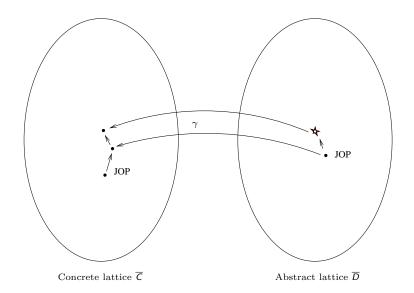
# Kildall's algorithm for over-approximate JOP

Deepak D'Souza and K.V. Raghavan

Department of Computer Science and Automation Indian Institute of Science, Bangalore.

# Why over-approximation of JOP in abstract lattice is useful

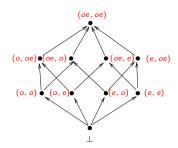


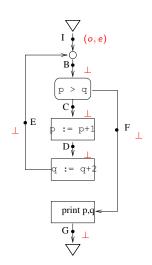
# Kildall's algorithm to compute over-approximation of JOP

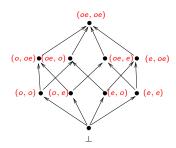
Input: An instance  $(P, d_0)$  of a monotone data-flow framework  $((D, \leq), F)$ .

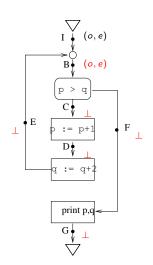
Output: For each program point N in P, a data-value  $d_N$  such that  $\mathrm{JOP}_N^{d_0} \leq d_N$ .

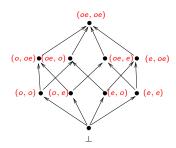
- Initialize data value at each program point to  $\perp$ , entry point to  $d_0$ .
- Mark all points.
- Repeat while there is a marked point:
  - Choose a marked point M with value  $d_M$ , unmark it, and "propagate" it to successor points (i.e. for each successor N, replace value at N by  $f_{MN}(d_M) \sqcup d_N$ ).
  - Mark successor point if old value was marked, or new value strictly dominates than old value.
- Return data values at each point as over-approx of JOP.

