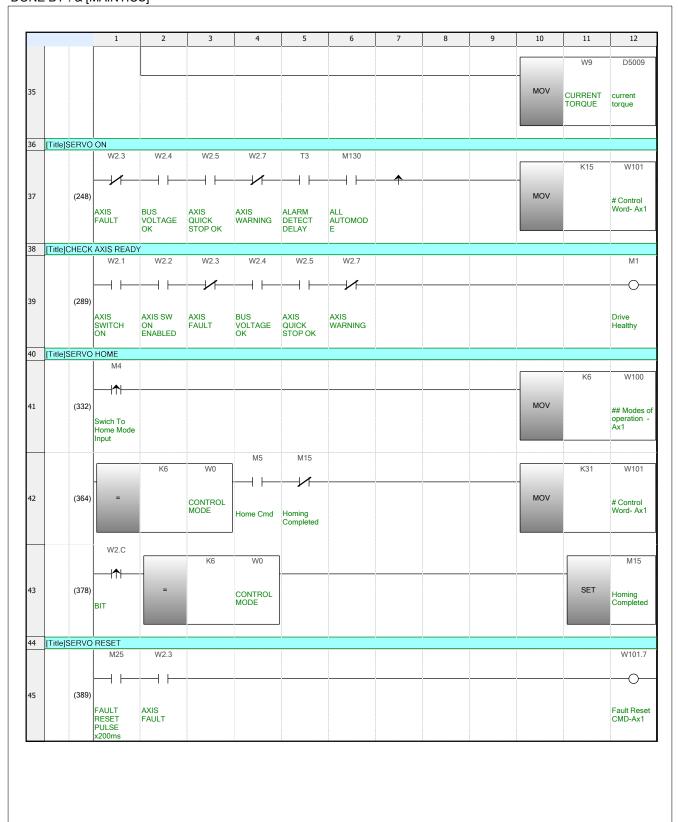
		1	2	3	4	5	6	7	8	9	10	11	12
.	[Title]START	COMMUNIC	ATION								•		
		SM400											Y177
		\vdash											+-0
2	(0)												
		Always ON											SERVO
													COMM READY
		X177											MO
		XIII											IVIO
		\vdash \vdash											 0-
3	(36)												
	(,												DRIVE
		SERVO COMMUNIC ATION OK											DRIVE COMM OK
		ATION OK											
		SM402											
		l										K0	W101
		\vdash											
ł	(40)										MOV		# Control Word- Ax1
		After RUN 1 Scan ON											Word- Ax1
		Scan ON											
		M130											
		IVITO											
		\longrightarrow	_										
5													
		ΔΙΙ											
		ALL AUTOMOD											
		E											
		M132											
												K0	D500
													
5	(51)										MOVP		Command
		AUTO MODE SS											Command Position(Pp Ax1
		WODE 33											
													M6
												_	
,												RST	Constants An
													Switch to Position Mode Pp
													Mode Pp
													M4
3												RST	Swich To Home Mod
													Input
													M160
												-	
)												RST	SERVO
													HOMING START
													START

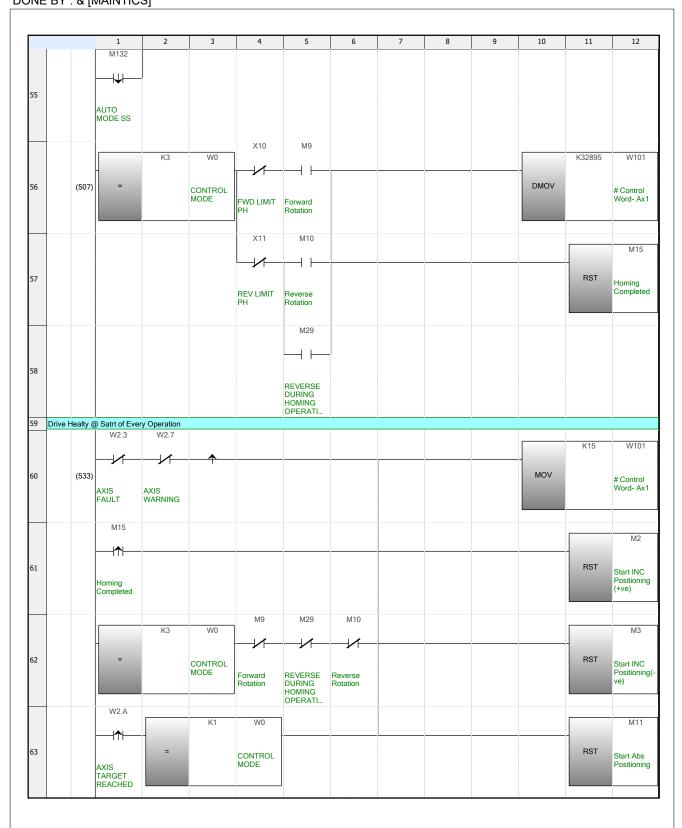
12	11	10	9	8	7	6	5	4	3	2	1		
										NG	ETER SETTI SM400	Title]PARAMI	10
D490	E1000	D500									3101400		
			-								\vdash		
A COLUMN		0	E*									(65)	11
ACCUMU TOR		Command Position(Pp) Ax1									Always ON		
		Ax1											
D492	D490												
BUFFER		FLT2DINT											12
	TOR												
W105	D492												
		-											
##Ax1-	BUFFER	DMOV											13
Position													
commano (Pp) (DV													
	=000	2500											
D494	E600	D502											
ACCUMU		Command	E*										14
TOR		Speed Pp (rpm)											
		(
D496	D494												
		4											
		FLT2DINT											15
BUFFER	ACCUMULA TOR												
W100	D496												
##Ax1-		DMOV											16
Comman speed (P													
speed (P (DWRD).													
D480	E600	D506											
			-										
A C C ! ! ! !!		log \/-!!t	E*										17
ACCUMU TOR		Jog Velocity (rpm*100)- Ax1											
		Ax1											
D482	D480												
BUFFER	ACCUMULA TOR	FLT2DINT											18
	TOR												
_													

