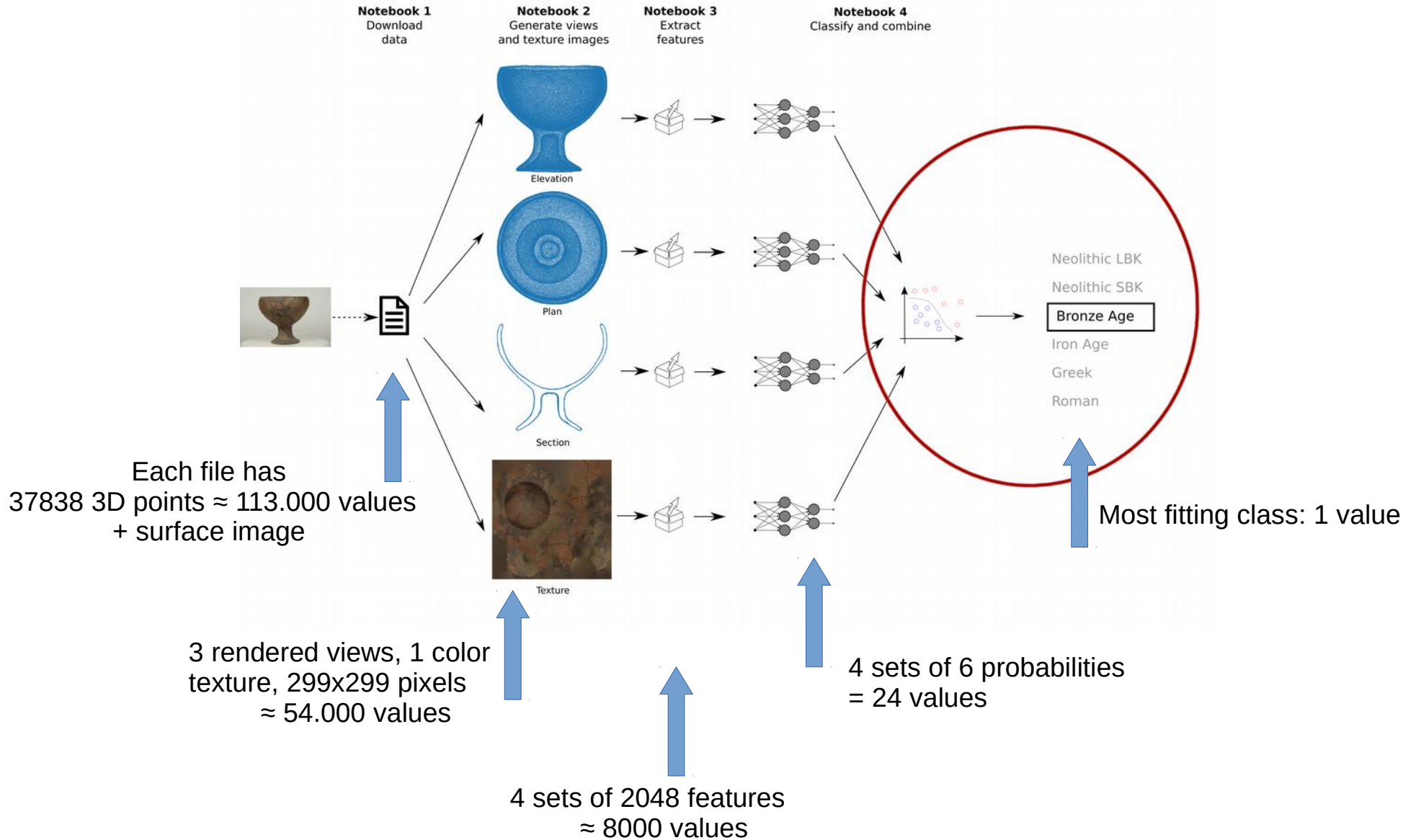
For the first artifact, for the "elevation view"

Neolithic LBK	50%
Neolithic SBK	40%
Bronze Age	80%
Iron Age	70%
Greek	20%
Roman	60%

