

THE ISLAMIC UNIVERSITY – FACULTY OF ENGINEERING Computer ENGINEERING DEPARTMENT Embedded Systems HOMEWORK 2

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Submitted for:

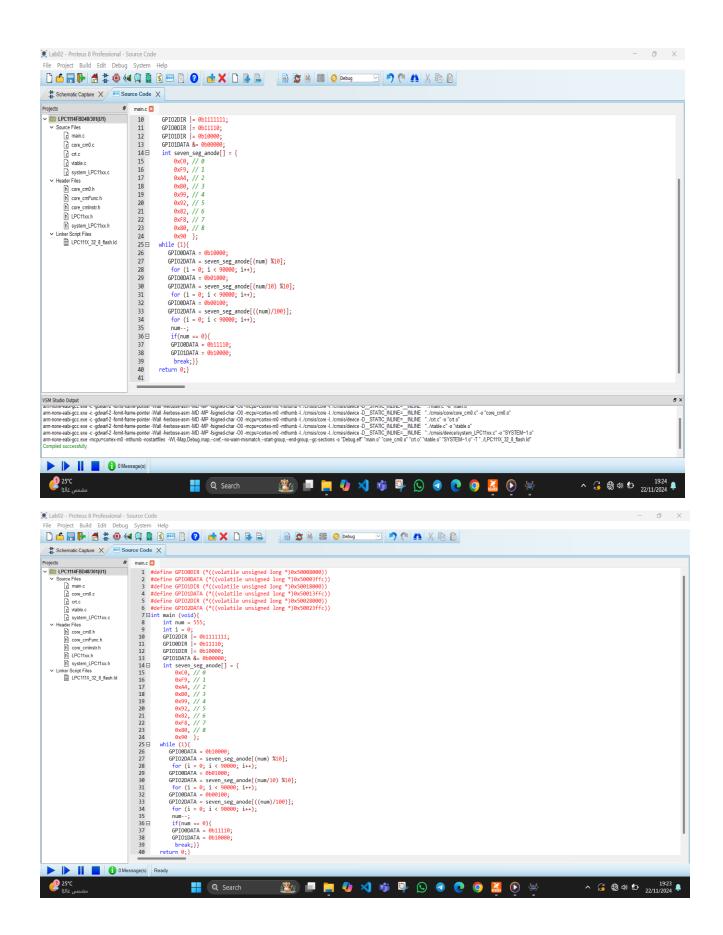
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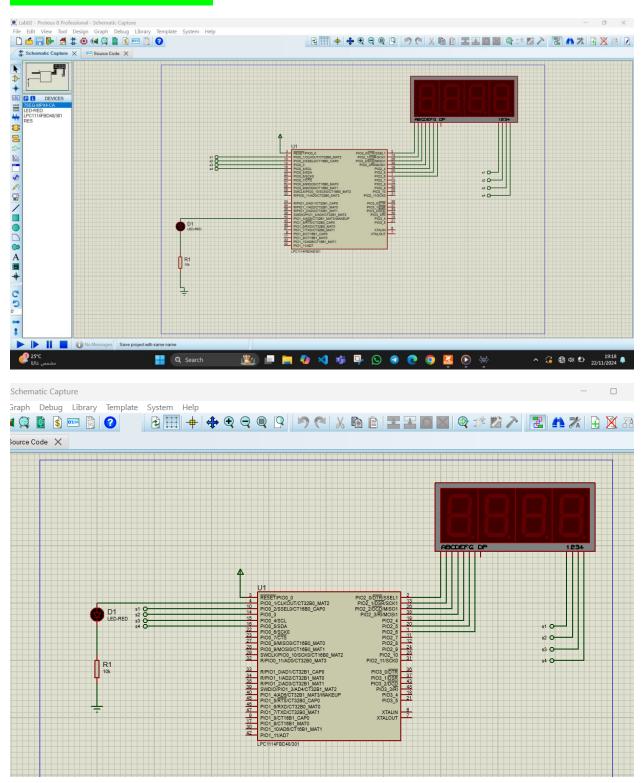
November 22,2024

