

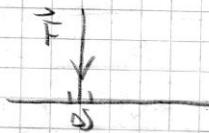
TEORIJA

① NAPRETANJE

$$\sigma = \frac{F}{A}$$

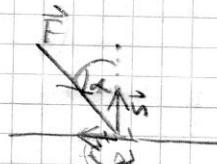
TENTOR

$$\sigma = \lim_{\Delta s \rightarrow 0} \frac{\Delta F}{\Delta s} = \frac{dF}{ds}$$



$$\sigma = \lim_{\Delta s \rightarrow 0} \frac{P \cdot n}{\Delta s} = \lim_{\Delta s \rightarrow 0} \frac{F \sin \alpha}{\Delta s}$$

TANKER
Napretanje



$$\sigma_n = \lim_{\Delta s \rightarrow 0} \frac{P \cdot n}{\Delta s} = \lim_{\Delta s \rightarrow 0} \frac{F \cos \alpha}{\Delta s}$$

Napredno
Napretanje

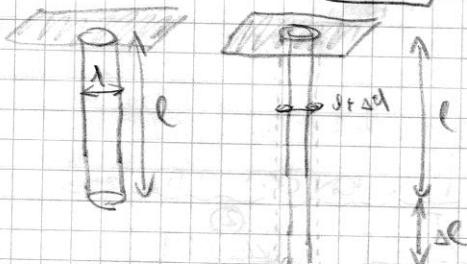
$$E = \frac{\text{projekcija na vrijednost}}{\text{potrebna deponovanje (i u } \sigma)}$$

I.) linearna projekcija (real)

$$\sigma = \frac{F}{A} = E \epsilon = E \frac{\Delta l}{l}$$

$$\boxed{\sigma = E \epsilon}$$

↳ Yukonu moze razlikovati



$$\frac{\Delta l}{l} = -\mu \frac{\Delta l}{l} \Rightarrow \mu = \frac{-\epsilon_1}{\epsilon_2}$$

pojedinačno

II.) volumen projekcija (real)

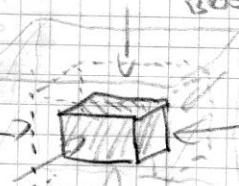
$$p = -B \epsilon = -B \frac{\Delta V}{V}$$

$$\boxed{p = -B \epsilon}$$

↳ Yukon kompresije

$$\epsilon = \frac{\Delta V}{V}$$

$$\bar{\sigma} = p$$



$$k = \frac{1}{3}$$

$$\frac{p}{s} = E \frac{\Delta l}{l} \Rightarrow F = \frac{(E s)}{l} \Delta l$$

Hooke
zakon

$$B = \frac{E}{3(1-2k)}$$

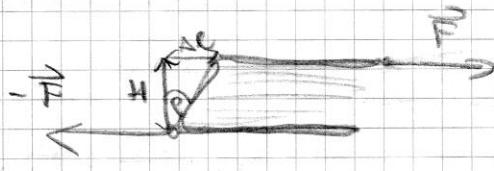
$$\boxed{F = k \Delta l}$$

↳ Yukon zavoj

$$\hat{F}_{el} = -\hat{F}$$

III) skalaže (smrk)

$$\epsilon = \frac{\Delta l}{l} = \tan \varphi \approx \varphi$$



$$\sigma = G \epsilon = G \cdot \varphi$$

$$G = Q_E$$

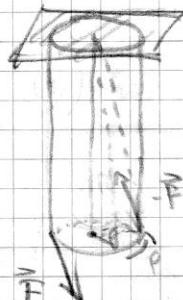
↳ nové
SMRKANÝ

$$G = \frac{B}{2(1+\mu)}$$

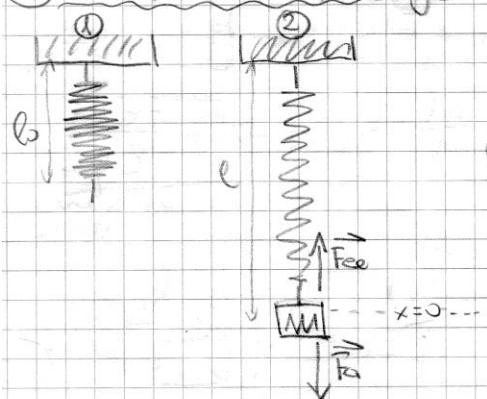
IV.) Tortíja

$$D = \frac{dM}{dp} = \frac{\pi r^4}{2e} G$$

↳ TORTÍJA
KONTAKT



(2) HARMONICKÝ POKRÁČOVÁNÍ



②

② rovnovážní poloha

$$\vec{F}_a = -\vec{F}_e$$

$$Mg = -k(l-x) \quad \text{Hodov} \\ Mg = -k(l-b) \quad \text{obecn}$$

③ počítání x

$$M\ddot{x} = F \quad \underline{\underline{2NA}}$$

$$M \frac{d^2x}{dt^2} = F_e + F_{ext}$$

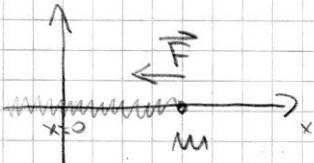
$$M \frac{d^2x}{dt^2} = Mg - k(l+x-b)$$

$$M \frac{d^2x}{dt^2} = (Mg - k(l-b)) - kx = 0$$

$$\boxed{m \frac{d^2x}{dt^2} + kx = 0}$$

HARMONIC OSCILLATION
U DIFERENCIJALNOJ OBILICI

$$\underline{x(t) = ?}$$



$$\vec{F} = -k \vec{x}$$

$$\left. \begin{array}{l} \text{(P.U. } t=0 \\ x=x_0 \\ v=v_0 \end{array} \right\}$$

$$m \frac{d^2x}{dt^2} + kx = 0$$

(lin. dif. jedn s hom.
koeficijentom)

$$x = C e^{\alpha t}$$

$$m \alpha^2 C e^{\alpha t} + k C e^{\alpha t} = 0$$

$$(C e^{\alpha t}) (m \alpha^2 + k) = 0 \Rightarrow m \alpha^2 + k = 0$$

$$\alpha^2 = -\frac{k}{m} = -\omega^2$$

$$\underline{\alpha = \pm i\omega}$$

rješenje lin. dif. jednačine:

$$x = C e^{i\omega t} + D e^{-i\omega t}$$

$$\underline{v(t) = ?}$$

$$v(t) = \frac{dx}{dt} = i\omega (e^{i\omega t} - e^{-i\omega t})$$

$$\left. \begin{array}{l} \text{(P.U. } t=0 \\ x_0 = C + D \\ v_0 = i\omega(C - D) \end{array} \right\}$$

$$C + D = R e C + i S i n C + R e D + i S i n D$$

$$*\left(\frac{?}{?}\right) \frac{x_0\omega}{v_0} = \frac{\sin \varphi}{\cos \varphi} \Rightarrow \boxed{\tan \varphi = \frac{x_0\omega}{v_0}} \quad \begin{matrix} \text{POČETNA} \\ \text{FAZA} \end{matrix}$$

$$x(t+\tau) = x(t)$$

$$\text{Asin}(\omega t + \varphi) = \text{Asin}(\omega t + \varphi)$$

$$\omega t + \omega \tau + \varphi = \omega t + \varphi + 2\pi$$

$$\tau = \frac{2\pi}{\omega} = 2\pi f$$

$$\boxed{T = 2\pi \sqrt{\frac{m}{k}}} \quad \text{PERIODA}$$

③ ENERGIJA HARU OSILJATOREA

$$E_k = \frac{mv^2}{2}$$

$$U = \frac{1}{2}kx^2$$

$$E = E_k + U = kx^2, *$$

$$x = \text{Asin}(\omega t + \varphi)$$

$$v = A\omega \cos(\omega t + \varphi)$$

$$E_k = \frac{m A^2 \omega^2 \cos^2(\omega t + \varphi)}{2} = A^2 m \frac{k}{m} \omega^2 (\omega t + \varphi) = \frac{1}{2} k A^2 \cos^2(\omega t + \varphi)$$

$$E_k(t) = \frac{1}{2} k A^2 \cos^2(\omega t + \varphi), \quad \text{fj. u. s. t.}$$

$$E_k = \frac{1}{2} k A^2 (1 - \sin^2(\omega t + \varphi)) = \frac{1}{2} k (A^2 - \overbrace{A^2 \sin^2(\omega t + \varphi)}) = \frac{1}{2} k (A^2 - x^2)$$

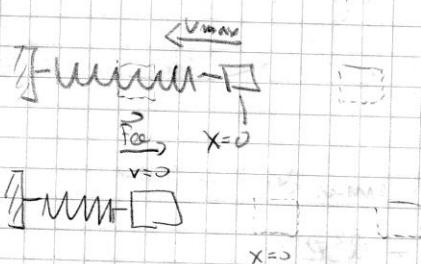
$$E_k(x) = \frac{1}{2} k (A^2 - x^2) \quad \text{fj. u. a. x}$$

$$\boxed{E_{k\max} = \frac{1}{2} k A^2} \quad (x=0, v=v_{\max})$$

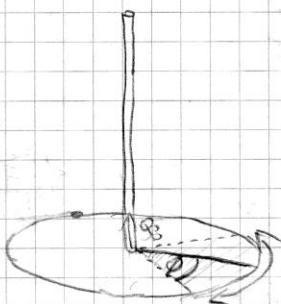
$$E_{k\min} = 0 \quad (x=A, v=0)$$

$$\text{iz } 20E(*) \Rightarrow \boxed{U_{\max} = \frac{1}{2} k A^2} \quad (x=A, v=0)$$

$$\boxed{U(t) = \frac{1}{2} k A^2 \sin^2(\omega t + \varphi),}$$



(4) Torzione Mjihalo



$$\vec{\phi} = \phi \vec{\phi}_0$$

iz torzony naprasy

$$\vec{M} = D\vec{\phi}$$

$$\vec{M}_{ee} = -\vec{M} = -D\vec{\phi}$$

$$M_{ee} = -D\phi$$

harmonicki oscilator (analogija na rotaciju)

$$I \frac{d^2\phi}{dt^2} = M_{ee} = -D\phi$$

$$\boxed{\omega^2 = \frac{D}{I}}$$

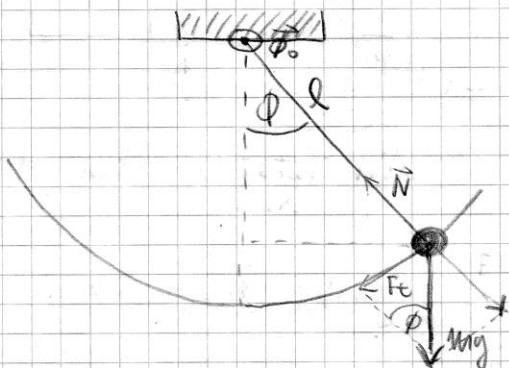
$$I \frac{d\phi}{dt} + D\phi = 0$$

$$\boxed{T = 2\pi \sqrt{\frac{I}{D}}}$$

$$\frac{d^2\phi}{dt^2} + \frac{D}{I}\phi = 0$$

$$\boxed{\phi(t) = \phi_{max} \sin(\omega t + \varphi)}$$

(5) MATEMATICKO MJIHALO



$$\vec{\phi} = \phi \vec{\phi}_0$$

$$\vec{M} = L F_t \vec{\phi}$$

$$\vec{M}_{ee} = -\vec{M} = -L F_t \vec{\phi}$$

$$M_{ee} = -L F_t = -mg \sin \phi$$

harmonicki oscilator:

$$I \frac{d^2\phi}{dt^2} = M_{ee} = -mg \sin \phi$$

$$(I \frac{d\phi}{dt})' + mg \frac{d\phi}{dt} = -mg \sin \phi$$

(damping)

$$\frac{d^2\phi}{dt^2} + \frac{g}{l} \sin \phi = 0$$

$$\phi \rightarrow 0$$

$$\sin \phi \rightarrow \phi$$

$$\frac{d^2\phi}{dt^2} + \frac{g}{l} \phi = 0$$

$$\boxed{\varphi(t) = \varphi_{\max} \sin(\omega t + \varphi)}$$

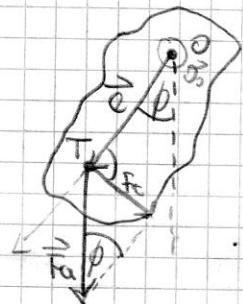
$$\omega^2 = \frac{g}{l}$$

$$T_0 = 2\pi \sqrt{\frac{l}{g}}$$

→ period T₀ rojedi samo za
maks amplitudu

→ za reellu amplitudu: $T = T_0 \left(1 + \frac{1}{4} \sin^2 \frac{\varphi_0}{2} + \frac{9}{64} \sin^4 \frac{\varphi_0}{2} + \dots \right)$

⑥ Fizicks nihalo



$$\vec{\theta} = \varphi \vec{\theta}_0$$

$$\vec{M} = l \vec{F}_r \vec{\theta}$$

$$\vec{M}_{\text{ext}} = -\vec{M}$$

$$M_{\text{ext}} = -l F_r = -l mg \sin \varphi$$

harmonični oscilatori:

$$I \frac{d^2\varphi}{dt^2} = M_{\text{ext}} = -mg l \sin \varphi$$

$$\frac{d^2\varphi}{dt^2} + \frac{mgl}{I} \sin \varphi = 0$$

$$\varphi \rightarrow 0 \quad \sin \varphi \rightarrow \varphi$$

$$\frac{d^2\varphi}{dt^2} + \frac{mgl}{I} \varphi = 0$$

$$\boxed{\varphi(t) = \varphi_{\max} \sin(\omega t + \varphi)}$$

$$\omega^2 = \frac{mgl}{I}$$

$$T = 2\pi \sqrt{\frac{I}{mgl}}$$

→ dvojnog matematičkog nihala bez mrač i sli T kuo i
fizicks nihalo:

$$2\pi \sqrt{\frac{l}{g}} = 2\pi \sqrt{\frac{I}{mgl}}$$

$$\boxed{C_R = \frac{I}{mgl}}$$

REDUCIRANA
DODJELA

→ reducerea de la un uniforme stator la un L

$$b = \frac{L}{2} \left\{ \begin{array}{l} 0 \\ \text{cm} \end{array} \right. I = I_{\text{cm}} + m d^2 = \frac{1}{12} m L^2 + m \frac{L^2}{4} = \frac{1}{3} m L^2$$

$$l_r = \frac{I}{mb} = \frac{\frac{1}{3} m L^2}{m \frac{L}{2}} = \frac{2}{3} L$$

$$\boxed{l_r = \frac{2}{3} L} \quad \begin{array}{l} \text{SREDISTE} \\ \text{VARA} \\ (\text{TITRANJA}) \\ \text{STAPP} \end{array}$$

(za $\frac{2}{3} L$ veličina je osi rotacije)

SREDISTE VARA → polozaj za l r uveličen je osi rotacije

7) Prijenosno titranje

$$\vec{F}_a = -b \vec{v}$$

b - konstanta trenja

2.NA

$$m \frac{d^2 x}{dt^2} = F_{el} + F_a = -kx - bv$$

$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = 0 \quad | : m$$

$$\frac{d^2 x}{dt^2} + \frac{b}{m} \frac{dx}{dt} + \frac{k}{m} x = 0$$

$$\frac{d^2 x}{dt^2} + 2\zeta \frac{dx}{dt} + \omega_0^2 x = 0$$

$$\underline{x(t) = ?}$$

$$\left. \begin{array}{l} \text{(P.U. } A=0 \\ x=x_0 \\ v=v_0 \end{array} \right\}$$

$$x = C e^{At}$$

$$\alpha^2 C e^{At} + 2\zeta \alpha C e^{At} + \omega_0^2 C e^{At} = 0$$

$$(C e^{At}) (\alpha^2 + 2\zeta \alpha + \omega_0^2) = 0$$

$$\alpha^2 + 2\zeta \alpha + \omega_0^2 = 0$$

$$\alpha_{1,2} = \frac{-2\zeta \pm \sqrt{4\zeta^2 - 4\omega_0^2}}{2}$$

$$\frac{m}{J} = 2\zeta = \frac{b}{m}$$

$$\boxed{\zeta = \frac{m}{2b}} \quad \begin{array}{l} \text{FAKTORE} \\ \text{POVLAČENJE} \end{array}$$

$$\boxed{\frac{k}{m} = \omega_0^2} \quad \begin{array}{l} \text{VLAJNITI} \\ \text{FEKCIJA} \\ \text{TIREZIJE} \end{array}$$

$$\omega_{1,2} = -\zeta \pm \sqrt{\zeta^2 - \omega_0^2}$$

a.) SLABO PRIGOREV: $\omega_0^2 > \zeta^2$ ($F_{\text{HARM}} > F_R$)

$$\boxed{\omega^2 = \omega_0^2 - \zeta^2} \quad \text{FREQUENZ} \quad \rightarrow \zeta^2 < \omega^2$$

$$\omega_{1,2} = -\zeta \pm \sqrt{-\omega^2} = -\zeta \pm i\omega$$

$$x = C e^{(\zeta+i\omega)t} + D e^{(\zeta-i\omega)t} = C e^{-\zeta t} e^{i\omega t} + D e^{-\zeta t} e^{-i\omega t}$$

$$\underline{v(t) = ?}$$

$$v(t) = \frac{dx}{dt} = (\zeta+i\omega) C e^{(\zeta+i\omega)t} + (\zeta-i\omega) D e^{(\zeta-i\omega)t}$$

$$\left. \begin{array}{l} \text{P.U. } t=0 \\ x_0 = C+D \\ v_0 = (\zeta+i\omega)C + (\zeta-i\omega)D \end{array} \right\}$$

$$C+D = \text{Re}C + i\text{Im}C + \text{Re}D + i\text{Im}D$$

$$x \in \mathbb{R} \Rightarrow C+D \in \mathbb{R} \rightarrow \boxed{\text{Im}C = -\text{Im}D} \quad (*)$$

$$\begin{aligned} (\zeta+i\omega)C + (\zeta-i\omega)D &= (\zeta+i\omega)(\text{Re}C + i\text{Im}C) + (\zeta-i\omega)(\text{Re}D + i\text{Im}D) \\ &= -\zeta(\text{Re}C + i\text{Im}C - \text{Re}D + i\text{Im}D) + i\omega(\text{Re}C + i\text{Im}C - \text{Re}D - i\text{Im}D) \end{aligned}$$

$$x \in \mathbb{R} \Rightarrow (\zeta+i\omega)C + (\zeta-i\omega)D \in \mathbb{R} \Rightarrow \boxed{\text{Im}C = -\text{Im}D} \quad (**) \\ \text{Re}C = \text{Re}D$$

