Imples let 
$$A = \begin{pmatrix} 1 & 0 & 1 \\ 3 & 4 & 5 \\ 2 & 3 & 4 \end{pmatrix}$$
, then tind  $A^{-1}$  vsing determinant method.

Olutions Now,  $|A| = \begin{pmatrix} 1 & 0 & 1 \\ 3 & 4 & 5 \\ 2 & 3 & 4 \end{pmatrix}$ 

$$= 1 \begin{pmatrix} 4 & 5 \\ 3 & 4 \end{pmatrix} - 0 \begin{pmatrix} 3 & 5 \\ 2 & 4 \end{pmatrix} + 1 \begin{pmatrix} 3 & 4 \\ 2 & 3 \end{pmatrix}$$

$$= 1 \begin{pmatrix} 4 & 5 \\ 3 & 4 \end{pmatrix} - 0 \begin{pmatrix} 3 & 5 \\ 2 & 4 \end{pmatrix} + 1 \begin{pmatrix} 3 & 4 \\ 2 & 3 \end{pmatrix}$$

$$= (16 - 15) - 0 + (9 - 8) = 1 + 1 = 2 \neq 0$$

He know that  $A^{-1} = \frac{\text{adj}(A)}{1A1} = \frac{\text{adj}(A)}{2}$ 

Now co-factor matrix =  $\begin{pmatrix} 1 & 5 \\ 3 & 4 \end{pmatrix} - \begin{pmatrix} 3 & 5 \\ 2 & 3 \end{pmatrix}$ 

Now co-factor matrix = 
$$\begin{vmatrix} 1 & 5 \\ 3 & 4 \end{vmatrix} = \begin{vmatrix} 3 & 4 \\ 2 & 4 \end{vmatrix} = \begin{vmatrix} 3 & 4 \\ 2 & 3 \end{vmatrix}$$

$$= \begin{vmatrix} 0 & 1 \\ 3 & 4 \end{vmatrix} = \begin{vmatrix} 1 & 6 \\ 2 & 4 \end{vmatrix} = \begin{vmatrix} 1 & 6 \\ 2 & 3 \end{vmatrix}$$

$$= \begin{vmatrix} 0 & 1 \\ 4 & 5 \end{vmatrix} = - \begin{vmatrix} 1 & 1 \\ 3 & 5 \end{vmatrix} + \begin{vmatrix} 1 & 6 \\ 3 & 4 \end{vmatrix}$$

$$= \begin{pmatrix} 1 & -2 & 1 \\ 3 & 2 & -3 \\ -4 & -2 & 4 \end{pmatrix}$$

 $= \begin{pmatrix} 1 - 2 & 1 \\ 3 & 2 - 3 \\ -4 & -2 & 4 \end{pmatrix} = \begin{pmatrix} 1 & 3 & -4 \\ -2 & 2 & -2 \\ 1 & -3 & 4 \end{pmatrix}$ 

$$\begin{pmatrix} 3 & 2 & 3 \\ -4 & -2 & 4 \end{pmatrix} \qquad \begin{pmatrix} 1 & -3 & 4 \\ 1 & & 2 & -4 \end{pmatrix}$$

$$A^{-1} = \frac{1}{2} \text{ adj } A = \frac{1}{2} \begin{pmatrix} 1 & 3 & -9 \\ -2 & 2 & -2 \\ 1 & -3 & 9 \end{pmatrix}$$

Examples 
$$2 - y + 2z = 6$$
  $\Rightarrow$   $\begin{pmatrix} 3 & 1 & 1 \\ 1 & -1 & 2 \\ 2 & +2y - z = -3 \end{pmatrix}$   $\begin{pmatrix} 3 & 1 & 1 \\ 1 & -1 & 2 \\ 1 & 2 & -1 \end{pmatrix}$   $\begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix}$  Here the coefficient determinant

So Écameris rule can be applied.

$$D_{L} = \begin{bmatrix} 4 & 1 & 1 \\ 6 & -1 & 2 \\ -3 & 2 & -1 \end{bmatrix} = -3$$

$$D_{2} = \begin{bmatrix} 3 & 4 & 1 \\ 1 & 6 & 2 \\ 1 & -3 & -1 \end{bmatrix} = 3$$

So by Coameri's Rule

$$x = \frac{D_{\perp}}{D} = \frac{-3}{3} = \bot$$

$$y = \frac{D_2}{D} = \frac{3}{-3} = -1$$

$$z = \frac{b_3}{D} = \frac{-6}{-1} = 2$$

## Elementory Row operation:

An elementary row operation on a matrix Amxn is an operation of the following three types:

is denoted by Rij

type 20 Multiplication of the ith slow by a non-zero scalar c is denoted by eRi

type 30 Addition of e times the jth row to the ith row is denoted by RiteRj

Example 
$$^{\circ}$$
 let  $A = \begin{pmatrix} \pm & 0 & \pm \\ 3 & 4 & 5 \\ 2 & 3 & 4 \end{pmatrix}$ 

Now example of type 18

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 3 & 4 & 5 \\ 2 & 3 & 4 \end{pmatrix} \xrightarrow{R_{23}} \begin{pmatrix} 1 & 0 & 1 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{pmatrix}$$

Now example of type 20

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 3 & 4 & 5 \\ 2 & 3 & 4 \end{pmatrix} \xrightarrow{2 R_3} \begin{pmatrix} 1 & 0 & 1 \\ 3 & 4 & 5 \\ 4 & 6 & 8 \end{pmatrix}$$

Now example of type 3 9

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 3 & 4 & 5 \\ 2 & 3 & 4 \end{pmatrix} \xrightarrow{R_2 - 2R_1} \begin{pmatrix} 1 & 0 & 1 \\ 1 & 4 & 3 \\ 2 & 3 & 4 \end{pmatrix}$$