Trabajo Fin de Máster
Máster en Ingeniería Electrónica, Robótica y Automática

Aerial co-workers: a task planning approach for multi-drone teams supporting inspection operations

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El tribunal nombrado para juzgar el trabajo arriba indicado, compuesto por los siguientes profesores:

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Abstract

Lorem itsum This Master's Thesis has faced problems that arise from the recent increase in the applications of cooperative UAV teams, which are the autonomy to operate for a long time with robustness in the face of possible failures, and the difficulty of providing the team with capabilities cognitive skills to be able to operate in dynamic environments with humans.

Short Outline

Abstract III
Short Outline V

1 Introduction **1**
1.1 Motivation 1
1.2 Objectives 1

2 Preliminaries **3**
2.1 Current technology 3
2.2 Related work 3
2.3 Tools 3

3 Problem Formulation **5**
3.1 Description of tasks 5
3.2 Battery recharges 5
3.3 Connection losses 5
3.4 Task replanning situations 5

4 Design of the proposed solution **7**
4.1 Node diagram 7
4.2 Centralized module: task planner 7
4.3 Distributed module: behavior manager 7
4.4 Lower and upper level modules faker 7

5 Results **9**
5.1 Task planning 9
5.2 Drone behaviour manager results 9
5.3 Simulations 9

6 Conclusions and future work **11**
6.1 Conclusions 11
6.2 Future work 11

List of Figures 13
List of Tables 15

List of Codes 17
Bibliography 19
Index 23
Glossary 23

Contents

Abstract III
Short Outline V

1 Introduction **1**
1.1 Motivation 1
1.2 Objectives 1

2 Preliminaries **3**
2.1 Current technology 3
2.1.1 UAVs 3
2.1.2 Aerial co-workers 3
2.1.3 Multi-drone teams 3
2.2 Related work 3
2.2.1 Inspection applications with UAVs 3
2.2.2 Task planning in multi-drone teams 3
2.2.3 Drone behavior management 3
2.3 Tools 3
2.3.1 ROS 3
2.3.2 Gazebo 3
2.3.3 Rviz 3
2.3.4 UAL 3
2.3.5 Behaviour Trees 3
2.3.6 Groot 3

3 Problem Formulation **5**
3.1 Description of tasks 5
3.1.1 Inspection tasks 5
3.1.2 Monitoring tasks 5
3.1.3 Tool delivery tasks 5
3.2 Battery recharges 5
3.3 Connection losses 5
3.4 Task replanning situations 5

4 Design of the proposed solution **7**
4.1 Node diagram 7
4.2 Centralized module: task planner 7

4.3 Distributed module: behavior manager 7
4.3.1 Main tree 7
4.3.2 Inspection task tree 7
4.3.3 Monitoring task tree 7
4.3.4 Tool delivery task tree 7
4.4 Lower and upper level modules faker 7

5 Results 9
5.1 Task planning 9
5.1.1 Battery 9
5.1.2 Connection lost 9
5.1.3 Replanning 9
5.2 Drone behaviour manager results 9
5.2.1 Battery management 9
5.2.2 Connection lost management 9
5.2.3 Replanning management 9
5.3 Simulations 9
5.3.1 One drone simulations 9
5.3.2 Multi-drone simulations 9

6 Conclusions and future work 11
6.1 Conclusions 11
6.2 Future work 11
6.2.1 Augmented reality 11

List of Figures 13
List of Tables 15
List of Codes 17
Bibliography 19
Index 23
Glossary 23

1 Introduction

Lorem itsum

1.1 Motivation

1.2 Objectives

2 Preliminaries

Lorem itsum

2.1 Current technology

2.1.1 UAVs

2.1.2 Aerial co-workers

2.1.3 Multi-drone teams

2.2 Related work

2.2.1 Inspection applications with UAVs

2.2.2 Task planning in multi-drone teams

2.2.3 Drone behavior management

2.3 Tools

2.3.1 ROS

2.3.2 Gazebo

2.3.3 Rviz

2.3.4 UAL

2.3.5 Behaviour Trees

2.3.6 Groot

3 Problem Formulation

Lorem itsum

3.1 Description of tasks

3.1.1 Inspection tasks

3.1.2 Monitoring tasks

3.1.3 Tool delivery tasks

3.2 Battery recharges

3.3 Connection losses

3.4 Task replanning situations

4 Design of the proposed solution

Lorem itsum

4.1 Node diagram

4.2 Centralized module: task planner

4.3 Distributed module: behavior manager

4.3.1 Main tree

4.3.2 Inspection task tree

4.3.3 Monitoring task tree

4.3.4 Tool delivery task tree

4.4 Lower and upper level modules faker

5 Results

Lorem itsum

5.1 Task planning

5.1.1 Battery

5.1.2 Connection lost

5.1.3 Replanning

5.2 Drone behaviour manager results

5.2.1 Battery management

5.2.2 Connection lost management

5.2.3 Replanning management

5.3 Simulations

5.3.1 One drone simulations

5.3.2 Multi-drone simulations

6 Conclusions and future work

6.1 Conclusions

6.2 Future work

6.2.1 Augmented reality

List of Figures

List of Tables

List of Codes

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