

# Predictive Analysis in Formula 1

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# Introduction, Motivation & Research Questions

**Motivation:** To quantify the F1 industry's core adage: "Is it 90% Car, 10% Driver?"

Studies in Machine Learning and econometrics have applied Elo ranking systems and multi-level regression models to decompose performance, aiming to statistically separate the contribution of the driver's skill from the car's speed, a key aim we share in this project.

**Prediction Goal:** Predict whether a driver will score championship points (Top 10).

**Research Questions:**

1. Can pre-race data accurately predict scoring probability?
2. Is F1 performance primarily **Linear** (Lasso) or defined by **Non-Linear Interactions** (Deep Learning)?
3. Do engineered contextual features (Momentum, Skill) add critical predictive value?



# Data Scope, Features and Justification

## Source and Scope:

The dataset was found using Kaggle, however for consistency the data was filtered from 2000–2024, as rules in the 20<sup>th</sup> century were different to what is used now.

To allow for analysis, missing qualifying positions were imputed to 25 (back of the grid), rather than treating these as NAs

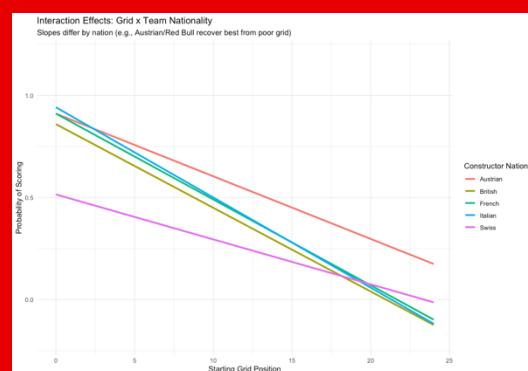
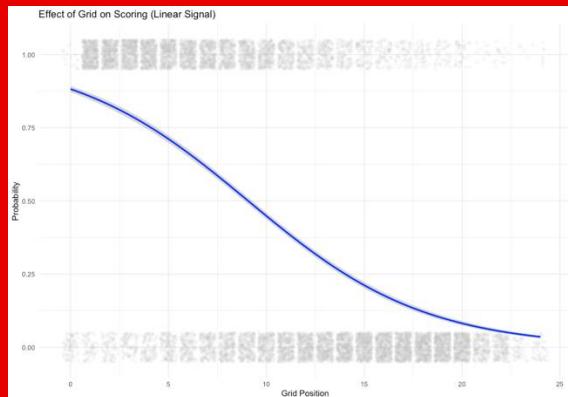
## Feature Engineering:

Features engineered to capture the human element:

1. **Driver Form:** Rolling Avg. of points (Last 3 Races)
2. **Skill Isolation:** Qualifying position relative to the teammate
3. **Car Strength:** Cumulative constructor points.

## Exploratory Data Analysis:

Initial EDA revealed both simple and complex patterns - Grid Position is Linear; Age and Team Interactions are Non-Linear.



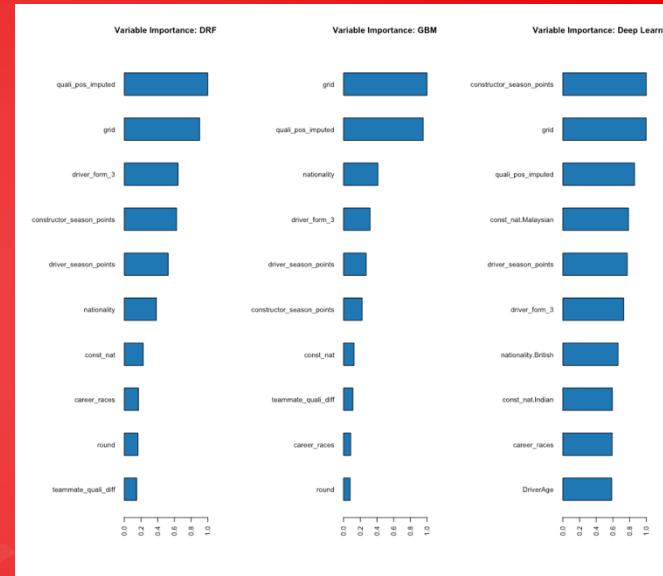
# The Final Verdict: Linearity Beats Complexity

**The Finding:** Deep Learning achieved the highest AUC (0.8576), but the difference from the third-place Lasso GLM was only **0.53%**.

Model	AUC Score	Rank
Deep Learning	0.8576	1
Random Forest	0.8568	2
Lasso GLM	0.8523	3
GBM	0.8516	4

**Success:** Variable importance charts confirmed that **Driver Momentum (driver\_form\_3)** was consistently the #2 or #3 most important predictor.

