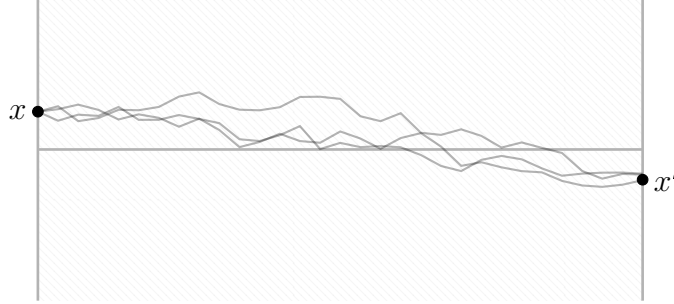


NOTES ON QFT

ALEXEI LATYNTSEV

2. Brownian motion as summing over paths



One can think of Brownian motion on X as a one-dimension quantum field theory. Given a point $x \in X$ (think of it as being a particle at x), the probability of it moving to point x' after time t is

$$\mathbf{P}(x \rightarrow x') = \frac{\#\{\text{Brownian walks } x \rightarrow x'\}}{\#\{\text{Brownian walks } x \rightarrow ?\}}.$$

In the discrete setting where X is a weighted graph, this formula is literally correct, and if X is a Riemannian manifold we need to replace each count by an integral over paths, and replace x' by an arbitrary measurable subset.

In the above case, the probability is a normal distribution with mean x and variance t .

2.1. The general structure of the above is we have a correspondence

$$\begin{array}{ccc} & \{\text{paths } [0, t] \xrightarrow{\gamma} X\} & \\ \text{Res}_0 \swarrow & & \searrow \text{Res}_t \\ X & & X \end{array}$$

of measurable spaces, with relative measures on the restriction maps given in this case by the Brownian motion measure. Calling these correspondences C'_{t_1, t_2} , we require them to be compatible in the obvious sense. This allows us to push-and-pull functions,

$$\begin{array}{ccc} & \mathcal{O}(\text{Maps}([0, 1], X)) & \\ \text{Res}_0^* \nearrow & & \searrow \int_{\text{Res}_t} \\ \mathcal{O}(X) & \xrightarrow{\mathcal{Z}_t} & \mathcal{O}(X) \end{array}$$

and the compatibility condition thus gives us an action of $\mathbf{R}_{\geq 0}$ on $\mathcal{O}(X)$.¹ If we impose enough smoothness requirements, it must take the form $\mathcal{Z}_t = e^{Ht}$ for an endomorphism H of $\mathcal{O}(X)$.

¹This includes the condition that $\mathcal{Z}_0 = \text{id}$ and that $\mathcal{Z}_{t+t'} = \mathcal{Z}_t \cdot \mathcal{Z}_{t'}$.

2.1.1. In the above context, it might be useful to think of functions $f \in \mathcal{O}(X)$ also as “random points on X ” if they have norm one, or as “the wavefunction of a particle on X ”. If we work with a function space that contains the Dirac delta δ_x , this should be thought of as a non-random point, although typically applying \mathcal{Z}_t will not give back a delta function.

2.1.2. We can write the above definition in symbols as

$$\mathcal{Z}_t : f \mapsto \int_{\text{Res}_0^{-1}(f)} \Psi d\mathcal{B}$$

where \mathcal{B} is the Brownian measure on the set of paths and we have integrated along the fibres of Res_t . In other words, the coefficient of an element $\alpha \in \mathcal{O}(X)^*$ in the above is

$$\langle \alpha, \mathcal{Z}_t f \rangle = \int_{\Psi : \Psi|_0 = f} \langle \alpha, \Psi|_t \rangle d\mathcal{B}.$$

2.2. The compatibility condition between the correspondences is that we have a pullback

$$\begin{array}{ccccc} & & (C_{t_1, t_3}, d\mathcal{B}_{t_1, t_3}) & & \\ & \swarrow & & \searrow & \\ (C_{t_1, t_2}, d\mathcal{B}_{t_1, t_3}) & & & & (C_{t_2, t_3}, d\mathcal{B}_{t_2, t_3}) \\ \swarrow & & \searrow & \swarrow & \searrow \\ X & & X & & X \end{array}$$

of measure spaces. In other words, the Brownian measure is compatible under cutting up of the time interval; this is also called the *Markov* property of the measure.