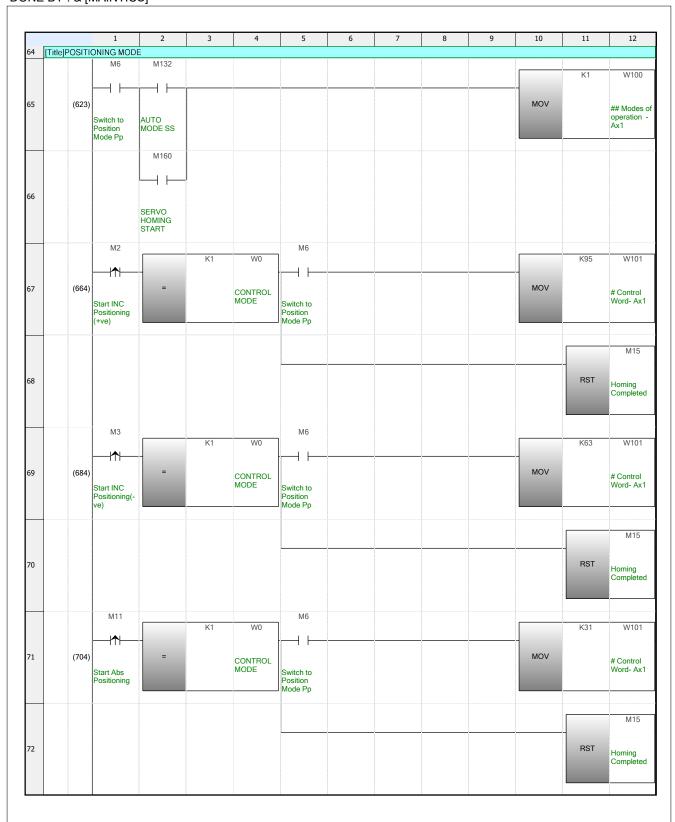
	1	2	3	4	5	6	7	8	9	10	11	12
		M9	M10								D482	W107
			<u> </u>							DMOV		
19		Forward	Reverse							DIVIOV	BUFFER	Target Velocity (P -Ax1 (DWRD)
		Rotation	Rotation									-Ax1 (DWRD)
		M10	M9									
										D482	K-1	W107
20									DMUL	BUFFER		Target
		Reverse Rotation	Forward Rotation							DOLLEY		Target Velocity (P -Ax1 (DWRD)
		rotation	rotation									(DWRD)
		M29										
		<u> </u>	_									
21												
		REVERSE DURING HOMING OPERATI										
		HOMING OPERATI										
											K1000	D508
										+		
22										MOV		Torque Lin + (%)
												(,
											K1000	D510
23										MOV		
												Torque Lin - (%)
										D508	K100	W114
24									MUL	Torque Limit		Ax1-Positiv
										Torque Limit + (%)		Ax1-Positiv torque Lim Value limit value
												limit value
										D510	K100	W115
									+			
25									MUL	Torque Limit - (%)		Ax1-
										- (%)		Negative Torque Lin Value
											K100	W10E
26										MOV		##Ax1- Acceleration
												Acceleration time Const (Pp Pv) (D

1	1	2	3	4	5	6	7	8	9	10	11	12
											K100	W110
										MOV		
27										MOV		##Ax1- Deceleration
												time Const (Pp Pv) (D
											W0	D5000
28										MOV	CONTROL	control
											CONTROL MODE	control mode
											14/0	DECOO
										4	W2	D5002
19										MOV	CONTROL	control
											STATUS	status
											W3	D5003
										+		
80										DINT2FLT	CURRENT POSITION	current position
											roomon	position
										D5003	E1000	D5003
31									E/			
,1										current position		current position
											W5	D5005
32										DINT2FLT	ACTUAL	current
											SPEED	speed
										D5005	E600	D5005
33									E/	current speed		current speed
										оросси		ореси
											W7	D5007
24										DMOV		
34										DIVIOV	DROOP SPEED	drop speed



		1	2	3	4	5	6	7	8	9	10	11	12
		M13										K271	W101
		\vdash									-		
46	(419)										MOV		# Control Word- Ax1
		Servo Stop											Word- Ax1
		X5											W101.2
		<u> </u>										-	VV 101.2
47	(426)											RST	#Emergeno
		EMG SWITCH EMG											#Emergeno /Quick Stop- Ax1
		M13											
48		$\dashv\vdash$											
10		Servo Stop											
		X11											
		\vdash											
49													
		REV LIMIT PH											
		X10											
		\vdash											
50													
		FWD LIMIT PH											
51 [Title]	DRIVE	UNHEALTHY											
		W2.3	SM401									K0	W101
		\vdash	-+								-		
52	(436)										MOV		# Control Word- Ax1
		AXIS FAULT	Always OFF										Word- Ax i
53 [Title]	JOG R	M8 M8											
												K3	W100
- 1		<u> </u>									MOV		
54	(473)										MOV		## Modes of operation - Ax1
		Velocity Mode Selection											Ax1





	1	2	3	4	5	6	7	8	9	10	11	12
												—{END
3 (724)												

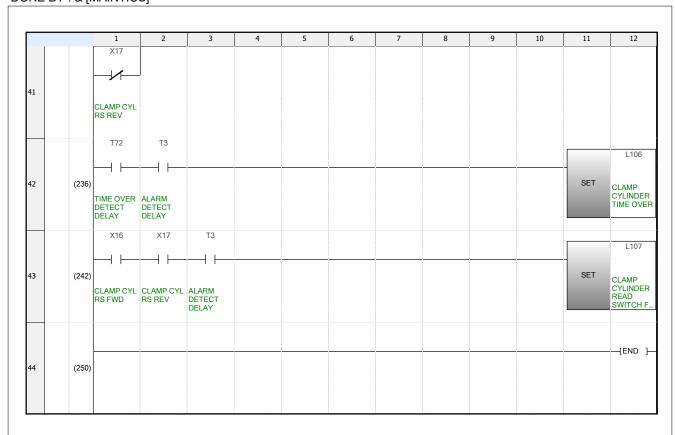
		1	2	3	4	5	6	7	8	9	10	11	12
		SM401										K0	D90
		\vdash	-								4		
L	(0)										MOV		SEQUENC
		Always OFF											CONTROL
			K0	D90									M60
			KU	D90									
2	(6)	=		SEQUENCE									
				SEQUENCE CONTROL									PLC CPU RUN OK
													RUNOK
												T2	K10
3											OUT	WAITING	
												WAITING SEQUENCE CONTROL	
												CONTROL	
		SM402	M60	T2									
		/	<u> </u>									K1	D91
1	(17)										MOV		
		After RUN 1 Scan ON	PLC CPU	WAITING									PLC CONTROL START
		Scan ON	RUN OK	WAITING SEQUENCE CONTROL									START
													M61
			K1	D91									
5	(27)	=											
,	(27)	_		PLC CONTROL START									PLC
				START									CONTROL START
		M61											
												T3	K20
	(00)	\vdash									OUT		
5	(33)	1									OUT	ALARM DETECT DELAY	
		PLC CONTROL START										DELAY	
		X5											
													L100
												-	
7	(40)	EMG										SET	EMERGEN CY FAULT
		SWITCH EMG											
		X177										T4	K50
		$-\mu$											
3	(44)										OUT	SERVO COMM	
		SERVO COMMUNIC										CHECK	
		ATION OK										JEG (1	

		1	2	3	4	5	6	7	8	9	10	11	12
		Т3	X177	T4									L113
		$\vdash\vdash\vdash$	\vdash \vdash \vdash	┼ ├									
9	(51)											SET	SERVO COMMUN
		ALARM DETECT	SERVO	SERVO COMM									ATION ERROR
		DELAY	SERVO COMMUNIC ATION OK	DELAY									Z.III.OII.
			X6										L109
			\vdash										
10			VED									SET	SPINDLE VFD
			VFD ALARM										ALARM
			X177	W2.3									
				VV2.3									L108
			\vdash	╁┤├─									
11			CEDVO	AVIC								SET	AXIS 1 SERVO
			SERVO COMMUNIC ATION OK	FAULT									SERVO ALARM
			AHONOK	W2.7									
													L114
				\vdash									
12				AVIC								SET	AXIS 1 SERVO
				AXIS WARNING									WARNING
		T3	X10										
													L111
42	(70)	\vdash										CET	
13	(78)		FWD LIMIT									SET	AXIS 1 FORWAR LIMIT
		ALARM DETECT DELAY	FWD LIMIT PH										LIMIT
			X11										
													L112
14			\vdash									SET	
14			REV LIMIT									J JL I	AXIS 1 REVERSE
			PH										LIMIT
		SM400											
		, ,									W0D	H0FF00	D10
15	(90)									WAND			
15		Always ON									ALARM CODE		SERVO ALARM CODE
													CODE
												D10	K8
16											SFR	SERVO	
												ALARM CODE	
												- CODE	

