

iitRACE: A Memory Efficient Engine for Fast Incremental Timing Analysis and Clock Pessimism Removal

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Introduction

STA, Incremental Timing, CPPR

- **Faster turnaround time** for timing analysis in presence of design changes
- Clock network as a source of pessimism: Need to update pessimism-free timing information (CPPR) incrementally

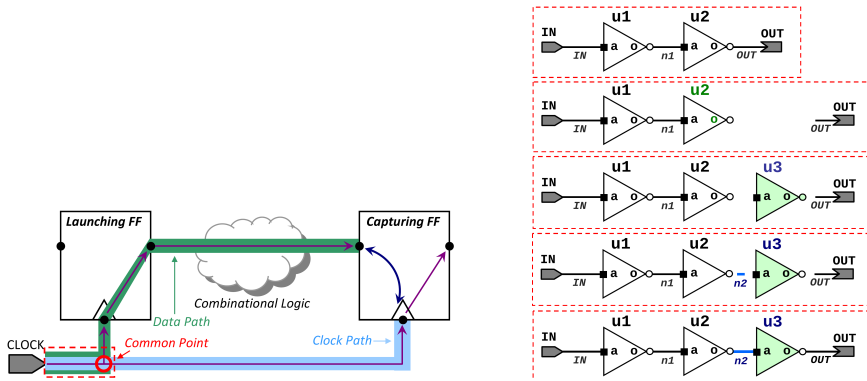


Figure: Example for CPPR and incremental changes to the design

Introduction

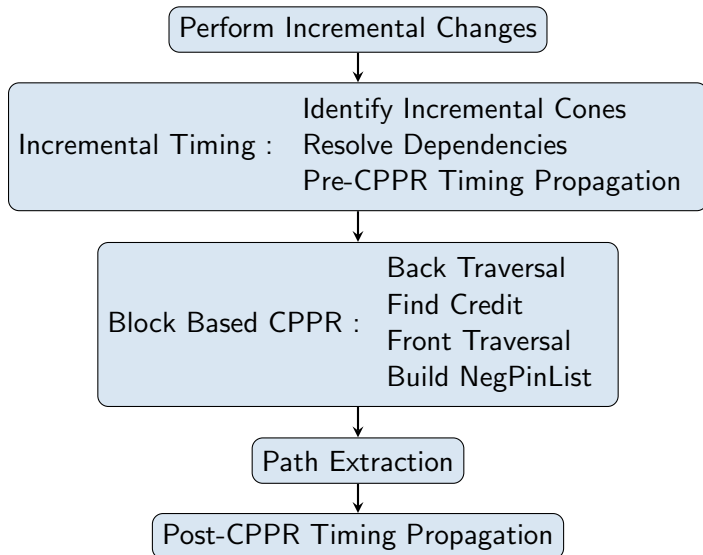
Problem Formulation

Given a circuit in standard file formats (.v , .lib , .spef , .timing)

The task is to perform incremental changes to the circuit (specified in .ops) and perform **timing analysis** & **CPPR** in the *affected regions* using **least time and resources**

Algorithm

Flow Chart



Algorithm

Incremental Timing: Identifying Incremental Cones and Resolving Dependencies

Cone-end Points

Every cone in the circuit can be associated with a unique primary output or flip-flop input pin, henceforth referred to as *Cone-end point (CEP)*

