

3. Consider the following saved array s computed during an instance of the MATRIX-CHAIN PRODUCT for $n = 7$ arrays. Recall that if $s[i, j] = k$ then the final multiplication for $A_i \cdots A_j$ will be between A_k and A_{k+1} .

2	3	4	5	6	7
1	1	1	1	4	4
2	3	3	3	4	2
3	3	5	5	3	
4	5	4	4		
5	6	5			
6	6				

MCP PARENTHESSES

Use this table to show the optimal order in which to multiply the matrices

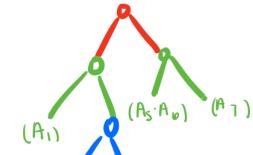
$$A_1 \cdot A_2 \cdot A_3 \cdot A_4 \cdot A_5 \cdot A_6 \cdot A_7.$$

Use parentheses to show the order.
the optimal solution can be constructed from the split table s .
each entry $s[i, j] = k$ shows where to split the product $A_1 \cdots A_7$.

$$(A_1)(A_2 \cdot A_3 \cdot A_4)(A_5 \cdot A_6)(A_7)$$

2	3	4	5	6	7
1	1	1	1	4	4
2	3	3	3	4	2
3	3	5	5	3	
4	5	4	4		
5	6	5			
6	6				

HOW THE TREE LOOKS:



4=splits it at position 4
then we look at $A_1 \cdots A_4$ and $A_5 \cdots A_7$.
then go to the index $s[1, 4]$ and $s[5, 7]$ to see where the sub parenthesis split $A_1 \cdots A_4$ splits @ 1 & $A_5 \cdots A_7$ splits @ 6 and these splits are within the outer brackets
 $A_2 \cdots A_4 = s[2, 4] = 3$ And then when there are only 1 or 2 within a parenthesis, you are done.

$$(((A_1)((A_2 \cdot A_3)(A_4)))(A_5 \cdot A_6)(A_7))$$

HW) Switch cities (C&D) based on which is cheaper for that month.

$$\text{moving_cost}(M) = 10 \quad C = \{1, 2, 10, 30\} \quad D = \{50, 20, 8, 4\}$$

Subproblem: $[c_1, d_1] \dots [c_i, d_i]$ array for the cost of living in and $C(i) = \min \text{cost ending in city } C$ and $D(i) = \min \text{cost ending in city } D$

Recurrence:

$$C(i) = \begin{cases} c_i & i=1 \\ \min[C(i-1), D(i-1)] + M & i>1 \end{cases}$$

$$D(i) = \begin{cases} D_i & i=1 \\ \min[D(i-1), C(i-1)] + d_i & i>1 \end{cases}$$

so: cost of best plan = $\min[C(n), D(n)]$

What is difference between memoization and dynamic programming?

Memoization is a term describing an optimization technique where you cache previously computed results, and return the cached result when the same computation is needed again.

Dynamic programming is a technique for solving problems of recursive nature, iteratively and is applicable when the computations of the subproblems overlap.

Dynamic programming is typically implemented using tabulation, but can also be implemented using memoization. So as you can see, neither one is a "subset" of the other.

A reasonable follow-up question is: What is the difference between tabulation (the typical dynamic programming technique) and memoization?

When you solve a dynamic programming problem using tabulation you solve the problem "bottom up", i.e., by solving all related sub-problems first, typically by filling up an n -dimensional table. Based on the results in the table, the solution to the "top" / original problem is then computed.

If you use memoization to solve the problem you do it by maintaining a map of already solved sub problems. You do it "top down" in the sense that you solve the "top" problem first (which typically recurses down to solve the sub-problems).

6. The longest common subsequence problem is to find the longest (non-contiguous) sequence of characters shared by two strings $X = x_1 x_2 \dots x_n$ and $Y = y_1 y_2 \dots y_m$. For example, if $X = CAB$ and $Y = BACB$, the answer is 2 (they both share length 2 subsequences AB and CB). Here, we define a sub-problem $C(i, j)$ to be the longest subsequence of $x_1 x_2 \dots x_i$ and $y_1 y_2 \dots y_j$. The recurrence we have seen for C is

$$C(i, j) = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ 1 + C(i-1, j-1) & \text{if } i > 0 \text{ and } j > 0 \text{ and } x_i = y_j \\ \max[C(i-1, j), C(i, j-1)] & \text{if } i > 0 \text{ and } j > 0 \text{ and } x_i \neq y_j \end{cases}$$

Use the recurrence to fill in a table for C for the strings $X = roror$ and $Y = orro$. You may use (or not) the sketch below.