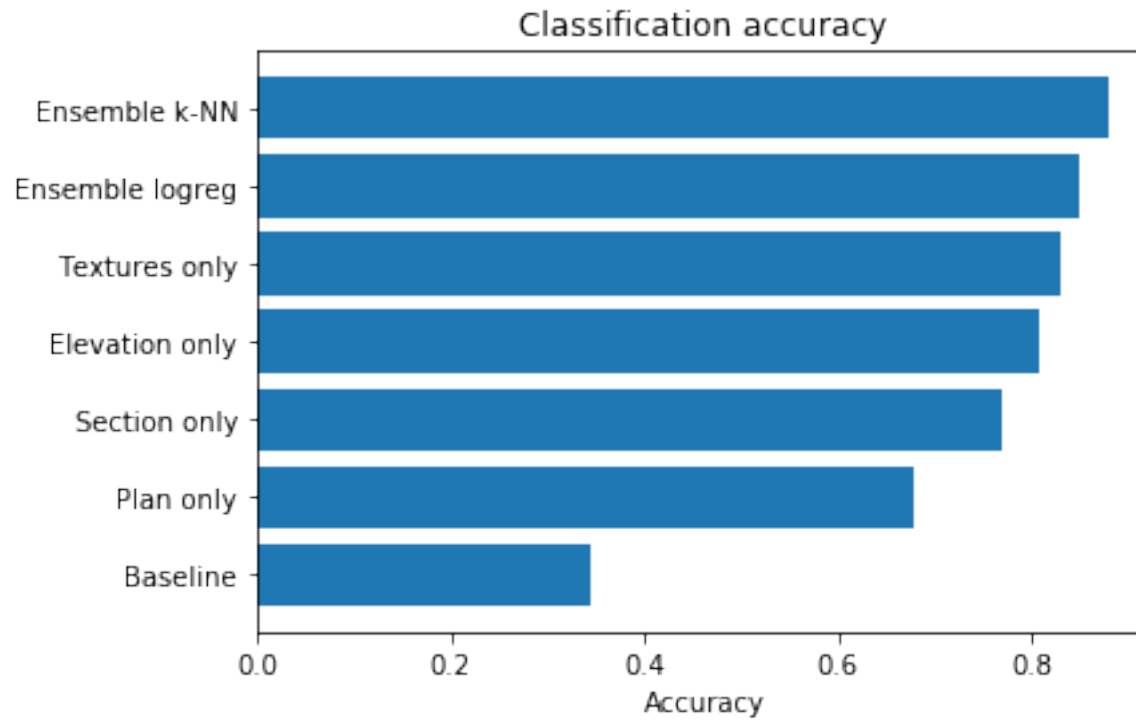
Classify and combine



Classify and combine



Results: Accuracy



Results: confusion matrix

	A	B	C	D	E	F	G	H
1			Predictions					
2			Bronze Age	Greek	Iron Age	Neolithic Linear Pottery Culture (LBK)	Neolithic Stroked Pottery culture (SBK)	Roman
3	True class	Bronze Age	97 %	0 %	0 %	3 %	0 %	0 %
4		Greek	0 %	87 %	3 %	0 %	0 %	0 %
5		Iron Age	7 %	0 %	83 %	0 %	0 %	0 %
6		Neolithic Linear Pottery Culture (LBK)	0 %	0 %	0 %	100 %	0 %	0 %
7		Neolithic Stroked Pottery culture (SBK)	10 %	0 %	0 %	40 %	50 %	0 %
8		Roman	0 %	14 %	43 %	0 %	0 %	43 %
9								

Evaluation

RQA: How much math is necessary to apply M.L. in practice?

- *Choice of model:*
Understand your models, investigate several suitable alternatives.
- *Apply corrections*
Expect data to be unbalanced or non-homogeneous data, know how to handle these data.
- *Expect incomplete data*
Keep up with library developments, as newer versions of scikit learn probably offer better imputer objects for missing data
- *Transfer learning*
Transfer learning does improve the results on small data sets considerably.
- *Optimize the training strategy:*
In this setup, training the whole setup in one go instead of each classifier in parallel could potentially improve the results, but would most certainly also require more powerful hardware

RQB: Given the current state of digitization of cultural artifacts, what results can be expected?

- *Larger data set*
Around 1000 3D-models do not seem to be enough for supervised learning
- *Choose a suitable scanning method for ML from the onset*
While point clouds with tens of thousands points have enough resolution, missing textures certainly are a problem. Therefore 3D-scanning methods that provide a texture should be preferred.