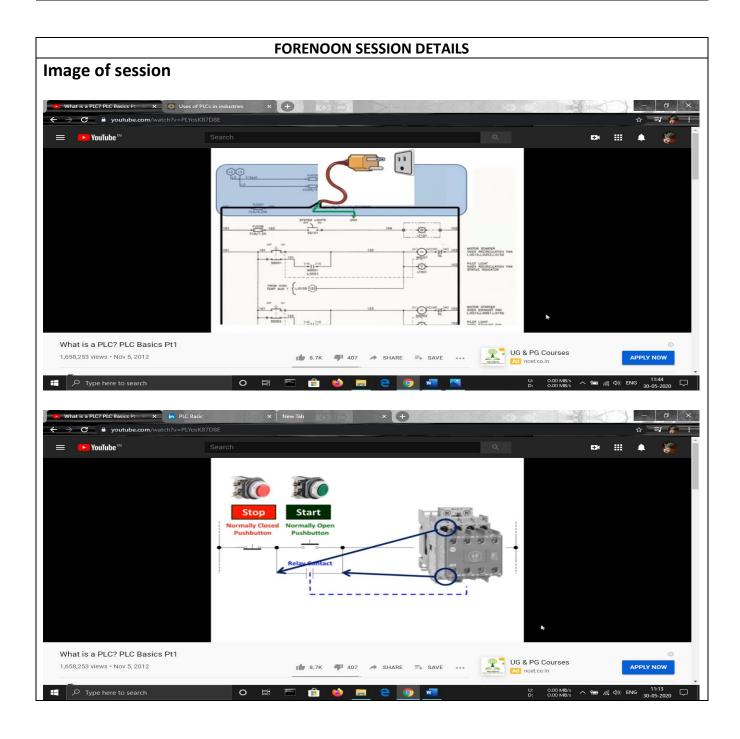
DAILY ASSESSMENT REPORT

Date:	30/05/2020	Name:	Abhishek M Shastry K
Subject:	Logic Design	USN:	4AL17EC002
Topic:	1] Applications of Programmable logic controllers	Semester & Section:	6 th 'A'
Github Repository:	AbhishekShastry-Courses		



Report

Programmable logic controllers

- **PLC** originated in the late 1960s in the automotive industry in the US and were designed to replace relay logic systems.
- **Relays** are switch that open and close circuits electromechanically or electronically. Relays control one electrical circuit by opening and closing contacts in another circuit. As relay diagrams show, when a relay contact is normally open (NO), there is an open contact when the relay is not energized. When a relay contact is Normally Closed (NC), there is a closed contact when the relay is not energized. In either case, applying electrical current to the contacts will change their state.