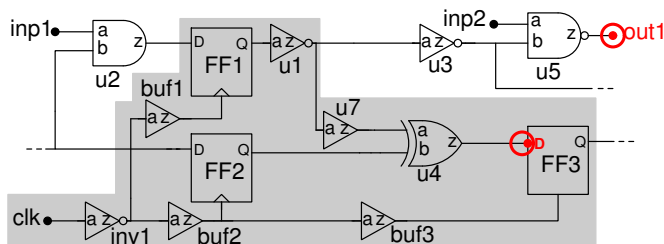


Figure: Cone-end Points: out1, FF3:D

Algorithm

Incremental Timing: Identifying Incremental Cones and Resolving Dependencies

Identifying Incremental CEPs

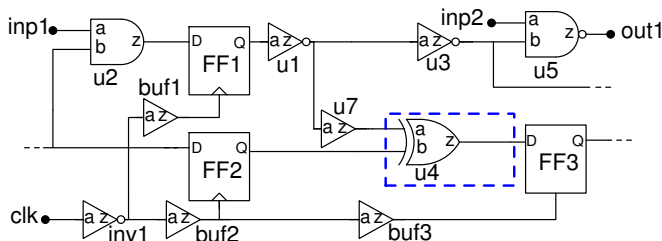


Figure: Adding a gate to the circuit

Algorithm

Incremental Timing: Identifying Incremental Cones and Resolving Dependencies

Identifying Incremental CEPs

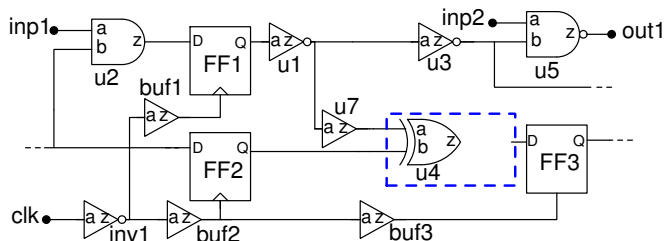


Figure: Adding a gate to the circuit: Disconnect net from u4:z

Algorithm

Incremental Timing: Identifying Incremental Cones and Resolving Dependencies

Identifying Incremental CEPs

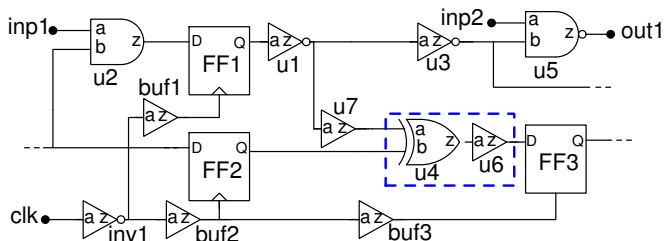


Figure: Adding a gate to the circuit: insert u6

Algorithm

Incremental Timing: Identifying Incremental Cones and Resolving Dependencies

Identifying Incremental Nets

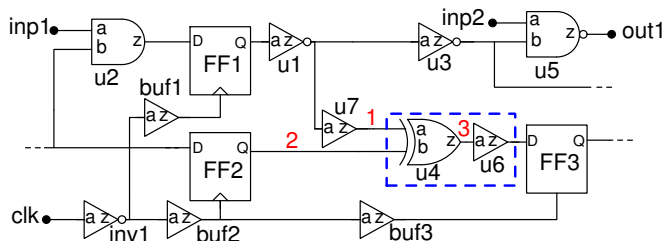


Figure: Adding a gate to the circuit: insert net 3 & connect net 3 to *u4*:z

Algorithm

Incremental Timing: Identifying Incremental Cones and Resolving Dependencies

Identifying Incremental Nets

- A net and associated timing information at its i/o pins may be dependent on the parameters of another incremental net
- Updating the values is only possible once we resolve the dependencies between incremental nets

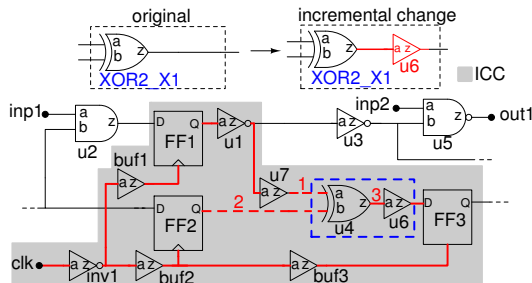


Figure: Incremental Nets

Algorithm

Incremental Timing: Identifying Incremental Cones and Resolving Dependencies

Resolving Dependencies

- Find a set of incrementally affected & independent nets: Based on a modified version of Breadth-First Search Algorithm
- Identify net 1 & 2 as independent nets & FF3:D as incremental CEP
- Cone of FF3:D is hence an incremental cone of change (ICC)