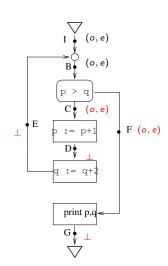


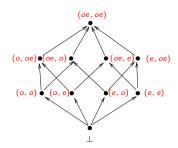


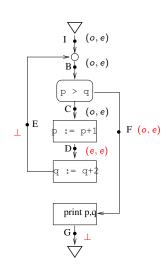


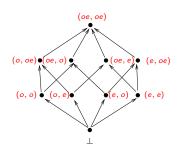


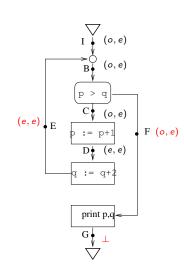


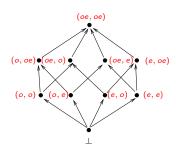


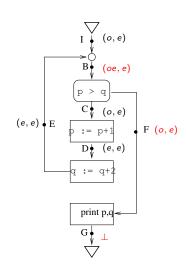


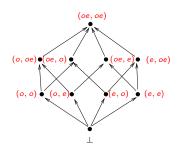


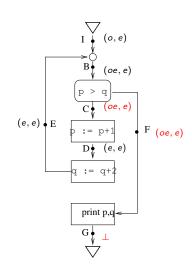


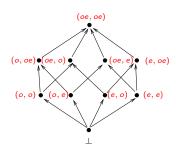


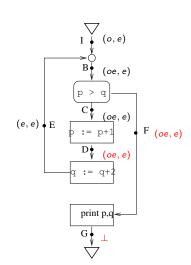


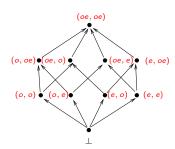


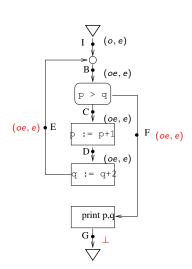


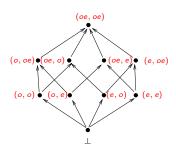


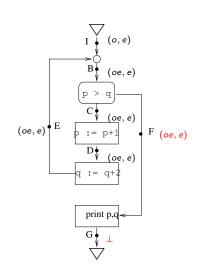


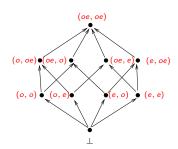


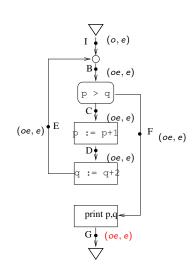




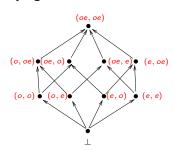


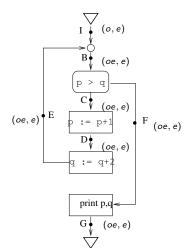






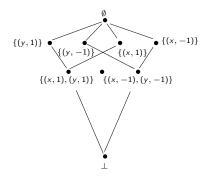
### Underlying lattice

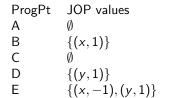


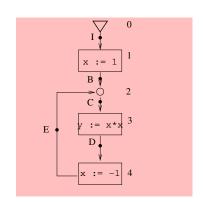


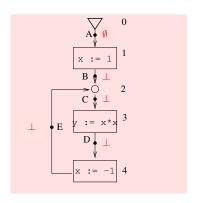
Values computed coincide with JOP values.

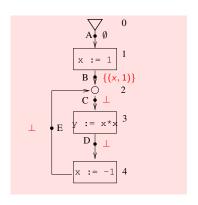
# Constant propagation example

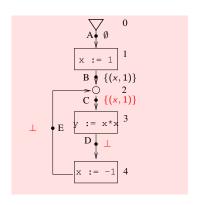


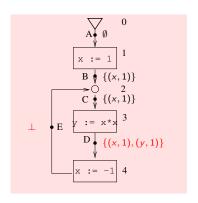


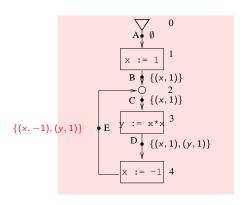


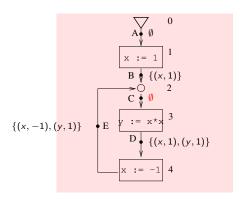


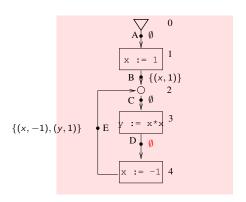


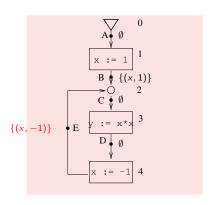


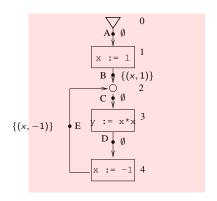






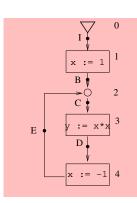






## Kildall's algo vs Actual Constant data

ProgPt	Actual JOP values	Kildall's data
A	Ø	Ø
В	$\{(x,1)\}$	$\{(x,1)\}$
C	Ø	Ø
D	$\{(y,1)\}$	Ø
E	$\{(x,-1),(y,1)\}$	$\{(x,-1)\}$



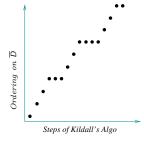
Note that Kildall's values are  $\geq$  the actual JOP values at all points.

## What Kildall's algo computes

- Always terminates if lattice has no infinite ascending chains.
- In general, computes the least solution to a system of equations induced by the given instance of the analysis.
- This value is always an over-approximation of the JOP for the given instance.

