

Trabajo Fin de Máster Máster en Ingeniería Electrónica, Robótica y Automática

Aerial co-workers: a task planning approach for multi-drone teams supporting inspection operations

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Sevilla, 2021



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El tribunal nombrado para juzgar el trabajo arriba indicado, compuesto por los siguientes profesores:

Presidente:

Vocal/es:

Secretario:

acuerdan otorgarle la calificación de:

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Abstract

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Short Outline

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1 Introduction

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1.1 Motivation

1.2 Objectives

Hypothesis 1.2.1 *"Dos Single Event Upset (SEU) próximos entre sí provocarán patrones de error similares a la salida".*

2 State of the art

2.1 Task planning in multi-drone teams

2.2 Drone behavior management

2.2.1 Finite state machines

2.2.2 Behaviour Trees

3 Problem Description

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4 Design of the proposed solution

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5 Conclusions and future work

5.1 Conclusions

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Glossary

SEU Single Event Upset. 1