		1	2	3	4	5	6	7	8	9	10	11	12
		SM400									K0	K4L500	K300
		-+								4			
17	(103)									FMOV			
		Always ON											
		SM400											
												D10	Z0
											1		
.8	(112)										MOV	SERVO ALARM CODE	
		Always ON										CODE	
													L499Z0
.9													
			H90	D10									L110
												1	
20	(122)	=		SERVO ALARM CODE								SET	MACHINE HOME REQUIRE
				CODE									REQUIRE
			H96	D10									
		-	1100	D10									
21		=		SERVO									
				SERVO ALARM CODE									
				OODE									
		M12											
											K0	K4L100	K10
22	(132)									FMOV		EMERGEN CY FAULT	
		Fault Reset											
													M25
												+	
23												SET	FAULT
													RESET PULSE x200ms
													x200ms
		M25											
		, ,										T6	K10
	/4 *0:										OUT		
24	(143)	EALILT									001	FAULT RESET	
		FAULT RESET										RESET PULSE TIME	
		PULSE x200ms											

25	(150)	T6								
										M25
		FAULT								
?6									RST	FAULT RESET
26		RESET PULSE								PULSE x200ms
<u>?</u> 6		TIME X12	Y7							
26			17						T70	K30
26			\sqcap					OUT		
	(154)		FEED CYL					OUT	TIME OVER DETECT	
		FEED CYL RS FWD	FWD						DELAY	
		X13								
27										
.,		FEED CYL								
		RS REV								
		X12	Y10							
28		1 1	' '							
		FEED CYL RS FWD	FEED CYL REV							
		RS FWD	REV							
		X13								
29										
		FEED CYL RS REV								
		T70	T3							L102
		\vdash								
30	(172)								SET	FEED
		TIME OVER DETECT	DETECT							CYLINDER TIME OVE
		DELAY	DELAY							
		X12	X13	Т3						L103
		\vdash	\vdash							
31	(178)	EEED CVI	EEED CVI	ALARM					SET	FEED CYLINDER
		FEED CYL RS FWD	RS REV	DETECT DELAY						READ SWITCH I
		X14	Y11							
									T71	K30
22	(400)	<u> </u>	\vdash					OUT		
32	(186)	MAT CYL	MAT CYL					001	TIME OVER DETECT	
		MAT CYL RS FWD	RS FWD						DELAY	

1		1	2	3	4	5	6	7	8	9	10	11	12
		X15											
_													
33		MAT CYL											
		RS REV											
		X14	Y12										
		<u> </u>											
34													
		MAT CYL RS FWD	MAT CYL RS REV										
		X15											
		<u> </u>											
35		MAT CYL											
		MAT CYL RS REV											
		T71	Т3										
		<u> </u>										-	L104
36	(204)											SET	MATERIA
		TIME OVER DETECT	DETECT										CYLINDEI TIME OVE
		DELAY	DELAY										
		X14	X15	Т3									L105
.7	(210)	\vdash	$\dashv \vdash$	++								CET	
37	(210)	MAT CYL	MAT CYL	ALARM								SET	MATERIA CYLINDEI
		RS FWD	RS REV	DETECT DELAY									READ SWITCH I
		X16	Y13									T72	K30
		/_	<u> </u>									172	K30
38	(218)										OUT	TIME OVER	
		CLAMP CYL RS FWD	CLAMP CYL RS FWD CLOSE									DETECT DELAY	
		X17	CLUSE										
39													
		CLAMP CYL RS REV											
		RSREV											
		X16	Y14										
		$\vdash\vdash\vdash$	НН	_									
40													
		CLAMP CYL RS FWD	RS REV										
			OI LIV										



		1	2	3	4	5	6	7	8	9	10	11	12
		SM8002										K0	D1030
		\vdash											
	(0)										MOV		CONTROL WORD
		After RUN 1 Scan ON											WORD
		SM8012	M1005	Т3									D1010
		├	<u> </u>									-	
!	(6)											INC	READ
		100 ms Clock	MODBUS PROCESSI	ALARM DETECT									WRITE SELECTIO
			NG	DELAY									
			K1	D1010									M1000
1	(17)	=		READ WRITE									EDO WDIT
				SELECTION									FRQ WRIT
													M1001
			K2	D1010									
	(00)	_		-									
•	(23)	=		READ WRITE									CONTROL
				SELECTION									CONTROL WRITE COMMANI
													M1002
			К3	D1010									
;	(29)	=											
	()			READ WRITE SELECTION									DATA
				SELECTION									MONITORI G COMMANI
			D1010	K4								K0	D1010
i	(35)	>=	READ								MOV		READ
			WRITE SELECTION										READ WRITE SELECTIO
		M1000											M1005
		├										-	M1005
	(43)											SET	MODBUS PROCESS
		FRQ WRITE COMMAND											NG NG
		M1001											
		─	-										
3		CONTROL											
		CONTROL WRITE COMMAND											
		COMMAND											