# Termination of Kildall's algo

- Let  $\overline{d}_i$  be the vector of values after the *i*-th step of algo.
- At step i+1 either  $\overline{d}_{i+1}$  strictly dominates  $\overline{d}_i$ , or  $\overline{d}_{i+1}=\overline{d}_i$ . In the latter case number of marks decreases.
- The maximum length of any contiguous non-"climbing" sequence is equal to the number of program points.
- Moreover, the maximum number of "climbing" steps in algorithm is at most the length of any chain in the lattice  $\overline{D}$ .
- Therefore, the algorithm is guaranteed to terminate on finite-height lattices.



# **Induced Equations**

The program induces a set of data-flow equations:

$$x_I = d_0$$
 for entry point  $I$   
 $x_N = f_{MN}(x_M)$  for an assignment or conditional node  $n$  with with incoming point  $M$  and outgoing point  $N$   
 $x_N = x_L \sqcup x_M$  for a junction node with incoming points  $L,M$  and outgoing  $N$ .  
... etc.

# **Induced Equations**

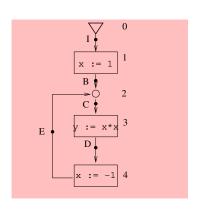
The program induces a set of data-flow equations:

$$x_I = d_0$$
 for entry point  $I$   
 $x_N = f_{MN}(x_M)$  for an assignment or conditional node  $n$  with with incoming point  $M$  and outgoing point  $N$   
 $x_N = x_L \sqcup x_M$  for a junction node with incoming points  $L,M$  and outgoing  $N$ .  
... etc.

Note: The collecting semantics is a solution to the above equations.

# **Example equations**

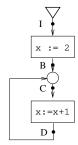
$$x_{I} = d_{0}$$
  
 $x_{B} = f_{1}(x_{I})$   
 $x_{C} = x_{B} \sqcup x_{E}$   
 $x_{D} = f_{3}(x_{C})$   
 $x_{E} = f_{4}(x_{D}).$ 



## **Equations can have multiple solutions**

Exercise: Give two solutions to equations induced for this program

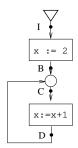
- Use lattice of subsets of concrete stores, with integer values for x.
- Write down induced equations.
- Give two different solutions to the equations. Let  $d_0 = State$ .



## **Equations can have multiple solutions**

Exercise: Give two solutions to equations induced for this program

- Use lattice of subsets of concrete stores, with integer values for x.
- Write down induced equations.
- Give two different solutions to the equations. Let  $d_0 = State$ .



Note: collecting semantics of any program is the least solution to its data-flow equations using the concrete lattice (to be shown).

# Function $\overline{f}$ induced by equations

## Equations:

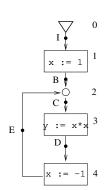
$$x_{I} = d_{0}$$

$$x_{B} = f_{1}(x_{I})$$

$$x_{C} = x_{B} \sqcup x_{E}$$

$$x_{D} = f_{3}(x_{C})$$

$$x_{E} = f_{4}(x_{D}).$$



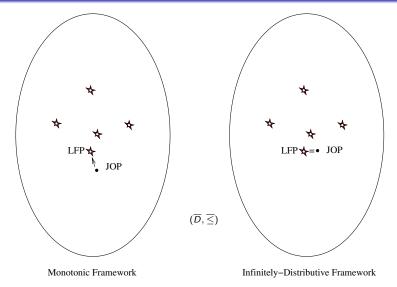
## Corresponding $\overline{f}$ function:

$$\overline{f}(d_I, d_B, d_C, d_D, d_E) = (d_0, f_1(d_I), d_B \sqcup d_E, f_3(d_C), f_4(d_D)).$$