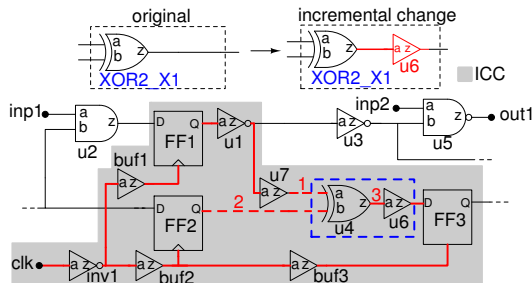


Figure: Nets 1, 2, 3: Incremental Nets 1 & 2: Dependencies resolved

Algorithm

Incremental Timing: Incremental AT/RAT/Slack Update

Pre-CPPR Timing Propagation in ICC

- Update AT by single block-based front traversal: start with net 1 & 2
- Update RAT/Slack by back traversal from incremental CEPs (FF3:D)
- Static run (full circuit) vs incremental run (only ICC)

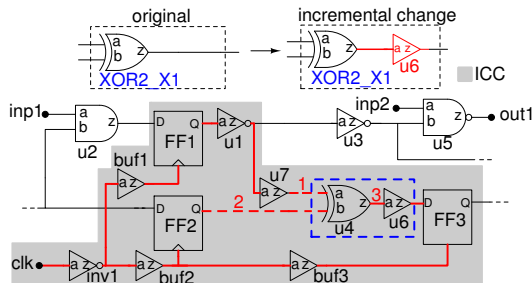


Figure: Timing propagation in ICC

Algorithm

Block-based topologically guided CPPR

Step 1 - Back Traversal

- Block based levelised back traversal from a CEP till a FF or PI
- Concept of criticalAT & criticalRAT
- Setting RAT (pre-CPPR) and criticalRAT at pins encountered and marking the cone

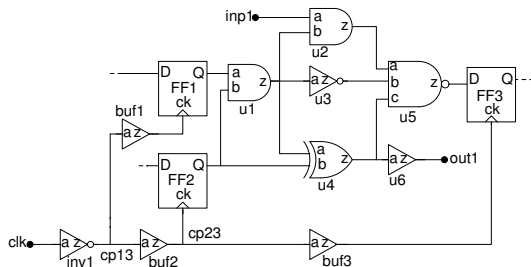


Figure: CPPR Algorithm - Back traversal from FF3:D

Algorithm

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Step 1 - Back Traversal

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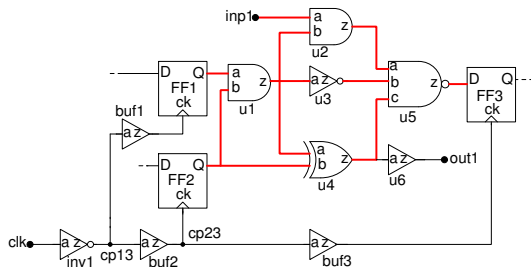


Figure: CPPR Algorithm - Back traversal from FF3:D

Algorithm

Block-based topologically guided CPPR

Step 2 - Identifying Common Points & Finding Credits

- Identifying common point of data path and clock path for each pair of launching and capturing FFs: cp13, cp23