\rightarrow zu (*) i (**) folgern:

$$\boxed{C=0}$$

$$\left\{ \begin{array}{l} \text{Re}z = \cos \varphi \\ \text{Im}z = \sin \varphi \end{array} \right\} \text{EUREKAS} \\ z = a + bi = |z| e^{i\varphi}$$

$$C = E e^{i\psi}$$

$$D = E e^{-i\psi}$$

$$\begin{aligned} x &= E e^{i\psi} e^{-\delta t} e^{i\omega t} + E e^{-i\psi} e^{-\delta t} e^{i\omega t} = E e^{-\delta t} (e^{i(\psi+\omega t)} + e^{-i(\psi+\omega t)}) \\ &= E e^{-\delta t} (\cos(\psi + \omega t) + i \sin(\psi + \omega t) + \cos(\psi + \omega t) - i \sin(\psi + \omega t)) \\ &= (2E e^{-\delta t}) \cos(\omega t + \psi) \end{aligned}$$

$$x(t) = A_0 e^{-\delta t} \cos(\omega t + \psi)$$

$$\varphi = \psi + \frac{\pi}{2}$$

$$x(t) = A_0 e^{-\delta t} \sin(\omega t + \varphi)$$

$$\omega = \sqrt{\omega_0^2 - \delta^2} = \sqrt{\frac{k}{m} - \frac{b^2}{4m^2}}$$

$$T = \frac{2\pi}{\omega} = \frac{2\pi}{\sqrt{\frac{kL}{m^2} - \frac{b^2}{4m^2}}}$$

$$A(t) = A_0 e^{-\delta t}$$

- f(ji)

maxim A

$$\lambda = \ln \frac{A(t)}{A(t+\tau)} = \ln \frac{A_0 e^{-\delta t}}{A_0 e^{-\delta(t+\tau)}}$$

$$= \ln \frac{e^{-\delta t}}{e^{-\delta(t+\tau)}} = \ln e^{\delta \tau} = \delta \tau = \delta T$$

$$\lambda = \delta T$$

logarithmsci
derektivat
periwata

$$\langle E \rangle = (e^{-\delta t})$$

$$\propto T \Rightarrow \ln \frac{A(t)}{A(t+\tau)} \propto T \Rightarrow A \propto \text{periwata T}$$

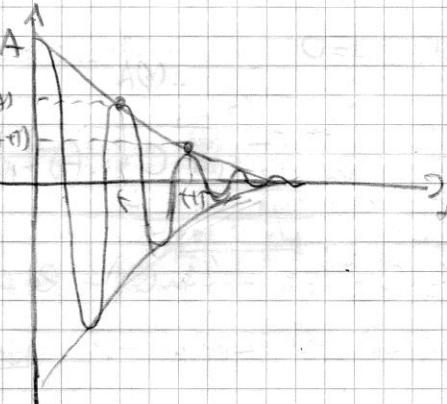
$$\langle E \rangle = \int_{t+\tau}^T E(t) dt$$

projected energy
per period

$$Q = 2\pi \frac{\langle E \rangle}{|\Delta E|}$$

FAKTOR
DOSEROK

projected energy up to joi oscillator ngs



$$Q = \frac{\pi}{\lambda}$$

$Q \gg \Rightarrow x \downarrow \Rightarrow$ prędkość \downarrow

Lj.

$Q \gg$ velik broj parow priblizno da je smanjji amplituda

$Q \ll$ prędkość jaka

b.) JAKO PRZYGŁĘBIE (APPROXIMACJA): $\omega^2 > \omega_0^2$

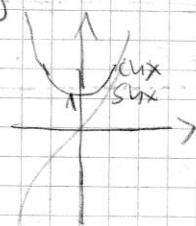
$$\omega^2 = \omega_0^2 + \omega^2 \quad \text{faktorajd}$$

$$\alpha_{112} = -\zeta \pm i\omega$$

$$x = A e^{(\zeta + i\omega)t} + B e^{(\zeta - i\omega)t}$$

$$\begin{cases} \text{ch } \omega = \frac{e^\omega + e^{-\omega}}{2} \\ \text{sh } \omega = \frac{e^\omega - e^{-\omega}}{2} \end{cases} \quad \begin{cases} \text{ch } \omega + \text{sh } \omega = e^\omega \\ \text{ch } \omega - \text{sh } \omega = e^{-\omega} \end{cases}$$

$$\begin{aligned} x &= A e^{-\zeta t} e^{i\omega t} + B e^{-\zeta t} e^{-i\omega t} = e^{-\zeta t} [A(\text{ch } \omega t + \text{sh } \omega t) + B(\text{ch } \omega t - \text{sh } \omega t)] \\ &= e^{-\zeta t} \left[\underbrace{\text{ch } \omega t (A + B)}_A + \underbrace{\text{sh } \omega t (A - B)}_B \right] \\ x(t) &\stackrel{?}{=} e^{-\zeta t} [A \text{ch } \omega t + B \text{sh } \omega t] \end{aligned}$$



$$v(t) = ?$$

$$v(t) = \frac{dx}{dt} = -\zeta e^{-\zeta t} [A \text{ch } \omega t + B \text{sh } \omega t] + e^{-\zeta t} \omega [A \text{sh } \omega t + B \text{ch } \omega t]$$

$$\left. \begin{array}{l} \text{P.U.} \\ t = 0 \end{array} \right\}$$

$$\boxed{x_0 = A}$$

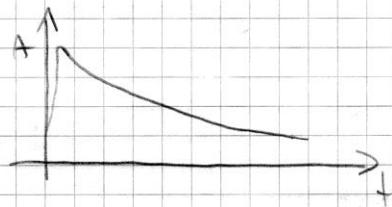
$$\left. \begin{array}{l} \\ v_0 = -\zeta \cdot 1 [A \cdot 1 + 0] + \omega \cdot [0 + B \cdot 1] = -A\zeta + B\omega \end{array} \right\}$$

$$B = \frac{v_0 + x_0 \omega}{\omega} = \frac{v_0 + x_0 j}{\omega}$$

$$jB = \frac{v_0 + x_0 j}{\omega}$$

$$x(t) = e^{-jt} \left[x_0 \cos \omega t + \frac{v_0 + x_0 j}{\omega} \sin \omega t \right]$$

→ APERIODISCHE TRENGE - nemus hranice vei oscilator
Slohu vekti n rame termu polozky



c.) KERITONO PRIAVÍSCHE: $\delta^2 = \omega_0^2$

$$\delta = \omega_0$$

$$\boxed{\omega=0}$$
 FERKUTUJU

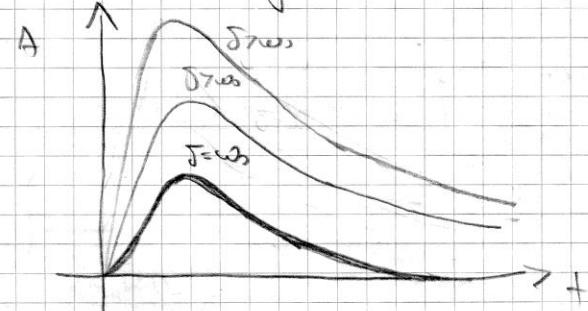
if APERIODICKA TRENGA:

$$x(t) = e^{-jt} \left[x_0 \cdot 1 + (v_0 + x_0 j) \frac{\sin \omega t}{\omega} \right] \quad (8)$$

$$\lim_{\omega \rightarrow 0} (v_0 + x_0 j) \frac{\sin \omega t}{\omega} = t(v_0 + x_0 j) \lim_{\omega \rightarrow 0} \frac{\sin \omega t}{\omega} = t(v_0 + x_0 j)$$

$$x(t) = e^{-jt} \left[x_0 + t(v_0 + x_0 j) \right] \quad \text{KERITOKO PERIODYK}$$

→ KERITOKO PERIODYK je najkratce APERIODICO PERIODYK:



⑧ ENERGIJA PRIGUŠENOG TITRANA

$$E_U = E_k + E_p \quad | \frac{d}{dt}$$

$$\frac{dE_U}{dt} = \frac{dE_k}{dt} + \frac{dE_p}{dt}$$

$$= \frac{dE_k}{dv} \left(\frac{dv}{dt} \right) + \frac{dE_p}{dx} \frac{dx}{dt} = Mv \cdot \frac{dv}{dt} + kxv$$

$$! = v(M \frac{dv}{dt} + kx)$$

→ prigušenog titrana:

$$M \frac{dv}{dt} = -kx + F_{\text{ext}}$$

$$M \frac{dv}{dt} + kx = -bv$$

$$\frac{dE_U}{dt} = -bv^2$$

$$| P = \vec{F} \cdot \vec{v} = bv^2$$

⑩ PRISILNO TITRANE

→ vremenska sile: $F_v = F_0 \sin \omega t$

2. NIA

$$M \frac{d^2x}{dt^2} = F_{\text{ext}} + F_{\text{int}} + F_v$$

$$M \frac{d^2x}{dt^2} = -kx - bv + F_0 \sin \omega t$$

$$M \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = F_0 \sin \omega t \quad | : M$$

$$\boxed{\frac{d^2x}{dt^2} + 2\zeta \frac{dx}{dt} + \omega_0^2 x = A_0 \sin \omega t} \quad \underline{A_0 = \frac{F_0}{M}}$$

→ vremenska titrana je

$$x = x_{\text{reg}} + x_{\text{per}}$$

$$x_{\text{proj}} = A(\omega) \sin(\omega t - \varphi)$$

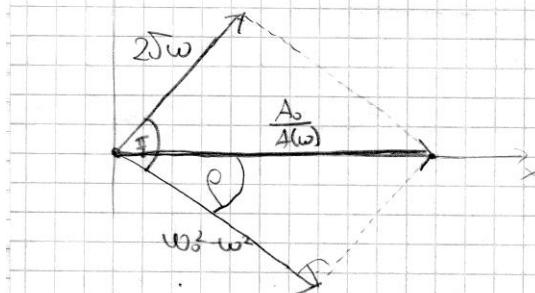
$$\underline{A(\omega), \varphi = ?}$$

$$-A(\omega) \omega^2 \sin(\omega t - \varphi) + 2\Im \omega A(\omega) \cos(\omega t - \varphi) + \omega_0^2 A(\omega) \sin(\omega t - \varphi) \\ = A_0 \sin(\omega t)$$

$$A(\omega) (\omega_0^2 - \omega^2) \sin(\omega t - \varphi) + 2\Im \omega A(\omega) \sin(\omega t - \varphi + \frac{\pi}{2}) \\ = A_0 \sin(\omega t) \quad | : A(\omega)$$

$$(\omega_0^2 - \omega^2) \sin(\omega t - \varphi) + 2\Im \omega \sin(\omega t - \varphi + \frac{\pi}{2}) = \frac{A_0}{A(\omega)} \sin(\omega t)$$

→ fator skala metoda:

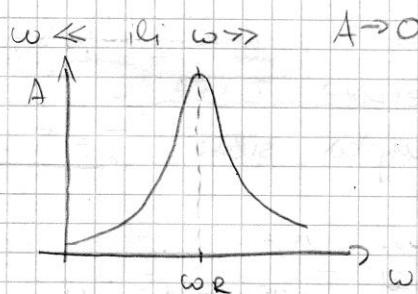


$$\frac{A_0}{A(\omega)} = \sqrt{(2\Im \omega)^2 + (\omega_0^2 - \omega^2)^2}$$

$$A(\omega) = \frac{A_0}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\Im^2 \omega^2}}$$

AMPLITUOA

$$\tan \varphi = \frac{2\Im \omega}{\omega_0^2 - \omega^2} \quad \text{FARA}$$



$$\underline{\omega_R, A_R = ?}$$

$$\frac{dA(\omega)}{d\omega} = 0$$

$$A(\omega) = A_0 \left((\omega_0^2 - \omega^2)^2 + 4\Im^2 \omega^2 \right)^{-\frac{1}{2}} \quad \left| \frac{d}{d\omega} \right.$$

$$0 = A_0 \left[\frac{1}{2} \left((\omega_0^2 - \omega^2)^2 + 4\Im^2 \omega^2 \right)^{\frac{1}{2}} \cdot (2(\omega_0^2 - \omega^2)(-2\omega) + 8\Im^2 \omega) \right]$$

$$0 = A_0 (-2) \sqrt{(\omega_0^2 - \omega^2)^2 + 4\Im^2 \omega^2} \cdot (-2(\omega_0^2 - \omega^2) + 2\Im^2 \omega)$$

$$\omega_0^2 - \omega^2 = 25^2$$

$$\omega^2 = \omega_0^2 - 25^2$$

$$\boxed{\omega_2 = \sqrt{\omega_0^2 - 25^2}}$$

RESONANZA
FREQUENZA

$$A(\omega_e) = \frac{A_0}{\sqrt{(\omega_0^2 - \omega_e)^2 + 4\zeta^2\omega_e^2}} = \frac{A_0}{\sqrt{(\omega_0^2 - \omega_0^2 + 25^2)^2 + 4\zeta^2(\omega_0^2 - 25^2)}}$$

$$A(\omega_e) = \frac{A_0}{2\zeta\sqrt{\zeta^2 + \omega_0^2 - 25^2}}$$

$$\boxed{A(\omega_e) = \frac{A_0}{2\zeta\sqrt{\omega_0^2 - \zeta^2}}} \quad \text{RESONANZA (MAX)} \quad \text{AMPLITUDE}$$

$$x_{obj} = A'e^{-\zeta t} \sin(\omega't + \rho_s)$$

$$x(t) = x_{obj} + x_{ref}$$

$$\boxed{x(t) = A'e^{-\zeta t} \sin(\omega't + \rho_s) + A(\omega) \sin(\omega t - \rho)} \quad \text{PRIMNO
TISTRANGE}$$

↳ na početku tihu sa frekvencijom ω' tj s vlastitim frejm
veličinama veliki neusredna vlastita frekvenca utvare
te dođe u STACIONARNO stanje gde je osnovni S_2
frekvenca

⑪ Lissajousove krivulje

$$x = A_1 \sin \omega t$$

$$y = A_2 \sin(\omega t + \Delta\phi)$$

a) $\omega_1 = \omega_2 = \omega$

$$\Delta\phi = C$$

$$y = A_2 \sin(\omega \arcsin \frac{x}{A_1})$$

$$\boxed{y = \frac{A_2}{A_1} x} \quad \text{②}$$

$$\omega t = \arcsin \frac{x}{A_1}$$

$$t = \arcsin \frac{x}{\omega}$$

b.) $\omega_1 = \omega_2 = \omega$

$$\Delta\varphi = \pi$$

$$y = A_1 \sin(\omega t + \pi) = -A_1 \sin \omega t$$

$$\frac{x}{y} = \frac{A_1 \cos \omega t}{-A_1 \sin \omega t}$$

$$y = \frac{-A_1}{A_1} x \quad (2)$$

c.) $\omega_1 = \omega_2 = \omega$

$$\Delta\varphi = \frac{\pi}{2}$$

$$y = A_2 \sin(\omega t + \frac{\pi}{2}) = A_2 \cos \omega t$$

$$\frac{x^2}{A_1^2} + \frac{y^2}{A_2^2} = \sin^2 \omega t + \cos^2 \omega t = 1$$

$$\left[\frac{x^2}{A_1^2} + \frac{y^2}{A_2^2} = 1 \right] \quad (3)$$

elipsen surjera konuslere rıza salır

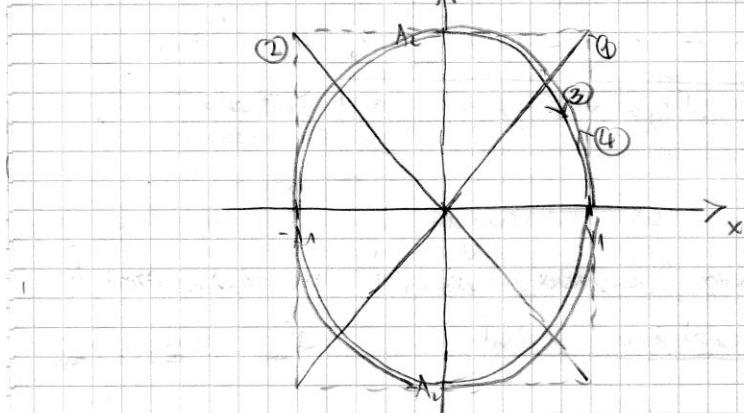
d.) $\omega_1 = \omega_2 = \omega$

$$\Delta\varphi = \frac{3\pi}{2}$$

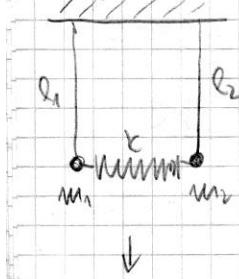
$$y = A_2 \sin(\omega t + \frac{3\pi}{2}) = -A_2 \cos \omega t$$

$$\left[\frac{x^2}{A_1^2} + \frac{y^2}{A_2^2} = 1 \right] \quad (4)$$

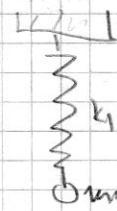
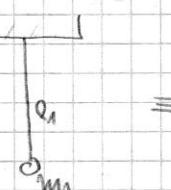
elipsen surjera obratıya konuslere rıza salır



