1시간민에 GAN 완전 정복하기(Generative Adversarial Network)

https://www.youtube.com/watch?v=odpjk7_tGY0&ab_channel=naverd2

① Branches of MI

Supervised Learning	UnSupervised Learnin	Semi-supervised Lear ning	Reinforcement Learni ng
The discriminative model learns how to classify input to its class. → Fully labelled	The generative learns the dis tribution of training data. → No labelled	When there is not enough I abeled data, the performanc e of supervised learning can be further improved by lear ning using unlabeled data. = Supervised Learning + Un	Reinforcement learning (RL) i s an area of machine learnin g concerned with how softw are agents ought to take acti ons in an environment in ord er to maximize the notion of cumulative reward.
= Discriminative Model	= Generative Model	supervised Learning	

+) Weakly-supervised(self-training): Start with a small number of samples, create a classifier, predict a positive example, label it, and retrain to grow the classifier.(Unlabeled)

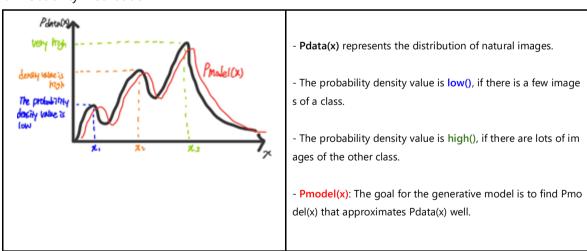
https://medium.com/@kabbi159/semi-supervised-learning-%EC%A0%95%EB%A6%AC-a7ed58a8f023

https://hoya012.github.io/blog/Self-Supervised-Learning-Overview/

https://blog.lunit.io/2019/04/25/ficklenetweakly-and-semi-supervised-semantic-image-segmentation-using-stochastic-inference

e/

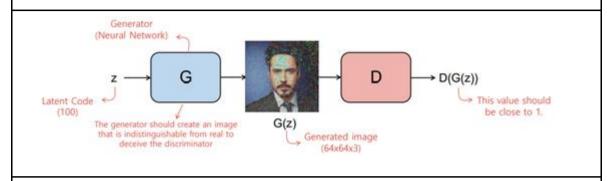
② Probability Distribution



③ Intuition GAN

- 1) First, the discriminator model trains a real image. The D(x) has a value, which is the probability of that x ca me from the real data(0~1).
- 2) The discriminator(Neural Network) should classify a real image as real. The value of D(x) should be close t o 1.

3) When a fake image is generated by the generator, the discriminator should classify a fake image as fake. T he value of D(x) should be close to 0.



4) The generator should create an image that is indistinguishable from real to deceive the discrimi nator. It is a goal that makes value close to 1 like above.

https://m.blog.naver.com/euleekwon/221557899873

https://yamalab.tistory.com/98


```
import torch import torch.nn as nn
```

Discriminator

```
D = nn.Sequential(
nn.Linear(784, 128),
nn.ReLU(),
nn.Linear(128, 1),
nn.Sigmoid())
```

Generative

```
G = nn.Sequential(
nn.Linear(100, 128),
nn.ReLU(),
nn.Linear(128, 784),
nn.Tanh())
```

BinaryCrossEntorpyLoss(h(x),y) = -ylogh(x) - (1-y)log(1-h(x)) criterion = nn.BCELoss()

There is a conflict when d and g are learning, so they must by optimized separately

```
d optimizer = torch.optim.Adam(D.parameters(), Ir=0.01)
q optimizer = torch.optim.Adam(G.parameters(), Ir=0.01)
# Assume x be real images of shape(batch size, 784)
# Assume z be random noise of shape(batch_size, 100)
while True:
  # train D
 loss = criterion(D(x), 1) + criterion(D(G(z)), 0)
  loss.backward()
                                # Gradient value are calculated over all weights
  d_optimizer.step()
                                # Leaning the AdamOptim Gradient previously defined
                                # to minimize the loss(True is close to 1/ Fake is close to 0)
  # train G
  loss = criterion(D(G(z)), 1)
                                # Creating fake images: When the generated fake
                                # images are put in D, loss.backward() it is learned
                                # and calculated to be close to 1.
  g_optimizer.step()
                                # Learn only the parameter for G for the
                                # parameters to be learned.
```

Based on tensorflow: https://m.blog.naver.com/PostView.nhn?blogId=euleekwon&logNo=221560040601&targetKeyword=&tar

getRecommendationCode=1

Based on keras: https://yamalab.tistory.com/98

+) Variants of GAN: DCGAN, LSGAN, SGAN, ACCGAN and so on...

+) Extension of GAN: CycleGAN, stackGAN, StyleGAn and so on...

 $\underline{\text{https://www.youtube.com/watch?v=odpjk7_tGY0\&ab_channel=naverd2}}$

https://github.com/yunjey

https://medium.com/@kabbi159/semi-supervised-learning-%EC%A0%95%EB%A6%AC-a7ed58a8f023

[Additional]

⑤ Adam(Adaptive Moment Estimation) optimizer

: It is an algorithm like the combination of RMSProp and Momentum method, and has the advantage t hat stepsize is not affected by gradient rescalling. Even if the gradient increases, the stepsize is bound, so it is possible to stably descend for optimization no matter what objective function is used.

- Adaptive Gradient Algorithm(AdaGrad) that maintains a per-parameter learning rate that improves performance on problems with sparse gradients.
- Root Mean Square Propagation(RMSProp) that also maintains per-parameter learning rates th
 at are adapted based on the average of recent magnitudes of the gradients for the weight(e.g.
 how quickly it is changing). This means the algorithm does well on online and non-stationary
 problems(e.g. noisy).

- Benefits of using Adam on non-convex optimization problems
 - Straightforward to implement
 - Computationally efficient
 - Little memory requirement
 - Invariant to diagonal rescale of the gradients
 - Well suited for problems that are large in terms of data and/or parameters
 - Appropriate for problems with very noisy/or sparse gradients
 - · Hyper-parameters have intuitive interpretation and typically require little tuning

https://machinelearningmastery.com/adam-optimization-algorithm-for-deep-learning/

Focus on equation https://mjgim.me/2018/01/22/adam.html

Paper Review https://dalpo0814.tistory.com/29

Gradient Descent Optimization Algorithms http://shuuki4.github.io/deep%20learning/2016/05/20/Gradient-Descent-Algorithm-

Overview.html