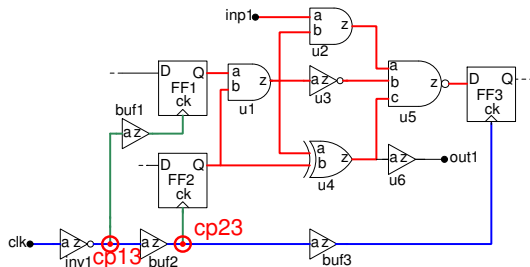


Figure: CPPR Algorithm - Identifying Common Points

Step 2 - Identifying Common Points & Finding Credits

- Credit at a launching FF can be found using eqn -

$$credit^{hold} = at_{cp}^L - at_{cp}^E$$

$$credit^{setup} = at_{cp}^L - at_{cp}^E - (at_{clk_src}^L - at_{clk_src}^E)$$

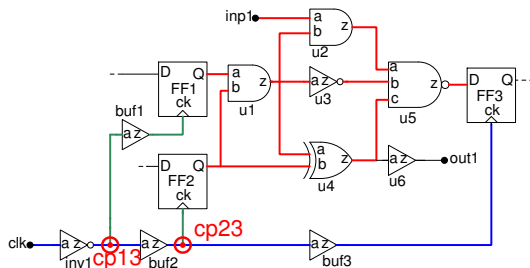


Figure: CPPR Algorithm - Finding Credits

Algorithm

Block-based topologically guided CPPR

Step 3 - Updating fakeAT

- fakeAT: Adjust AT values to carry credit information at a pin

$$fake_at_{FF:Q}^{L(E)} = at_{FF:Q}^{L(E)} \mp credit^{L(E)}$$

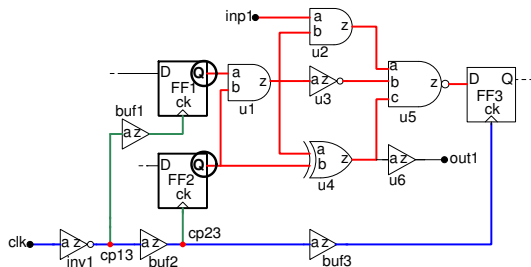


Figure: CPPR Algorithm - Setting fakeAT at output of launching FFs

Algorithm

Block-based topologically guided CPPR

Step 4 - Front Traversal

- Block-based levelised front traversal within the colored cone
- Propagate fakeAT with setting criticalAT
- fakeAT propagation ensures propagation of worst post-CPPR slack

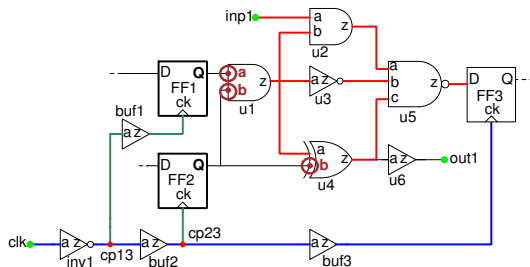


Figure: CPPR Algorithm - Front Traversal

Algorithm

Block-based topologically guided CPPR

Step 4.1 - Building NegPinList During Front Traversal

- Find the updated slacks using fakeAT and RAT values
- NegPinList & Global Path Table (GPT): Initially empty !
- Add failing pins to NegPinList

NegPinList	
Pins	Slack
u1:a ^L	-33
u1:b ^L	-25
u4:b ^L	-15

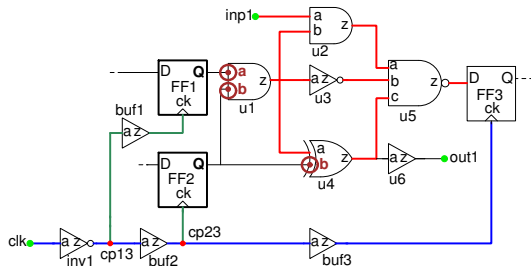


Figure: CPPR Algorithm - Building NegPinList

Algorithm

Block-based topologically guided CPPR

Step 4.1 - Building NegPinList During Front Traversal

- Find the updated slacks using fakeAT and RAT values
- NegPinList & Global Path Table (GPT): Initially empty !
- Add failing pins to NegPinList

NegPinList	
Pins	Slack
u1:a ^L	-33
u1:b ^L	-25
u4:b ^L	-15
u2:b ^L	-28
u2:a ^E	-13
u3:a ^L	-23
u4:a ^L	-33
u5:a ^L	-28
u5:a ^E	-13
u5:b ^L	-23
u5:c ^L	-33
FF3:D ^L	-33
FF3:D ^E	-13

