

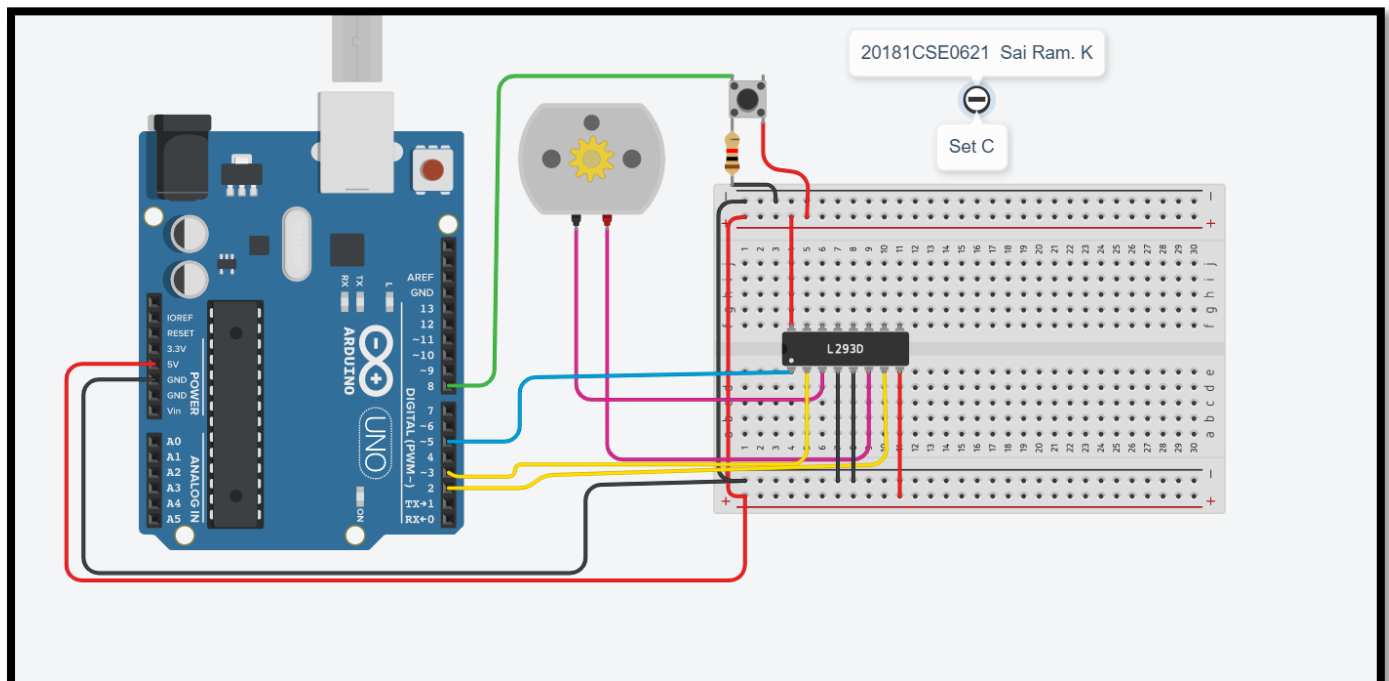
## Set – C

Question 1 : Rotating a DC Motor using a push button to control the direction.

**Aim : To rotate a DC motor using a push button to control the direction.**

**Components Required :** Arduino, bread board, jumper wires, IC L293D.

**Initial Circuit Design :**



**Sketch :**

```
int enable=5;
int inp2=3;
int inp3=2;
void setup()
{
  pinMode(5,OUTPUT);
  pinMode(3,OUTPUT);
  pinMode(2,OUTPUT);
```