		1	2	3	4	5	6	7	8	9	10	11	12
		M1002											
		<u> </u>	_										
9													
		DATA											
		MONITORIN G											
		COMMAND M1000											
		<u> </u>						K1	H6	H2001	K1	D1020	M1100
10	(57)						ADPRW						
												VFD RUNNING FRQ CMD	FRQ COMMANE RUNNING
		FRQ WRITE COMMAND										FRQ CMD	RUNNING
			M1101										
													M1005
11			EDO									RST	MODBUS PROCESSI
			FRQ COMMAND DONE OK										NG
			M1102										
12													
			FRQ COMMAND										
			DONE NG										
			M1102										L115
			<u></u>									4	2110
13												SET	VFD COMMUING
			FRQ COMMAND										COMMUING ATION ERROR
			DONE NG										ERROR
		M1010	M1011										M1012
			/_										
14	(91)												
		NETWORK FWD	NETWORK REV										NETWORK STOP
		COMMAND	COMMAND										COMMAND
		M1010	M1011	M1012									
		\vdash										K17	D1030
15	(97)										MOV		CONTROL
	` ′	NETWORK	NETWORK	NETWORK									WORD
		FWD COMMAND	REV COMMAND	STOP COMMAND								4	
		M1011	M1010	M1012									
			1 4	1.4								K33	D1030
16	(107)		<u> </u>								MOV		
10	(107)		NETWORK	NETWORK							IVIOV		CONTROL WORD
		REV COMMAND	FWD COMMAND	STOP									

		1	2	3	4	5	6	7	8	9	10	11	12
		M1012	M1010	M1011								K1	D1030
		\vdash	<u> </u>	/_									
17	(117)										MOV		CONTROL
		NETWORK STOP	NETWORK FWD	NETWORK REV									CONTROL WORD
		COMMAND	COMMAND	COMMAND									
		M1001											
		1.1						K1	H6	H1	K0	D1030	M1103
18	(127)						ADPRW						
10	(127)	CONTROL					ADITW					CONTROL WORD	CONTROL COMMAN RUNNING
		WRITE COMMAND											RUNNING
			M1104										
			1011104										M1005
			├									+	
19												RST	MODBUS
			CONTROL COMMAND										PROCESS NG
			DONE OK										l
			M1105										
			<u></u>										
20													
			CONTROL COMMAND										
			DONE NG										
			M1105										
			1.										L115
21			<u></u>									SET	
21			CONTROL									JEI	VFD COMMUIN
			COMMAND DONE NG										ATION ERROR
		M1002	50112114										
		W11002						K1	H3	H2100	K7	D1100	M1106
		$\vdash\vdash\vdash$											
22	(161)						ADPRW					VFD ALARM CODE	MONITOR
		DATA MONITORIN										CODE	COMMANI RUNNING
		G COMMAND											RUNNING
			M1107										M1005
			<u></u>									_	M1005
23												RST	MODBUS
			MONITORIN	ı									PROCESS NG
			G COMMAND DONE OK										
			M1108										
24													
24			MONITORIN										
			G COMMAND DONE NG										
			DONE NG										

		1	2	3	4	5	6	7	8	9	10	11	12
			M1108										L115
5			MONITORIN G COMMAND DONE NG									SET	VFD COMMUINO ATION ERROR
			K0	D1103		K0	D1104		K0	D1106			M1200
6	(195)	=		OUTPUT FREQUENC Y	=		OUTPUT CURRENT	=		OUTPUT VOLTAGE			MOTOR STOP
													——{END }-
7	(209)												(Eile)

		1	2	3	4	5	6	7	8	9	10	11	12
		SM400	M24	M132								D5003	D1300
		\vdash	├	— <u>//</u>								20000	D1000
	(0)										EMOV	current	OFFSET
		Always ON	offset set pulse	AUTO MODE SS								position	OLLOCI
			pulse	MODE SS									
											D1300	E2	D1302
										-			
										E-	OFFSET		STEP 1 POS
													PU3
											D1300	D1304	D1306
										_	D1300	D1304	D1306
,										E+	OFFOFT	ODOOVINO.	TOTAL
											OFFSET	GROOVING SIZE	STROKE
												D1302	D1200
											EMOV	STEP 1 POS	STEP 1 POSITION
												POS	POSITION
												D1306	D1204
;											EMOV		
											201	TOTAL STROKE	STEP 2 POSITION
		L51											
		LSI										K0	D250
		$\vdash\vdash\vdash$											
i	(36)										DMOV		PART
		COUNTER											PART COUNT ACTUAL
		RESET PULSE											
[Titl	e]INITIAL	IZATION	!	-	!	!		!					
		M35	SM411									D5009	D256
		\vdash	 ↑									D3003	D230
	(43)										D+	current	TORQUE
		CHECK TORQUE	200 ms									torque	COUNTIN
		TORQUE START	Clock										
		X2	M150										
													M153
		<u> </u>	$\vdash\vdash\vdash$							+		+	
1	(83)											SET	STOP
		AUTO STOP PB	AUTO START										MEMORY
			AUX.										