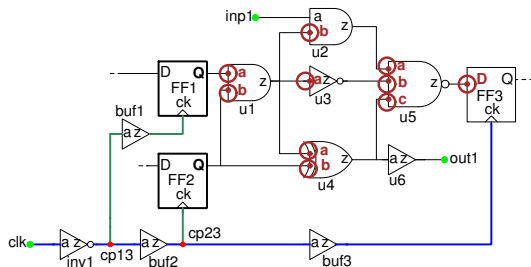
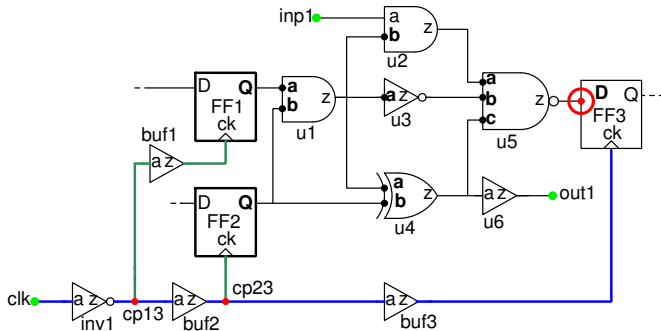


Figure: CPPR Algorithm - Building NegPinList

Algorithm

Path Extraction from NegPinList of a cone

Step 5 - Extract Paths from NegPinList

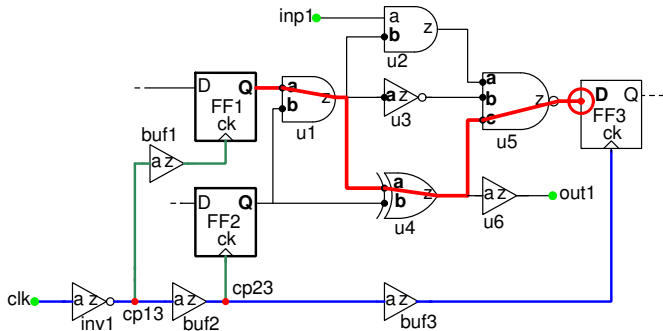


Step	Path	NegPinList
0	-	$FF3:D^L, u5:c^L, u4:a^L, u1:a^L, u5:a^L, u2:b^L, u1:b^L, u5:b^L, u3:a^L, u4:b^L, FF3:D^E, u5:a^E, u2:a^E$

Algorithm

Path Extraction from NegPinList of a cone

Step 5 - Extract Paths from NegPinList

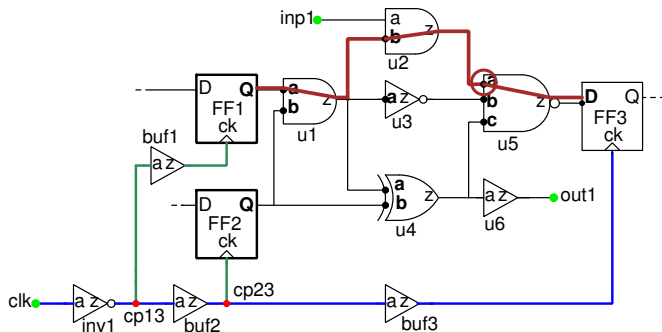


Step	Path	NegPinList
1	P ₁	FF3:D^L, u5:c^L, u4:a^L, u1:a^L , u5:a ^L , u2:b ^L , u1:b ^L , u5:b ^L , u3:a ^L , u4:b ^L , FF3:D ^E , u5:a ^E , u2:a ^E