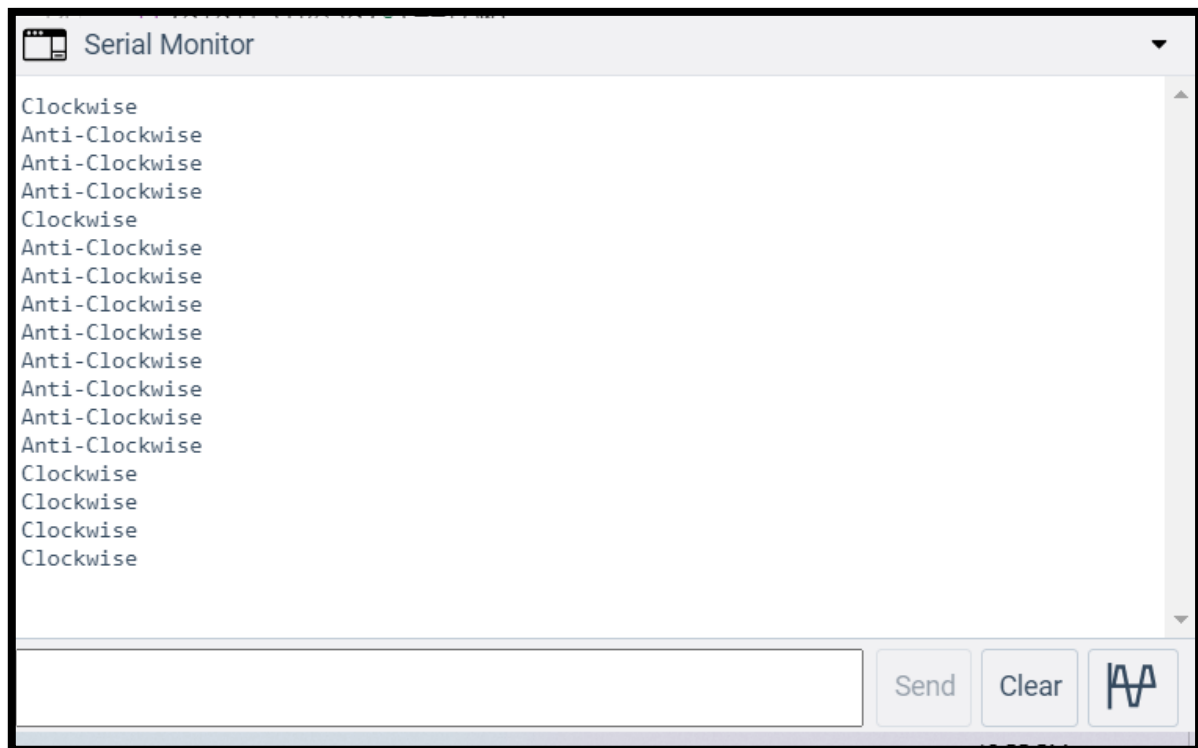
```
Serial.begin(9600);

digitalWrite(enable,HIGH);
}

void loop()
{
  if(digitalRead(8)==LOW)
  {
    digitalWrite(inp2,HIGH);
    digitalWrite(inp3,LOW);
    Serial.println("Clockwise");
    delay(2000);
  }
  else if(digitalRead(8)==HIGH)
  {
    digitalWrite(inp2,LOW);
    digitalWrite(inp3,HIGH);
    Serial.println("Anti-Clockwise");
    delay(2000);
  }
}
```