		1	2	3	4	5	6	7	8	9	10	11	12
		SM402										K15	D0
10	(89)	├									MOV		
10		After RUN 1 Scan ON									IVIOV		BASE SCREEN
		M153											M152
		<u> </u>											
11	(97)	STOP MEMORY											AUTO STOP
******			K0	K4L100									M140
12	(101)	<>		EMEDOENO									 0-
				EMERGENC Y FAULT									MACHINE FAULT
		M140											M131
40	(100)	<u> </u>											
13	(108)	MACHINE FAULT											RUN READY
		X0											M132
14	(112)	\vdash											
		AUTO/MAN UAL SS											AUTO MODE SS
****		M132	Х3										M9
15	(110)	<u> </u>	\vdash										
15	(116)	AUTO MODE SS	JOG FWD SS										Forward Rotation
*******			X4		E-20	D5003							M10
16			<u> </u>	E<=									
			JOG REV SS			current position							Reverse Rotation
		M4101	M4111	M4141	M4151	M4161	M4171	M132					M130
		<u> </u>	—//	<u> </u>	—//	<u> </u>							
17	(134)	SPINDLE MOTOR/MA NUAL	BRAKE/MA NUAL	FEED CYL/MANU AL	MATERIAL CYL/MANU AL	CLAMPING CYL/MANU AL	COOLING PUMP/MAN UAL	AUTO MODE SS					ALL AUTOMOE

		1	2	3	4	5	6	7	8	9	10	11	12
		M130	M131		K0	K4L100	M150						Y2
		\vdash	-+		RO	N4E 100	<u> </u>						
18	(150)			=		EMERGENC							
		ALL	RUN			Y FAULT	AUTO						PATLIGHT
		AUTOMODE	READY				START AUX.						Υ
		M150											Y3
	(100)	\vdash											
19	(163)	AUTO											PATLIGHT
		START											G
		AUX.											
		M140	SM412										Y1
		-+	$\vdash\vdash\vdash$										
20	(167)												
		MACHINE FAULT	1 s Clock										PATLIGHT RED &
		PAULI											BUZZER
			SM412	SM411									
21				1									
21			1 s Clock	200 ms									
				Clock									
		M140											M110
		W140											IVITIO
		$-\nu$											
22	(179)												
		MACHINE FAULT											MACHINE NORMAL
			DEOOS	FF	T21	T24	T27						M154
			D5003	E5	\vdash								
23	(183)	E<=	current										
	, ,		position		FEED CYL	MAT CYL	CLAMP CYL						MACHINE
					REV END	REV END	REV END						HOME
		M130	M110	M154	M150	SM412	M153	SM411					Y0
		\vdash	$\dashv\vdash$										$\overline{}$
24	(197)												
		ALL AUTOMODE	MACHINE NORMAL	MACHINE HOME	AUTO START	1 s Clock	STOP MEMORY	200 ms Clock					AUTO RUN
					AUX.								
				M150			M153						
				\vdash			<u> </u>						
25													
				AUTO			STOP MEMORY						
				START AUX.			WEWORY						
		L		1	1	1	1			I	i.		

		1	2	3	4	5	6	7	8	9	10	11	12
		X1										M151	M153
		├											
26	(21	9)									ZRST	AUTO	STOP
		AUTO START PB										STOP WAITING	MEMORY
												M20	M23
												IVIZU	IVIZS
27											ZRST	POSITION	GROOVING
												STEP 1	COMPLETE
		M154	X1	M110	M130								M150
		\vdash		<u></u>									
28	(23												
	(20	MACHINE	AUTO	MACHINE	ALL								AUTO
		HOME	START PB	NORMAL	AUTOMODE								START AUX.
		M150											
20													
29		AUTO											
		START AUX.											
		M150											
		WITSU											M156
												+	
30	(24											RST	MACHINE STOP CMD
		AUTO START											STOP CIVIL
		AUX.											
		M130										S0	S100
		 											
31											ZRST	AUTO	
		ALL AUTOMODE	=									CYCLE START	
		10.011102											
32	[Title]DEVI	CE CONTROL											
		L109	L100										M4100
		<u> </u>	— <i>/</i> /—										
33	(25	1											
		SPINDLE VFD ALARM	EMERGENC Y FAULT										SPINDLE MOTOR/RE ADY
													ADY
		M25											Y4
		\vdash											
34	(29:												
													VFD ALARI RESET
		FAULT RESET PULSE x200ms											RESET
		x2uums											