Algorithm

Path Extraction from NegPinList of a cone

Step 5 - Extract Paths from NegPinList

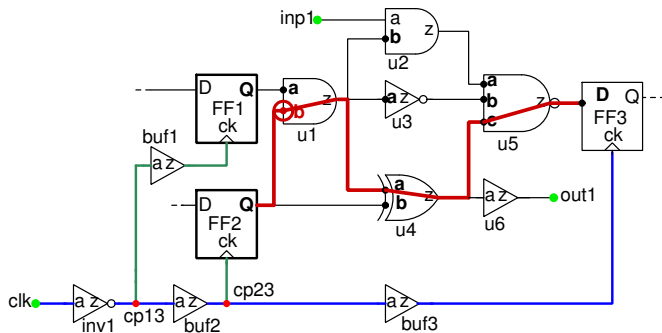


Step	Path	NegPinList
2	P ₂	$FF3:D^L, u5:c^L, u4:a^L, u1:a^L, u5:a^L, u2:b^L, u1:b^L, u5:b^L, u3:a^L, u4:b^L, FF3:D^E, u5:a^E, u2:a^E$

Algorithm

Path Extraction from NegPinList of a cone

Step 5 - Extract Paths from NegPinList

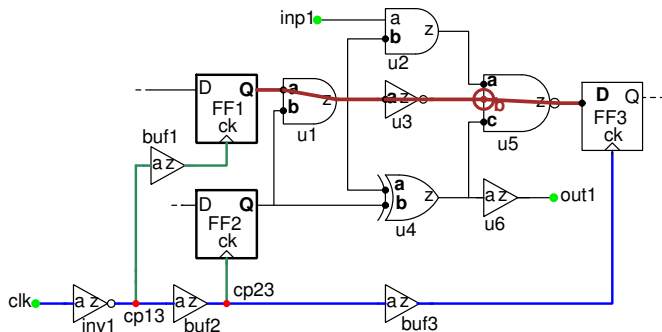


Step	Path	NegPinList
3	P ₃	$FF3:D^L, u5:c^L, u4:a^L, u1:a^L, u5:a^L, u2:b^L, u1:b^L, u5:b^L, u3:a^L, u4:b^L, FF3:D^E, u5:a^E, u2:a^E$

Algorithm

Path Extraction from NegPinList of a cone

Step 5 - Extract Paths from NegPinList

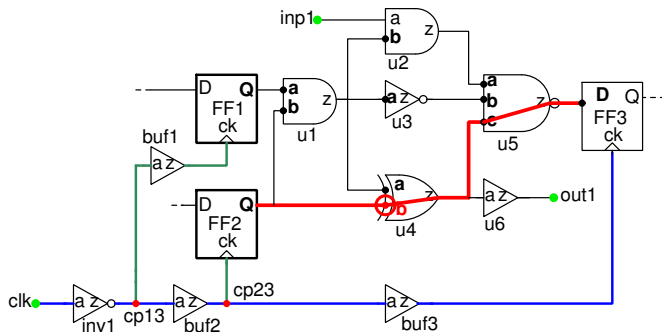


Step	Path	NegPinList
4	P ₄	$FF3:D^L, u5:c^L, u4:a^L, u1:a^L, u5:a^L, u2:b^L, u1:b^L, u5:b^L, u3:a^L, u4:b^L, FF3:D^E, u5:a^E, u2:a^E$

Algorithm

Path Extraction from NegPinList of a cone

Step 5 - Extract Paths from NegPinList

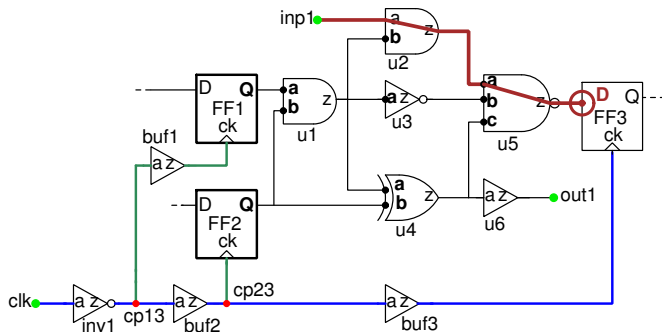


Step	Path	NegPinList
5	P ₅	$FF3:D^L, u5:c^L, u4:a^L, u1:a^L, u5:a^L, u2:b^L, u1:b^L, u5:b^L, u3:a^L, u4:b^L, FF3:D^E, u5:a^E, u2:a^E$

