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## → Introduction to Global Positioning:

- Why SBAS? : GNSS Aviation Integrity.
- GNSS is Cornerstone for National.
- Satellite Navigation's Mission SBAS / GBAS implementation.
- Indian Regional Navigation Satellite System (IRNSS)

## Brief History of Navigation:

- Landmark based navigation: Stones - Trees - Mountains (local use).
- Celestial Navigation: OK for latitude, poor for longitude until accurate clock invented ~ 1760
- 13<sup>th</sup> Century: Magnetic Compass.
- 1907: Gyrocompass.
- 1912: Radio Direction Finding.
- 1930's: Radar and Inertial Nav.

## • Precise point Positioning:

- The Automatic Precise Positioning Service (APPS)
- Leica CSmartLink (worldwide correction service)
- RTX services by Trimble.

- Satellite Based Augmentation System:
- The Role of the Geostationary Satellite.
- Long term (2020-25) plan - Global SBAS.



- Satellite Navigation:

- Global:

- GLONASS.

→ BEIDOU.

→ GALILEO.

- Regional:

- IRNSS

→  $\phi_{ZSS}$

- The GPS / GLONASS / Galileo:

- Develop by the US DOD/USSR/EU.

→ Provides. - Position, Velocity, Time.

→ WGS84: Parameter Zenith (990 (PZ-90.11))

→ Designed to replace existing navigation systems

→ Accessible by civil & military.

- Program Description:

- The next generation GPS III/GPS IV.

- GPS signal Structure:

→ Each GPS satellite transmits a number of signals.



• Bandwidth allocated for L1-24MHz, L2-22MHz, L5-28MHz.

• The signal comprises two UHF carrier and two codes as low power radio signals as well as a satellite orbit message.

• GLONASS fundamental frequency is 5.0MHz.

• Except from Global Positioning System (GPS) Standard Positioning Service.

• Receivers: → Single Frequency.  
→ Dual & Multi-Frequency.

• 3 Classes of GPS receivers.

• Geodetic class:

• Mapping grade:

• Navigation.

• GPS Surveying Techniques:

→ Static:

→ Rapid Static / Fast static.

→ Stop and Go.

→ Kinematic.

→ Differential GPS.

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• Principle of Differential - GPS / GNSS.

• Stereo Vision / Stereo plotting.

• Steps in photogrammetry.