## Harmouijski, Osolatori

- Idaalno titranje pod utjerajem el. sile, da tijelo beskonačno titra

$$\frac{d^{2}}{dt} \times [t] + \omega_{0}^{2} \times [t] = 0$$

$$\frac{d^{2}}{dt} \times [t] + \omega_{0}^{2} \times [t] = 0$$

$$\omega_{0}^{2} = \frac{k}{m} = 2\pi f$$

$$X[t] = Aros (wt + \emptyset)$$

$$E_{h} = \frac{mv^{2}}{2} \quad E_{p} = \frac{4}{2} kx^{2}$$

dalje izvedi sam

to sue pouvis Euj!

Prigniseno - prisilno titranje

$$\frac{d^2}{dt^2} \times [t] + 2 \int \frac{d}{dt} \times [t] + w_0^2 \times [t] = \int_{P} [w_0 \in [wt]]$$

$$2\delta = \frac{b}{m} \qquad \omega_0^2 = \frac{k}{m} \qquad f_p = \frac{F_p}{m}$$

Fizicho P=V.m L=1.w njihalo X C- P F= m. 9 M=I. P

## Jodnadába gibanja!

$$\frac{JL}{Jt} = M = \frac{d}{Jt} I \cdot \omega$$

$$V_{\text{randal}} = mgb \sin \theta = \overline{L} \cdot \theta$$

$$\frac{d}{dt} = mgb \sin \theta = \overline{L} \cdot \theta$$

$$\frac{d}{dt} = mgb \sin \theta = 0$$

· + ω2 φ=0

Bilo Loje tijelo koje Milo koje uje vaj njiše ali je obježeno u točki koja nije na osi ng

$$w_0^2 = \frac{mgb}{I} = \frac{g}{l_{red}}$$

$$l_{red} = \frac{I}{mb}$$

Transverzalni - Stojni van un iici

$$\begin{cases}
A_{1} = F_{2} \\
F_{3} = F_{4}
\end{cases}$$

$$\begin{cases}
A_{1} = F_{2} \\
A_{2} = A_{1} \\
A_{3} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{1} = A_{2} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{1} = A_{2} \\
A_{2} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{2} = A_{4} \\
A_{3} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{1} = A_{2} \\
A_{3} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{2} = A_{4} \\
A_{3} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{3} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$\begin{cases}
A_{4} = A_{4} \\
A_{4} = A_{4}
\end{cases}$$

$$A_{4} = A_{4} = A_{4}
\end{cases}$$

$$A_{4} = A_{4} = A_{4} = A_{4}
\end{cases}$$

$$A_{4} = A_{4} = A_{4} = A_{4}$$

$$A_{4} = A_{4} = A_{4}
\end{cases}$$

$$A_{4} = A_{4} = A_{4}$$

$$A_{4} = A_{4}$$

$$A_{4} = A_{4} = A_{4}$$

$$A_{4} = A_{4}$$

$$A_{$$

V = V F

Scanned by CamScanner

Interference ja Valora!

$$\frac{1}{E_A}(t,x) + \frac{1}{E_A}(t,x_2) = \frac{1}{E}(t,x)$$

$$Eo coss(wt-tx_A) + f_{ocos}(wt-tx_A) = \frac{1}{E}(t,x)$$

$$\cos d + \cos B = 2 \cos \frac{d-B}{2} \cdot \cos \frac{d+B}{2}$$

$$\frac{1}{E}(t,x) = 2E_{ocos} \left[ \frac{k(y_2-y_4)}{2} \right] \cdot \cos \left[ wt - \frac{k}{2}(y_2-y_4) \right]$$

$$+ \lim_{n \to \infty} hidda$$

$$\text{Rowstrul ting interference ja } S = \text{m.R.}$$

$$\text{Destruktiva interference ja } S = \text{kinea} \right] \frac{R}{2}$$

$$\nabla \cdot D = \int_{S}$$

$$\nabla x E = -\frac{\partial B}{\partial t}$$

$$\forall xH = \int + \frac{\partial D}{\partial t}$$

spo provilo de une roke dodoje se (-) V faradijevous zabono!

$$\nabla \cdot D = 0$$

$$\nabla \cdot B = 0$$

$$\nabla \times E = -\frac{\partial B}{\partial t}$$

$$\nabla \times H = \frac{\partial D}{\partial t}$$

$$\frac{\partial D}{\partial t^{2}} = -\frac{1}{M} \left( \nabla \times E \right)$$

$$\frac{\partial D}{\partial t} = -\frac{1}{M} \left( \nabla \times E \right)$$

$$\nabla \times (\nabla \times \vec{E}) = -\nabla (\nabla \cdot \vec{E}) + \vec{E} (\nabla \cdot \nabla) = -\nabla (\nabla \cdot \vec{E}) + \Delta \vec{E} = 0$$

$$\frac{\Im^2 \vec{D}}{\Im^2} = \frac{1}{M} \Delta \vec{E}$$

$$\frac{\partial^2 \vec{E}}{\partial t^2} + \frac{1}{\xi M} \Delta \vec{E} = 0$$

# Difralcija broe pulotine.

$$J : E_{o}^{2} \frac{Sin^{2} \left(N \Lambda^{\frac{4}{2}}\right)}{Sin^{2} \left(\frac{\Lambda^{\frac{4}{2}}}{2}\right)}$$

## Planch

E= h.w = h.f = h c

## Fotostet

- 1.) Stroja ako je Ima je vazmjeva intoreiteta
- 2.) Als je fretvoncija nobe gravine ili R veći odnote granice, struja nestaje
- 3.) Postoji gornja granična enorgija elobtroma! Egr = h·f

Ey > Wiz + Ezin

Boron model atoma

P1 Postoje dozvoljene staze za koje je p=m.v=0

P2 Kutua kolićina gibanja je L=r.p=r.m.v = h.n nemi.

P3 Pri prolosku iz jednog u dvogo stanje atom zraći toton

evergije koja je jednaka vaclici energija tih dviju stavija

Fcp = Fculumb

$$A.) \frac{m \cdot v^2}{r} = \frac{e^2}{4\pi \epsilon R^2}$$

2.) 
$$L = r \cdot m \cdot V = h \cdot n \rightarrow V = \frac{h \cdot \eta}{r \cdot m}$$

$$N \rightarrow b \sim 1 \int_{0.2}^{2} q^{\alpha} v^{\alpha}$$

$$\frac{dN}{N} = -R dt$$

$$\ln N = -R t + C$$

$$N[t] = e^{C} \cdot e^{-Rt} = N_{0} \cdot e^{-Rt}$$

$$A = R \cdot N_0$$

$$A = R \cdot N_0$$

Virgone polovespedq

$$N[T_{1/2}] = \frac{1}{2} N[0]$$

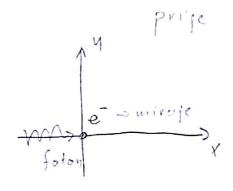
$$N_0 e^{-RT_{1/2}} = \frac{1}{2} N_0$$

$$= RT_{1/2} = \frac{1}{2}$$

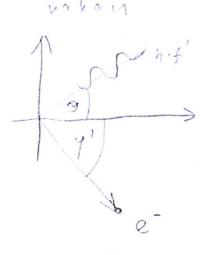
$$\ln z - RT_{1/2}$$

$$T_{1/2} - \frac{\ln z}{R}$$

## Camponovo raspršenje



Sudar



$$\gamma' = \frac{1}{\sqrt{1 - \left(\frac{ve'}{c}\right)^2}}$$

$$\Delta R = \frac{h}{m.c} \left( 1 - \cos \theta \right)$$