Thus if we modify the measure to $e^S d\mathcal{B}$, it is consistent in the above sense if and only if the function

$$S_{0,t} \in \mathcal{O}(\text{Maps}([0, t], X))$$

is memoryless, i.e. satisfies the cocycle condition

$$S_{t_1, t_3} = S_{t_1, t_2} + S_{t_2, t_3}$$

where all three are viewed as functions on $\text{Maps}([t_1, t_3], X)$ by restriction. The set of such functions (modulo functions supported on the measure zero set $\{t_2\} \times X$) is closed under addition and multiplication.

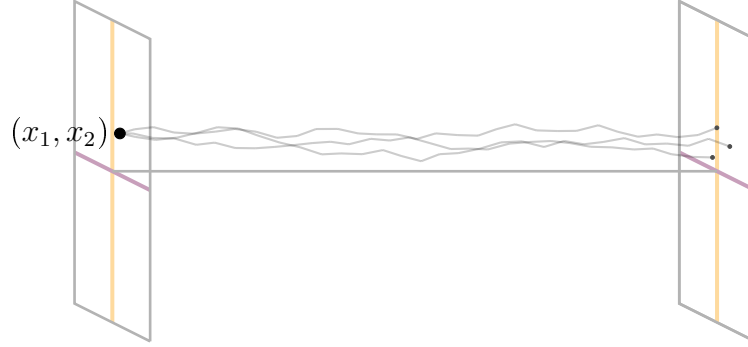
For instance, we may take a function $s \in \mathcal{O}(X)$ and integrate it over $[0, t]$ to get a function $S_{0,t}(\gamma) = \int_{[0,t]} \gamma^* s$ on the path space. Taking the constant function gives for instance $S_{0,t}(\gamma) = kt$. We could also take a covector field $\xi \in \mathcal{O}(T^*X)$ and evaluate it on the derivative of the path to get $S_{0,t}(\gamma) = \int_{[0,t]} \langle \xi, d\gamma \rangle$. Taking higher order differential forms gives more examples. A non-example is evaluating the path at a particular point.

A popular choice is

$$S_{0,t}(\gamma) = \int_{[0,t]} (\gamma', \gamma') dt$$

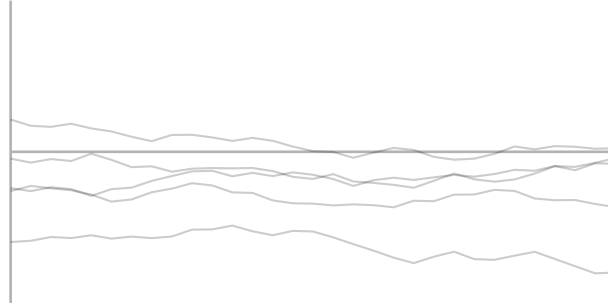
where we have used the Riemannian metric on X .

2.3. There are variants one could consider. For instance, one could consider *coloured* points on X , which is then equivalent to Brownian motion on $X^{\# \text{colours}}$,



If we want to allow the colours to interact, then we need to change the metric on $X^{\# \text{colours}}$, adding off-diagonal terms. This will mean the Laplacian and hence Brownian motion will have off-diagonal terms.

2.3.1. Another variant is Brownian motion with drift. If a random sample of paths with respect to the Brownian motion measure looks like



then Brownian motion with drift will look like



The Brownian motion with drift \mathcal{D} satisfies the following stochastic differential equation:

$$d\mathcal{D} = d\mathcal{B} + k dt$$

where real number k is the drift term. Or, viewing \mathcal{D} and \mathcal{B} as random paths $[0, t] \rightarrow X$, we have

$$\mathcal{D} = \mathcal{B} + k t.$$

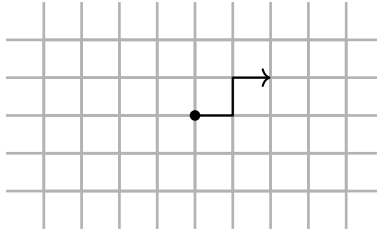
On a general space X with one parameter family of automorphisms $\varphi_t = e^{tv}$ where here v is a vector field on X , we can likewise define Brownian motion with drift as

$$\mathcal{D}_t = \varphi_t^* \mathcal{B}_t.$$

Taking the translation vector field on the real line gives back ordinary Brownian motion with drift. We can view the above as changing the projection map:

$$\begin{array}{ccc} & \{\text{paths } [0, t] \xrightarrow{\gamma} X\} & \\ \text{Res}_0 \swarrow & & \searrow \varphi_t \cdot \text{Res}_t \\ X & & X \end{array} \quad (1)$$

2.3.2. Brownian motion on \mathbf{R}^n are a limit of random walks on $r\mathbf{Z}^n$, taking the limit $r \rightarrow 0$.