(12) OBERBAKKALI NİHALA



analizi

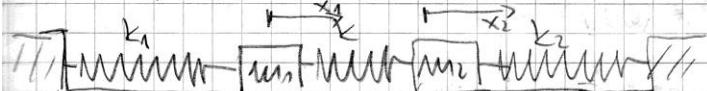


$$\omega_{MNj} = \omega_{HO}$$

$$\frac{g}{\ell_1} = \frac{k_1}{m_1}$$

$$l_1 = l_2 \quad m_1 = m_2 \quad \downarrow$$

→ transformieren in doppelte System:



$$\frac{g}{g_1} = \frac{k_1}{m_1}$$

$$\frac{g}{g_2} = \frac{k_2}{m_2}$$

ZNA:

$$\begin{aligned} m_1 \frac{d^2x_1}{dt^2} &= -k_1 x_1 + k(x_2 - x_1) \\ m_2 \frac{d^2x_2}{dt^2} &= -k_2 x_2 - k(x_2 - x_1) \end{aligned} \quad \left. \begin{array}{l} \text{jedneinde} \\ \text{gibende} \end{array} \right\}$$

k steht bei

$$l_1 = l_2 \Rightarrow \frac{k_1}{m_1} = \frac{k_2}{m_2} = \omega_0^2$$

$$\frac{k}{m_1} = \frac{k}{m_2} = \Omega^2$$

$$\frac{d^2x_1}{dt^2} = -\frac{k_1}{m_1} x_1 + \frac{k}{m_1} x_2 - \frac{k}{m_1} x_1$$

$$\frac{d^2x_2}{dt^2} = -\frac{k_2}{m_2} x_2 - \frac{k}{m_2} x_2 + \frac{k}{m_2} x_1$$

$$(1) \frac{d^2x_1}{dt^2} + x_1 (\omega_0^2 + \Omega^2) = -\Omega^2 x_2$$

$$x_1 = A \sin(\omega t + \psi)$$

$$x_2 = A' \sin(\omega t + \psi')$$

$$(2) \frac{d^2x_2}{dt^2} + x_2 (\omega_0^2 + \Omega^2) = \Omega^2 x_1$$

$$(1) -A \omega^2 \sin(\omega t + \psi) + (\omega_0^2 + \Omega^2) A \sin(\omega t + \psi) = \Omega^2 A' \sin(\omega t + \psi')$$

$$(2) -A' \omega^2 \sin(\omega t + \psi') + (\omega_0^2 + \Omega^2) A' \sin(\omega t + \psi') = \Omega^2 A \sin(\omega t + \psi)$$

zugehöriges: $\boxed{\omega = \omega'}$

a.) TITRAGE \cup FAZI: $\boxed{\psi = \psi'}$

$$x_1 = A \sin(\omega t + \psi)$$

$$x_2 = A' \sin(\omega t + \psi)$$

$$(1) -A \omega^2 \sin(\omega t + \psi) + (\omega_0^2 + \Omega^2) A \sin(\omega t + \psi) = \Omega^2 A' \sin(\omega t + \psi)$$

$$-A \omega^2 + (\omega_0^2 + \Omega^2) A = \Omega^2 A' \quad | : A$$

$$-\omega^2 + (\omega_0^2 - \Omega^2) - \frac{A'}{A} \Omega^2 = 0 \quad (*)$$

$$(1) - A' \omega^2 \sin(\omega t + \psi) + (\omega_0^2 + \Omega^2) A' \sin(\omega t + \phi) = \Omega^2 A \sin(\omega t + \psi)$$

$$- A' \omega^2 + A' (\omega_0^2 + \Omega^2) - \Omega^2 A = 0 \quad / : A'$$

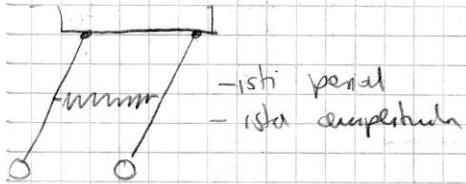
$$-\omega^2 + (\omega_0^2 + \Omega^2) - \frac{A'}{A} \Omega^2 = 0 \quad (**)$$

$$(*) = (**) \quad \text{---}$$

$$-\omega^2 + (\omega_0^2 - \Omega^2) - \frac{A'}{A} \Omega^2 = -\omega^2 + (\omega_0^2 + \Omega^2) - \frac{A}{A'} \Omega^2$$

$$\frac{A'}{A} = \frac{A}{A'} \Rightarrow \boxed{A = A'} \Rightarrow -\omega^2 + (\omega_0^2 + \Omega^2) - \Omega^2 = 0$$

$$\begin{aligned} \omega^2 &= \omega_0^2 + \Omega^2 - \Omega^2 \\ \omega &= \omega_0 \end{aligned}$$



$$b.) \text{ TITRANGE } \cup \text{ PROTUPATI } \boxed{\psi' = \psi + \pi}$$

$$x_1 = A \sin(\omega t + \psi)$$

$$x_2 = A' \sin(\omega t + \psi + \pi)$$

$$(1) - A \omega^2 \sin(\omega t + \psi) + (\omega_0^2 + \Omega^2) A \sin(\omega t + \psi) = \Omega^2 A' \sin(\omega t + \psi + \pi)$$

$$- A \omega^2 + A (\omega_0^2 + \Omega^2) + \Omega^2 A' = 0 \quad / : A \quad - \Omega^2 A' \sin(\omega t + \psi)$$

$$-\omega^2 + (\omega_0^2 + \Omega^2) + \frac{A'}{A} \Omega^2 = 0 \quad (*)$$

$$(2) - A' \omega^2 \sin(\omega t + \psi + \pi) + (\omega_0^2 + \Omega^2) A' \sin(\omega t + \psi + \pi) = \Omega^2 A \sin(\omega t + \psi)$$

$$A' \omega^2 \sin(\omega t + \psi) - (\omega_0^2 + \Omega^2) A' \sin(\omega t + \psi) = \Omega^2 A \sin(\omega t + \psi)$$

$$A' \omega^2 - (\omega_0^2 + \Omega^2) A' - \Omega^2 A = 0 \quad / : A$$

$$\frac{A'}{A} \omega^2 - \frac{A'}{A} (\omega_0^2 + \Omega^2) - \Omega^2 = 0 \quad (**)$$

$$(*) = (\star\star) \quad 1:-1$$

$$-\omega^2 + (\omega_0^2 + \Omega^2) + \frac{A'}{A} \omega^2 = -\frac{A'}{A} \cos^2 + \frac{A'}{A} (\omega_0^2 + \Omega^2) + \omega^2$$

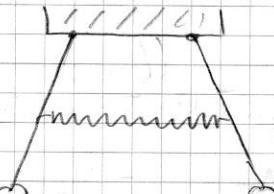
$$\frac{A'}{A} (\omega^2 + \omega_0^2 - (\omega_0^2 + \Omega^2)) = \omega^2 + \omega^2 - (\omega_0^2 + \Omega^2)$$

$$\frac{A'}{A} = 1$$

$$A = A' \Rightarrow \omega^2 - (\omega_0^2 + \Omega^2) - \omega^2 = 0$$

$$\omega^2 = 2\Omega^2 + \omega_0^2$$

$$\omega = \sqrt{\omega_0^2 + 2\Omega^2}$$



- period kraci

- amplituda vlny

fizicko tvaruje

$$x_1 = A_1 \sin(\omega_1 t + \psi_1)$$

$$x_2 = A_2 \sin(\omega_2 t + \psi_2)$$

potuliformo tvaruje

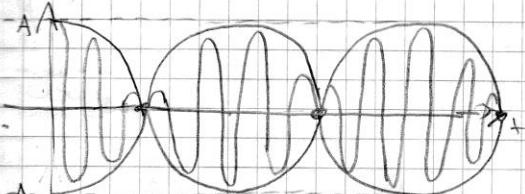
$$x_1 = A_2 \sin(\omega_2 t + \psi_2)$$

$$x_2 = -A_2 \sin(\omega_2 t + \psi_2)$$

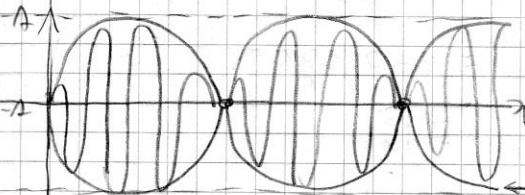
$$x_1 = A_1 \sin(\omega_1 t + \psi_1) + A_2 \sin(\omega_2 t + \psi_2)$$

$$x_2 = A_1 \sin(\omega_1 t + \psi_1) - A_2 \sin(\omega_2 t + \psi_2)$$

OPČE RJEŠENJE
LIM DIF. ZAKONIĆE



1. oscilator



2. oscilator

vlny

$$x_1 = 2A \cos\left(\frac{\omega_1 - \omega_2}{2}t + \frac{\psi_1 - \psi_2}{2}\right) \sin\left(\frac{\omega_1 + \omega_2}{2}t + \frac{\psi_1 + \psi_2}{2}\right)$$

$$x_2 = 2A \sin\left(\frac{\omega_1 - \omega_2}{2}t + \frac{\psi_1 - \psi_2}{2}\right) \cos\left(\frac{\omega_1 + \omega_2}{2}t + \frac{\psi_1 + \psi_2}{2}\right)$$

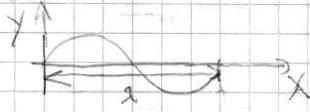
$$\omega = A_1 = A_2 = A$$

(13) VALNA FUNKCIJA

→ periodični, kemi slični, transverzalni val

$$y(t, x) = A \sin(\omega t - kx + \phi)$$

$$\boxed{V = \frac{\lambda}{T}} \quad [\text{VALNI BROJ}]$$



21

$$y(T, 0) = y(T, \lambda)$$

$$\text{Asin}(\omega T) = \text{Asin}(\omega T - k\lambda)$$

$$\omega T - 2\pi = \omega T - k\lambda$$

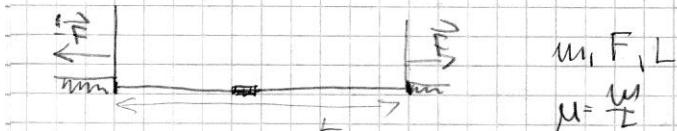
$$\boxed{k = \frac{2\pi}{\lambda}} \quad [\text{VALNI BROJ}]$$

$$x = \frac{2\pi}{k} \Rightarrow v = \frac{\omega}{k}$$

$$\boxed{v = \frac{\omega}{k}}$$

(14) TRANSVERZALNI VAL NA ŽICI

{ P. U. tanka žica $d \ll \lambda$ }
 Silmenski elastičnost žica
 homogenost žica



$$m, F, L$$

$$\mu = \frac{m}{L}$$

$$y(x, t) \rightarrow A \ll \lambda \quad dF_y = F_{r2} - F_{l1} = F \sin \alpha_2 - F \sin \alpha_1$$

$$= [\lambda \gg, \sin \alpha \Rightarrow \alpha] = P(\alpha - \pi)$$

$$= F d\alpha =$$

$$\tan \alpha = \frac{\partial y}{\partial x} = \alpha / d$$

$$d\alpha = \frac{\partial^2 y}{\partial x^2} dx$$

$$dF_y = F \frac{\partial^2 y}{\partial x^2} dx \quad (*)$$

2.NA

$$dFy = \frac{\partial^2 y}{\partial t^2} du = \frac{\partial^2 y}{\partial t^2} u dx \quad (**)$$

$$(*) = (**)$$

$$F \frac{\partial^2 y}{\partial x^2} dx = \frac{\partial^2 y}{\partial t^2} u dx$$

$$\boxed{\frac{\partial^2 y}{\partial x^2} - \frac{u}{F} \frac{\partial^2 y}{\partial t^2} = 0} \quad \begin{array}{l} \text{VALMA} \\ \text{JEDNADŽBA} \end{array}$$

→ valna f-ja se obogatila novim jednačinom:

$$\sin(\omega t \mp kx) = \underbrace{\sin(\omega(t \mp \frac{x}{v}))}_{f(t \mp \frac{x}{v})}$$

jer je $s(x,t) = f(x-vt) + g(x+vt)$ opis novih
difuznečjelih jednačina.

$f(x-vt) \rightarrow$ opisuje vel velnu

$g(x+vt) \rightarrow$ opisuje vel velnu

Dokaz je sljedeći:

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial u} \frac{du}{dx} = \frac{\partial f}{\partial u}$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial u} \right) = \frac{\partial}{\partial u} \left(\frac{\partial f}{\partial x} \right) \cdot \frac{\partial}{\partial u} \left(\frac{\partial f}{\partial u} \right) = \frac{\partial^2 f}{\partial u^2}$$

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial u} \frac{du}{dt} = \frac{\partial f}{\partial u} (-v)$$

$$\frac{\partial^2 f}{\partial t^2} = \frac{\partial}{\partial t} \left(\frac{\partial f}{\partial t} \right) = \frac{\partial}{\partial t} \left(\frac{\partial f}{\partial u} (-v) \right) = \frac{\partial}{\partial u} \left(\frac{\partial f}{\partial t} \right) (-v) = \frac{\partial}{\partial u} \left(\frac{\partial f}{\partial u} (-v) (-v) \right) = \frac{\partial^2 f}{\partial u^2} v^2$$

$$\frac{\partial^2}{\partial x^2} - \frac{1}{F} \frac{\partial^2}{\partial t^2} v^2 = 0 \Rightarrow v^2 = \frac{F}{\mu} \Rightarrow v = \sqrt{\frac{F}{\mu}} \quad \text{FAZNA BOMINA}$$

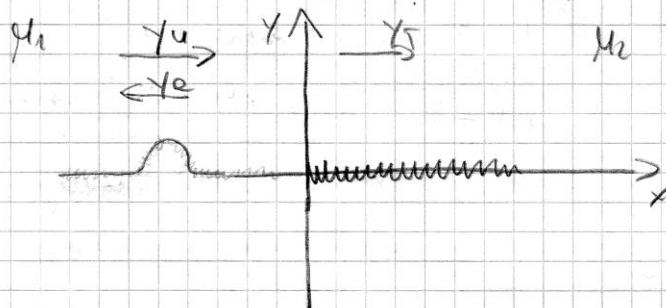
K

brzina ne ovisi o
frekvenciji \Rightarrow Nedispersivna
sredstvo

$$w = k \sqrt{\frac{F}{\mu}} \quad \text{DISPERZIJSKA
SREDSTVA}$$

(15) REFLEKSija VALA

{ P.U. nije nedispersivno sredstvo \Rightarrow vala formira bozine
 { nije kontinuirano ①
 { nije bes signal ② }



$$n_1 = \sqrt{\frac{F_1}{\mu_1}}$$

$$n_2 = \sqrt{\frac{F_2}{\mu_2}}$$

$$\left| \frac{v_1}{v_2} = \frac{n_2}{n_1} \right|$$

$$y_i = A_i \sin(\omega(t - \frac{x}{v_1}))$$

$$y_e = A_e \sin(\omega(t + \frac{x}{v_1}))$$

$$y_r = A_r \sin(\omega(t - \frac{x}{v_2}))$$

① uvjet:

$$y_i(t, 0) + y_e(t, 0) = y_r(t, 0)$$

$$A_i \sin(\omega t) + A_e \sin(\omega t) = A_r \sin(\omega t)$$

$$(A_i + A_e) = A_r$$

② uvjet:

$$\frac{\partial y_i}{\partial x} + \frac{\partial y_e}{\partial x} = \frac{\partial y_r}{\partial x} \quad x=0$$

$$A_1 \cos(\omega t + \frac{x}{v_1}) \left(\frac{1}{v_1} \right) + A_2 \cos(\omega t + \frac{x}{v_2}) \left(\frac{1}{v_2} \right) = A_1 \cos(\omega t + \frac{x}{v_1}) \left(\frac{1}{v_1} \right)$$

$$\frac{Av}{v_1} - \frac{Ae}{v_1} = \frac{At}{v_2}$$

$$\frac{Av - Ae}{v_1} = \frac{At}{v_2}$$

①; ②

$$\frac{Av - Ae}{v_1} = \frac{Av + Ae}{v_2}$$

$$Av v_2 - Ae v_2 = Av v_1 + Ae v_1$$

$$Av(v_2 - v_1) = Ae(v_1 + v_2)$$

$$Ae = \frac{v_2 - v_1}{v_1 + v_2} Av$$

$$\frac{Av - (At - Ae)}{v_1} = \frac{At}{v_2}$$

$$Av v_2 - At v_2 + Av v_1 + Ae v_1 = At v_1$$

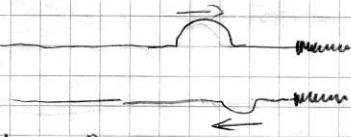
$$2Av v_2 = At(v_1 + v_2)$$

$$At = \frac{2v_2}{v_1 + v_2} Av$$

Slučajai:

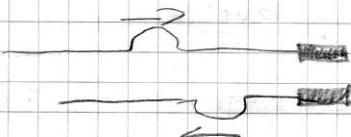
$$\textcircled{1} \quad [v_1 < v_2] \Rightarrow v_1 > v_2 \Rightarrow Ae < 0$$

$$y_R = -|Ae| \sin(\omega(t + \frac{x}{v_1})) = |Ae| \sin(\omega(t + \frac{x}{v_1}) + \pi)$$