		0	r	r	0
C	0	1	2	3	4
0	0	0	0	0	0
R	1	0	0	1	1
0	2	0	1	1	2
R	3	0	1	2	2
0	4	0	1	2	3
R	5	0	1	2	3

Different:

i R vs. 0
 $i=1 \quad j=1 \quad \max[c(0,1), c(1,0)]$
 $c(0,1), c(1,0)$

Same:

R vs. r
 $i=2 \quad j=1 \quad 1 + C(1,0)$
 $1 + 0 = 1$

" " " bottom and track where it can from to find the longest sequence. only keep track when its the same

		0	r	r	0
C	0	1	2	3	4
0	0	0	0	0	0
R	1	0	0	1	1
0	2	0	1	1	2
R	3	0	1	2	2
0	4	0	1	2	3
R	5	0	1	2	3

longest sequence:
0, r, r

HW) Place mile post 100m apart if it is not exactly 100m apart \rightarrow penalty of $(100-x)^2$
So avg post spots to minimize penalties:

Subproblem: $S(i) = \min \text{possible total penalty}$ when placing sign at m_i all the way up to M_i . Answer = $S(n)$

Recurrence:

$$S(i) = \begin{cases} 0 & i=1 \\ \min, \exists j : S(j) + (100 - (m_i - m_j))^2 & i>1 \end{cases}$$

Now $S(i) = \text{total possible penalty b/wn } m_i \rightarrow m_n$

Class 1) having low/high stress job. High stress must have week prior = no work.

Subproblem: $J(i) = \text{value of best job choices ending in week } i$ at finishing either H/L stress

Recurrence: $J(i) = \begin{cases} 0 & i=0 \\ \max(h_i, l_i) & i=1 \\ (\max[e_i + J(i-1), h_i + J(i-2)]) & i>1 \end{cases}$

Now $J(i) = \text{best job choice}$

Class 2) max continuous sum

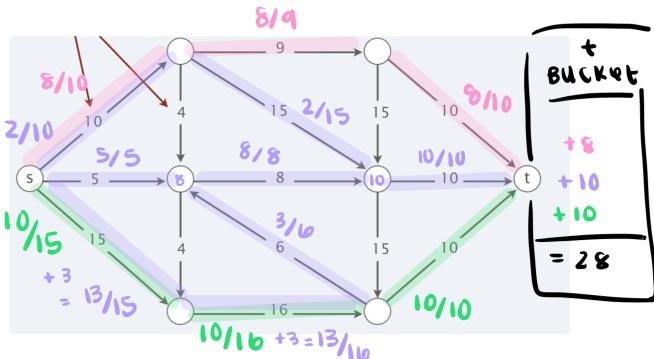
Subproblem: $MCS(i) = \text{value of max cont. subseq. sum ending at position } i$

Recurrence: $MCS(i) = \begin{cases} 0 & i=0 \\ a_i & i=1 \\ \max[a_i, a_i + MCS(i-1)] & i>1 \end{cases}$

Start new seq ↑ attach to tail of prev. best

NETWORK FLOW

Time complexity: $O(V \cdot E \cdot C)$ or $O(V \cdot E^2)$



Ford-Fulkerson Method

input: graph G , source s , terminus t

1. initialize flow f of each edge to 0
2. while there exists an augmenting path p in the residual network G_f
3. augment flow along p
4. return f

- flow increases by at least 1 with each iteration
- could be slow if C is large
- many improvements
- Edmonds-Karp is $O(V^2E)$
- idea is to use BFS to find $s-t$ path in G_f

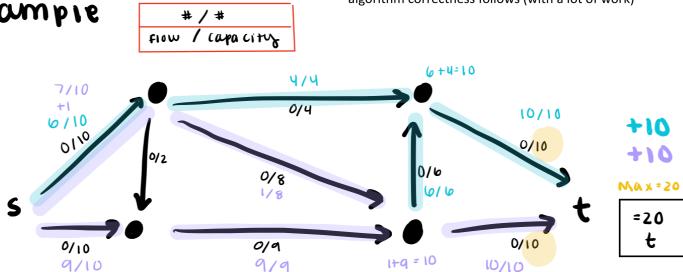
max-flow min-cut theorem

The size of the maximum flow from s to t is the capacity of the minimum (s,t) -cut