**Conclusion:** Engineered features were critical for achieving peak performance.



# Methodology

## Model Architectures

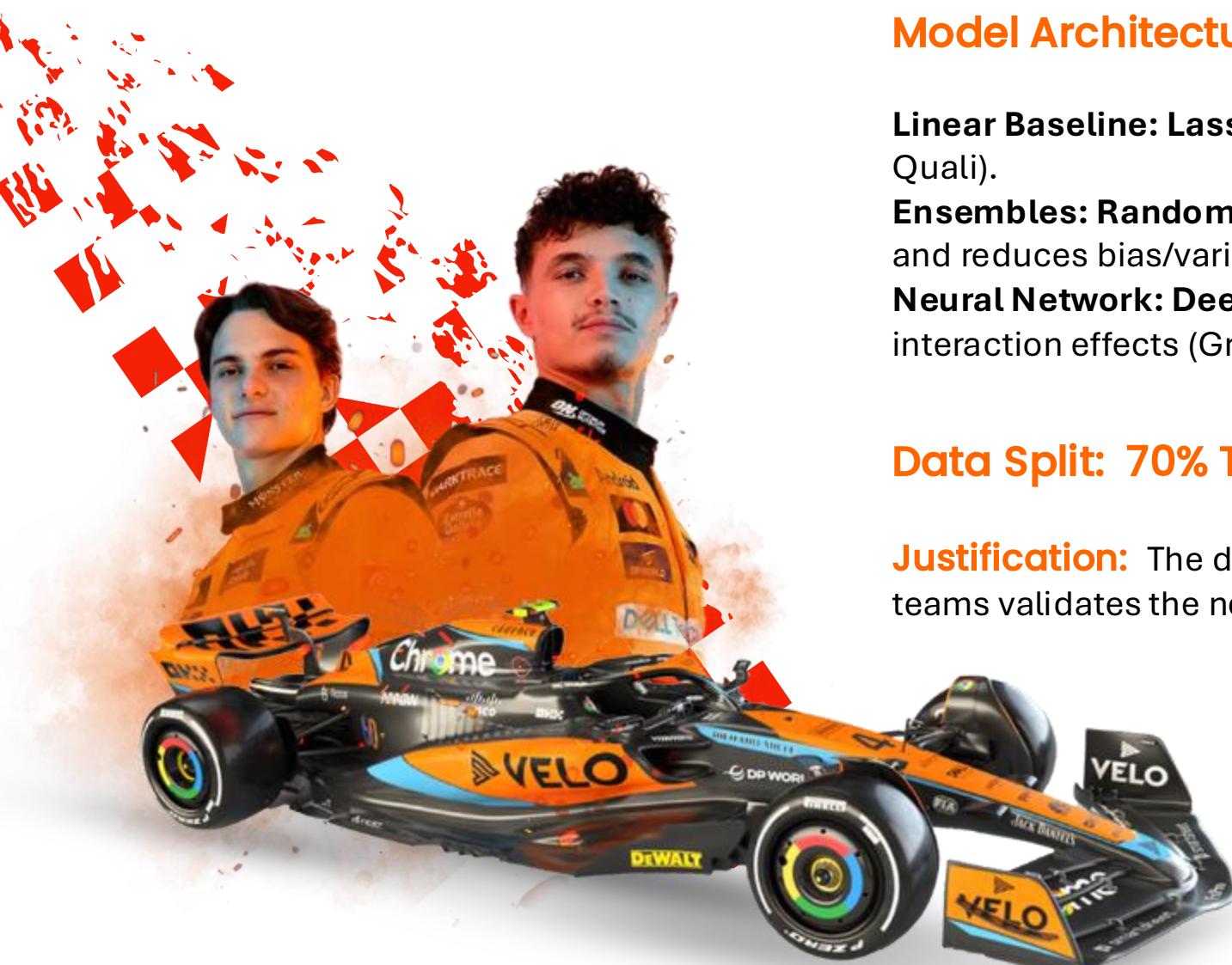
**Linear Baseline: Lasso GLM** - Handles multicollinearity (Grid vs. Quali).

**Ensembles: Random Forest & GBM** - Captures non-linearity (Age) and reduces bias/variance.

**Neural Network: Deep Learning (H2O)** - Targets high-order interaction effects (Grid x Team).

## Data Split: 70% Training/30% Testing

**Justification:** The differing grid penalty slopes across teams validates the need for non-linear models.



# Conclusion

## Recommendation

**Lasso GLM** is the recommended model for business deployment. It offers the best balance of **Interpretability** and **Efficiency**, achieving near-optimal AUC with minimal cost.



**F1 is Primarily a Linear Problem:** The strong car signal dominates. The complex non-linear models were ultimately redundant.

## Limitations

No model exceeded 86% AUC due to **Irreducible Error**. The models cannot predict unrecorded chaos variables (Weather, Mechanical Failure).

Future projects should focus on integrating external data:

1. **Live Weather API** to predict chaos.
2. **External Penalties** (grid position changes) for full context.