## Natural ordering on solutions to Eq

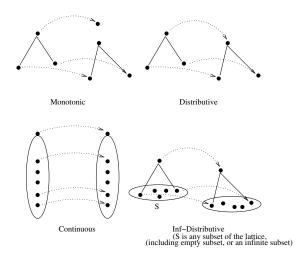
- Consider "vectorised" lattice  $\overline{D} = (D^k, \leq)$ , where D is the underlying lattice.
- Each solution to the equations is a point in this vectorised lattice.
- The solutions are precisely the fix-points of the function  $\overline{f}$ :  $\overline{D} \to \overline{D}$ .
- If D is a complete lattice and  $f_i$ 's are monotone, then  $\overline{D}$  is complete and  $\overline{f}$  is monotone.
  - Note: Concrete analysis satisfies these properties. So do many abstract interpretations.
- Therefore, Knaster-Tarski theorem applies. Therefore, there exists a least solution to  $\overline{f}$ .
- Kildall's algorithm computes this Ifp (if it terminates).
  - So does the Kleene iteration  $\perp_{\overline{D}}, \overline{f}(\perp_{\overline{D}}), \overline{f}^2(\perp_{\overline{D}}), \ldots$  if it reaches a stable value.

#### **Correctness**



Kildall's algo always computes LFP of  $\overline{f}$ .

# Monotonicity, distributivity, and continuity



### 1. $JOP \leq LFP$ for monotone framework

- Let  $\overline{c}$  be any FP of  $\overline{f}$ . Consider any program point N. Let  $c_N \equiv \overline{c}[N]$ .
- Claim: For any path p, if N is the point at the end of p,  $c_N$  dominates  $d \equiv f_p(d_0)$  reaching N.

The argument is by induction on length of path p.

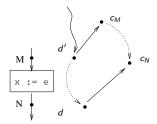
- Base case |p| = 0: Then N = I, and  $d = c_N = d_0$ .
- Let path p be of length i+1. Let M be the program that p passes through just before reaching N. Let d' be  $f_p^M(d_0)$ , where  $f_p^M$  is the path transfer function of the prefix of path p that ends at point M. The inductive hypothesis is that  $d' \sqsubseteq c_M$ .

The rest of the proof is in two cases.

#### 1. $JOP \leq LFP$ for monotone framework

Case (node between M and N is not a join node): Since  $\overline{c}$  is a solution to the equations, and since the equation for  $x_N$  is  $x_N = f_{MN}(x_M)$ , we have  $c_N = f_{MN}(c_M)$ .

Now, since  $d = f_{MN}(d')$ , by monotinicity of  $f_{MN}$ , and from the hypothesis  $d' \sqsubseteq c_M$ , it follows that  $d \sqsubseteq c_N$ .

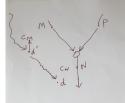


### 1. JOP ≤ LFP for monotone framework

Case (node between M and N is a join node): Let P be the other predecessor of the join node.

- d = d' (because join nodes have identity transfer function)
- ② The dataflow equation for  $x_N$  is  $x_N = x_M \sqcup x_P$ . Since  $\overline{c}$  is a solution to the equations,  $c_N = c_M \sqcup c_P$ . That is,  $C_M \sqsubseteq C_N$ .
- **3** By inductive hypothesis,  $d' \sqsubseteq c_M$ .

The observations above imply that  $d \sqsubseteq c_N$ .



## 1. $JOP \leq LFP$ for monotone framework

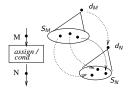
- That is, for every path p that reaches a point N,  $f_p(d_0) \sqsubseteq c_N$ .
- Therefore, JOP  $d_N$  at N is  $\sqsubseteq c_N$

Proof: Enough to show that the JOP  $\overline{d}$  is a fixpoint of  $\overline{f}$ . We denote  $\overline{d}[M]$  as  $d_M$ ,  $\overline{d}[N]$  as  $d_N$ , etc.

Proof: Enough to show that the JOP  $\overline{d}$  is a fixpoint of  $\overline{f}$ . We denote  $\overline{d}[M]$  as  $d_M$ ,  $\overline{d}[N]$  as  $d_N$ , etc.