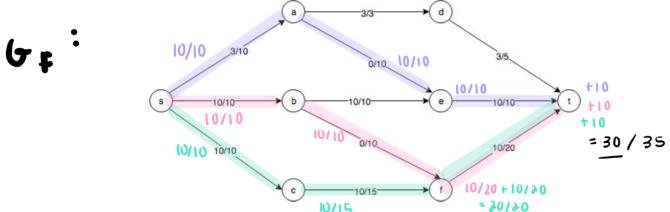
note

- An (s,t) -cut is a partition of the nodes S and $V-S$ with s in S and t in $V-S$
- the capacity of that cut is the sum of the flow leaving S
- algorithm correctness follows (with a lot of work)

example

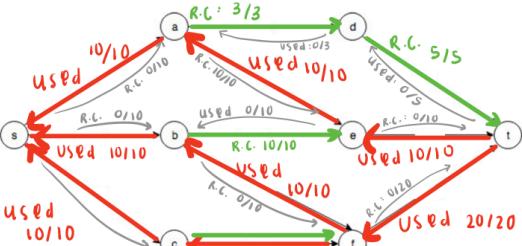


5. The following flow graph G has some flow assignments already made. Use the Ford-Fulkerson method to continue the process of deriving the maximum flow from s to t . Show the residual graph G_f , find an augmenting path in G_f , and then update the flow in G . One step should be enough to find the max-flow.



Residual graph:

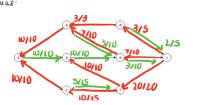
MUSED
Residual capacity



Another way:



another way:



NP

NP = non-deterministic polynomial

Time complexity = polynomial

$n = \text{input size}$ $O(n^2) / O(n^k)$

$k = \text{constant (like 2)}$

• it allows a choice of next-step

• uses yes/no problems

↓

accepts

NP-Complete: If one NP-complete problem can be solved in poly-time, then all of NP can be solved in poly-time

no one knows if this is possible
but if you prove one, you prove it all.

1) If a single NP-complete problem is shown to have a polynomial time (deterministic) algo, then it can be concluded that $P=NP$

TRUE. IF YOU PROVE ONE, YOU PROVE ALL.

2) Whether any NP-complete problem is P OPEN.

3) If a single NP-complete problem is shown to require exponential time, then it can be concluded that $P=NP$.

FAKE

4) Every problem that can be solved in polynomial time non-deterministically can be solved by a polynomial time deterministic algo. OPEN MILLION \$?

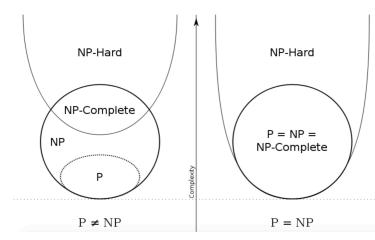
5) There is an NP-complete problem with a poly-time algo. OPEN

6) If one NP-complete problem is proved to require exponential time, then $P=NP$. FAKE

7) If one NP-complete problem is proved to require exponential time, then $P \neq NP$. TRUE

```

nondeterministic algorithm
for i = 1 to n
    set x[i] = 0 or 1 (nondet step)
if F(x[1], ..., x[n]) is true
    then ACCEPT
    else REJECT
  
```



GRQdY

EVERY GREEDY algorithm NEEDS:

- SUBPROBLEMS
- OPTIMAL SUBSTRUCTURE
(like dynamic programming)
- GREEDY choice algorithm ★

RECURSIVE ALGO

RAS on inputs s (start times), f (finish times), K (subproblem), and n

```
RAS(s,f,k,n)
m=k+1
while m≤n and s[m] <= f[k]
    m=m+1
if m=n
    return {a_m}URAS(s,f,m,n)
else return Ø
```

finish times already sorted.
time now looks like O(n)

find first a_m in s_i to finish

ITERATIVE ALGO

```
A={a_1}
k=1
for m=2 to n
    if s[m] >= f[k]
        A=A ∪ {a_m}
        k=m
return A
```

time is pretty clearly O(n), but
don't forget the O(nlg n) time
used to sort f

GREEDY STRATEGY

1) DETERMINE OPTIMAL SUBSTRUCTURE OF THE PROBLEM

2) DEVELOP A RECURSIVE SOLUTION

3) SHOW THAT IF GREEDY CHOICE MADE, ONLY ONE SUBPROBLEM REMAINS

4) PROVE IT IS ALWAYS SAFE TO MAKE GREEDY CHOICE

5) DEVELOP RECURSIVE ALGORITHM

IMPLEMENTING GREEDY

6) CONVERT RECURSIVE VERSION TO ITERATIVE

- Derive a greedy strategy solving the following problem: We have a company with n workers. Worker w_i works a shift (s_i, f_i) , where s_i is that worker's start time and f_i the finish time. (We will also refer to a shift as an interval, and you can assume $0 \leq s_i < f_i$ are integers.)

We want to form a small committee $C \subseteq \{w_1, \dots, w_n\}$ which is *complete*, in other words for every worker not on the committee, that worker's shift overlaps (at least partially) with the shift of some other worker who is on the committee. Or formally, for every worker w_i there exists a worker $w_c \in C$ such that the shift of w_i overlaps with the shift of w_c (the intervals (s_i, f_i) and (s_c, f_c) must non-trivially intersect).

