

DAILY ASSESSMENT FORMAT

Date:	22-05-2020	Name:	BINDUSHRI
Course:	TCSion	USN:	4AL17EC011
Topic:	1.Artificial intelligence part 1 & 2 2.certificate	Semester & Section:	6th A
Github Repository:	Bindushri		

FORENOON SESSION DETAILS

Digital Learning
Empowering Learning Outcomes

Bindu

✕

ITEMS

Learn Telephone

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Career Edge - Knockdown the Lockdown : Batch 01

95.21%

Final Assessment

Total Marks

30.0

Pass Marks

18.0

Attempts Taken

01

Duration

30 Mins

Start Time

16 May 2020 12:00 AM

TO

15 Jul 2020 12:00 AM

View Assessment Analysis Already cleared

At the End of Assessment assessment.

My Attempts

Attempted On	Attempted Duration (Submission Time)	Marks Obtained	Status	Action
22 May 2020 11:40 AM	0:28:32 Hrs(12:09 PM)	24.0/30.0	Pass	-

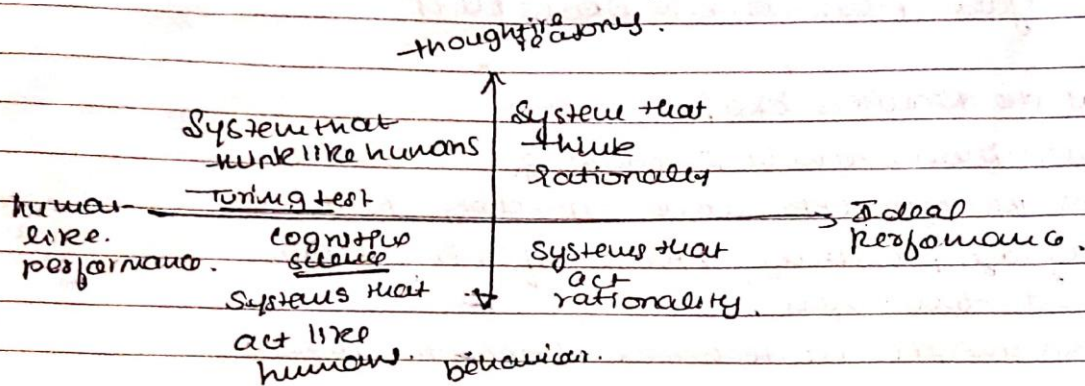
22-05-2020 .

Day 13: Artificial Intelligence - Part 1

- understand the role of basic
- Knowledge of representation
- Problem solving

* Assess the applicability, strength & weakness

* Artificial Intelligence: is concerned with the design of intelligence in an artificial device



Basic Intelligence behaviour

- 1) Perception 2) Reasoning 3) Learning 4) Solving Problem 5) Understand the language

Application ~~for~~ Robotics, Image Recognition

Day 14: Artificial Intelligence - Part 2

* Agent: operates in an environment. receives percepts from environment and its action can change the environment.

~~Agent~~ Agent has actuators or effectors to take the actions also have the sensor to sense the change in environment

* Action conscious agent decides automatically which measure its performance is maximum

Task Mapping:

Types of agent: 1) Software 2) Expert Systems
3) Autonomous Spacecraft 4) Intelligent Building

Determinism Environment

1) Deterministic. 2) Stochastic 3) Strategic
4) Episodic / Sequential.

Table based agent :- Simple way to specify a mapping from percept to action.

* Tables may become very large.

* Mapping is implicitly defined by program

1) Rule Based 2) Neural networks 3) Algorithms

State-based agent :- Information comes from sensors - percepts

changes the agent's current to the state of world

Summary: An agent program maps from percepts to action & updates its internal state

This is to certify that
Bindu shri
has successfully completed
Career Edge - Knockdown the Lockdown
online course offered by TCS iON

Start Date: 16 May 2020 | End Date: 22 May 2020

Topics:

- Communication Skills ■ Presentation Skills ■ Soft Skills ■ Career Guidance Framework ■ Resume Writing
- Group Discussion Skills ■ Interview Skills ■ Business Etiquette ■ Effective Email Writing ■ Telephone Etiquette
- Accounting Fundamentals ■ IT Foundational Skills ■ Overview of Artificial Intelligence* (Source: NPTEL)



Mehul Mehta

Mehul Mehta
Global Delivery Head, TCS iON

Date:22may2020
Course: python
Topic:
Basics:sec16-17

Name:Bindushri
USN:4AL17EC011
Sem&Sec:6th A

AFTERNOON SESSION DETAILS

Image of session

Overview

Q&A

Notes

Announcements

Course content

- ☐ 123. Convert Images to Numpy Arrays
6min [Resource](#)
- ☐ 124. Indexing, Slicing, and Iterating Numpy Arrays
4min
- ☐ 125. Stacking and Splitting Numpy Arrays
6min

Section 17: Application 2: Create Webmaps with Python and Folium

0 / 16 | 1hr 20min

Section 18: Fixing Programming Errors

0 / 6 | 39min

Section 19: Application 3: Build a Website Blocker

0 / 10 | 1hr 20min

Section 20: Application 4: Build a Personal

22-05-2020 .

classmate

Date
Page

Section 16: numpy

* to install numpy

→ Precompiled Extension package of python
→ `numpy-1.11.0+mk1-cp35-cp35m-win_amd64.whl`

* In [1]: `import numpy`

→ `n = numpy.arange(27)`

In [2]: `type(n)`

Out[2]: `numpy.ndarray`

In [2]: `print(n)`

0 → [0 1 2 26]

→ In order to get 2-dimensional array

In [3]: `n.reshape(3,9)`

o/p. array ([0, 1, ..., 6],
[9, ..., 17],
[18, ..., 26])

→ In order to get 3-dimensional array.

