

Super Hexagon Bot

Kevin Baichoo (kbaichoo),¹ Peter Do (peterhdo)¹

¹Department of Computer Science, Stanford University

Stanford Computer Science

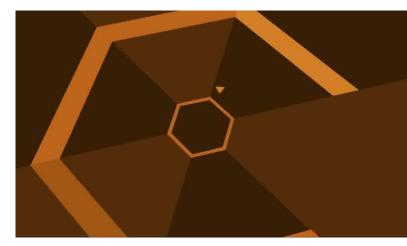
Overview

- **Problem**: How can we use neural networks that classify images in order to play Super Hexagon well?
- **Solution**: We present two different models (one based on **MNIST** and one utilizing **ResNet**) and a bootstrapping framework that allows us to play Super Hexagon with neural networks in real-time.

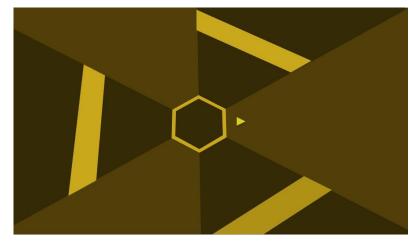
Predictions Based on Screenshot Data



"Left" Classification



"Right" Classification

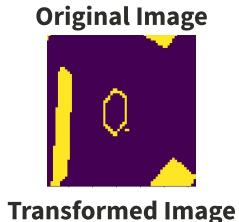


"Stay" Classification

- We modeled the task as an image classification problem
 - Models are implemented in Python using PyTorch
- 3 classifications: move "left", move "right", and "stay"
 - These commands allow the player (triangle) to avoid the wall obstacles to proceed further in the game
- Game loop runs with python script, taking screenshots, passing them into the model, and pressing keys based on the model's output
- **Data Collection**: We used a combination of self-recorded and YouTube video data that we fed into FFMPEG for screenshots.
- With these screenshots, we manually classified training, validation, and test data sets, being sure to balance our data
 - Representative dataset skewed towards staying
 - We were able to augment the data size (by 4x) by rotating the image 90 degrees (Rotation Symmetry)
 - 1K+ Data points

Features





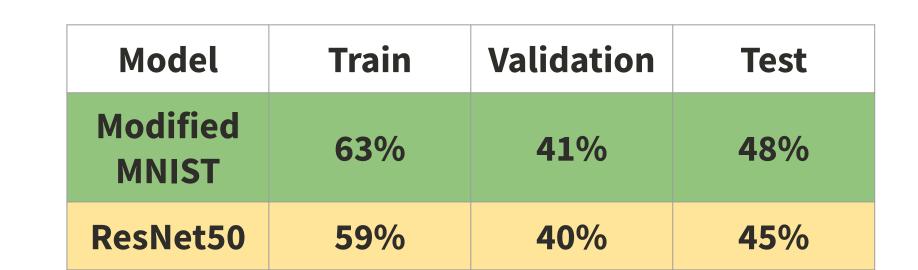
 We transformed the images to leave only the minimal set of relevant features in the image
Knowing where the walls / player is

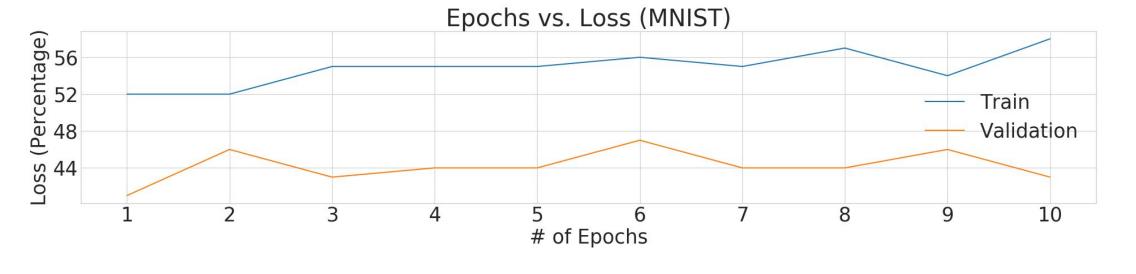
- Knowing where the walls / player is enough to make good decisions
- Transformations:
 - Grayscale (single channel)
 - Resizing (downsampling to 64x64)
 - Binarization

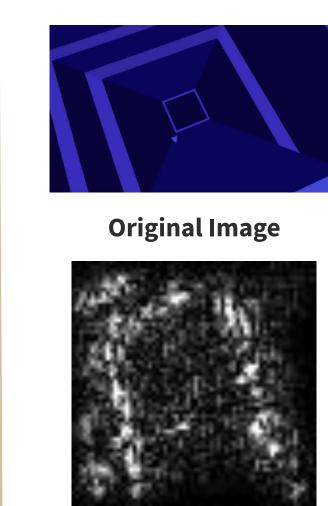
Models

- 1. MNIST-based classifier
 - 2 conv. layers each followed by max pool, then hooked up to two linear layers; ReLu activations; Softmax on final output
 - SGD optimizer with NLL Loss function
 - Quicker to train, with decent results (around 50% accuracy across validation/test)
- 2. ResNet
 - Utilized PyTorch's implementation of ResNet (18 and 50 layers) without pretraining (tried pretrained model)
 - ResNet was able to fit the training data well with Adam optimizer and Cross Entropy Loss
 - Overfitting was a concern, mitigated with early stopping

Results







Saliency Map

Discussion

- There is a significant amount of bias towards predicting "stay" (as seen in the confusion matrix)
 - High error rate on "left" and "right" classification
- However, "left"/"right" can both be valid
- Overall, our networks do seem able to determine which features are relevant in classification and play the game in real-time with some success
- Our MNIST-based model likely needs more layers to be more expressive.
- Nontrivial to tune ResNet for our purposes without overfitting.

Future

- We plan to refine the models (via hyperparameter tuning, data augmentation, data regularization, transformations, etc.) in order to improve classification accuracy.
- We may experiment with other types of networks (RNNs) or other techniques (RL) to compare results

References

- 1. Deep Residual Learning for Image Recognition: https://arxiv.org/pdf/1512.03385.pdf
- 2. Densely Connected Convolutional Networks: https://arxiv.org/pdf/1608.06993.pdf
- 3. MNIST Classifier: https://github.com/pytorch/examples/tree/master/mnist
- 4. Generating Saliency Maps: https://github.com/utkuozbulak/pytorch-cnn-visualizations