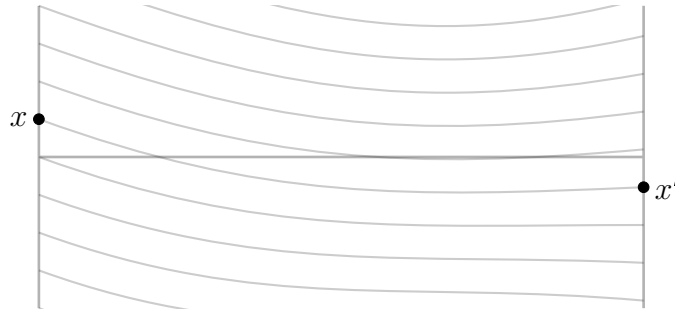


If we use discrete time, we can replace $X = \mathbf{Z}^n$ with any Markov chain, and define $\mathcal{Z}_t = P^t$ in terms of the Markov transition matrix P . We do not know how to pass to continuous time by taking limits in this general case.

2.3.3. In dynamical systems or ergodic theory, one often considers one-parameter families of automorphisms $\Phi_t : X \xrightarrow{\sim} X$. This gives a map

$$X \rightarrow \text{Maps}([0, t], X)$$

and we can take the pushforward of the usual measure. In other words, given an initial starting point x the only point with nonzero probability it goes to is $\Phi_t(x)$.



Or in the previous notation, the only path γ restricting at 0 to x is the path $\gamma(-) = \Phi_-(x)$,

$$\begin{array}{ccc} & \gamma & \\ \swarrow & & \searrow \\ x & & \Phi_t(x) \end{array}$$

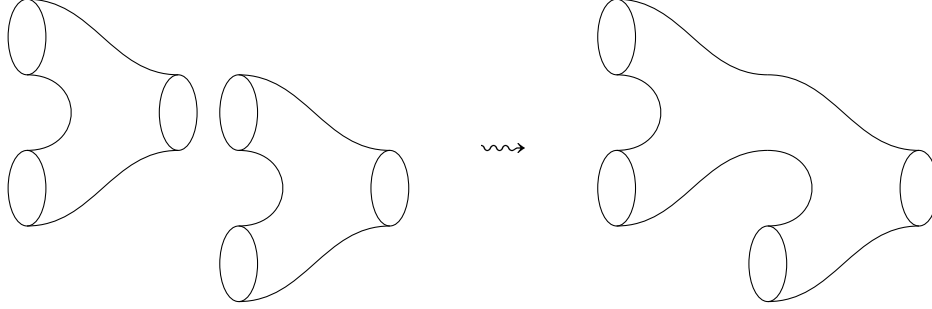
Thus this is a “classical” example. To get non-classical examples, one needs to consider *random* dynamical systems, see for instance [Ar].

3. Two dimensions

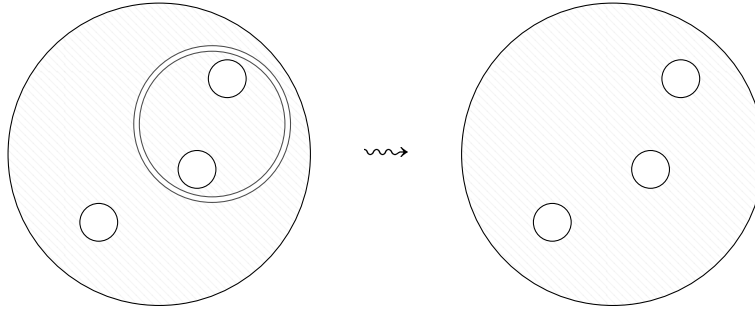
We now replace $[0, t]$ with a two-dimensional surface Σ , i.e. consider two-dimensional quantum field theories. Thus we consider “particles on two-dimensional spacetime”. The Markov compatibility condition, which previously had to do with gluing intervals:



will now be replaced with the Markov *domain* property, which has to do with gluing surfaces:



or in other words, it is a Markov property for splitting up a region using codimension one walls:



The basic example is the Gaussian free field. [\(explain\)](#)

3.1. The general structure is [\(cobordism stuff\)](#)

3.2. We now consider variants.

3.2.1. What is the two-dimensional analogue of Brownian motion with drift? To begin with we need to understand the role of $\mathbf{R}_{\geq 0}$ in the one-dimensional case: we identify it as

$$\mathbf{R}_{\geq 0} \simeq \text{Hom}_{\text{Cob}_1}(\text{pt}, \text{pt}) = \text{Cob}_1(\text{pt}, \text{pt}).$$

Thus, in line with (1) given a functor $F : \text{Cob}_1 \rightarrow \text{Sp}^\mu$ out from Cob_1 to the category of spaces equipped with a measure, for each correspondence

$$\begin{array}{ccc} & C \simeq [t_1, t_2] & \\ \nearrow & & \nwarrow \\ \{t_1\} & & \{t_2\} \end{array}$$

we can ask for an action $\varphi_C : F(\{t_2\}) \rightarrow F(\{t_2\})$. In the case of Brownian motion with drift this will be just be $\varphi_{t_2-t_1}$. We want this to be compatible in the the sense that the composition (pullback) of

$$\begin{array}{ccccc} & F(C) & & F(C') & \\ \text{Res}_{t_1} \swarrow & & \xrightarrow{\varphi_C \cdot \text{Res}_{t_2}} & & \searrow \varphi_{C'} \cdot \text{Res}_{t_3} \\ \{t_1\} & & \{t_2\} & & \{t_3\} \end{array}$$

is equal to

$$\begin{array}{ccc} & F(C \sqcup \{t_2\} C') & \\ \text{Res}_{t_1} \swarrow & & \searrow \varphi_{C \sqcup \{t_2\} C'} \cdot \text{Res}_{t_3} \\ \{t_1\} & & \{t_3\} \end{array}$$

In other words, whenever C, C' are composable cobordisms (this is always true in the one dimensional case), we have the cocycle condition

$$\varphi_{C \cup C'} = \varphi_C \cdot \varphi_{C'}.$$

Equivalently, note that Mor Cob_1 is a groupoid over Cob_1 , i.e. we have head and tail maps

$$\begin{array}{ccc} & \text{Mor Cob}_1 & \\ & \swarrow \quad \searrow & \\ \text{Cob}_1 & & \text{Cob}_1 \end{array}$$

and φ may be viewed as an action of this groupoid on F . (write details)

3.2.2. In particular, in the two-dimensional case we will need an action of (write explicitly)

As a consequence, we can ask for an action of the semigroup \mathcal{A} of parametrised annuli (or, monoid of thin annuli) on $F(S^1)$. To be explicit, it is

$$\mathcal{A} = \{A \subseteq \mathbf{C} \text{ an annulus, } S^1 \sqcup S^1 \xrightarrow{\sim} \partial A\} / \Delta S^1,$$

see [Se], which as a topological space is homeomorphic to

$$\mathcal{A} \simeq (0, 1) \times (\text{Aut}^+(S^1) \times \text{Aut}^+(S^1)) / \Delta S^1,$$

given by the ratio of the two annulus radii, and automorphisms of the parametrisations. For thin annuli, we (presumably) use $\mathbf{R}_{\geq 0}$ instead of $(0, 1)$. One step up, for each pair of Riemannian pants we have an action on $F(S^1)$, and this action is compatible with the semigroup of annuli action. Likewise we have compatible data for other surfaces.

(maybe we want to act on $F(S^1 \sqcup S^1)$ also?)

3.2.3. What is the two-dimensional analogue of Markov chains?

For ordinary Markov chains, we use that $r\mathbf{N}$ is a discrete analogue of $\mathbf{R}_{\geq 0}$, which in some sense converges to $\mathbf{R}_{\geq 0}$ as $r \rightarrow 0$. Thus, we need to construct a discrete analogue of the category of cobordisms. (or something like that?)