		1	2	3	4	5	6	7	8	9	10	11	12
		M150	M40	M4101	M132	M4100	Y15						Y5
		\vdash	\vdash	/I	\vdash	┼	$-\!$						 0-
35	(296)												
		AUTO START AUX.	SPINDLE MOTOR	SPINDLE MOTOR/MA NUAL	AUTO MODE SS	SPINDLE MOTOR/RE ADY	SPINDLE BRAKE ON						VFD FWD RUN
					M422	AUT							
		M4102	M4103	M4101	M132								
		\vdash		+	<u> </u>	_							
36		SPINDLE	SPINDLE	SPINDLE	AUTO								
		MOTOR/ST ART-PB	MOTOR/ST OP-PB	MOTOR/MA NUAL									
		Y5											
27		\dashv											
37		VFD FWD											
		RUN											
		SM400	L100										M4110
38	(321)		—//—										
50			EMERGENC										BRAKE/R
			Y FAULT										DY
		M150	M48	M4111	M132	M4110							Y15
		L.,	<u> </u>		<u> </u>	<u></u>							
39	(327)												Ů
		AUTO START	SPINDLE BRAKE ON	BRAKE/MA	AUTO MODE SS	BRAKE/REA DY							SPINDLE BRAKE O
		AUX.	CMD	INOAL	WODE 33								BIVARE OF
		M4112	M4113	M4111	M132								
		<u> </u>		\vdash		_							
40													
		BRAKE/STA RT-PB	BRAKE/STO P-PB	BRAKE/MA NUAL	AUTO MODE SS								
		Y15											
		\vdash											
41													
		SPINDLE BRAKE ON											
		CM400	1.100										M4170
		SM400	L100										M4170
		\vdash	<u> </u>										
42	(350)		EMERGENO										COOLING
		niways ON	EMERGENC Y FAULT										COOLING PUMP READY

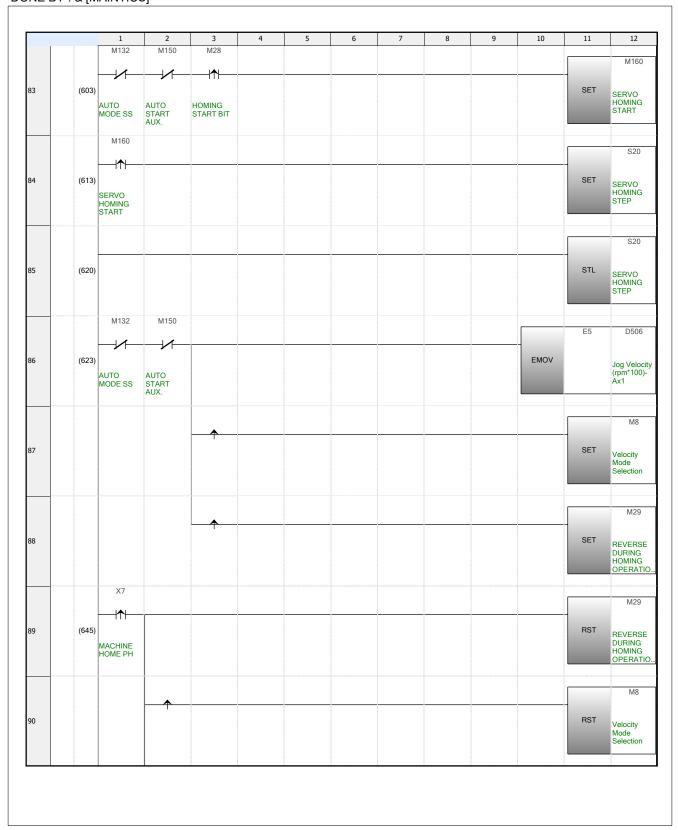
		1	2	3	4	5	6	7	8	9	10	11	12
		M150	M41	M4171	L50	M132	M4170						Y6
		\vdash	$\vdash\vdash\vdash$	<u> </u>	$-\!$	\vdash \vdash \vdash	+1 $-$						
43	(356)												
		AUTO START	FLUID PUMP RUN	PUMP/MAN	COOLANT PUMP	AUTO MODE SS	COOLING PUMP						COOLANT PUMP
		AUX.	CMD	UAL	BYPASS		READY						
			Y6										
			<u> </u>	_									
14													
			COOLANT										
			PUMP										
		M4172	M4173	M4171	M132								
		\vdash			_//_								
45		1 1		1 1									
		COOLING	COOLING	COOLING	AUTO								
		PUMP/STA RT-PB	PUMP/STO P-PB	PUMP/MAN UAL	MODE SS								
		Y6											
		\vdash											
46		1 1											
		COOLANT											
		PUMP											
		X12											
		\vdash										T20	K5
47	(384)										OUT	FEED CYL	
		FEED CYL										FWD END	
		RS FWD											
		Y7											
		\vdash											
48		1 1											
		FEED CYL											
		FWD											
		X13											
		<u> </u>										T21	K5
49	(393)										OUT	FEED CYL	
		FEED CYL RS REV										REV END	
		RS REV											
		L102	L103	L100									M4140
		/_	/_	<u> </u>									
50	(400)												
			FEED	EMERGENC Y FAULT									FEED CYL/READ
		CYLINDER TIME OVER	READ										CYL/READ
			SWITCH F										