Algorithm

Path Extraction from NegPinList of a cone

Step 5 - Extract Paths from NegPinList



Step	Path	NegPinList
6	P ₆	$FF3:D^L, u5:c^L, u4:a^L, u1:a^L, u5:a^L, u2:b^L, u1:b^L,$ $u5:b^L, u3:a^L, u4:b^L, FF3:D^E, u5:a^E, u2:a^E$

Algorithm

Path Extraction from NegPinList of a cone

Paths Skipped

Name	Slack	Mode	Path
P ₇	-20	L	FF2:Q→u1:b→u1:z→u2:b→ u2:z→ u5:a→u5:z→FF3:D
P ₈	-15	L	FF2:Q→u1:b→u1:z→u3:a→ u3:z→ u5:b→u5:z→FF3:D

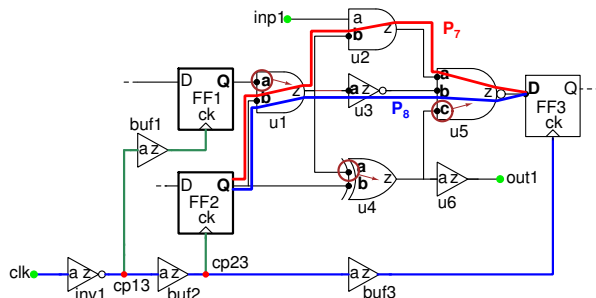


Figure: Path Extraction - Paths skipped

Algorithm

Path Extraction from NegPinList of a cone

Paths Extraction: Redundant Paths

- None of the pins in path P7 (or P8) have P7 (P8) as worst path through them in the cone under consideration
- It is highly probable that correcting only the reported paths (P1 to P6) would correct the skipped paths (P7 and P8) as well

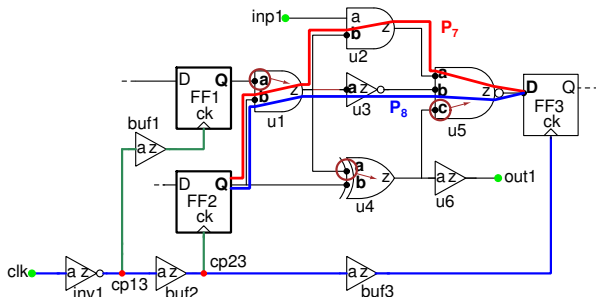


Figure: Path Extraction - Paths skipped

Algorithm

Path Extraction from NegPinList of a cone

Paths Extraction: Redundant Paths

Most importantly, our proposed algorithm ensures that for **every path** that is reported, this path is the **most critical** for some pin in the path, for some logic cone in the circuit. This is not ensured by regular algorithms that report the N worst paths in a circuit, due to which such algorithms typically report many paths that are in some sense **redundant**

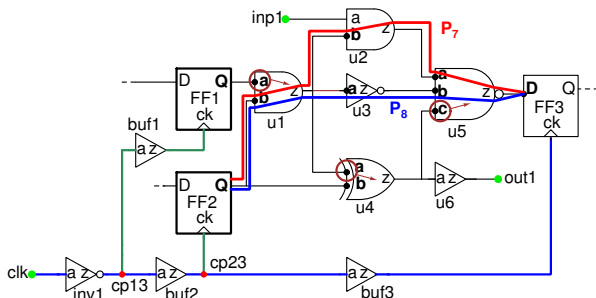


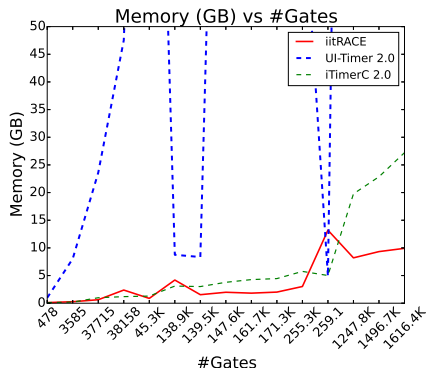
Figure: Path Extraction - Paths skipped

Experimental Results

Accuracy and Memory Efficiency

TAU Results: Comparison of iitRACE With Other Academic Timers

Average value accuracy **99%** with the **least** memory requirement !
(Average **2X** lower than the first place timer)



