

MINI PROJECT

AIM: CREATE A ROBOT WHICH WILL MOVE ONLY ON YELLOW PATH IN GIVEN IMAGE.

CODE:

```
import ch.aplu.robotsim.*;

public class Miniproject1 {

    public Miniproject1() {
        LegoRobot robot = new LegoRobot();
        Gear g = new Gear();
        LightSensor ls = new LightSensor(SensorPort.S3);

        robot.addPart(g);
        robot.addPart(ls);

        g.setSpeed(50);
        g.forward();

        while(true) {
            int value = ls.getValue();
            if(value >= 1000)
                g.forward();
            if(value < 1000)
```

```
        g.left();
        if(value < 100)
            g.stop();
    }
}

static {
    RobotContext.setStartPosition(430, 230);
    RobotContext.useBackground("sprites/yellowpath.gif");
}

public static void main(String[] args) {

    Miniproject1 robo = new Miniproject1();

}

}
```

OUTPUT:

