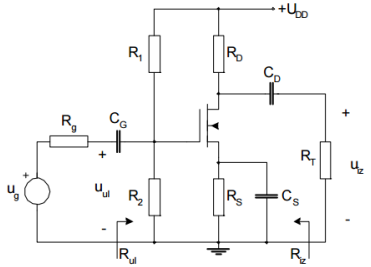
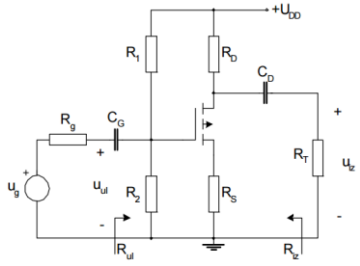
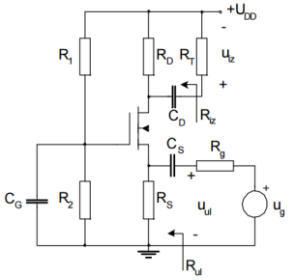
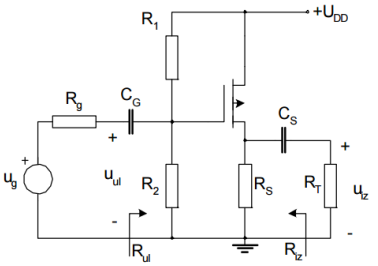
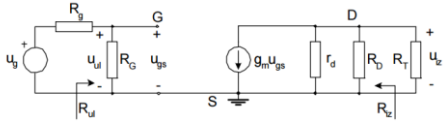
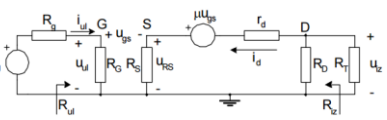
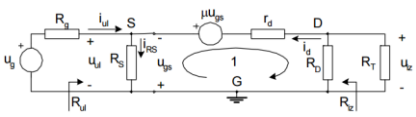
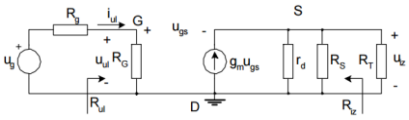
Vrsta					
					
Naziv		Spoj zajedničkog uvoda	Spoj zajedničkog uvoda s degeneracijom	Spoj zajedničke elektrode	Spoj zajedničkog odvoda
Statička radna točka	**U_{GG}**	$U_{GG} = \frac{R_2}{R_1 + R_2} \cdot U_{DD}$			
	U_{GG}	$U_{GG} = U_{GSQ} + I_{DQ} \cdot R_S$			
	I_{DQ}	$I_{DQ} = \frac{K}{2}\left(U_{GSQ} - U_{GS0}\right)^2$			
	U_{DSQ}	$U_{DSQ} = U_{DD} - I_{DQ} \cdot \left(R_D + R_S\right)$			
Dinamički parametri	**g_m**	$K\left(U_{GSQ} - U_{GS0}\right)\left(1 + \lambda U_{DSQ}\right)$			
	r_d^{-1}	$\lambda \frac{K}{2}\left(U_{GSQ} - U_{GS0}\right)^2 = \lambda I_{DQ}$			
Parametri pojačala	**A_V**	$-g_m \cdot r_d \left\| R_D \right\| R_T$	$-\frac{\mu \cdot R_D \left\| R_T \right.}{R_S \cdot (1+\mu) + r_d + R_D \left\| R_T \right.}$	$\frac{g_m \cdot r_d \cdot R_D \left\| R_T \right.}{r_d + R_D \left\| R_T \right.} = g_m \cdot r_d \left\| R_D \right\| R_T$	$\frac{g_m \cdot r_d \left\| R_S \right\| R_T}{1 + g_m \cdot r_d \left\| R_S \right\| R_T}$
	A_{Vg}	$A_V \cdot \frac{R_G}{R_g + R_G}$			
	R_{ul}	$R_G = R_1 \left\| R_2 \right.$	$R_G = R_1 \left\| R_2 \right.$	$R_S \left\| \frac{r_d + R_D \left\| R_T \right.}{r_d \cdot g_m} \right. = R_S \left\| \frac{1}{g_m} \right.$	$R_G = R_1 \left\| R_2 \right.$
	R_{iz}	$r_d \left\| R_D \right.$	$R_D \left\| \left(r_d + (1+\mu) \cdot R_S\right) \right.$	$R_D \left\| \left(r_d + (1+\mu) \cdot R_S \left\| R_g \right.\right) \right.$	$\frac{r_d \left\| R_S \right.}{1 + g_m \left(r_d \left\| R_S \right.\right)} = R_S \left\| \frac{r_d}{1+\mu} \right. = R_S \left\| \frac{1}{g_m} \right.$
SRP		**Q**(U_{DSQ}, I_{DQ}) , **x**=> U_{DD} , **y**=> $I_D = U_{DD}/(R_D + R_S)$			
DRP		**u_{DS}**= $-i_d(R_D \| R_T)$, **x**=> $U_{DS1} = U_{DSQ} + I_{DQ}(R_D \| R_T)$, **y**=> $I_{D1} = I_{DQ} + U_{DSQ}/(R_D \| R_T)$			