In [5]: `n.reshape(3,3,3)`

array ([[0, 1, 2],
[3, 4, 5],
[6, 7, 8]],

[[9, 10, 11],
[12, 13, 14],
[15, 16, 17]],

[[18, 19, 20],
[21, 22, 23],
[24, 25, 26]])

Installing opencv :- pip install opencv-python

* Converting Images to Numpy Arrays

In[2]: Import cv2

In[]: img = cv2.imread("smallogray.png", 0)
img

also can
change
to 1
we get
3 dimension
array of
img

Out : array([[187, 158, 104, 121, 143],
[198, 128, 255, 255, 141],
[209, 134, 255, 97, 182]], dtype=uint8)

In[]: cv2.imwrite("newsmallogray.png", img)

Out → true

→ Indexing, Slicing and Iterating Numpy Arrays

In[39]: img[0:2, 2:4]

Out[39]: array([[104, 121],
[255, 255]], dtype=uint8)

How to Iterate values by values

In[47]: for i in img.flat:
print(i)

Out 187
158
104
121
.
.
.
182

Section 17

Application: Create webmaps with python and folium.

~~* map has built using python library~~

✓ to build map in python (map1.html)

Methods:

[Create folder → mapping → and open
atom .vscode. ~~atom~~ → open terminal
→ pip install folium. → pip install pip2]

~~>>> python~~

>>> import folium

>>> map = folium.map(location=[80, -100])

>>> map

>>> map.save("map1.html")

cofo :- (this creates the map.?)

note: ~~tileset~~ = "MapboxBright"

→ tiles = "stamen-terrain"

these are two types of basemaps but
mapbox bright doesn't work anymore
stamen terrain works great

* Adding points to map

✓ map1.py → folder. ~~for~~ mapping.

1. `import folium`
2. `map = folium.Map(location = [38.58, -99.09], zoom_start = 6, tiles = "Mapbox Bright")`
3. `map.save("map1.html")`

How to add elements to the map then.

```
map.add_child(folium.Marker(location=[38.2, -99.1],
                             popup="HP I am a Marker",
                             icon=folium.Icon(color='green')))
```

O/P :- ~~check~~ popup the ~~map~~ ~~your~~ ~~map~~ window
 shows the ~~of~~ location of your place with
 "HP I am a Marker" PS printed.]

1. `import folium`
2. `map = folium.Map(location = [38.58, -99.09], zoom_start = 6, tiles = "Mapbox Bright")`
3. `fg = folium.FeatureGroup(name = "my map")`
4. `fg.add_child(folium.Marker(location = [38.2, -99.1], popup = "HP I am a Marker", icon = folium.Icon(color = 'green')))`

can also
write this
line
multiple
times
with
changing
location
values

5. `map.add_child(fg)`
6. `map.save("map1.html")`

Adding multiple points

this is adding a for loop before the line 4.

Mapping → (volcano.txt) → Extract data. under (map.py)

↓
Loading ~~multiple~~ points from the file:

>>> pip install pandas

>>> import pandas

>>> data = pandas.read_csv("volcanoes.txt")

>>> data.

→ (produces the o/p)

>>> data.columns

>>> lat = list(data["LAT"])

>>> lon

code

1. import folium
2. import pandas.
3. data = pandas.read_csv("volcanoes.txt")
4. lat = list(data["LAT"])
5. lon = list(data["LON"])
6. elev = list(data["ELEV"])
7. map = folium.Map(location = [38.58, -99.09],
Zoom_start = 6, tiles = "Mapbox Bright")
8. fg = folium.FeatureGroup(name = "my map")
9. for lt, ln, elev in zip(lat, lon, elev):
fg.add_child(folium.Marker(location =
[lt, ln], popup = str(elev) + "m",
folium.Icon(color = 'green')))
10. map.add_child(fg)
11. map.save("map.html")

Color points

import folium

import pandas

data = pandas.read_csv("volcanoes.txt")

lat = 187 (data["LAT"])

lon = 187 (data["LON"])

elev = 187 (data["ELEV"])

def color_producer (elevation):

if elevation < 1000:

return 'green'

elif 1000 <= elevation < 3000:

return 'orange'

else:

return 'red'

map = folium.map [location=[38.58, -99.09],
zoom_start=6, tiles="mapbox Bright"]

fg = folium.FeatureGroup (name="my map")

for lt, ln, el in zip (lat, lon, elev):

fg.add_child (folium.marker (location=
[lt, ln], popup=str(el)+"m", icon=
folium.Icon (color_producer (el)))

map.add_child (fg)

map.save ("map1.html")

