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Amaan Rahman ECE 472: Deep Lea Professor Curro	arning	
	Assignment 2 Binary Classification	
Remar	cks:	
ion functions een fully and wasted on flow. The tegration ausing my utation. e the built	Attempts to implement ReLU, Leaky-ReLU, and Sigmoid ac	tivat
	were made and unsuccessful; the functions themselves h	ave b
	properly implemented, however an unecessary amount tim	e was
	integrating the "handmade" activation functions into T	ensor
	realization that "handmade" activation functions requi	re in
	was realizing that this very reason of no integration	was c
	model to be unable to train due to failure of gradient	comp
	The quick solution that has been used instead was to u	tiliz
	in functions instead.	
Multi	Perceptron Design Considerations:	
ithin my output layer).	One thing to note is that I don't include the input la	yer w
	discussion of design considerations (only hidden layer	s and
	Initially, I decided on testing 8->4->2->1 setup, howe	ver m
y loss didn't converge. I ramped the widths up by about times 4, and it didn't		conv
erge. I then ramp	widths by 10 fold about and then I noticed convergence	over
1500 iterations	a batch size of 32. This "funnel" design yielded losse	s to
as low as 0.003 or possibly even lower. I tested out my final design, which is the		"hou
rglass" configrua	ation:	
	100->75->50->25->50->75->100->1	
utations I have t	This design yielded optimal convergence compared to all tested out thus far, yielding losses as low as 0.000002.	perm
C	Citations:	
	Training function reference from Professor Curro's exam	ple
ning) (Algorithma	<pre>@misc{brownlee_plot_2020,</pre>	{Lear

url = {https://machinelearningmastery.com/plot-a-decisio

abstract = {Classification algorithms learn how to assig

n class labels to examples, although their decisions can appear opaque. A popula

ning} {Algorithms} in {Python}},

n-surface-for-machine-learning/},

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r diagnostic for [âM-^@|]},
                        language = {en-US},
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                        journal = {Machine Learning Mastery},
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BM7XD\\plot-a-decision-surface-for-machine-learning.html:text/html},
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ense},
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edean_spiral&oldid=1039754847},
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ithmetic spiral) is a spiral named after the 3rd-century BC Greek mathematician
Archimedes. It is the locus corresponding to the locations over time of a point
moving away from a fixed point with a constant speed along a line that rotates w
ith constant angular velocity. Equivalently, in polar coordinates (r, Î) it can
be described by the equation
                            b
                            âM-^KM-^E
                        \{{\textbackslash}displaystyle r=a+b{\textbackslash}cdot
 {\textbackslash}theta \}
                    with real numbers a and b. Changing the parameter a moves th
e centerpoint of the spiral outward from the origin (positive a toward \hat{I}_{i} = 0 an
d negative a toward \hat{I} = \ddot{I}M^{-0}) essentially through a rotation of the spiral, wh
ile b controls the distance between loops.
                    From the above equation, it can thus be stated: the position
of particle from the point of start is proportional to the angle Î, as time ela
pses.
                    Archimedes described such a spiral in his book On Spirals.
Conon of Samos was a friend of his and Pappus states that this spiral was discov
ered by Conon. },
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as-matplotlib-plot-a-bar-graph-on-existing-scatter-plot-or-vice-versa},

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37TGY\\pandas-matplotlib-plot-a-bar-graph-on-existing-scatter-plot-or-vice-versa
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