

PRORAČUNO PLINUSKI NABOJ IMAO NIZ TOČKASTIH

$$E = \sum_{n=1}^m \frac{q}{4\pi\epsilon_0} \cdot \frac{1}{r_n^2} \cdot k \quad r_n = |2L - x_n|$$

$$E = k \cdot \sum_{n=1}^m \frac{q}{4\pi\epsilon_0} \cdot \sum_{n=1}^m \frac{1}{(2L - x_n)^2} \quad | \quad \lim$$

$$E = k \cdot Q \cdot \int_a^b \frac{1}{(2L - x)^2} dx$$

ZA PRVI NABOJ IMAMO (POZITIVAN)

$$E = kQ \int_0^{\frac{L}{3}} \frac{1}{(2L - x)^2} dx \quad 2L - x = t \quad dt = -dx$$

$$E = -kQ \cdot \int_{2L}^{\frac{5L}{3}} \frac{1}{t^2} dt = kQ \left[\frac{1}{t} \right]_{\frac{5L}{3}}^{2L} = \frac{1}{10} \frac{kQ}{L}$$

$$\vec{E}_1 = \frac{1}{10} \frac{kQ}{L} \vec{e}$$

ZA DRUGI NABOJ IMAMO (NEGATIVAN)

$$E = kQ \int_{\frac{2L}{3}}^L \frac{1}{(2L - x)^2} dx$$

$$E = -kQ \cdot \int_{\frac{5L}{3}}^L \frac{1}{t^2} dt = kQ \cdot \left[\frac{1}{t} \right]_{\frac{5L}{3}}^L = \frac{1}{4} \frac{kQ}{L}$$

$$\vec{E}_2 = -\frac{1}{4} \frac{kQ}{L} \vec{e}$$

$$\vec{E}_{uk} = \vec{E}_1 + \vec{E}_2 = -\frac{3}{20} \frac{kQ}{L} \vec{e} \quad \text{GDJE } x$$

$$k = \frac{1}{4\pi\epsilon_0}$$

DZ 15

HORVAT

5. DZ.

FIZ 2

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_V \frac{\rho(\vec{r}')}{r^2} \vec{r}' dV'$$

$$E(r) = \frac{1}{4\pi\epsilon_0} \int_V \frac{\rho(r')}{r^2} dV'$$

PRELIMINAR U FERNER
KOORDINATEN:

$$x = r \sin\theta \cos\phi$$

$$y = r \sin\theta \sin\phi$$

$$z = r \cos\theta$$

$$J =$$

$$E = \frac{1}{4\pi\epsilon_0} \int_0^{2\pi} d\phi \int_0^\pi \sin\theta d\theta \int_0^R \frac{\rho}{r^2} r^2 dr$$

$$E = \frac{1}{4\pi\epsilon_0} \int_0^{2\pi} d\phi \int_0^\pi \sin\theta d\theta \int_0^R \frac{\rho_0}{1 + \left(\frac{r}{R}\right)^2} dr$$

$$\rho_0 = \frac{Q_0}{\frac{4}{3}R^3\pi}$$

$$E = \frac{\rho_0}{4\pi\epsilon_0} \cdot 2\pi \cdot 2 \int_0^R \frac{1}{1 + \left(\frac{r}{R}\right)^2} dr$$

$$= \frac{\rho_0}{\epsilon_0} R^2 \cdot \frac{1}{R} \arctan \frac{r}{R} \Big|_0^R = \frac{\rho_0}{\epsilon_0} R \cdot \arctan 1$$

$$\rho_0 \text{ SE } 12R^3\pi \rightarrow \text{KAU} \quad \frac{\rho_0}{\frac{4}{3}R^3\pi} \quad , \quad \text{mit } \alpha_1 = 1, \alpha_2 = 3$$