

Aug -10
2020

Date
Page No.

Rashmi
HAL18EC043

Self driving car

Report

Vehicle longitudinal control
→ proportional - integral - Derivative

Lesson 1 : proportional - integral, derivative

Supplementary reading

Lesson 2 : longitudinal Speed control

Lesson 3 : feedforward Speed control

Supplementary reading

Lesson from industry Expert -
=> 200 x'p approach to self
driving car.

Aug 10
2020

Date
Page No.

Rashmi, K

4AL18EC043

Salesforce

Report-

- * Create a functional project plan
- * create a functional check list
 - * Learning Objectives
 - * Introduction
- * E commerce business activities
- * create a architecture diagram
- * create a button and an action
- * Improve the user experience
- * Learn the basic of interface
- * manage the launch and post launch