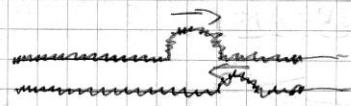
$$\textcircled{2} \quad [m_2 = \infty] \text{ įniti koky} \Rightarrow v_2 = 0 \Rightarrow Ae = -Av$$

$$y_R = -Av \sin(\omega(t + \frac{x}{v_1})) = Av \sin(\omega(t + \frac{x}{v_1}) + \alpha)$$



$$\textcircled{3} \quad [v_1 > v_2] \Rightarrow v_1 > v_2 \Rightarrow Ae > 0$$

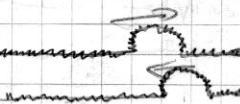
$$y_R = |Ae| \sin(\omega(t + \frac{x}{v_1}))$$



$$\textcircled{4} \quad [m_1 = 0] \text{ /slabolinis kokyj}$$

$$Ae = \frac{\sqrt{k_2} - \sqrt{k_1}}{\sqrt{k_1} + \sqrt{k_2}} A / \sqrt{k_1} = \frac{1 - \sqrt{\frac{k_2}{k_1}}}{1 + \sqrt{\frac{k_2}{k_1}}} Av = Av$$

$$Ae = Av$$

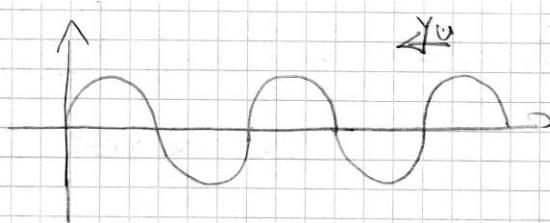


⑯ STOJNÍ VAL

$$y_u = A \sin(\omega t + kx)$$

$$y_R = A \sin(\omega t - kx + \pi)$$

$$\therefore = -A \sin(\omega t - kx)$$

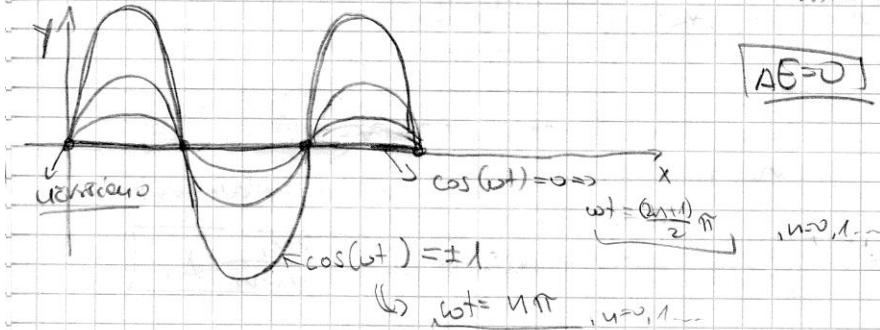


$$Y = y_u + y_R = A \sin(\omega t + kx) - A \sin(\omega t - kx)$$

$$= A 2 \cos\left(\frac{\omega t + \omega t - kx + kx}{2}\right) \sin\left(\frac{\omega t - kx - \omega t + kx}{2}\right)$$

$$Y = 2A \cos(\omega t) \sin(kx)$$

JEDNAKOSTA SPOJENÍ
VZORKA (Rozdíl uve.)



$$\boxed{\Delta E = 0}$$

CYKL $\rightarrow Y=0$ (po prahu)

$$\sin(kx_u) = 0$$

$$kx_u = n\pi \Rightarrow x_u = \frac{n\pi}{2k}$$

$$\boxed{x_u = \frac{n\pi}{2}} \quad , n = 0, 1, 2, \dots$$

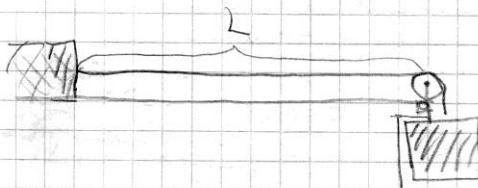
TERMIN $y = y_{\max}$ (po prahu)

$$\sin(kx_u) = \pm 1$$

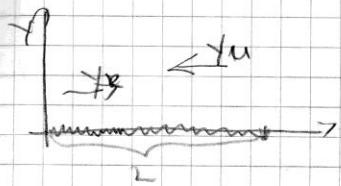
$$kx_u = \frac{(2n+1)\pi}{2} \Rightarrow x_u = \frac{(2n+1)\pi}{2 \cdot 2k}$$

$$\boxed{x_u = \frac{(2n+1)\pi}{4}} \quad , n = 0, 1, 2, \dots$$

⑰ TRANSVERZALNÍ STOJNÍ VAL NA NAPĚTOJ řici



\rightarrow do obou krajů učesávána ①



$$y_A(x,t) = A_1 \sin(\omega t + kx)$$

$$y_B(x,t) = A_2 \sin(\omega t - kx)$$

$$y = y_A + y_B = A_1 \sin(\omega t + kx) + A_2 \sin(\omega t - kx)$$

$$\Rightarrow (1) \Rightarrow y(t, 0) = 0$$

$$0 = A_1 \sin(kx) + A_2 \sin(-kx)$$

$$\underline{[A_1 = -A_2]} \Rightarrow y_B = -A_1 \sin(\omega t - kx) = \underline{A_1 \sin(\omega t - kx + \pi)}$$

$$y = A \sin(\omega t + kx) + A \sin(\omega t - kx + \pi) = 2A \cos(\omega t) \sin(kx)$$

\hookrightarrow stojni
val

$$\Rightarrow (1) \Rightarrow y(t, L) = 0$$

$$2A \cos(\omega t) \sin(kL) = 0$$

$$\sin(kL) = 0 \Rightarrow kL = n\pi$$

$$L = \frac{n\pi}{2} \cdot \frac{2}{k}$$

$$L = \frac{n\pi}{2} \cdot u$$

$$x_n = \frac{2L}{n}$$

n - broj harmonika

$$n = 1, 2, 3, \dots$$

$$f_n = \frac{V}{x_n} = \frac{n}{2L} \sqrt{\frac{F}{\mu}}$$

$$f_n = \frac{n}{2L} \sqrt{\frac{F}{\mu}}$$

VLASNI
FREKVENCIJA

$$f_1 = \frac{1}{2L} \sqrt{\frac{F}{\mu}}$$

OSNOVNA
FREKVENCIJA

$$f_n = n f_1$$

$$y(x, t) = \sum_{n=1}^{\infty} (A_n \cos \omega_n t + B_n \sin \omega_n t) \sin k_n x$$

VALNA FUNKCIJA
STOJANOG VALA
(Fourierov val)

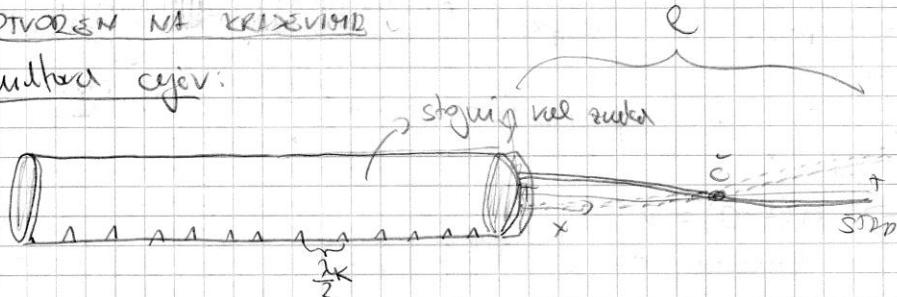
$$P.U. s(t=0, x) = s_0(x) = \sum_{n=1}^{\infty} A_n \sin k_n x$$

$$s_0(x, t=0) = \frac{1}{2} s(x)$$

18) LONGITUDINALNI STOJINI VAL

a.) OTVORENI NA KRIZEVIMU

→ Kužnični cevi:



na otvorenom kraju velika padača u fazi:

$$y_1 = A \sin(\omega t - kx)$$

$$y_2 = A \sin(\omega t + kx)$$

$$y = 2A \cos kx \sin \omega t$$

longitudinalni
stotni val

$$\left. \begin{array}{l} \text{P.U. } \textcircled{1} y(t, L) = \max \\ \textcircled{2} y(t, \frac{L}{2}) = 0 \end{array} \right\}$$

$$\textcircled{1} \quad \cos k_n L = \pm 1$$

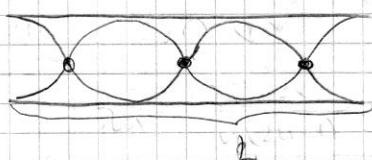
$$k_n L = n\pi, \quad n=0, 1, \dots$$

$$L = \frac{(2n+1)\pi}{2k_n} R_n$$

$$R_n = \frac{2L}{(2n+1)\pi}, \quad n=1, 2, \dots$$

SLOBODNI KRIZVI

* OTVORENA SURPLA



$$R_n = \frac{2L}{n\pi}$$

broj harmonika

$$\textcircled{2} \quad \cos k_n \frac{L}{2} = 0$$

$$k_n \frac{L}{2} = \frac{(2n+1)\pi}{2}, \quad n=0, 1, \dots$$

$$L = \frac{(2n+1)\pi}{2k_n} R_n$$

$$R_n = \frac{2L}{(2n+1)\pi}, \quad n=0, 1, \dots$$

$$R_n = \frac{2L}{2n+1}, \quad n=1, 2, \dots$$

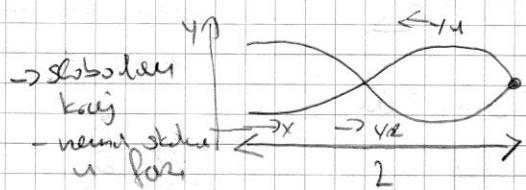
↳ zatvorenje i prethodno
ugrij

SLOBODNI KRIZVI, VENJSKI
NA SREDIN

* STAP KUŽNIČNI CEVI

$$V_k = f_k \lambda_k$$

b.) SLOBODAN KREJ - ČVOR



$$y_1 = A \sin(\omega t - kx)$$

$$y_2 = A \sin(\omega t + kx)$$

$$y = 2A \cos(kx) \sin(\omega t)$$

- (P.U. ① $y(t, 0) = \max y \rightarrow$ mijet
 ② $y(t, L) = 0 \rightarrow$ mijeti su globali lanj}

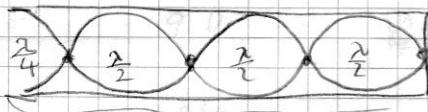
$$\text{② } \cos k_n L = 0$$

$$k_n L = \frac{(2n+1)\pi}{2} \quad n = 0, 1, \dots$$

$$L = \frac{(2n+1)\pi}{4} \lambda$$

$$\lambda_n = \frac{4L}{(2n+1)} \quad n = 0, 1, 2, \dots$$

* ZATVORENA SVIRALA



$$n=3$$

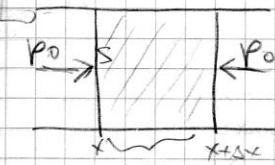
$$L = 3\frac{\lambda}{2} + \frac{\lambda}{4} = \frac{7\lambda}{4}$$

Pravcra:

$$L = \frac{(2n+1)}{4} \lambda$$

$$L = \frac{7}{4} \lambda$$

⑨ LONGITUDINALNI VALJOVI ZVUKA BRIJINA ZVUKA



$$\Delta V_0 = S \Delta x$$

$$\Delta m = \rho \Delta V_0 = \rho S \Delta x$$

↪ mijenja se tlak:



$$p_1 = p_0 + \Delta p$$

$$\Delta \psi = \psi(t, x + \Delta x) - \psi(t, x)$$

$$p_2 = p_0 + \Delta p + \Delta \psi$$

$$\Delta p = p_2 - p_1 \quad (\text{pct. } p_2 > p_1)$$

HOOKEOV ZAKON

$$\Delta \psi = \psi(t, x) + \frac{\partial \psi}{\partial x} \Delta x - \psi(t, x)$$

$$\Delta \psi = \frac{\partial \psi}{\partial x} \Delta x$$

2 M4

$$\Delta x \rightarrow dx$$

$$dm = \rho S dx$$

$$\left. \begin{array}{l}
 p = -B \frac{\Delta V}{\Delta V_0} = -B \frac{\Delta \Psi \delta x}{\delta \Delta x} = -B \frac{\Delta \Psi}{\delta x} \\
 p = -B \frac{\partial \Psi}{\partial x} \quad |d \\
 dp = -B \frac{\partial^2 \Psi}{\partial x^2} dx \\
 dp = -B \frac{\partial \Psi}{\partial x} dx
 \end{array} \right| \quad \begin{array}{l}
 p_2 - p_1 = dp \\
 dF = -S dp \\
 dF = -S dp = dm \frac{\partial \Psi}{\partial T} \\
 = S g dx \frac{\partial \Psi}{\partial T}
 \end{array} \quad \begin{array}{l}
 (p_2 - p_1 > 0, \text{ real gas}) \\
 (\text{u sogen } \rightarrow)
 \end{array}$$

$$8B \frac{\partial^2 \Psi}{\partial x^2} dx = 8g dx \frac{\partial^2 \Psi}{\partial r^2}$$

$$\boxed{\frac{\partial^2 \Psi}{\partial x^2} - \frac{1}{B/g} \frac{\partial^2 \Psi}{\partial r^2} = 0}$$

VALNA SEDMÄOSTK
LÖNG. VALA (2WCF)

$$\boxed{v^2 = \frac{B}{\rho}} \quad \text{BRAINZ + KKA (Tokunow)}$$

$$\rho(t, x) = A \rho_{\max} \cos(\omega t - kx) \quad | \quad \text{FUNKIJĘ} \quad \text{TLAKĄ} \quad | \quad A_{\text{pum}} = A_{\text{pw}},$$

$$V^2 = \frac{E}{S} \quad \text{BEMNA}$$

zuver (stetig)

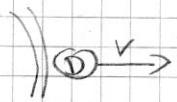
(29) DOPPLEROV EFEKT

a) 



$$f' = \frac{v_0 + v}{\lambda} = \frac{v_0 + v}{\frac{v}{f}} = \left(\frac{v_0 + v}{v}\right) f$$

$$f' = f \left(1 + \frac{v_0}{v}\right)$$



$$f' = \frac{v - v_0}{\lambda} = \frac{v - v_0}{\frac{\lambda}{f}} = f(1 - \frac{v_0}{v})$$

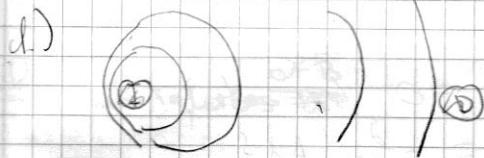
$$\boxed{f' = f(1 - \frac{v_0}{v})}$$



$$\lambda' = \lambda - v_I T$$

$$f' = \frac{v}{\lambda'} = \frac{v}{\lambda - v_I T} = \frac{v}{\frac{\lambda}{f} - \frac{v_I T}{f}} = f(\frac{v}{v - v_I})$$

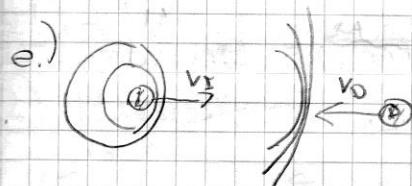
$$\boxed{f' = f(\frac{v}{v - v_I})}$$



$$\lambda' = \lambda + v_I T = \frac{\lambda}{f} + \frac{v_I T}{f}$$

$$f' = \frac{v}{\lambda'} = \frac{v}{\frac{\lambda}{f} + \frac{v_I T}{f}} = f(\frac{v}{v + v_I})$$

$$\boxed{f' = f(\frac{v}{v + v_I})}$$



$$v' = v + v_0$$

$$\lambda' = \lambda - v_I T = \lambda - \frac{v_I T}{f}$$

$$f' = \frac{v'}{\lambda'} = \frac{v + v_0}{\lambda - \frac{v_I T}{f}} = \frac{v + v_0}{\frac{\lambda}{f} - \frac{v_I T}{f}} = f(\frac{v + v_0}{v - v_I})$$

$$\boxed{f' = f(\frac{v + v_0}{v - v_I})}$$

ausmultipliziert

$$\boxed{f' = f \left(\frac{v \pm v_0}{v} \right) \left(\begin{array}{c} \textcircled{1} \\ \textcircled{2} \end{array} \right)}$$

$$\boxed{f' = f \left(\frac{v \mp v_0}{v \mp v_I} \right) \left\{ \begin{array}{c} \textcircled{1} \\ \textcircled{2} \end{array} \right\}}$$

TEORIJA

① VALNA JEDNADŽB. ELEKTROMAGNETIČKE VALA

$$\left. \begin{array}{l} (\text{vakuum}) \\ \text{P.U.} \\ \left. \begin{array}{l} \vec{D} = 0 \\ \vec{J} = 0 \\ \epsilon_0, \mu_0 \end{array} \right\} \end{array} \right.$$

b.)

u vakuumu $\sigma = 0$

MAXWELLOVE JEDNADŽBE:

④ $\nabla \cdot \vec{D} = \rho$

$$① \nabla \cdot \vec{E} = 0 \quad \int \vec{D} dS = \frac{1}{\epsilon_0} \int \rho dV$$

$$② \nabla \cdot \vec{B} = 0 \rightarrow \phi = \oint \vec{D} dS = 0 \quad \text{kao zato, platiti}$$

$$③ \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \rightarrow \epsilon = \oint \vec{E} d\vec{l} = -\frac{\partial \phi}{\partial t} \int \vec{B} dS$$

$$④ \nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \mu_0 \frac{\partial \vec{B}}{\partial t} \quad \oint \vec{B} d\vec{l} = \mu_0 \int \vec{J} d\vec{l} + \mu_0 \epsilon_0 \int \vec{E} d\vec{l}$$

$$\text{a.) } \nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} / \frac{\partial \vec{B}}{\partial t}$$

$$\oint (\nabla \times \vec{B}) d\vec{l} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\nabla \times \frac{\partial \vec{B}}{\partial t} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}, \quad ①$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} / \text{rot}$$

$$\nabla \times (\nabla \times \vec{E}) = -\nabla \times \frac{\partial \vec{B}}{\partial t}, \quad ②$$

jednačina indukcije:

$$\text{rot}(\text{rot} \vec{E}) = \text{grad}(\text{div} \vec{E}) - \Delta \vec{E}$$

$$\Delta \vec{E} = (\nabla \times)^2 \vec{E}$$

$$\nabla \times (\nabla \times \vec{E}) = \text{grad}(\nabla \cdot \vec{E}) - \Delta \vec{E}$$

= 0 (14)

$$\nabla \times (\nabla \times \vec{E}) = -\nabla \Delta \vec{E}, \quad ③$$

$$\stackrel{②, ③}{\Rightarrow} \Delta \vec{E} = -\nabla \times \frac{\partial \vec{B}}{\partial t}$$

$$\stackrel{①}{\Rightarrow} \Delta \vec{E} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\boxed{\Delta \vec{E} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = 0} \quad \text{VALNA JEDNADŽBA} \\ \text{ZAK. POGA}$$

3.4

$$b.) \nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \quad | \quad \frac{\partial}{\partial t}$$

$$\frac{\partial}{\partial t} (\nabla \times \vec{E}) = - \frac{\partial^2 \vec{B}}{\partial t^2}$$

$$\nabla \times \frac{\partial \vec{E}}{\partial t} = - \frac{\partial^2 \vec{B}}{\partial t^2}, \textcircled{1}$$

$$\nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \quad | \text{ rot}$$

$$\nabla \times (\nabla \times \vec{B}) = \nabla \times (\mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}) \textcircled{2}$$

\textcircled{2}; \textcircled{3}

$$-\Delta \vec{B} = \nabla \times (\mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t})$$

$$-\Delta \vec{B} = \mu_0 \epsilon_0 (\nabla \times \frac{\partial \vec{E}}{\partial t})$$

$$\textcircled{3} \quad -\Delta \vec{B} = -\mu_0 \epsilon_0 \frac{\partial^2 \vec{B}}{\partial t^2}$$

$$\boxed{\Delta \vec{B} - \mu_0 \epsilon_0 \cdot \frac{\partial^2 \vec{B}}{\partial t^2} = 0}$$

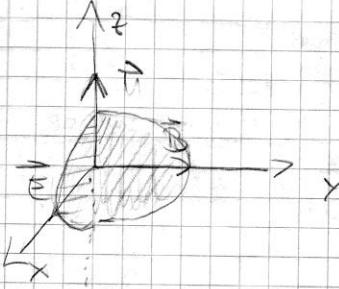
VALNA SEDMADÍSÍ
MAGNETICKÁ PÝD

$$\Rightarrow \frac{1}{c^2} = \mu_0 \epsilon_0$$

$$C = \boxed{\frac{1}{\mu_0 \epsilon_0}}$$

$$L C \approx 2,998 \cdot 10^{-8} \text{ M s}^2$$

② HARMONIJSKI RAVNI ELEKTROMAGNETSKI VAL



P. U.
 $\vec{S}, \vec{j} = 0$ (vakuum)
 magnetomatski val
 $\vec{E}, \vec{B}, \vec{n}$ - desni svitak
 $C = \frac{1}{\mu_0 \epsilon_0}$

magnetomatski el val (samo jedan frekvencij) iji je poljivoj ujedinjen
 $E_x = E_0 \sin(\omega t - k_z z)$

$$[3.14.3] \quad \nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \vec{j}$$

$$\left| \begin{array}{ccc} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \vec{E}_x & 0 & 0 \end{array} \right| = - \frac{\partial \vec{B}}{\partial t} \vec{j}$$

$$\underbrace{\vec{B}_0}_{\text{0}} = \vec{j} \left(\frac{\partial}{\partial x} \vec{E}_0 - \frac{\partial}{\partial z} |\vec{E}_0| \right) + \vec{k} \left(\frac{\partial}{\partial x} \vec{E}_0 - \frac{\partial}{\partial y} |\vec{E}_0| \right) = - \frac{\partial \vec{B}}{\partial t} \vec{j}$$

$$\vec{j} \frac{\partial}{\partial z} |\vec{E}_0| = - \frac{\partial \vec{B}}{\partial t} \vec{j}$$

$$\frac{\partial |\vec{E}_0|}{\partial z} = - \frac{\partial \vec{B}}{\partial t}$$

$$k E_{0x} \cos(\omega t - k z) = - \frac{\partial \vec{B}}{\partial t} \quad | \int$$

$$k E_{0x} \int \cos(\omega t - k z) dt = B_y$$

$$k E_{0x} \frac{\sin(\omega t - k z)}{\omega} = B_y$$

$$E_{0x} \sin\left(\frac{\omega}{k} z\right) = B_y$$

$$B_y = \frac{E_{0x}}{c} \sin(\omega t - k z)$$

$$B_y = B_{0y} \sin(\omega t - k z)$$

$$\boxed{\vec{B}_y = B_{0y} \sin(\omega t - k z) \vec{j}}$$

$\vec{E}, \vec{B}, \vec{n} \rightarrow$ desni sustav

$$\vec{B} = \frac{1}{c} (\vec{n} \times \vec{E})$$

HARMONIJSKI RAVNI
ELEMTRONAGNETSKI
VPLZ

$$\vec{E} = c \cdot (\vec{B} \times \vec{n})$$

$$B_{0y} = \frac{E_{0x}}{c}$$

$$B_y = \frac{E_y}{c}$$

③ GUSTOĆA ENERGIJE EH VALA ; Poyntingov vektor

Volume ($\mu_0, \epsilon_0, \vec{j} = 0, \vec{g} = 0$)

$\vec{E}, \vec{B}, \vec{n} \rightarrow$ desni sustav

$$B_y = \frac{E_x}{c} = E_x \sqrt{\mu_0 \epsilon_0} \Rightarrow B_y^2 = E_x^2 / c^2$$

$$\omega = \omega_x + \omega_B = \frac{1}{2} \epsilon_0 E_x^2 + \frac{1}{2 \mu_0} B_y^2$$

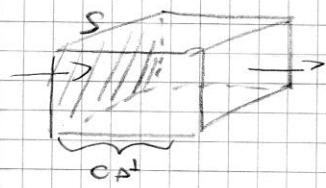
$$\text{I.) } \omega = \frac{1}{2} \epsilon_0 E_x^2 + \frac{1}{2 \mu_0} E_x^2 \cancel{\mu_0 \epsilon_0} = \epsilon_0 E_x^2$$

$$\text{II.) } \omega = \frac{1}{2} \epsilon_0 \frac{B_y^2}{\mu_0} + \frac{1}{2 \mu_0} B_y^2 = \frac{B_y^2}{\mu_0}$$

$$\text{III.) } \omega = \epsilon_0 E_x B_y$$

$$\omega = \sqrt{\epsilon_0} E_x B_y$$

$$\boxed{\omega = \epsilon_0 E_x^2 = \frac{B_y^2}{\mu_0} = \sqrt{\frac{\epsilon_0}{\mu_0}} \sum_{x,y} E_x B_y}$$



$$\Delta t$$

$$E = \omega \cdot v = \omega S c \Delta t$$

$$|\vec{s}| = \frac{E}{S \Delta t} = \frac{\omega S c \Delta t}{S \Delta t} = \omega c$$

$$a) |\vec{s}| = \epsilon_0 E_x^2 c = \sqrt{\frac{\epsilon_0}{\mu_0}} E_x^2 \Rightarrow |\vec{s}| = \int \int \int |\vec{s}| = \frac{1}{T} \int \int \epsilon_0 c E_x^2$$

$$b) |\vec{s}| = \frac{B_y^2}{\mu_0} c = \frac{B_y^2}{\mu_0 \mu_0 c}$$

$$c) |\vec{s}| = c \cdot \sqrt{\frac{\epsilon_0}{\mu_0}} E_x B_y = \frac{1}{\mu_0} E_x B_y$$

$$|\vec{s}| = \frac{1}{\mu_0} E_x B_y$$

$$= \frac{1}{T} \int \epsilon_0 c E_x^2 \sin(\omega t - k_x) dt$$

$$\boxed{I = \frac{1}{2} \epsilon_0 c E_{ox}^2} \quad \begin{matrix} \text{INTENSIITÄT} \\ \text{EM VALTA} \end{matrix}$$

$$\boxed{I = \frac{1}{2} \epsilon_0 c^2 E_{ox} B_{oy}}$$

$$\boxed{I = \frac{1}{2} \frac{c}{\mu_0 \mu_0 c} B_{oy}^2}$$

$$\vec{s} = s \hat{n} (\vec{s} \parallel \hat{n})$$

$$\boxed{\vec{s} = \frac{1}{N_0} (\vec{E} \times \vec{B})} \quad \begin{matrix} \text{POYNTEEN} \\ \text{VEKTÖR} \end{matrix}$$

④ FOTOMETRIJA

$$\boxed{\phi = I \Omega}$$

intensitas
valo
luminans
valo
luminans

$$\boxed{\Omega = \frac{S}{\pi r^2}}$$

[lm]

$$\boxed{d\phi = I d\Omega}$$

suurim valo pinnal
lumos valo mõlema pinnal

$$\boxed{d\Omega = \sin\theta d\theta d\rho}$$

$$\boxed{1W = 683 \text{ lm}}$$

$$\boxed{n = \frac{\phi_{lk}}{P}} \quad \begin{matrix} \text{kõrval} \\ \text{tuled} \end{matrix}$$



$$\boxed{E = \frac{d\phi}{dS} [lx]}$$

luminesents
pinnal

$$\phi = I \Omega = I \frac{\pi}{4} \Rightarrow \frac{\phi}{S} = E = \frac{I}{R^2} \Rightarrow$$

$$\boxed{E = \frac{I}{R^2} \cos\theta} \quad \begin{matrix} \text{luminesents} \\ \text{pinnal} \end{matrix}$$



⑤ ZAKONI GEOMETRIJSKE OPTIKE

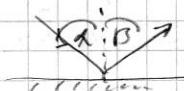
$$x \ll D \quad \begin{matrix} \text{distančna} \\ \text{pretpostava} \end{matrix}$$

UVJET APROXIMACIJE
SVJETLOVSKI TRAKAMP

1.) zakon \rightarrow svjetlost se prenosi u sin u konjecima refleksionog zracenja.

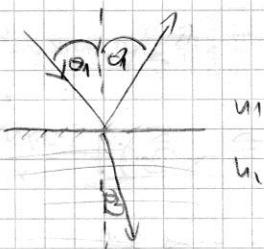
2.) zakon \rightarrow za nekonečno daleke objekte da ječem u dnevoj ve utjecaji u koj se projekciju.

3.) zakon \rightarrow $x = p$ ZAKON
REFLEKCIJE



4.) zakon \rightarrow $\frac{\sin \theta_1}{\sin \theta_2} = \frac{u_2}{u_1}$ ZAKON
REFRAKCIJE

$$\begin{cases} u = \frac{c}{v} \\ u^2 = v \cdot u_1 \end{cases}$$



5.) zakon \rightarrow svjetlost se prenosi 2-ju zakonom tako da ima istu stazu za boje joj red
najma uji vremena: FERMATOV PRINCIPI

$$t_{AB} = \int_{A(f)}^B \frac{de}{v} = \int_{A(f)}^B \frac{ude}{c} \Leftrightarrow \frac{d}{du} t = 0 \quad (\text{minim, vrijec})$$

np. $\nabla u = \text{kant}$ (konavni, hijeli)

$$t_{AB} = \int_A^B \frac{ude}{c} = \frac{u}{c} \int_A^B de$$

putanja \Rightarrow
je pravac

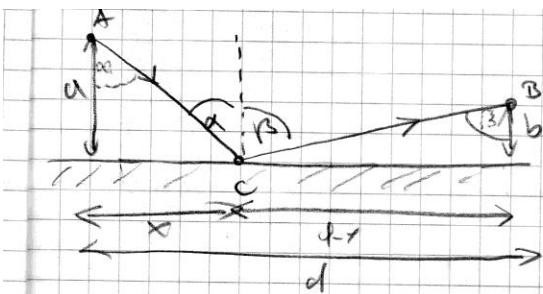
$$t_{AB} = \frac{u}{c} \int_A^B de = \frac{u}{c} |AB|$$

1. ZAKON GEOM.
OPTIKE

⑥ ZAKON REFLEKCIJE (Fermatov princip)

{ P.U.

u-kant 1.zakon: $t_{AB} = \frac{u}{c} |AB|$



$$t_{AB} = t_{AC} + t_{CB}$$

$$t_{AB} = \frac{u_1}{c} |AC| + \frac{u_2}{c} |CB|$$

$$t_{AB} = \frac{u_1}{c} \left(\sqrt{a^2+x^2} + \sqrt{(d-x)^2+b^2} \right) = \frac{u_1}{c} \left((a^2+x^2)^{\frac{1}{2}} + ((d-x)^2+b^2)^{\frac{1}{2}} \right)$$

$$\frac{d}{dx} t_{AB} = 0 \quad (\text{minimum value})$$

$$\frac{u_1}{c} \left(\frac{1}{2} (a^2+x^2)^{\frac{1}{2}} x + \frac{1}{2} ((d-x)^2+b^2)^{\frac{1}{2}} 2(d-x)(-1) \right) = 0$$

$$\frac{u_1}{c} \left[((d-x)^2+b^2)^{\frac{1}{2}} (d-x) + (a^2+x^2)^{\frac{1}{2}} x \right] = 0$$

$$\frac{x}{\sqrt{a^2+x^2}} = \frac{d-x}{\sqrt{(d-x)^2+b^2}}$$

$$\sin \alpha = \sin \beta$$

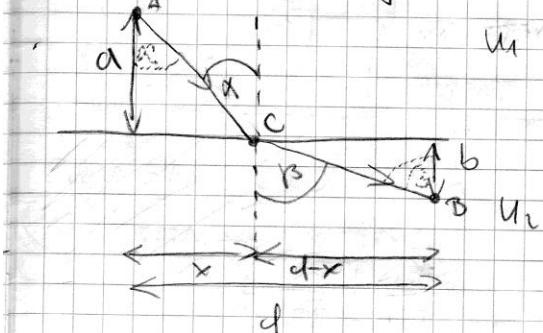
$$\boxed{\alpha = \beta} \quad \text{ZAKON SINUSU}$$

7. ZAKON SINUSU (Perronov princip)

P.4.

$$1. \text{ ZAKON: } t_{AB} = \frac{u_1}{c} |AC| + \frac{u_2}{c} |CB|$$

Uzantı fonksiyonu (harmonik sekiller)



$$t_{AB} = t_{AC} + t_{CB} = \frac{u_1}{c} |AC| + \frac{u_2}{c} |CB|$$

$$t_{AB} = \frac{u_1}{c} \sqrt{a^2+x^2} + \frac{u_2}{c} \sqrt{(d-x)^2+b^2}$$

$$t_{AB} = \frac{1}{c} \left[u_1 (a^2+x^2)^{\frac{1}{2}} + u_2 ((d-x)^2+b^2)^{\frac{1}{2}} \right]$$

$$\frac{d}{dx} t_{AB} = 0 \quad (\text{minimum value})$$

$$\frac{1}{c} \left[u_1 \frac{1}{2} (a^2+x^2)^{\frac{1}{2}} 2x + u_2 \frac{1}{2} ((d-x)^2+b^2)^{\frac{1}{2}} 2(d-x)(-1) \right] = 0$$

$$u_1 \times (a^2+x^2)^{\frac{1}{2}} = u_2 (d-x) ((d-x)^2+b^2)^{\frac{1}{2}}$$

$$u_1 \frac{x}{\sqrt{a^2+x^2}} = u_2 \frac{d-x}{\sqrt{(d-x)^2+b^2}}$$

$$u_1 \sin \alpha = u_2 \sin \beta$$

$$\left[\frac{\sin \alpha}{\sin \beta} = \frac{u_2}{u_1} \right] \text{ZAKON LOMA}$$

⑧ Optički put

$u \neq \text{kost}$

$$t_{AB} = \int_A^B \frac{udx}{c} = \Delta \int_A^B u dx$$

$$t_{AB} \propto \int_A^B u dx$$

$$S = \int_A^B u dx \quad \begin{cases} \text{optički} \\ \text{put} \end{cases}$$

$u = \text{kost}$

$$S = u \int_A^B dx$$

$$S = u |AB| \quad \begin{cases} \text{optički put} \\ u \text{ konst} \end{cases}$$