- Memory peaks: corner cases
- **On the fly** interconnect delay computation
- Pin slack, criticalAT, criticalRAT as the only implicit representation of path

Figure: Memory Usage Comparison

Coverage

- A measure of the number of unique CEPs among the pins in the set of worst paths
- **Higher coverage:** Our algorithm typically captures a much larger number of such CEPs than the actual N worst paths in the circuit
- Beneficial in identifying all the failing cones

Experimental Results

Test Coverage

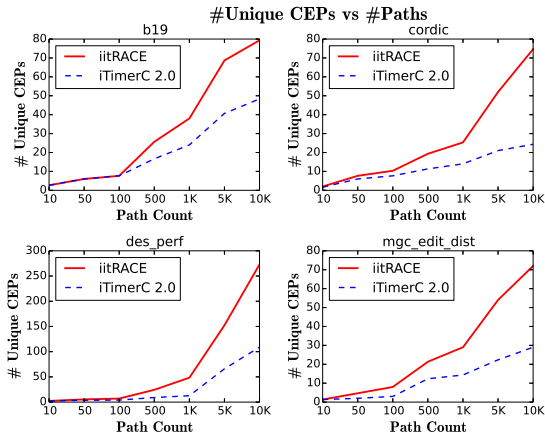


Figure: Test coverage comparison against actual top N worst paths

- Higher coverage of pins: aid to identify critical regions

Experimental Results

Post-contest Improvements in Performance Without Compromising the Accuracy

Post-Contest Speed-up: 10X !

Benchmark	MMR (GB)		CPU (s)	
	C	Post-C	C	Post-C
b19	3.02	3.33	426	132
cordic	0.87	0.84	60	31
des_perf	4.19	1.74	189	94
edit_dist	1.98	2.16	562	84
fft	2.38	0.63	44	26
leon2	9.92	12.4	13800	582
leon3mp	8.20	10.17	4920	463
mgc_edit_dist	1.82	2.14	566	79
mgc_matrix_mult	2.01	2.37	239	82
netcard	9.33	11.6	3800	516
tau_cordic_core	0.27	0.21	8	7
tau_crc32d16N	0.11	0.11	1	1
tau_softusb_navre	0.19	0.2	13	7
tau_tip_master	0.63	0.65	39	18
vga_lcd_1	13.22	2.76	742	409
vga_lcd_2	1.54	1.76	243	64
Total	59.68	53.07	25680	2590

MMR: Maximum Memory Requirement, CPU: Runtime (s)

C: Contest, Post-C: Post-Contest

- Resolved the memory peaks: corner cases
- Cut-off technique**: search space reduction
- Algorithmic optimization: **sparse table** implementation for finding lowest common ancestor (common point), improvement in incremental circuit connection
- Multithreading**: parallel processing of the cones

Conclusion

- Proposed a novel **memory efficient** incremental timing analysis technique with **block-based CPPR** framework
- The approach is rooted from a highly **practical** perspective, in which we accurately report only non-redundant critical paths
- Significantly **higher coverage** of cone-end points corresponding to critical paths than regular algorithms for worst path reporting. This can be used by the designers as an **additional aid** to identify critical areas in the circuit from a path correction perspective
- **Future extensions:** static/incremental statistical timing analysis

Acknowledgements

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 - Greg Schaeffer, IBM Corp.
 - Vibhor Garg, Cadence
- We would also like to thank the authors of UI-Timer 2.0 and iTimerC 2.0 for sharing their timer binaries of TAU 2015 Contest