4.3.19 OMR_SetSleepTime

Prototype	BOOL OMR_SetSleepTime(int iSleepTime, int iStandbyTime)		
	Use the energy-saver command ES to set the time interval before the machine goes into sleep/standby mode.		
Process			
	This option may not be available on some models. Please consult your user's manual.		
		Time to sleep mode 1-60 (minutes)	
	iSeepTime	SR_SLEEPTIME_DISABLE :Disable	
Parameters		SR_SLEEPTIME_INITIAL :Return to Default Setting	
	iStandbyTime	Time to standby mode 1-60 (minutes)	
	istandbyrine	SR_STANDBYTIME_DISABLE :Disable	
Retern Value	TRUE	Successful	
Neterii value	FALSE	Failed	

4.3.20 OMR_GetSleepTime

Prototype	BOOL OMR_GetSleepTime(int* piSleepTime, int* piStandbyTime)		
	Use the energy-saver command ES to get the time interval before the machine		
Process	sleep/standby mod	le.	
	This option may not be available on some models. Please consult your user's manual.		
	piSleepTime	Time to sleep mode 1-60 (minutes)	
Parameters -	різівертініе	SR_SLEEPTIME_DISABLE :Disable	
I didiliotois	piStandbyTime	Time to standby mode 1-60 (minutes)	
		SR_STANDBYTIME_DISABLE :Disable	
Retern Value	TRUE	Successful	
neterii value	FALSE	Failed	

4.4 Operation Requirements

4.4.1 OMR_Reset

Prototype	BOOL OMR_Reset(void)		
Process	Use Reset command SR to re-set the OMR to initial status before power was initiated.		
Parameter	None		
Return value	TRUE	Successful	
Tiotaili value	FALSE	Failure	

4.4.2 OMR_FeedSheet

Prototype	BOOL OMR_FeedSheet(void)		
Process	Use the FeedSheet command SF to send one sheet through the OMR.		
Parameter	None		
Return value	TRUE	Successful	
Tietaili value	FALSE	Failure	

4.4.3 OMR_MoveHopper

Prototype	BOOL OMR_MoveHopper(int iDrection)		
Process	Use the MoveHopper command HU to enable up/down movement of the hopper.		
		Hopper Direction	
Parameter	iDirection	SR_HOPPER_DOWN	: down
		SR_HOPPER_UP	: up
Return value	TRUE	Successful	_
neturi value	FALSE	Failure	

4.4.4 OMR_EjectSheet

Prototype	BOOL OMR_EjectSheet(int iDirection)			
Process	Use the Eject	the EjectSheet command ER to activate sheet eject fanction.		
		Setting eject action		
		SR_EJECT_MAIN	:Eject sheet to Main Stacker	
	iDirection	SR_EJECT_SELECT	:Eject sheet to Select Stacker	
Parameter		SR_EJECT_MAIN_ON_NEXT		
		:Eject sheet to Ma	in Stacker on the next SF command.	
		SR_EJECT_SELECT_O	N_NEXT	
		:Eject sheet to Sel	ect Stacker on the next SF command.	
Return value	TRUE	Successful		
Trotain value	FALSE	Failure		

4.4.5 OMR_InitialSetting

Prototype	BOOL OMR_InitialSetting(void)		
Process	Use InitialSetting command is to return and save OMR setting to time of shipment from factory.		
Parameter	None		
Return value	TRUE	Successful	
Trotain value	FALSE	Failure	

4.4.6 OMR_CancelError

Prototype	OMR_STATUS OMR_CancelError(void)		
Process	Use CancelError command CE to gain status data from OMR.		
Parameter	None		
Retern Value	OMR_STATUS	Refer to OMR_STATUS constant list for further details	
Details	Also reflected in OMR_STATUS available from OMR_GetLastError		

4.3.12 OMR_GetWarningError

Prototype	BOOL OMR_GetWarningError(DWORD *dwConfigDate, int *iSkewCol, int *iSkewLevel)			
Process	Use the GetWarningError command WE to obtain the designated conditions for warnings.			
Parameter	*dwConfigData	Return whether warning should be enabled/disabled using bits. SR_WARN_AUTO_REJECT : Automatic paper output enabled SR_WARN_SHEET_EMPTY : Sheet empty detected SR_WARN_TM_ERROR : Timing marker error detected SR_WARN_DF_ERROR : Double feed detected SR_WARN_LEFT-SKEW : Left skew detected SR_WARN_MARK_SKEW : Marked skew detected The logic sum of the above.		
	*iSkewCol	Address to save the mark skew detection column.		
	*iSkewLevel	Address to save the mark skew detection level.		
Retern Value	TRUE	Successful		
Tiotom vaido	FALSE	Failure		
Details	Example DWORD warm_info; int SkewCol; int SkewLevel; warm_info = OMR_GetWarningError(); if(!OMR_GetWarningError(&warm_info, &SkewCol, &SkewLevwl)){ //Error process is noted here } if((wam_info&SR_WARN_DF_EFFOR)!=0){ //Double field detection enabled at this point }			
	mark skew enable OMR_SetWarni	he current setting, hopper empty enabled, timing mark error enabled, d columns=13 set to detection level 7. ngError((warm_info SR_WARN_EMPTY _MARK_SKEW)& ~SR_WARN_TM_ERROR, 13, 7);		

4.3.13 OMR_SetPanelConfig

Prototype	BOOL OMR_SetPanelConfig(int iPanelEnable)			
Process	Use SetPanelCor	onfig command PO to enable/disable panel operations.		
		/disable		
Dommotor	Parameter iPanelEnable	SR_DISABLE	: Disable panel operations	
Falailletei		SR_ENABLE	: Enable panel operations	
		SR_INITIAL	: Return to Initial value (enabled)	
Retern Value	TRUE	Successful		
	FALSE	Failure		

4.3.14 OMR_GetPanelConfig

Prototype	int OMR_GetPanelConfig(void)		
Process	Use GetPanelConfig con	mmand PO to obtair	setting for enable/disable panel operation.
Parameter	None		
	SR_FUNCTION_FAIL	Failure	
Retern Value	Others	SR_DISABLE	: Panel opperation is set at disabled
		SR_ENABLE	: Panel operation is set at enabled