⑨ RAVNO I SPERNO ZRCALO

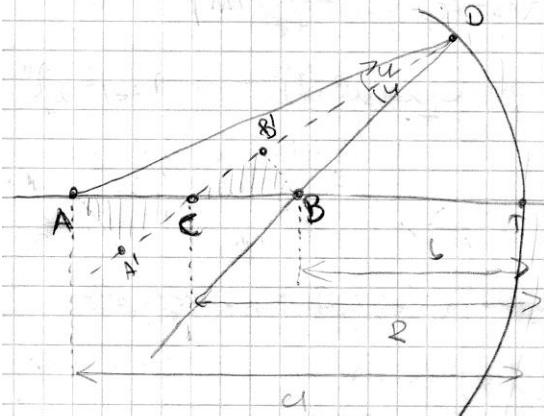
$$a = -b \quad \begin{matrix} \text{NWW} \\ \text{traces} \end{matrix}$$

$$\begin{array}{c|c} a > 0 & a < 0 \\ b > 0 & b < 0 \end{array}$$

P.U. Gaussove aksimacije

- + ravni blizu osi
- mali kutovi refleksija

$$AA' \sim CB' \quad ; \quad AAD \sim BBD$$



$$\frac{\overline{AC}}{\overline{AA'}} = \frac{\overline{BC}}{\overline{BB'}}$$

$$\frac{\overline{AD}}{\overline{AA'}} = \frac{\overline{BD}}{\overline{BB'}}$$

$$\Rightarrow \overline{BB'} \overline{AC} = \overline{AA'} \overline{BC}$$

(10)

$$\frac{\overline{BB'}}{\overline{AA'}} = \frac{\overline{BC}}{\overline{AC}} \quad ①$$

$$\rightarrow \overline{AD} \overline{B'} = \overline{A'P} \overline{B}$$

$$\frac{\overline{BB'}}{\overline{AA'}} = \frac{\overline{BD}}{\overline{AD}} \quad ②$$

$$①=② \Rightarrow \frac{\overline{BC}}{\overline{AC}} = \frac{\overline{BD}}{\overline{AD}}$$

$$\overline{AD} \overline{DC} = \overline{AC} \overline{BD}$$

$$\frac{\overline{AC}}{\overline{AD}} = \frac{\overline{BC}}{\overline{BD}}$$

\rightarrow 2 G.A.:

$$\frac{\overline{AC}}{\overline{AT}} = \frac{\overline{BC}}{\overline{BT}} \quad \text{MP} \quad \frac{a-R}{a} = \frac{r-b}{b}$$

$$ab - br = ar - ab$$

$$2ab = r(a+b)$$

$$\frac{2ab}{a+b} = r$$

$$\frac{ab}{a+b} = \frac{r}{2}$$

$$\frac{a+b}{ab} = \frac{2}{r}$$

$$\boxed{\frac{1}{a} + \frac{1}{b} = \frac{2}{r} = \frac{1}{f}}$$

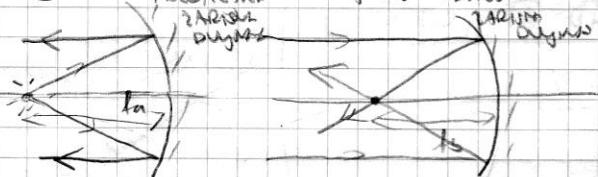
JEDNADZB
STERNA
ZACZ.

$$f = \frac{r}{2}$$

$r \rightarrow \infty$: równy
zakres

$$a = f_a \quad b = \infty \quad \boxed{\frac{da}{d\alpha} = \frac{r}{2}}$$

$$a = \infty \quad b = f_b \quad \boxed{\frac{df_b}{d\alpha} = \frac{r}{2}}$$



$$m = \frac{y'}{y} = \frac{\overline{BB'}}{\overline{AA'}} = \frac{\overline{BT}}{\overline{AT}} = \frac{b}{a}$$

$$\boxed{m = -\frac{b}{a}} \quad \text{POWIEJSZE SIŁKI}$$

$$a > 0 \quad ; \quad a < 0$$

$$b > 0 \quad ; \quad b < 0$$

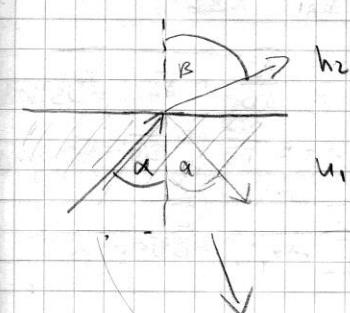
$$\begin{array}{c} \longrightarrow \\ m > 0 \\ \longleftarrow \end{array} \quad \begin{array}{c} \longrightarrow \\ m < 0 \\ \longleftarrow \end{array}$$

(obrotu skrótu)

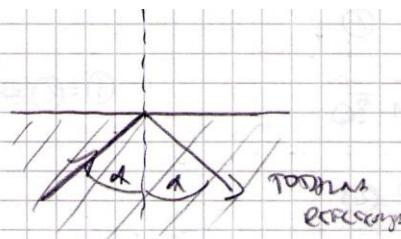
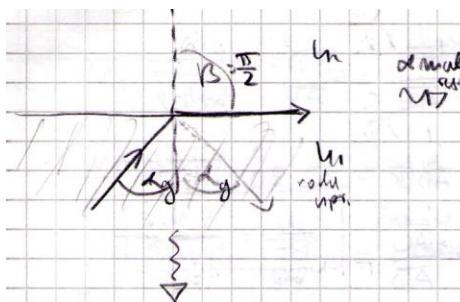
$m < 0$ (obrotu skrótu)

$m > 0$ (usprawn skrótu)

(10) TOTALNA REFLEKSIJA



$$\left. \begin{array}{l} (\beta > \alpha \text{ za } u_1 \text{ i } u_2 \text{ (zak. i wycieczka j. rekt. zak.)}) \\ \frac{\sin \alpha}{\sin \beta} = \frac{n_2}{n_1} < 1 \text{ za } u_1 \text{ i } u_2 \\ \Rightarrow \beta > \alpha \text{ (jedna kąt. wycieczka tot. refleksji)} \end{array} \right\}$$



$$\frac{\sin \alpha}{\sin \beta} = \frac{n_2}{n_1}$$

$$\Rightarrow \frac{\sin \alpha}{\sin \beta} = \frac{n_2}{n_1} \quad \text{GEANTONI KUT}$$

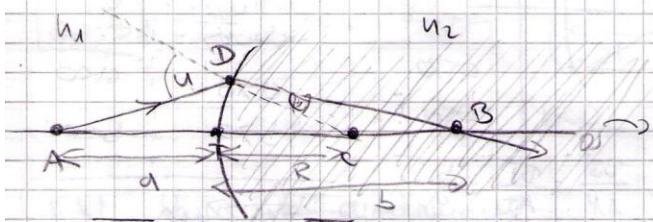
(uyet $n_2 > n_1$)

11) SFERNI DIOPTAR

{ P.U. Gaussove dioptrické

$$\overline{BD} = \overline{BT}, \overline{AD} = \overline{AT}, \overline{CD} = \overline{CT}$$

Möbiusov zákon:



$$n_1 \frac{AC}{AD} = n_2 \frac{BC}{BD} \quad \text{upravený ještě}$$

Möbiusov zákon formu

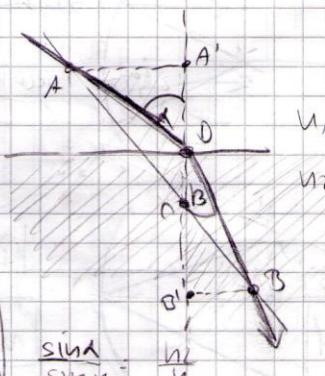
(P.U.)

$$n_1 \frac{AC}{AT} = n_2 \frac{BC}{BT}$$

(A → pravý systém)

$$n_1 \frac{AC}{AT} = \text{konst.} \Rightarrow n_2 \frac{BC}{BT} = \text{konst.}$$

Sv. konstante nazve sférické dioptrické systém optickým a u hledi B



$$\frac{\sin \alpha}{\sin \beta} = \frac{n_2}{n_1}$$

$$AA' \sim BB'$$

$$\frac{AC}{AA'} = \frac{BC}{BB'} \quad \textcircled{1}$$

$$\sin \alpha = \frac{AA'}{AD} \quad \text{upr} \overline{AA'} = \overline{AD} \sin \alpha$$

$$\sin \beta = \frac{BB'}{BD} \quad \text{upr} \overline{BB'} = \overline{BD} \sin \beta$$

$$\frac{AC}{AD \sin \alpha} = \frac{BC}{BD \sin \beta}$$

$$u_1 \frac{a+r}{a} = u_2 \frac{b-r}{b}$$

$$u_1 ab + u_1 br = u_2 ab - u_2 ar$$

$$ab(u_1 - u_2) = r(-u_1 b - u_2 a)$$

$$\frac{ab}{u_1 b + u_2 a} = \frac{r}{u_2 - u_1} \quad | -1$$

$$\frac{u_1 a + u_2 b}{ab} = \frac{u_2 - u_1}{R}$$

$$\frac{u_1}{a} + \frac{u_2}{b} = \frac{u_2 - u_1}{R} \quad \left| \begin{array}{l} \text{jeonačina} \\ \text{strenka} \\ \text{dijester} \end{array} \right.$$

$$R \rightarrow \infty \quad \begin{array}{l} \text{RAVN} \\ \text{DIOVATEL} \end{array}$$

$$b = \frac{-u_2}{u_1 a} \quad \Rightarrow \quad -bu_1 = u_2 a$$

$$\frac{u_2}{b} = -\frac{u_1}{a}$$

$$a > 0 \quad a < 0$$

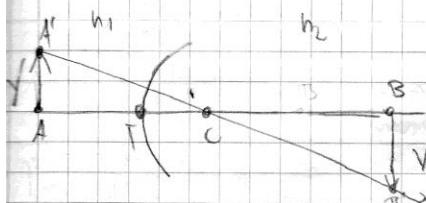
$$b < 0 \quad b > 0$$

(deo)

$$\begin{cases} a = fa \\ b = \infty \end{cases} \quad f_a = \frac{u_1}{u_2 - u_1} R$$

$$\begin{cases} a = \infty \\ b = fs \end{cases} \quad b = \frac{u_2}{u_2 - u_1} R$$

$$\frac{f_b - f_a}{f_a} = R$$



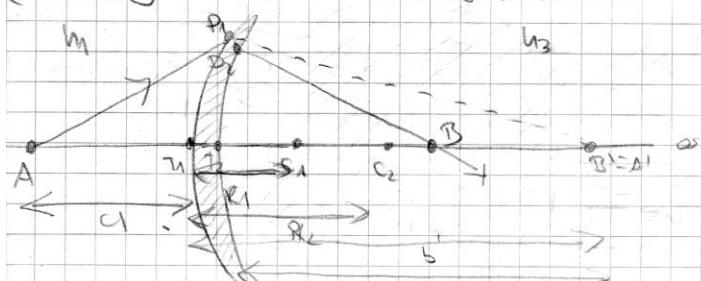
$$|u_1| = \frac{1}{\gamma} - \frac{\bar{B}B'}{AA'} = \frac{\bar{B}C}{AC} = \left| \begin{array}{l} \text{Moščava} \\ \text{popis} \end{array} \right|$$

$$= \frac{u_1}{AD} = \frac{u_2}{BD} \quad \Rightarrow \quad \frac{BC}{AC} = \frac{u_1 BD}{u_2 AD}$$

$$|u_1| \cdot \frac{u_1 \bar{B}T}{u_2 AT} = \frac{u_1}{u_2} \frac{b}{a} \quad \left| \begin{array}{l} \text{MD} \\ u_1 = \frac{u_1}{u_2} \frac{b}{a} \end{array} \right| \quad \begin{array}{l} \text{POVEČAV} \\ \text{SLIKE} \end{array}$$

12) TANKA LEĆA

P. U. Gaussove optičke leće i tanka leća: $\bar{B}B' \rightarrow 0$



Ručni račun:

1. sl. dijester:

$$\frac{u_1 + u_2}{b} = \frac{u_2 - u_1}{R_1}$$

2. sl. dijester:

$$\frac{u_2 + u_3}{b} = \frac{u_3 - u_2}{R_2}$$

(P.U) Funkcija sečiva:

$$|ab|=|b'a'|$$

$$\underline{a' = \frac{b}{b}}$$

$$\begin{array}{l} a>0 \\ b<0 \end{array} \quad \left| \begin{array}{l} a>0 \\ b>0 \end{array} \right.$$

$$a' < 0$$

$$b' > 0$$

(3)

{ P.U

or

else

$\frac{1}{2}$

$$\frac{u_1}{a} + \frac{u_2}{b} = \frac{u_1 - u_2}{R_1}$$

$$-\frac{u_2}{a} + \frac{u_3}{b} = \frac{u_3 - u_2}{R_2}$$

$$\boxed{\frac{u_1}{a} + \frac{u_3}{b} = \frac{u_2 - u_1}{R_1} + \frac{u_3 - u_2}{R_2}} \quad \left| \begin{array}{l} \text{JEDNOSTVANJE TAKO} \\ \text{ZECE} \end{array} \right.$$

$$\left. \begin{array}{l} a=f_a \\ b=\infty \end{array} \right\} f_a = \frac{u_1 u_2 u_3}{R_2(u_1 - u_3) + R_1(u_3 - u_1)} \quad (*)$$

$$\left. \begin{array}{l} a=\infty \\ b=f_b \end{array} \right\} f_b = \frac{u_3 u_1 u_2}{R_2(u_2 - u_1) + R_1(u_1 - u_2)} \quad (*)$$

$$\frac{f_a}{a} + \frac{f_b}{b} = 1 \quad (***)$$

Slučaj: $u_1 = u_3 = u$; $u_2 = u'$

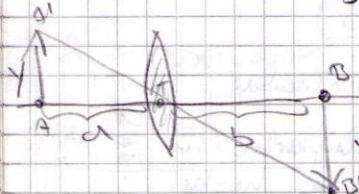
$$u \left(\frac{1}{a} + \frac{1}{b} \right) = (u - u') \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$$

$$\boxed{\frac{1}{a} + \frac{1}{b} = \frac{u - u'}{u} \left(\frac{1}{R_1} - \frac{1}{R_2} \right)} \quad \left| \begin{array}{l} \text{JEDNOSTVANJE} \\ \text{ZECE} \vee \text{SPLIT} \\ \text{INDIREKTNA U} \end{array} \right.$$

$$(*) \text{ i } (**) \Rightarrow f_a = f_b = f$$

$$(***) \Rightarrow \boxed{\frac{1}{a} + \frac{1}{b} = \frac{1}{f}} \quad \left| \begin{array}{l} \text{JEDNOSTVANJE} \\ \text{ZECE} \end{array} \right.$$

$$\boxed{f = \frac{1}{\frac{1}{a} + \frac{1}{b}}} = \frac{u - u'}{u} \left(\frac{1}{R_1} - \frac{1}{R_2} \right) \quad \left| \begin{array}{l} \text{JACOST ZECE, DIOPTRIK} \end{array} \right.$$



$$h_{AB} = \frac{y'}{y} = \frac{BB'}{AA'} = \left| \frac{AAT}{BBT} \right| = \frac{b}{a}$$

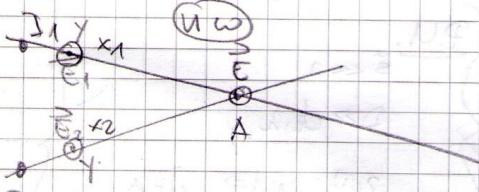
$$\boxed{M = \frac{-b}{a}} \quad \left| \begin{array}{l} \text{POJAKUJENJE} \\ \text{SLIKE} \end{array} \right.$$

(13) INTERFERENCA 2 KOMERCIJALNI RAVORA

(P.U.)

amplitudine istaknute $E_1 = E_2 = E_0$

elek i mag. polarizaciju

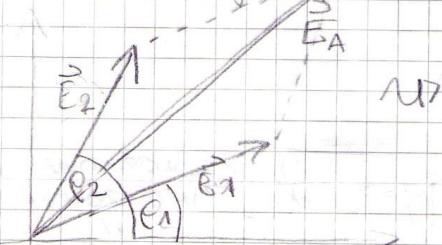


I_2

tacka A:

$$\vec{E}_A = \vec{E}_1 + \vec{E}_2$$

→ metoda rotirajućih vektora:



↳ ravn iste frekvencije ali
staleme razlike u fazama
(monokromatski zvori)

$$\left\{ \begin{array}{l} v = \frac{c}{n} \\ \lambda = \frac{v}{f} \end{array} \right.$$

$$\vec{E}_1 = E_0 \sin(\omega t - \frac{1}{v} x_1) \hat{j}$$

$$\vec{E}_2 = E_0 \sin(\omega t - \frac{1}{v} x_2) \hat{j}$$

$$\vec{E}_1 = E_0 \sin(\omega t - \frac{n}{c} x_1) \hat{j}$$

$$\vec{E}_2 = E_0 \sin(\omega t - \frac{n}{c} x_2) \hat{j}$$

$$\vec{E}_1 = E_0 \sin(\omega t - \underbrace{\omega \frac{n}{c} x_1}_{\phi_1}) \hat{j}$$

$$\vec{E}_2 = E_0 \sin(\omega t - \underbrace{\omega \frac{n}{c} x_2}_{\phi_2}) \hat{j}$$

$$P_2 \quad \phi = \frac{p_2 - p_1}{\lambda} = \frac{p_2 - p_1}{w_2(x_2 - x_1)}$$

$$\lambda = w_2^2 (x_2 - x_1)$$

$$E_A^2 = E_0^2 + E_0^2 - 2E_0 E_0 \cos(\pi - \phi)$$

$$\frac{2\pi - 2\phi}{2} = \pi - \phi$$

$$E_A = \sqrt{2E_0^2 + 2E_0^2 \cos \phi} = E_0 \sqrt{2(1 + \cos \phi)} =$$

$$\left\{ \cos \frac{\phi}{2} = \frac{1 + \cos \phi}{2} \quad \text{N} \quad 1 + \cos \phi = 2 \cos^2 \frac{\phi}{2} \right\}$$

$$= E_0 \sqrt{2(2 \cos^2 \frac{\phi}{2})}$$

$$| E_A = 2E_0 \cos \frac{\phi}{2} |$$

① MAXIMUM:

$$\cos \frac{\phi}{2} = \pm 1$$

$$\frac{\phi}{2} = k\pi$$

$$\frac{1}{2} \frac{\omega}{c} n(x_1 - x_2) = k\pi$$

$$\frac{1}{2} \frac{2\pi}{\lambda} n(x_1 - x_2) = k\pi$$

$$j = v(x_1 - x_2)$$

RAZINA periodiciteta

$$j = v\Delta$$

$$j = l\pi$$

MAX.

Let!

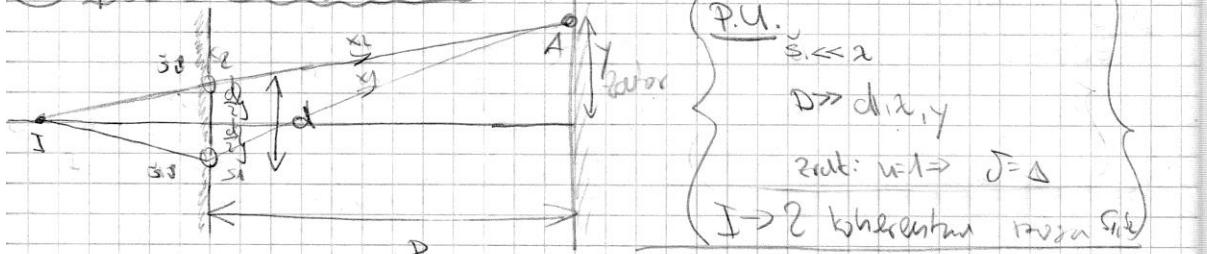
② Minimum:

$$\cos \frac{\phi}{2} = 0$$

$$\frac{\phi}{2} = \frac{2l+1}{2}\pi$$

$$l = \frac{2l+1}{2} - 1$$

④ YOUNGSCHE Interferenz



$$\Delta = \Delta = x_1 - x_2 = \sqrt{(y + \frac{d}{2})^2 + D^2} - \sqrt{(y - \frac{d}{2})^2 + D^2} = D \left(\sqrt{(\frac{d}{D})^2 + 1} - \sqrt{(\frac{-d}{D})^2 + 1} \right)$$

$$= \sqrt{1 + \frac{d^2}{D^2}} \approx 1 + \frac{dy}{2} \quad \text{approximation (bis 1. Ordnung)}$$

$$J = \left(1 + \frac{dy}{2} \right)^2 - 1 = \frac{(dy)^2}{4}$$

$$\bar{J} = \frac{D}{2} \left(\frac{y^2 + dy + \frac{d^2}{4} - y^2 + dy - \frac{d^2}{4}}{D^2} \right) = \frac{1}{2} \frac{2dy}{D}$$

$$\boxed{J = \frac{dy}{D}}$$

→ ① Max.

→ ② Min.

$$J = dy \quad \boxed{y = l \frac{2D}{d}}$$

Konstruktive
Interferenz

$$J = \frac{2l+1}{2} \frac{xD}{D} \quad \boxed{y = \frac{2l+1}{2} \frac{xD}{d}}$$

Destruktive
Interferenz

$$I = \frac{1}{2} E_0 \cos^2 E_{0A}$$

$$E_{0A} = 2 E_0 \cos \frac{\phi}{2}$$

$$\phi = \frac{w}{\lambda} J \Rightarrow \phi = k J \Rightarrow \phi = \frac{2\pi}{\lambda} J$$

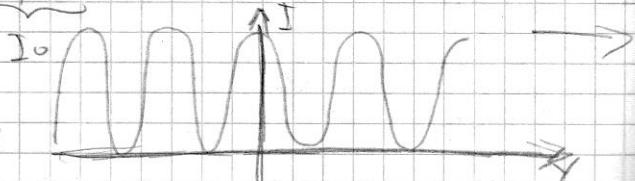
$$\frac{\phi}{2} = \frac{\pi}{\lambda} J$$

$$J = \frac{dy}{D}$$

$$\bar{I} = \frac{1}{2} \int_{-\infty}^{\infty} 4 E_0^2 \cos^2 \left(\frac{\pi}{\lambda} J \right) = 2 \underbrace{\int_{-\infty}^{\infty} E_0^2}_{20} \cos^2 \left(\frac{\pi}{\lambda} \frac{dy}{D} \right)$$

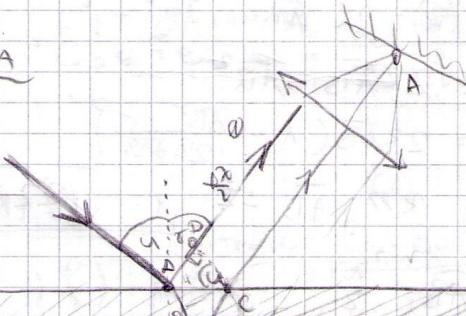
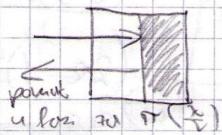
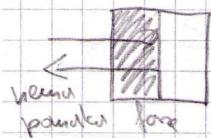
$$I = I_0 \cos^2 \left(\frac{\pi}{\lambda} \frac{dy}{D} \right)$$

INTERFERENZ
KREISE NW
WAGENARTIG
NUR ZWISCHEN



TEORIJA

15) INTERFERENCIJA JANKIH LISTICA



$$J = u(\bar{AB} + \bar{BC}) - 1 \cdot (\bar{AD} + \frac{\lambda}{n})$$

$$J = u(\bar{AB} + \bar{AC}) - \bar{AD} - \frac{\lambda}{n}$$

$$J = 2u\bar{AB} - \bar{AD} - \frac{\lambda}{n}$$

$$\begin{cases} \cos \alpha = \frac{d}{\bar{AB}} \\ \bar{AB} = \frac{d}{\cos \alpha} \\ \sin u = \frac{\bar{AB}}{AC} \end{cases}$$

$$\bar{AD} = AC \sin u$$

$$\bar{AC} = 2x = 2\bar{AB} \sin \alpha = 2d \frac{\sin \alpha}{\cos \alpha} = 2d \tan \alpha \quad \left\{ \begin{array}{l} \bar{AD} = 2d \tan \alpha \sin u = 2d \tan \alpha n \sin u \\ \bar{AD} = 2n d \frac{\sin u}{\cos u} \end{array} \right.$$

$$J = 2ud \frac{1}{\cos \alpha} - 2ud \frac{\sin^2 \alpha}{\cos^2 \alpha} - \frac{\lambda}{n} = 2ud \frac{1}{\cos \alpha} (1 - \sin^2 \alpha) - \frac{\lambda}{n}$$

$$J = 2ud \frac{1}{\cos^2 \alpha} - \frac{\lambda}{n}$$

$$J = 2ud \cos \alpha - \frac{\lambda}{n} \rightarrow \textcircled{1} \text{ MAX } J = ex$$

$$ex = 2ud \cos \alpha - \frac{\lambda}{n}$$

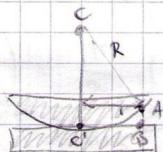
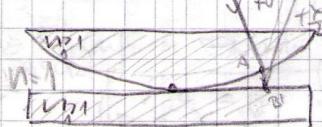
$$2ud \cos \alpha = (e + \frac{\lambda}{n}) \lambda$$

KONSTRUKCIJA
INTERFERENCIJE

REZ

$$\frac{2e+1}{2} \lambda = 2ud \cos \alpha - \frac{\lambda}{n} \quad \left\{ \begin{array}{l} 2ud \cos \alpha = \left(\frac{2e+1}{2} + \frac{1}{n} \right) \lambda \\ 2ud \cos \alpha = (e+1) \lambda \end{array} \right. \quad \begin{array}{l} \text{DESTRUKCIJA} \\ \text{INTERFERENCIJE} \end{array}$$

16) NEWTONOV KOLOBARI



$$\left\{ \begin{array}{l} \text{P.U. } R > > \bar{AB} \Rightarrow \bar{AB}' = \bar{AB} \\ n=1 \text{ (voda)} \end{array} \right.$$

$$J = 2\bar{AB} + \frac{\lambda}{2}$$

$$R^2 = (r - \bar{AB})^2 + r^2$$

$$R^2 = R^2 - 2R\bar{AB} + \bar{AB}^2 + r^2$$

$$R^2 = 2R\bar{AB} + \bar{AB}^2$$

$$r^2 = 2R\bar{AB}\left(1 - \frac{\bar{AB}^2}{2R\bar{AB}}\right)$$

uyet $R \gg \bar{AB} \Rightarrow r = \sqrt{R^2 - \bar{AB}^2}$

$$\sqrt{r^2} = \sqrt{2R\bar{AB} + \frac{\bar{AB}^2}{2}}$$

① MAX $\delta = 2x$

$$l\lambda = 2\bar{AB} + \frac{x}{2}$$

$$(l - \frac{1}{2})\lambda = 2\bar{AB}$$

$$(2l-1)\frac{\lambda}{2} = 2\bar{AB}$$

$$r_{\text{max}} = \sqrt{R(2l-1) \frac{\lambda}{2}}$$

SUBORI
KOLIBARI

općenito

$$r_{\text{max}} = \sqrt{\frac{8(2l-1) \frac{\lambda}{2}}{n}}$$

② MIN $\delta = \frac{2l+1}{2}\lambda$

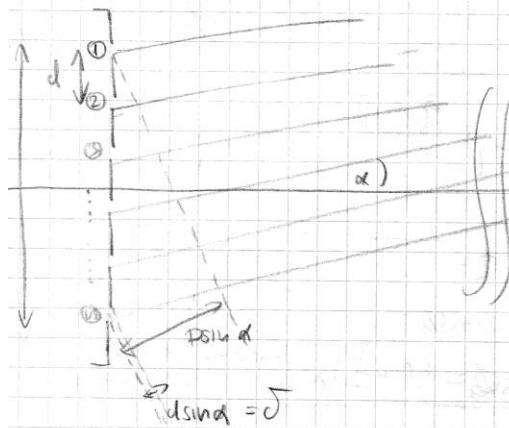
$$\frac{2l+1}{2}\lambda = 2\bar{AB} + \frac{x}{2} \Rightarrow r_{\text{min}} = \sqrt{R\lambda}$$

TAKOVI
KOLIBARI

općenito

$$r_{\text{min}} = \sqrt{\frac{R\lambda}{n}}$$

17) INTERFERENCIJA NA N KOHERENTNIM REZNIKOMA



$$\begin{cases} p = \frac{2\pi}{\lambda} \delta; \text{ muk} \\ \frac{p}{2} = \frac{\pi}{\lambda} \delta \\ \delta = n\Delta = \Delta - dsina \\ \lambda, E_0 \end{cases}$$

$$E_1 = E_0 \cos \omega t = E_0 e^{i\omega t}$$

$$E_2 = E_0 \cos(\omega t + \phi) = E_0 e^{i(\omega t + \phi)}$$

$$E_3 = \dots = E_0 e^{i(\omega t + 2\phi)}$$

...

$$E_N = \dots = E_0 e^{i(\omega t + (N-1)\phi)}$$

$$E_F = E_1 + E_2 + \dots + E_N$$

$$E_F = E_0 e^{i\omega t} (1 + e^{i\phi} + e^{i2\phi} + \dots + e^{i(N-1)\phi})$$

$$S_N = d\lambda \frac{q^{N-1}}{q-1}$$

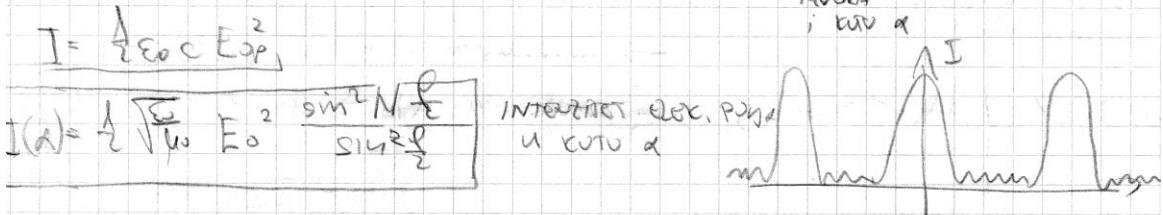
$$\begin{cases} d\lambda = 1 \\ q = e^{i\phi} \end{cases} \quad S_0 = \frac{e^{iN\phi} - 1}{e^{i\phi} - 1}$$

$$\begin{aligned}
 E_p &= E_0 e^{i\omega t} \cdot \frac{e^{iN\frac{\ell}{2}} - e^{-iN\frac{\ell}{2}}}{e^{i\frac{\ell}{2}} - e^{-i\frac{\ell}{2}}} = E_0 e^{i\omega t + i(N-1)\frac{\ell}{2}} \frac{\sin N\frac{\ell}{2}}{\sin \frac{\ell}{2}} \\
 &= E_0 \frac{\sin N\frac{\ell}{2}}{\sin \frac{\ell}{2}} e^{i(\omega t + (N-1)\frac{\ell}{2})} \\
 &\boxed{E_p(\alpha) = E_0 \frac{\sin N\frac{\ell}{2}}{\sin \frac{\ell}{2}} \cos(\omega t + (N-1)\frac{\ell}{2})}
 \end{aligned}$$

(A)

$$\begin{aligned}
 E_p &= E_0 \frac{\sin N\frac{\ell}{2}}{\sin \frac{\ell}{2}} \\
 &\text{ELEKTRON} \quad \text{POJE} \\
 &\text{POLE} \quad \text{DRAZ} \\
 &\text{BESI} \quad \text{RIVOKA} \\
 &\text{i KUV} \alpha
 \end{aligned}$$

$$\rho = \frac{\pi}{2} dsma$$



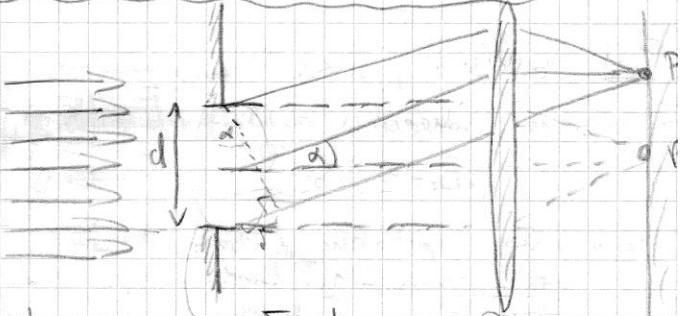
18. FRAUNHOFEROVA DIFFRAKCIJA NA JESENĚ POKUDYM

E.P.U. $d \ll \lambda$; rovnice 3

$$\rho = \frac{2\pi}{\lambda} d$$

$$d = n s = s = dsma$$

$$E_p = E_0 \frac{\sin N\frac{\ell}{2}}{\sin \frac{\ell}{2}}$$



jevište difrakce na m. dýbku je vzdále $\rho = d \sin \alpha$
když se měří vzdále (P je pevný)

$$\begin{cases} \text{měříme } \frac{d}{m} = d' \\ 1.1 \quad m = N \end{cases}$$

$$E(0) = m E_0 \Rightarrow E_0 = \frac{E(0)}{m}$$

$$E_p = E_0 \frac{\sin(N \frac{\pi}{\lambda} d \sin \alpha)}{\sin(\frac{\pi}{\lambda} d \sin \alpha)} = E_0 \frac{\sin(N \frac{\pi}{\lambda} \frac{d}{m} \sin \alpha)}{\sin(\frac{\pi}{\lambda} \frac{d}{m} \sin \alpha)}$$

$$E_p(\alpha) = \frac{E(0)}{m} \frac{\sin(\frac{\pi}{\lambda} d \sin \alpha)}{\sin(\frac{\pi}{\lambda} \frac{d}{m} \sin \alpha)} \quad \left\{ N=m^2 \right.$$

m=>

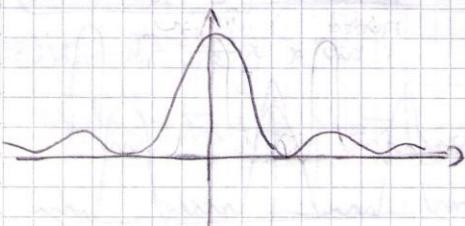
$$\lim_{m \rightarrow \infty} \left(m \sin \left(\frac{\pi}{\lambda} \frac{d}{m} \sin \alpha \right) \right) = \frac{\pi}{\lambda} d \sin \alpha$$

$$E_p(\alpha) = E(0) \frac{\sin(\frac{\pi}{\lambda} d \sin \alpha)}{\frac{\pi}{\lambda} d \sin \alpha} \quad \begin{array}{l} \text{ELEKTRON} \quad \text{POJE} \\ \text{POLE} \quad \text{DRAZ} \\ \text{BESI} \quad \text{RIVOKA} \\ \text{i KUV} \alpha \end{array} \quad (\text{A})$$

$$I = \frac{1}{2} \sqrt{\epsilon_0 E_p}^2$$

$$I(\alpha) = \frac{1}{2} \sqrt{\epsilon_0 E_p} \sin^2 \left(\frac{\pi d}{\lambda} \sin \alpha \right)$$

$$I(\alpha) = I_0 \frac{\sin^2 \left(\frac{\pi d}{\lambda} \sin \alpha \right)}{\left(\frac{\pi d}{\lambda} \sin \alpha \right)^2}$$



intensiteetige
o kuu

centralieni maksimum I_0

minimum: $\sin^2 \left(\frac{\pi d}{\lambda} \sin \alpha \right) = 0$

maksimum: $y = \frac{\pi}{2} \sin \alpha$

$$\frac{dy}{d\alpha} = 0$$

(19) FRAUNHOFERNA DIFFRAKCIJA NA 2 PUKUDU

P.U. $\text{zrak}(n=1); d \ll \lambda$

- pukudine: 2 koherentne pukud.