### **Output Screenshots :**



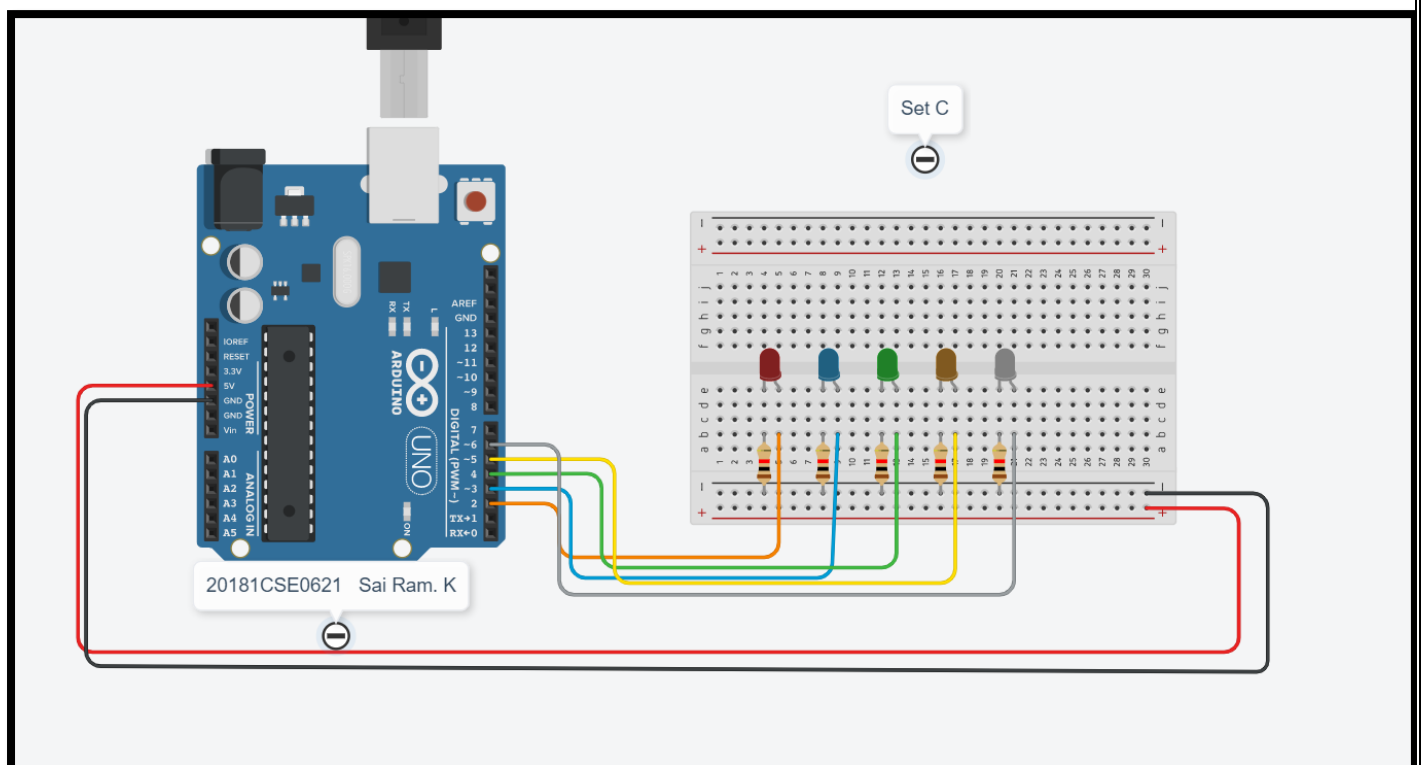


## **Question 2 :** Write and execute a program to Scroll 5 LEDs.

Aim : To scroll 5 LED's.

Components Required : Arduino uno, Breadboard, jumper wires, LEDs, resistors.

Initial Circuit Design :



Sketch:

```
int Pins[]={2,3,4,5,6};
int timer=1000;
void setup()
{
  for(int i=0;i<5;i++)
  {
    pinMode(Pins[i], OUTPUT);
  }
}
```

```
Serial.begin(9600);  
  
}  
  
void loop()  
{  
  for(int i=0;i<5;i++)  
  {  
    digitalWrite(Pins[i],HIGH);  
    delay(timer);  
    digitalWrite(Pins[i],LOW);  
  }  
  for(int i=4;i>=0;i--)  
  {  
    digitalWrite(Pins[i],HIGH);  
    delay(timer);  
    digitalWrite(Pins[i],LOW);  
  }  
}
```

## Output Screenshots :