To begin with, we find a discrete analogue of \mathcal{A} . We have $r \cdot \mathbf{N}_{\geq 0}$ a discrete analogue of $\mathbf{R}_{\geq 0}$, and a discrete analogue of $\text{Aut}^+(S^1)$ is (what? use the root lattice of $\mathfrak{aut}^+(S^1)$ and exponentiate it) This is

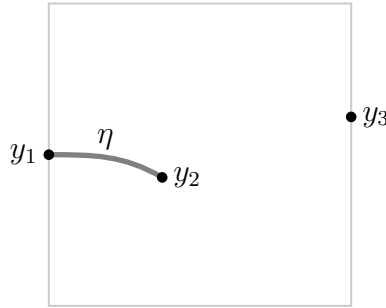
$$\mathbf{N}_{\geq 0} \times \Lambda$$

where $\Lambda \subseteq \mathfrak{witt}$ is a lattice inside the Witt Lie algebra of vector fields on S^1 , closed under the bracket. For instance, in the holomorphic case we can take

$$\mathbf{N}_{\geq 0} \times \mathbf{Z}[z^n \partial_z].$$

3.3. The loop-erased random walk does *not* give an example, however it in some sense lies between the dimension one and two cases.

It satisfies the domain Markov property in the sense that if we have a loop-erased random η walk on Y ,



then the loop-erased random walk conditional on starting at η is equivalent to the loop-erased random walk from y_2 to y_3 . In other words, it has to do with gluing

$$Y_1 = \eta, Y_2 = (Y \setminus \eta) \quad \rightsquigarrow \quad Y.$$

We thus define a category whose objects are dimension zero and one manifolds with boundary, and morphisms are *cobordisms*, i.e. manifolds with boundary N with submanifolds

$$Y_1, Y_2 \hookrightarrow N$$

such that the complement has no boundary and (what?)

For instance, the above picture represents two cobordisms

$$\{y_1\} \xrightarrow{\eta} \{y_2\} \xrightarrow{Y \setminus \eta} \{y_3\}.$$

(maybe instead we should consider manifolds with defect?)

maybe instead we need to consider

$$\eta \xrightarrow{Y} \{y_3\}$$

3.3.1. One can likewise consider loop-erased Markov chains, see [La].

Brownian motion is a certain random real-valued function on the interval $[0, t]$. In particular, it is a measurable map

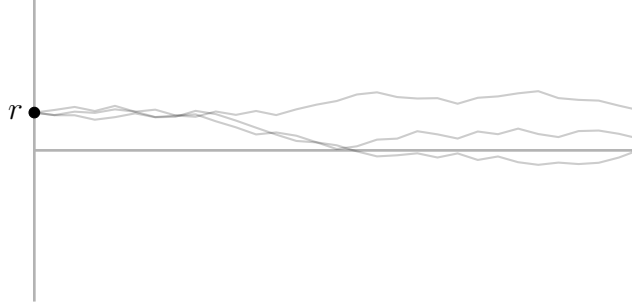
$$B : \Omega \rightarrow \text{Fun}([0, t])$$

and so this induces a probability measure on $\text{Fun}([0, t])$. See above for a few functions picked randomly according to this distribution.

For any real number r we can also define a random function on the interval that always begins at r ,

$$B_r : \Omega \rightarrow \text{Fun}_r([0, t]) \subseteq \text{Fun}([0, t]).$$

Some samples from the induced measure on $\text{Fun}_r([0, t])$:



Taking average endpoint of one of these random functions gives us a linear map:

$$H_t : \mathbf{R} \xrightarrow{r \mapsto \int_{\text{Fun}_r([0, t])} B_r(t)} \mathbf{R}$$

Thus H_t is defined as “summing over all paths” to get a transformation. Note that

$$H_t \cdot H_{t'} = H_{t+t'}$$

by the Markov property of Brownian motion. In physics terminology, this gives us a $1d$ quantum field theory. In fact in this case $H_t = \text{id}$, but we will now follow these ideas to get more interesting examples.