Code:

```
Source Code X
   main.c 🖾
      3 #define GPIO1DIR (*((volatile unsigned long *)0x50018000))
        #define GPIO1DATA (*((volatile unsigned long *)0x50013ffc))
      5 #define GPIO2DIR (*((volatile unsigned long *)0x50028000))
     6 #define GPIO2DATA (*((volatile unsigned long *)0x50023ffc))
     7 ⊟int main (void){
     8
             int num = 555;
     9
             int i = 0;
             GPIO2DIR |= 0b1111111;
     10
     11
             GPI00DIR |= 0b11110;
     12
             GPI01DIR |= 0b10000;
    13
             GPIO1DATA &= 0b00000;
     14 ⊟
             int seven_seg_anode[] = {
     15
                 0xC0, // 0
     16
                 0xF9, // 1
     17
                 0xA4, // 2
     18
                 0xB0, // 3
     19
                 0x99, // 4
     20
                 0x92, // 5
                 0x82, // 6
     21
     22
                 0xF8, // 7
                 0x80, // 8
     23
                 0x90 };
     24
     25 ⊟
            while (1){
     26
               GPIO0DATA = 0b10000;
     27
               GPIO2DATA = seven_seg_anode[(num) %10];
                for (i = 0; i < 10000; i++);
     28
     29
               GPIO0DATA = 0b01000;
     30
               GPIO2DATA = seven_seg_anode[(num/10) %10];
     31
                for (i = 0; i < 10000; i++);
     32
               GPIO0DATA = 0b00100;
     33
               GPIO2DATA = seven_seg_anode[((num)/100)];
     34
                for (i = 0; i < 10000; i++);
                num--;
     35
     36 ⊟
                if(num == 0){
     37
                GPIOODATA = Ob111110;
     38
                GPIO1DATA = 0b10000;
     39
                 break;}}
     40
            return 0;}
     41
```

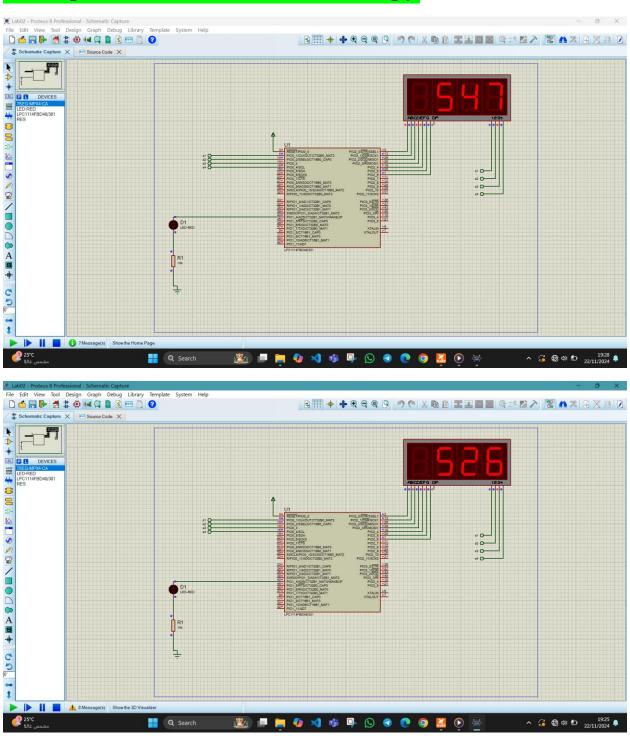


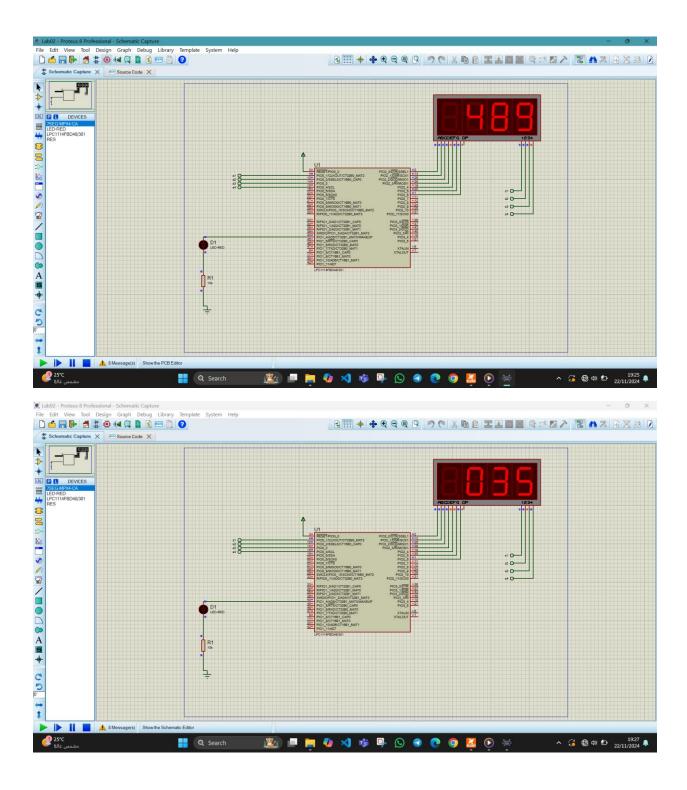
Circuit Connection:



Running the circuit simulation:

Running the numbers on screen decreasingly..





When it stops running:

