# Aman Chandra

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## EDUCATION

## **KHARAGPUR**

B.Tech + M.Tech in Biotechnology SOPHOMORE

Expected April 2020 | Kharagpur, India CGPA: 7.33/10.0

#### ST. MICHAEL'S HIGH SCHOOL

ALL INDIA SENIOR SCHOOL CERTIFICATE Grad. April 2015 Patna, India Percentage: 95.6%

#### ST. XAVIER'S HR. SEC. SCHOOL

**CERTIFICATE OF MERIT** Grad. April 2013 Bettiah, India CGPA: 10.0/10.0

## LINKS

Github://amanchandra333 LinkedIn://amanchandra333 Robotix://team

## **COURSEWORK**

Programming & Data Structures Partial Differential Equations The Arduino Platform and C Prog. (Coursera) Control of Mobile Robots (Coursera) Robotics: Aerial Robotics (Coursera) C++ for C Programmers (Coursera) Intro to Java Programming (Udacity) Developing Android Apps (Udacity)

## TECHNICAL EXPERTISE

#### **HARDWARE**

ATmega • Arduino • Raspberry Pi SOFTWARE

After Effects • SolidWorks • Android Studio •Atmel Studio • Proteus

#### LANGUAGES

C • C++ • Python • LTFX • Java • HTML Bash

#### Systems

ROS • GIT • MATLAB • OpenCV • Gazebo • Internet of Things

## EXTRA-CURRICULARS

Eloquent Speaker • Avid Quizzer • **Table Tennis** 

### **EXPERIENCE**

## INDIAN INSTITUTE OF TECHNOLOGY, AERIAL ROBOTICS KHARAGPUR | CONTROL SYSTEMS AND EMBEDDED ELECTRONICS TEAM | February 2016 - Present

Under Prof. Somesh Kumar

- Made Simulink model of quadrotor along with PID control on MATLAB.
- Designing control systems for a multicopter to take part in IARC 2017.
- Fabricating safety kill-switch according to IARC guidelines.

## **SWARM ROBOTICS** | EMBEDDED ELECTRONICS TEAM | October

2016 - Present

Under Prof. Somesh Kumar

- Interfaced nRF transceivers with Arduino for communication between multiple robots.
- Interfaced Xbee modules with Raspberry Pi for robot localization.

### MOTION IMITATING AND PATH REPLICATING ROBOT | PROJECT HEAD & INSTRUCTOR | December 2016

- Accomplished IEEE certified project of making an autonomous robot which could imitate motion of another robot on ATmega 16 and Arduino.
- Mentored a team of 30 students.

## STEP COUNTER HEADING FOLLOWING ROBOT | PROJECT MEMBER | December 2015

• Accomplished IEEE certified project of making a semi- autonomous robot which could follow a human on ATmega32.

## HEX-DECODING AND PATH PLANNING ROBOT | TEAM LEADER | January 2016

• Built an autonomous robot which could decode hex-encoded data from IR LEDs and reach its destination, Kshitij '16, IIT Kharagpur.

## POSITIONS OF RESPONSIBILITY

## TECHNOLOGY ROBOTIX SOCIETY | SUB-HEAD | February

2016 - Present

- As part of the university's official robotics and hobby maker group, conducted the largest robotics related fest in India, Robotix 2016.
- Spearheaded multiple workshops across India to spread the culture of robotics.

## KRAIG | Instructor Kharagpur Robotics and Artifical Intelligence

February 2016 - Present | Kharagpur, India

- Organized weekly lectures on Manual and Autonomous Robotics for over 200 first year students round the year.
- Conceptualized 10 IEEE certified projects for over 800 students.

## SCHOLASTIC ACHIEVEMENTS

Sept, 2016  $4^{th}$  in Event Sensorous, National Students' Space Challenge' 16 Qualified JEE Main and Advanced for science & engineering Jun. 2015 education entrance in India with percentiles of 98.97 (All India Rank 3030) and 96.5 (All India Rank 5263) respectively.