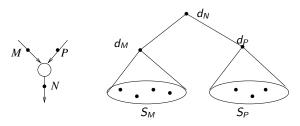
Let N be any program point.

Case (the node before N is not a join node):



- Let  $S_M$  (resp.  $S_N$ ) be the set of all facts that reach M (resp. N) along all paths.
- It is clear that  $S_N = \{f_{MN}(s) | s \in S_M\}$ .
- It is clear that the JOP  $d_M$  at M is equal to  $\sqcup S_M$ , and the JOP  $d_N$  at N is equal to  $\sqcup S_N$ .
- Therefore, by the previous two observations, and due to infinite distributivity, it follows that  $d_N = f_{MN}(d_M)$ .
- Therefore,  $\overline{d}$  satisfies N's equation, which is  $x_N = f_{MN}(x_M)$ .

Case (the node before N is a join node):



- Say  $S_M$  (resp.  $S_P$  resp.  $S_N$ ) is the set of lattice values reaching M along all paths (resp. reaching P resp. reaching N).
- Clearly,  $d_M$  (resp.  $d_P$  resp.  $d_N$ ) is equal to  $\sqcup S_M$  (resp.  $\sqcup S_P$  resp.  $\sqcup S_N$ ).
- It is clear that  $S_N = S_M \cup S_P$ . Therefore,  $d_N = d_M \sqcup d_P$ .
- Therefore,  $\overline{d}$  satisfies N's equation, which is  $x_N = x_M \sqcup x_P$ .

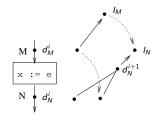
- Since the argument in the previous two slides applies at all points N, we have shown that the vector  $\overline{d}$  satisfies all the equations, and is hence a fix-point of  $\overline{f}$ .
- Note: Lattice is finite, and functions are pairwise distributive, and  $f_i(\bot) = \bot$  implies framework is infinitely distributive.

### **Back to Constant Propagation**

- $f_n^{CP}$  is monotonic
- $f_n^{CP}$  is not distributive.
  - Consider node n with statement y := x \* x. Show two CP values  $P_1$  and  $P_2$  such that  $f_n(P_1 \sqcup P_2) \sqsupset f_n(P_1) \sqcup f_n(P_2)$ .
- The *nstate* functions are all distributive.

- Let  $\overline{d}$  be values computed by Kildall's algo upon termination, and  $\overline{l}$  be LFP of  $\overline{f}$ . Let  $l_N$  denote  $\overline{l}[N]$ ,  $l_M$  denote  $\overline{l}[M]$ , etc.
- Intermediate vector  $\overline{d}^i$  after any step i is bounded above by  $\overline{l}$ . We prove this using induction on number of steps.
- Let N by any program point whose value gets updated in Step i+1.

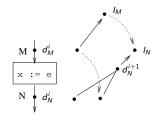
Case (the node before N is a non-join node):



#### Explanation:

•  $d_M^i \sqsubseteq I_M$  and  $d_N^i \sqsubseteq I_N$  by inductive hypothesis.

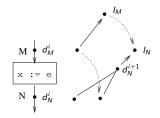
Case (the node before N is a non-join node):



#### Explanation:

- $d_M^i \sqsubseteq I_M$  and  $d_N^i \sqsubseteq I_N$  by inductive hypothesis.
- $I_N = f_{MN}(I_M)$ , because  $\bar{I}$  is a solution to the equations and because we have the equation  $x_N = f_{MN}(x_M)$ .

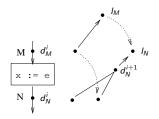
Case (the node before N is a non-join node):



#### Explanation:

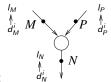
- $d_M^i \sqsubseteq I_M$  and  $d_N^i \sqsubseteq I_N$  by inductive hypothesis.
- $I_N = f_{MN}(I_M)$ , because  $\bar{I}$  is a solution to the equations and because we have the equation  $x_N = f_{MN}(x_M)$ .
- Therefore, due to monotonicity of  $f_{MN}$ ,  $f_{MN}(d_M^i) \sqsubseteq I_N$ .

Case (the node before N is a non-join node):



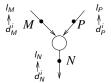
### Explanation:

- $d_M^i \sqsubseteq I_M$  and  $d_N^i \sqsubseteq I_N$  by inductive hypothesis.
- $I_N = f_{MN}(I_M)$ , because  $\bar{I}$  is a solution to the equations and because we have the equation  $x_N = f_{MN}(x_M)$ .
- Therefore, due to monotonicity of  $f_{MN}$ ,  $f_{MN}(d_M^i) \sqsubseteq I_N$ .
- Since  $d_N^{i+1} = d_N^i \sqcup f_{MN}(d_M^i)$ , we derive  $d_N^{i+1} \sqsubseteq I_N$ .



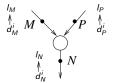
Case (the node before N is a join node):

• Let M and P be the points that precede the join node. Let  $d_M^i, d_P^i, d_N^i$  be the data values at the respective program points after Step i.



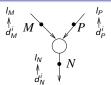
Case (the node before N is a join node):

- Let M and P be the points that precede the join node. Let  $d_M^i, d_P^i, d_N^i$  be the data values at the respective program points after Step i.
- Say propagation happens from M to N in Step i (argument is similar if propagation happened from P to N).



Case (the node before N is a join node):

- Let M and P be the points that precede the join node. Let  $d_M^i, d_P^i, d_N^i$  be the data values at the respective program points after Step i.
- Say propagation happens from M to N in Step i (argument is similar if propagation happened from P to N).
- Since  $\bar{I}$  is a solution to the equations, and since we have the equation  $x_N = x_M \sqcup x_P$ , it follows that  $I_N = I_M \sqcup I_P$ . In other words,  $I_M \sqsubseteq I_N$ . In conjunction with  $d_M^i \sqsubseteq I_M$  (inductive hypothesis), we get  $d_M^i \sqsubseteq I_N$ .



Case (the node before N is a join node):

- Let M and P be the points that precede the join node. Let  $d_M^i, d_P^i, d_N^i$  be the data values at the respective program points after Step i.
- Say propagation happens from M to N in Step i (argument is similar if propagation happened from P to N).
- Since  $\bar{I}$  is a solution to the equations, and since we have the equation  $x_N = x_M \sqcup x_P$ , it follows that  $I_N = I_M \sqcup I_P$ . In other words,  $I_M \sqsubseteq I_N$ . In conjunction with  $d_M^i \sqsubseteq I_M$  (inductive hypothesis), we get  $d_M^i \sqsubseteq I_N$ .
- By inductive hypothesis,  $d_N^i \sqsubseteq I_N$ . Therefore,  $(d_N^{i+1} = (d_M^i \sqcup d_N^i)) \sqsubseteq I_N$ .

Thus it follows that  $\frac{N}{d} < \overline{l}$ .

Let  $\overline{d}$  be the vector computed by the algorithm upon termination.

We now show that  $\overline{d} \geq \overline{f}(\overline{d})$  (i.e.  $\overline{d}$  is a postfixpoint of  $\overline{f}$ )

Let N be any program point.

Case (the node before N is a non-join node):

- Let M be the point that precedes this node. By definition of  $\overline{f}$ ,  $(\overline{f}(\overline{d}))[N]$  is equal to  $f_{MN}(d_M)$ .
- Since all points are unmarked, value  $d_M$  must have been propagated to N. That is,  $d_N$  must dominate  $f_{MN}(d_M)$ . That is,  $d_N$  dominates  $(\overline{f}(\overline{d}))[N]$ .

Let  $\overline{d}$  be the vector computed by the algorithm upon termination.