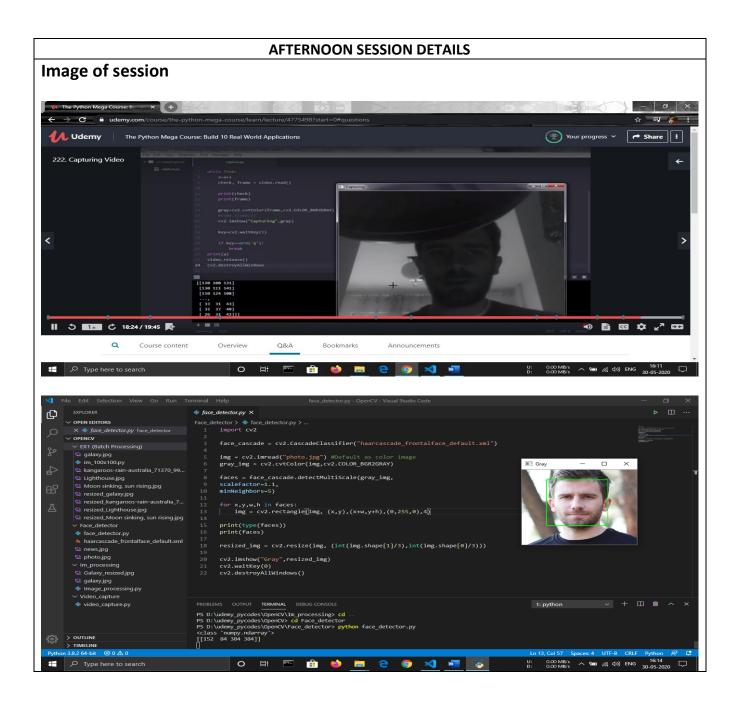


Fig: Electro-mechanical Relay

- A programmable logic controller (PLC) or programmable controller is an industrial digital computer which has been ruggedized and adapted for the control of manufacturing processes, such as assembly lines, or robotic devices, or any activity that requires high reliability, ease of programming and process fault diagnosis.
- PLCs can range from small modular devices with tens of inputs and outputs (I/O), in a housing
 integral with the processor, to large rack-mounted modular devices with a count of thousands
 of I/O, and which are often networked to other PLC and SCADA systems.

- PLCs were first developed in the automobile manufacturing industry to provide flexible, rugged
 and easily programmable controllers to replace hard-wired relay logic systems. Since then,
 they have been widely adopted as high-reliability automation controllers suitable for harsh
 environments.
- A PLC is an example of a "hard" real-time system since output results must be produced in response to input conditions within a limited time, otherwise it will result in unintended operation.
- Regular programmable logic controller consists of:
 - ✓ A processor unit (CPU) which interprets inputs, executes the control program stored in memory and sends output signals.
 - ✓ A power supply unit which converts AC voltage to DC.
 - ✓ A memory unit storing data from inputs and program to be executed by the processor.
 - ✓ An input and output interfaces, where the controller receives and sends data from/to external devices.
 - ✓ A communications interface to receive and transmit data on communication networks from/to remote PLCs.
- Some of the applications of PLC are:
 - ✓ Glass Industry The production of glass is an elaborate and sophisticated process so the companies involved often use PLCs with the bus technology in its control mode. Overall, the PLC is applied in both analogue data recording in the glass production, and in digital quality and position control.
 - ✓ Paper industry In the paper industry, PLCs are used in various processes. These include controlling the machines that produce paper products at high speeds. For instance, a PLC controls and monitors the production of book pages or newspapers in offset web printing.
 - ✓ Cement manufacturing A distributed control system comprised of PLC in its user mode and a configuration software are used in the industry's production and management processes. The PLC in particular, controls ball milling, coal kiln and shaft kiln.

Date:	30/05/2020	Name:	Abhishek M Shastry K
Course:	The Python Mega Course: Build 10 Real World Applications	USN:	4AL17EC002
Topic:	1] Python for Image and Video Processing with OpenCV	Semester & Section:	6 th 'A'
Github Repository:	AbhishekShastry-Courses		



Report

Python for Image and Video Processing with OpenCV

- OpenCV (Open Source Computer Vision Library) is a library of programming functions mainly aimed at real-time computer vision. Originally developed by Intel. The library is cross-platform and free for use under the open-source BSD license. In simple language it is library used for Image Processing. It is mainly used to do all the operation related to Images.
- The images are stored in the form of **n-dimensional numpy array**.
- Some of the functions used for image processing are:
 - ✓ cv2.imread () method loads an image from the specified file.
 - ✓ The shape of an image is accessed by **img.shape**. It returns a tuple of the number of rows, columns, and channels (if the image is color).
 - ✓ Resizing an image means changing the dimensions of it, be it width alone, height alone or both. Also, the aspect ratio of the original image could be preserved in the resized image. To resize an image, OpenCV provides cv2.resize () function.
 - ✓ cv2.imshow () method is used to display an image in a window. The window automatically fits to the image size.
 - ✓ cv2.imwrite () method is used to save an image to any storage device. This will save the
 image according to the specified format in current working directory.
 - ✓ waitKey() is a keyboard binding function. Its argument is the time in milliseconds. The
 function waits for specified milliseconds for any keyboard event. If you press any key in
 that time, the program continues.
 - ✓ destoyAllWindows () function will destroy all of the HighGUI windows.
- Some of the functions used for video capturing are:
 - ✓ cv2.VideoCapture () is used to get a video capture object for the camera.
 - ✓ Video.release () function Closes video file or capturing device.
 - ✓ Videos are captured in terms of frames, the number of frames to be saved can be adjusted using waitKey () function.
- For batch processing of images **glob** library is used which finds all the pathnames matching a specified pattern, although results are returned in arbitrary order in the form of list.