The problem here is to find the *smallest* possible complete set C of workers. A greedy strategy will work. Here are two possible (different) strategies. One works and one does not.

- choose the worker whose interval intersects the largest number other intervals, select that worker to add to C , and eliminate all intersecting intervals
- look at the earliest finishing uncovered interval w , and from among all intervals that intersect w add to the committee C the worker whose interval finishes the latest

- Choose one of the greedy choices above and prove that it yields the smallest possible C . (write your choice and justification on the next page)

#2 because interval I with the earliest finish time must be covered anyway. And if you select the shift that finishes last, then you will have a constant slight overlap so no gaps, and you can continue this for all the shifts next (hence the greedy approach. You are just looking at the current overlapping shifts, not the entire day schedule).

- In a few sentences, describe an algorithm that implements your greedy choice and give its run-time bound

min-cover[n]

sort intervals based on finishing times. Then if you have an overlap, continue checking, if you don't, add the last ($j-1$) shift to the solution set, after you complete this, you want to then start looking at the overlapping shifts of this new shift ($j-1$) and continue the same looping process. And then the solution set contains the min. interval cover.

Time complexity = $O(nlgn)$ because we loop through $O(n)$ and then sort n intervals $O(nlgn)$ so total = $O(nlgn)$.

Huffman Code

TIME COMPLEXITY: $O(nlgn)$
B/C STORE HEAP = $O(lgn)$ AND
 $O(n)$ ITERATIONS.

1) ORDER IN MIN-HEAP

2) COMBINE TWO SMALLEST FREQUENCIES

3) REPEAT STEP 2

then number each branch 0 or 1.

0 = LEFT branch

1 = RIGHT branch



A	1100
B	1101
C	010
D	011
E	111
F	00
G	10

CIS 315, Intermediate Algorithms

Spring 2019

Sample Solution to Something Like Problem 1 of the Sample Final Exam from the Previous Term

Derive a greedy strategy solving the following problem:

We have a company with n workers. Worker w_i works a shift (s_i, f_i) , where s_i is that worker's start time and f_i the finish time.

We want to form a small committee $C \subseteq \{w_1, \dots, w_n\}$ with the following property: for every worker w_i there exists a worker $w_c \in C$ such that the shift of w_i overlaps with the shift of w_c . That is, the intervals (s_i, f_i) and (s_c, f_c) must intersect.

So the problem here is to find the smallest possible set C of workers whose shifts overlap with all workers.

- Describe your greedy choice solving it. ("Choose the first worker with property \mathcal{P} .)"
- Show that if there is an optimal solution for which the greedy choice was not made, then an exchange can be made to conform with your greedy choice. ("Let schedule S use worker w_k who does not satisfy property \mathcal{P} , and let w_k be the worker that does. Here I show that the schedule S' , which is obtained by exchanging worker w_j for w_k , is just as good as S ...")
- Describe, in English, how to implement a greedy algorithm.
- How long would your algorithm take?

solution:

- Note: during the description of the greedy strategy we distinguish between the set of workers who need their shift covered V and those workers W who are eligible to serve on the committee. Initially both V and W are the set of all workers. The distinction is that V will shrink as the committee C increases, whereas W will always contain all workers (two committee members may need to overlap).

Consider the first worker $w_i \in V$ to finish - this is the critical shift to cover. Consider the set of workers in W that cover that w_i 's shift: $S = \{w_k \in W | s_k \leq f_i\}$. The greedy choice is that we add to C the $w_j \in S$ with the latest finish time. Then remove from V all workers whose shift intersects with w_j .

- Suppose an optimal solution C' is given which differs from the greedy solution above. Look at the first stage of our greedy approach, consider the earliest finisher w_i at that stage as

1

above, and take the $w \in C'$ which covers w_i 's shift. We can replace w with our w_j , getting committee $C' - \{w\} \cup \{w_j\}$, and get a solution that is just as good since w_j has a later finish time than w . Also note that no workers' shifts get uncovered, since w_i is the first to finish.

- Perhaps it would be convenient to sort the workers by finish time, and perhaps other optimizations may help the constants. But basically:

- scan the V to find w_i
- scan the W to find w_j
- add w_j to C , and scan the V removing all workers whose shift intersects with w_j
- repeat until V is empty

- Each scan is $O(n)$ and removes at least one worker. Total is $O(n^2)$.

MIDTERM TOPICS TIME COMPLEXITY:

DJIKSTRAS	$O(nlgn)$
PRIMS	$O(nlgn)$
KRUSKALS	$O(nlgn)$
FLOYD-W	$O(n^3)$
BFS	$O(n+m)$
DFS	$O(vt)$
TOPOLOGICAL	$O(vt)$