We now show that  $\overline{d} \geq \overline{f}(\overline{d})$  (i.e.  $\overline{d}$  is a postfixpoint of  $\overline{f}$ )

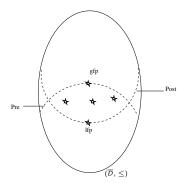
Let N be any program point. Case (the node before N is a non-join node):

- Let M be the point that precedes this node. By definition of  $\overline{f}$ ,  $(\overline{f}(\overline{d}))[N]$  is equal to  $f_{MN}(d_M)$ .
- Since all points are unmarked, value  $d_M$  must have been propagated to N. That is,  $d_N$  must dominate  $f_{MN}(d_M)$ . That is,  $d_N$  dominates  $(\overline{f}(\overline{d}))[N]$ .

Case (the node before N is a join node):

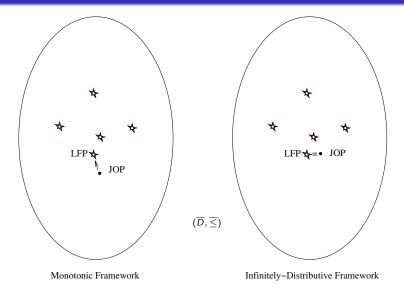
- Let M and P be the points that precede the join node. By definition of  $\overline{f}$ ,  $(\overline{f}(\overline{d}))[N]$  is equal to  $d_M \sqcup d_P$ .
- Since all points are unmarked, value  $d_M$  and  $d_P$  must have been propagated to N. That is,  $d_N$  must dominate both  $d_M$  and  $d_P$ . That is,  $d_N$  dominates  $d_M \sqcup d_P$ . Hence,  $d_N$  dominates  $(\overline{f}(\overline{d}))[N]$ .

• Therefore, by Knaster-Tarski theorem,  $\bar{l} = glb(Post)$ , and hence  $\bar{d} \geq \bar{l}$ .



• We have earlier proved that  $\overline{d} \leq \overline{l}$ . Therefore, it follows that  $\overline{d} = \overline{l}$ .

#### **Correctness**



Kildall's algo always computes LFP.

#### **Overview of correctness**

- Every program induces a set of equations on variables whose domain is lattice D. The equations, in turn, induce a function  $\overline{f}: \overline{D} \to \overline{D}$ .
- If each  $f_i$  is monotone and D is a complete lattice then f has a least fix-point LFP( $\overline{f}$ ).
  - If each  $f_i$  is infinitely distributive, then JOP = LFP(f).
  - Otherwise, if each  $f_i$  is only monotonic,  $JOP \leq LFP(\overline{f})$ .

### Overview of correctness

- If each  $f_i$  is monotone and D is a complete lattice then  $\overline{f}$  has a least fix-point LFP( $\overline{f}$ ).
  - If each  $f_i$  is infinitely distributive, then  $JOP = LFP(\overline{f})$ .
  - Otherwise, if each  $f_i$  is only monotonic,  $JOP \leq LFP(\overline{f})$ .
- Kildall's algorithm, for monotone frameworks:
  - Solution at any point during its execution is  $\leq \mathsf{LFP}(\overline{f})$
  - If and when it terminates, solution is equal to LFP( $\overline{f}$ )
  - Note this is a stronger claim than "Kildall's algo computes JOP for distributive frameworks" [Killdall, 'POPL 73].
  - Kildall's algorithm is not only for program analysis. It can be used to find least solution to *any* set of simultaneous equations, as long as (a) domain of variables' values is a complete lattice, (b) each variable occurs in the lhs of a unique equation, and (c) all operators occurring in rhs's are monotone.

# Summary of sufficient conditions

	Termination	LFP ≥ JOP	LFP = JOP	Kild computes LFP
				upon termination
f <sub>MN</sub> 's monotonic No inf. asc. chains	√ √	V		V
Inf. distributive				

- Each column is a property, and each row is a sufficient condition
- For a property to hold, each sufficient condition mentioned in its column needs to hold