3.4. **General picture.** We can restrict functions on an interval to either endpoint:

$$\begin{array}{ccc} & \text{Fun}([0, t]) & \\ q \swarrow & & \searrow p \\ \mathbf{R} \simeq \text{Fun}(\{0\}) & & \text{Fun}(\{t\}) \simeq \mathbf{R} \end{array}$$

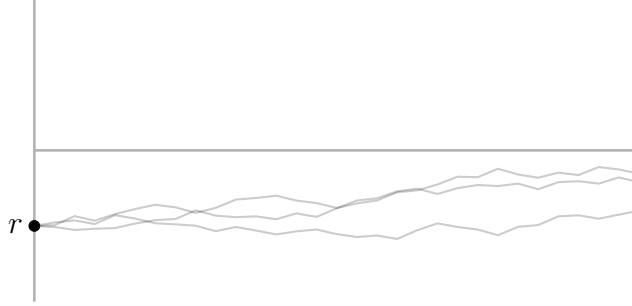
Whenever we have a measure μ_t on $\text{Fun}([0, t])$ plus conditional probability data along p, q , then we get a linear map

$$H_t : \text{Fun}(\{0\}) \rightarrow \text{Fun}(\{t\}) \quad r \mapsto p_* q^* r := \int_{F \in q^{-1}(r)} F(t)$$

as before. We need compatibility data to ensure that $H_t \cdot H_{t'} = H_{t+t'}$.

3.5. Examples.

3.5.1. *Brownian motion with drift.* We get that $H_t(r) = r + t$.



3.5.2. *Polynomials.* We can also take polynomials in B , for instance,

$$B^2 + B : \Omega \rightarrow \text{Fun}([0, t]).$$

All such random functions are bounded below by $-1/2$, i.e. the induced measure on $\text{Fun}([0, t])$ gives measure zero to any measurable set of functions not of this form.



The resulting $H_t : \mathbf{R} \rightarrow \mathbf{R}$ will clearly be non-linear. It is easy to compute as $H_t = t + r^2 + r$ since we know the expectation of $B_0(t)^2$ is t since it is a Gaussian distribution.² Thus it does not satisfy the Markov property so cannot come from a quantum field theory.

²Indeed, $\mathbf{E}(B_r(t)^2 + B_r(t)) = \mathbf{E}((B_0(t) + r)^2 + (B_0(t) + r)) = t + r^2 + r$.

3.5.3. *Remark.* The Markov or *memoryless* property of a random function is related to the fact that physics theories are *local*.

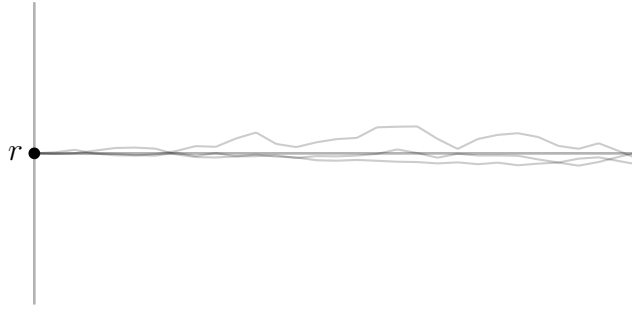
3.5.4. *Ito processes.* To get more examples with the Markov property, note that $B_r(t) = \int_0^r dB_r$, where dB_r is a random one-form. (check) Ito showed that

$$X(t) = \int_0^t f(B)dB$$

is a Markov process for f any L^2 function, and more generally (write). For instance,

$$\int_0^t BdB = \frac{1}{2}(B^2 - t)$$

which still gives $H_t = \text{id}$ since its expectation is zero.



(is this Markov?)

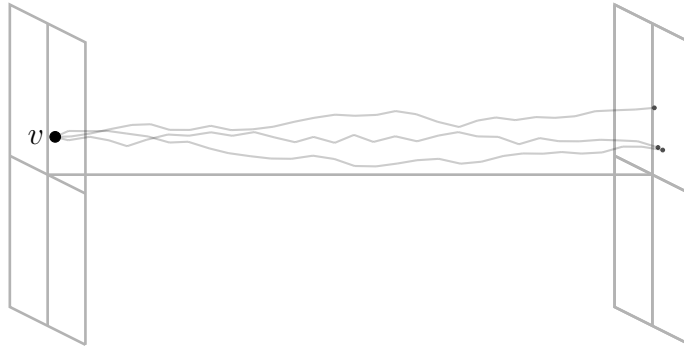
3.5.5. *Brownian motion in \mathbf{R}^d .* We can consider Brownian motion valued in a vector field V , which is a random function as before

$$B : \Omega \rightarrow \text{Fun}([0, t], V)$$

where V is a vector space.³ For a vector $v \in V$, we get a random function

$$B_v : \Omega \rightarrow \text{Fun}_v([0, t], V) = q^{-1}(v) \subseteq \text{Fun}([0, t], V)$$

as before, some samples of which are:

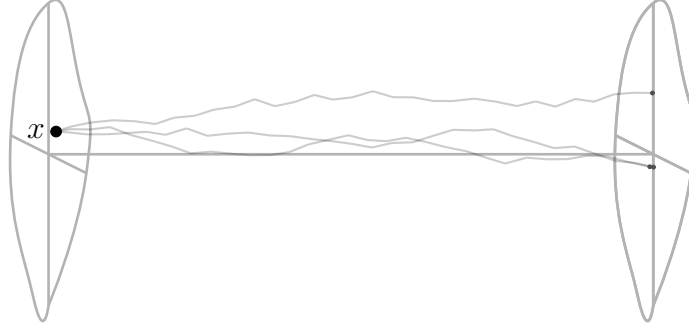


As before, $H_t : V \rightarrow V$ is the identity map, but we can take e.g. coordinatewise polynomials in B to get other maps.

³To specify B we also need to give a symmetric bilinear form on V giving the covariance of B .

3.5.6. *Brownian motion on general spaces, i.e. sigma models.* For a Riemannian manifold X , we can consider again Brownian motion on X ,

$$B : \Omega \rightarrow \text{Fun}([0, 1], X)$$



Because X does not have a group structure, we are not able to take the average value of $B_x(t)$ like before. As before we can restrict

$$\begin{array}{ccc} & \text{Fun}([0, t], X) & \\ q \swarrow & & \searrow p \\ X \simeq \text{Fun}(\{0\}, X) & & \text{Fun}(\{t\}, X) \simeq X \end{array}$$

But even if we have a measure on $\text{Fun}([0, t], X)$ with appropriate conditionals defined push-pull only gives a map on *functions*, which if we normalise to have integral one we can think of as a map on *random points*

$$p_* q^* : \mathcal{R}X \rightarrow \mathcal{R}X.$$

Here, if Y is a measurable space $\mathcal{R}Y = \text{Maps}(\Omega, Y)$ is the space of measurable maps from a fixed probability space Ω to Y , in other words the random points of Y .

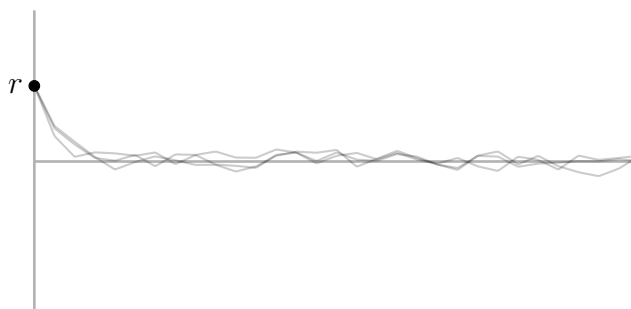
3.5.7. *Remark.* All Markov maps are of the form $\exp(tv) : X \rightarrow X$ where v is a vector field on X whose flow is complete.⁴ Pushing forward by this map induces $\exp(tv) : \mathcal{R}X \rightarrow \mathcal{R}X$, which inherits the Markov property.

3.5.8. *Ornstein-Uhlenbeck process.* We consider an equation

$$dX(t) = -2X(t)dt + dB(t)$$

which is Markov. Some samples of it are

⁴Indeed, if we have a homomorphism $\varphi : \mathbf{G}_a \rightarrow \text{Aut}(X)$ then the map on Lie algebras is $\mathbf{C} \rightarrow \Gamma(X, \mathcal{T}_X)$, the image of 1 gives a vector field v which exponentiates to φ .



Note that this is Markov in the sense that $H_t \cdot H_{t'} = H_{t+t'}$ as functions $\mathcal{R}X \rightarrow \mathcal{R}X$.

3.5.9. *Remark.* If we restrict to random functions $\mathcal{R}X$ which are smooth, this is preserved under $p_* q^*$, and the solution H_t satisfies the *Fokker-Planck* equation.

References

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