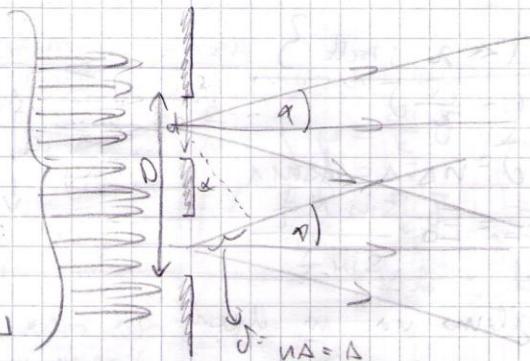
$$E_A = 2E_0 \cos \frac{\varphi}{2}$$

- na svakoj pukudini je moglo:

$$E = E(0) \frac{\sin \left(\frac{\pi d \sin \alpha}{\lambda} \right)}{\frac{\pi}{\lambda} d \sin \alpha}$$

interferencija 2 pukud. pukud.

$$\frac{\varphi}{2} = \frac{\pi}{2} \frac{D}{\lambda} - \frac{\pi}{\lambda} D \sin \alpha$$



$$E_A = 2E_0 \cos \frac{\varphi}{2} = 2E(0) \frac{\sin \left(\frac{\pi d \sin \alpha}{\lambda} \right)}{\frac{\pi}{\lambda} d \sin \alpha} \quad \cos \frac{\varphi}{2} = \begin{cases} \sin \frac{\varphi}{2} & \text{if } \sin \frac{\varphi}{2} \geq 0 \\ \cos \frac{\varphi}{2} & \text{if } \sin \frac{\varphi}{2} < 0 \end{cases}$$

$$E_A = 2E(0) \frac{\sin \left(\frac{\pi}{\lambda} d \sin \alpha \right)}{\frac{\pi}{\lambda} d \sin \alpha} \quad \frac{\sin \left(\frac{2\pi}{\lambda} D \sin \alpha \right)}{2 \sin \left(\frac{\pi}{\lambda} D \sin \alpha \right)}$$

$$E_A(\alpha) = E(0) \frac{\sin \left(\frac{\pi}{\lambda} d \sin \alpha \right)}{\frac{\pi}{\lambda} d \sin \alpha} \quad \frac{\sin \left(\frac{2\pi}{\lambda} D \sin \alpha \right)}{\sin \left(\frac{\pi}{\lambda} D \sin \alpha \right)}$$

difraccija na
velikoj pukudini

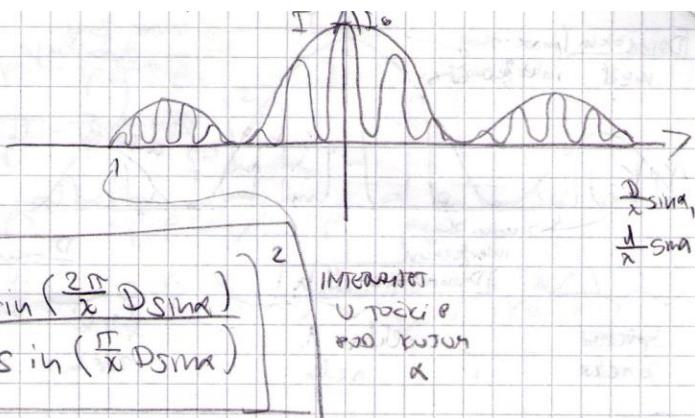
interferencija
na 2 pukudini

Ampliciranje elektricnosti
pojav u toku je zato
je ovo kucan dobit

$$I = \frac{1}{2} \sqrt{\frac{E_0}{\mu_0}} E_0^2$$

$$I = \frac{1}{2} \sqrt{\frac{E_0}{\mu_0}} E(0)^2 - \frac{1}{2} \frac{1}{2} I_0$$

$$I(\alpha) = I_0 \left[\frac{\sin(\frac{\pi}{\lambda} d \sin \alpha)}{\frac{\pi}{\lambda} d \sin \alpha} \right]^2 \left[\frac{\sin(\frac{2\pi}{\lambda} D \sin \alpha)}{\frac{2\pi}{\lambda} D \sin \alpha} \right]^2 \left[\frac{\sin(\frac{\pi}{\lambda} D \sin \alpha)}{\frac{\pi}{\lambda} D \sin \alpha} \right]^2$$



I_0 - intensitet centralnog
maksimuma

20) FRAUNHOFFEROVA DIFRAKCIJA NA N PUKOTINA

P.U. ($n=1$), mali $d \ll \lambda$

- pukotine: interfejsi u koherencijih intervalima

D = konstanta refleksije

$$E_{0A} = E_0 \frac{\sin \frac{N\pi}{2}}{\sin \frac{\pi}{2}}$$

- u svakoj pukotini je

$$\tilde{E}_{0P} = E(0) \frac{\sin(\frac{\pi}{\lambda} d \sin \alpha)}{\frac{\pi}{\lambda} d \sin \alpha}$$



$$J = D \sin \alpha$$

$$\frac{\rho}{2} = \frac{\pi}{\lambda} D \sin \alpha$$

$$E_{0A} = E_0 \frac{\sin \frac{N\pi}{2}}{\sin \frac{\pi}{2}}$$

" E_P "

$$E_{0A}(\alpha) = E(0) \frac{\sin(\frac{\pi}{\lambda} d \sin \alpha)}{\frac{\pi}{\lambda} d \sin \alpha} \frac{\sin(\frac{N\pi}{\lambda} D \sin \alpha)}{\sin(\frac{\pi}{\lambda} D \sin \alpha)}$$

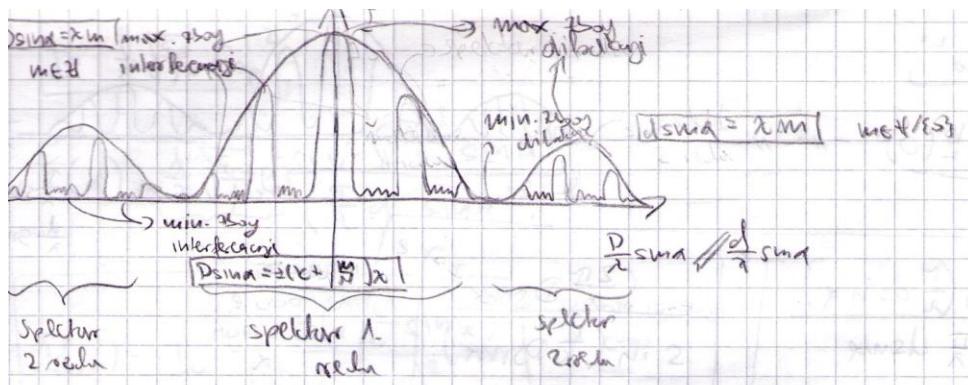
AMPLITUDA elektr. polja
u svaki je sun
kutem od α

$$I = \frac{1}{2} \sqrt{\frac{E_0}{\mu_0}} E_0^2$$

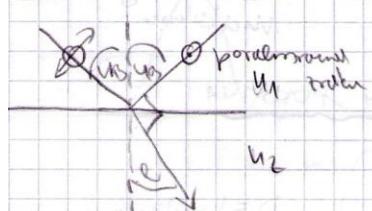
$$I = \frac{1}{2} \sqrt{\frac{E_0}{\mu_0}} E(0)^2 - \frac{1}{2} \frac{1}{2} I_0$$

INTERFERENCIJA U ZADNJI
O POKRET

$$I(\alpha) = I_0 \left[\frac{\sin^2(\frac{\pi}{\lambda} d \sin \alpha)}{\frac{\pi}{\lambda} d \sin \alpha} \right] \left[\frac{\sin^2(\frac{N\pi}{\lambda} D \sin \alpha)}{\sin^2(\frac{\pi}{\lambda} D \sin \alpha)} \right]$$



21) POLARIZACIJA



$$U_B = \sqrt{U_1^2 + U_2^2 + 2U_1 U_2 \cos(\beta - \alpha)}$$

$$\frac{\sin U_B}{\sin \beta} = \frac{U_2}{U_1}$$

$$\frac{\sin(U_B)}{\sin(\frac{\pi}{2} - \beta)} = \frac{U_2}{U_1}$$

$$\tan U_B = \frac{U_2}{U_1}$$

Brekstirer uč

- dikroicki neutraljali:

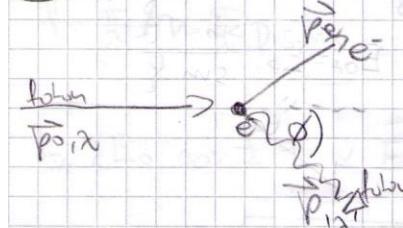
$$I = I_0 \cos^2 \alpha$$

↳ polarizirani svetlost

$$I = I_0/2$$

↳ ne-polarizirani svetlost

22) COMPTONOVO POGIJENJE



relativistički

$$E = h \frac{c}{\lambda}$$

$$p = \gamma m v \Rightarrow \gamma m c^2 \Rightarrow E = \gamma m c^2$$

$$E = \gamma m c^2 \Rightarrow p = \frac{E}{\gamma c} \Rightarrow p = \frac{E}{\gamma c} \cdot \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$p = \frac{E}{\gamma c} \cdot \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} = \frac{h}{\lambda}$$

D. Branačev
RELATI

ZOKQ:



$$\vec{p}_0 = \vec{p}_e + \vec{p}_r$$

$$\vec{p}_0 - \vec{p}_r = \vec{p}_e$$

$$p_0^2 - 2p_0 \cdot p \cos \phi + p^2 = p_e^2$$

$$\left(\frac{h}{\lambda}\right)^2 - 2 \frac{h}{\lambda} \frac{h}{\lambda} \cos \phi + \left(\frac{h}{\lambda}\right)^2 = p_e^2 (*)$$

ZOE

E folgen E alleine

$$hV_0 + mc^2 = hV' + E_e$$

Beziehung:

$$E_e^2 = p_e^2 c^2 + m^2 c^4$$

$$h \frac{c}{\lambda} + mc^2 = h \frac{c}{\lambda'} + E_e / c$$

$$\frac{h}{\lambda} + mc - \frac{h}{\lambda'} = \frac{E_e}{c}$$

$$\left(\frac{h}{\lambda} - \frac{h}{\lambda'}\right) + mc = \frac{E_e}{c}$$

$$\left(\frac{h}{\lambda} - \frac{h}{\lambda'}\right)^2 + 2\left(\frac{h}{\lambda} - \frac{h}{\lambda'}\right)mc + (mc)^2 = p_e^2 + m^2 c^2$$

$$p_e^2 = \left(\frac{h}{\lambda} - \frac{h}{\lambda'}\right)^2 + 2\left(\frac{h}{\lambda} - \frac{h}{\lambda'}\right)mc \quad (*) \neq$$

(*) ; (**)

$$\underbrace{\left(\frac{h}{\lambda} - \frac{h}{\lambda'}\right)^2 + 2\left(\frac{h}{\lambda} - \frac{h}{\lambda'}\right)mc}_{\left(\frac{h}{\lambda}\right)^2 - 2 \frac{h^2}{\lambda \lambda'} + \left(\frac{h}{\lambda'}\right)^2} = \left(\frac{h}{\lambda}\right)^2 - 2 \frac{h^2}{\lambda \lambda'} \cos \phi + \left(\frac{h}{\lambda'}\right)^2$$

$$\left(\frac{h}{\lambda}\right)^2 - 2 \frac{h^2}{\lambda \lambda'} + \left(\frac{h}{\lambda'}\right)^2 + 2\left(\frac{h}{\lambda} - \frac{h}{\lambda'}\right)mc$$

$$-2 \frac{h^2}{\lambda \lambda'} + 2h\left(\frac{1}{\lambda} - \frac{1}{\lambda'}\right)mc = -2 \frac{h^2}{\lambda \lambda'} \cos \phi$$

$$\left(\frac{1}{\lambda} - \frac{1}{\lambda'}\right)mc = \frac{h}{\lambda \lambda'} - \frac{h}{\lambda \lambda'} \cos \phi$$

$$\left(\frac{1}{\lambda} - \frac{1}{\lambda'}\right)mc = \frac{h}{\lambda \lambda'} (1 - \cos \phi)$$

$$-2 \frac{h^2}{\lambda \lambda'} mc = \frac{h}{\lambda \lambda'} (1 - \cos \phi)$$

$$\boxed{\Delta \lambda = \frac{h}{mc} (1 - \cos \phi)} = 2 \frac{h}{mc} \left(\frac{1 - \cos \phi}{2} \right) = 2 \frac{h}{mc} (\sin \phi)$$

REPLICA

VALMIH AMIN
COMPONENTE ERRENGA

$$\Delta \lambda = \frac{2h}{mc} \sin^2 \phi$$

(23) RADIOAKTIVITÄTSVERLÄUF

$$\left\{ \begin{array}{l} A = -\frac{dN}{dt} [\text{Bg}] \\ A = \lambda N \end{array} \right.$$

$$\underline{\lambda N = -\frac{dN}{dt}}$$

(abnimmt je kleinerer λ je länger
je länger)

$$\left\{ \begin{array}{l} t=0 \\ N=N_0 \end{array} \right.$$

$$-\lambda dt = \frac{1}{N} dN \quad | \int$$

$$-\lambda t = \ln N + C$$

$$\ln N = -\lambda t + C$$

$$N = e^{-\lambda t + C}$$

$$N = e^{-\lambda t} e^C$$

$$\boxed{N = N_0 e^{-\lambda t}}$$

RÄUMLICHE
RADIONUKLEIDE
VERTEILUNG

$$t=0 \Rightarrow e^C = N_0$$

$$A = -\frac{dN}{dt} = -N_0 e^{-\lambda t} \cdot (-\lambda) = \lambda N_0 e^{-\lambda t}$$

$$A_0 = A(t=0) = \lambda N_0$$

$$\boxed{A = A_0 e^{\lambda t}} \quad \text{PLATZHALTER}$$

$$N = \frac{N_0}{2}$$

$$\frac{N_0}{2} = N_0 e^{-\lambda t}$$

$$\frac{1}{2} = e^{-\lambda t} \quad | \ln$$

$$\ln 2^{-1} = -\lambda t \Rightarrow T_{1/2} = \frac{-\ln 2}{-\lambda}$$

$$\boxed{T_{1/2} = \frac{-\ln 2}{\lambda}}$$

verschiedene
Platzhalter

$$C = \frac{\frac{1}{2} \int_{N_0}^N \frac{dN}{N}}{\int_{N_0}^N \frac{dN}{N}} = \frac{1}{\lambda}$$

stetige Verteilung
zweite JETZT

(24) ZAKON ZELENJA ČRNOG TLEJA

Reljef - Jevonski zakon $f(\lambda, T) = \frac{2\pi c}{\lambda^4} E$

Hox Plank: $E = hV$
 $E_i = i h V$

$$\bar{E} = \frac{\sum_{i=0}^{\infty} N_i E_i}{\sum_{i=0}^{\infty} N_i} = \left| \begin{array}{l} \text{Boltmannova raspodjelj.} \\ \text{čestica } i \text{ energija} \\ N = N_0 e^{-\frac{E}{kT}} \end{array} \right| = \frac{\sum_{i=0}^{\infty} N_0 e^{-\frac{E_i}{kT}} E_i}{\sum_{i=0}^{\infty} N_0 e^{-\frac{E_i}{kT}}} = \left\{ e^{-\frac{E}{kT}} = x \right\}$$

$$= \frac{\sum_{i=0}^{\infty} x^i i h V}{\sum_{i=0}^{\infty} x^i} = hV \frac{\sum_{i=0}^{\infty} i x^i}{\sum_{i=0}^{\infty} x^i} = hV \frac{x + 2x^2 + 3x^3 + \dots}{1 + x + x^2 + x^3 + \dots}$$

$$\left\{ \text{g.vet} \quad S = \frac{dx}{1-x} = \frac{1}{1-x} \right\}$$

$$\bar{E} = hV \times \frac{1 + 2x + 3x^2 + \dots}{1 + x + x^2 + x^3 + \dots}$$

$$= hV \times \frac{d\left(\frac{1}{1-x}\right)}{dx} = hV \times \frac{\frac{1}{(1-x)^2}}{\frac{1}{1-x}} = hV \frac{-(x-1)^{-2}}{(x-1)} = hV \frac{x-1}{(x-1)^2}$$

$$\bar{E} = \frac{-hVx}{x-1} = \frac{-hVe^{-\frac{hV}{kT}}}{e^{-\frac{hV}{kT}} - 1} = \frac{e^{\frac{hV}{kT}} (-hV)}{e^{\frac{hV}{kT}} (1 - \frac{1}{e^{\frac{hV}{kT}}})} = \frac{hV}{e^{\frac{hV}{kT}} - 1}$$

$$f(\lambda, T) = \frac{2\pi c}{\lambda^4} \frac{h \frac{c}{\lambda^2}}{e^{\frac{hV}{kT}} - 1}$$

$$f(\lambda, T) = \frac{2\pi c^2 h}{\lambda^5} \frac{1}{e^{\frac{hV}{kT}} - 1} \quad \left[\begin{array}{l} \text{PLANARNE GUSTOĆE} \\ \text{ZRAČENJE ČESTICE TLEJA} \end{array} \right]$$

$$f(\lambda, T) = \frac{2\pi h V^3}{c^2} \frac{1}{e^{\frac{hV}{kT}} - 1} \quad \left[\begin{array}{l} \text{f(ja u V)} \end{array} \right]$$

$$\frac{e}{\lambda} = f(\lambda, T)$$