Aug 11
2020

Rashmi
4ALI8EC043

Self driving car.

<u>Report</u> –

* This week, you will learn about how
  lateral vechical

* Control ensures that a fixed path through
  the environment

* Tracked accurately you will see how
  to define

* Geometry of the path following of
  control problems

* And develop both a simple geometric
  control and dynamic model.

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Sales for

Report -

* The customer 360 platform, intergrated sower make your comtomize

* Application lifestyle & developments of models

* changing bit development plan for changes

* Use package development for more flexible

* learning objects

* Indentifying the key.