		1	2	3	4	5	6	7	8	9	10	11	12
		M150	M44	M4141	M4140	T20	Y10						Y7
		\vdash	\vdash	<u> </u>	╁┤┝	<u> </u>	$-\nu$						
51	(408)												
		AUTO START	FEED CYLINDER	FEED CYL/MANU	FEED CYL/READY	FEED CYL FWD END	FEED CYL REV						FEED CYI
		AUX.	FWD CMD	AL									
			Y7										
			\vdash	_									
52													
			FEED CYL FWD										
		M4142	M4141										
		\vdash	<u> </u>										
53													
		FEED CYL/ FWD-PB	FEED CYL/MANU										
			AL										
		Y7											
		<u> </u>											
54													
		FEED CYL FWD											
		M150	M45	M4141	M4140	T21	Y7						Y10
		<u> </u>	<u> </u>	/_									
55	(432)						- '						
		AUTO START	FEED CYLINDER	FEED CYL/MANU	FEED CYL/READY	FEED CYL	FEED CYL FWD						FEED CYI
		AUX.	REV CMD	AL	CTEMEADI	INEV END	I WD						ILL
			Y10										
			<u> </u>										
56													
			FEED CYL REV										
			I L V										
		M4143	M4141										
		<u> </u>											
57													
		FEED CYL/ REV-PB	FEED CYL/MANUL										
		REV-PB	AL										
		Y10											
		<u> </u>]										
58		' '											
		FEED CYL REV											
		REV											
	-	1		1		1	i .		1	<u> </u>			

		1 X14	2	3	4	5	6	7	8	9	10	11	12
												T23	K2
59	(456)										OUT		
33		MAT CYL									001	MAT CYL FWD END	
		RS FWD											
		X15										T24	K2
		$\vdash\vdash\vdash$									-	124	NZ
60	(463)										OUT	MAT CYL REV END	
		MAT CYL RS REV										NEV END	
		L104	L105	L100									M4150
61	(470)												
		MATERIAL CYLINDER	MATERIAL CYLINDER	EMERGENC Y FAULT									MATERIAL CYL/READ
		TIME OVER	READ SWITCH F										OTEMEND
		M150	M46	M4151	M4150	T23	Y12						Y11
		\vdash	$\vdash\vdash\vdash$	<u> </u>	$\sqcap \vdash$	<u> </u>	<u> </u>						
62	(478)	AUTO	MATERIAI	MATERIAL	MATERIAL	MAT CYL	MAT CYL						MAT CYL
		START AUX.	CYLINDER FWD CMD	CYL/MANU AL	CYL/READY	FWD END	RS REV						RS FWD
		M4152	M4151										
		\vdash											
63													
		MATERIAL CYL/ FWD- PB	MATERIAL CYL/MANU AL										
		Y11	AL										
64			-										
		MAT CYL RS FWD											
		1101111											
		M46										T11	K30
		$\vdash\vdash\vdash$									-		
65	(499)										OUT	MAT CYL REVERSE	
		MATERIAL CYLINDER FWD CMD										DELAY IN AUTO	
		T11											
		<u> </u>											M47
66	(506)											SET	MATERIAL
		MAT CYL REVERSE											CYLINDER REV CMD
		DELAY IN AUTO											

			1	2	3	4	5	6	7	8	9	10	11	12
														M46
67													RST	MATERIAL CYLINDER FWD CMD
														FWD CMD
			M150	M47	M4151	M4150	T24	Y11						Y12
			\vdash	$\dashv \vdash$	<u> </u>	++	<u> </u>	<u> </u>						
58		(512)	ALITO											
			AUTO START AUX.	CYLINDER REV CMD	MATERIAL CYL/MANU AL	MATERIAL CYL/READY	REV END	MAT CYL RS FWD						MAT CYL RS REV
			M4153	M4151										
			<u> </u>											
59														
			MATERIAL CYL/ REV-	MATERIAL CYL/MANU AL										
	1		PB Y12	AL										
			——————————————————————————————————————											
70														
			MAT CYL RS REV											
			X16										T26	K5
71		(F22)	\vdash									OUT		
/1		(533)	CLAMP CYL RS FWD									001	CLAMP CYL FWD END	
			RS FWD											
			Y13											
			$\vdash\vdash\vdash$											
72			CLAMP CYL											
			RS FWD CLOSE											
			X17										TO7	1/5
			\vdash										T27	K5
73		(542)										OUT	CLAMP CYL REV END	
			CLAMP CYL RS REV										NEV END	
			Y14											
			<u> </u>											
74														
			CLAMP CYL RS REV											
			OPEN											

		1	2	3	4	5	6	7	8	9	10	11	12
		L106	L107	L100									M4160
		<u> </u>	$-\mu$	─ //									
75	(551)	CLAMP	CLAMP CYLINDER READ SWITCH F	EMERGENC Y FAULT									CLAMPING CYL/READ
		M150	M43	M4161	M4160	T26	Y14						Y13
76	(559)	<u> </u>		-1/-									
		AUTO START AUX.	CLAMP CLOSE CMD FWD	CLAMPING CYL/MANU AL	CLAMPING CYL/READY		CLAMP CYL RS REV OPEN						CLAMP C' RS FWD CLOSE
		M4162	M4161										
77		<u> </u>											
,,		CLAMPING CYL/ FWD- PB	CLAMPING CYL/MANU AL										
		Y13											
		\vdash											
78													
		CLAMP CYL RS FWD CLOSE											
		M150	M42	M4161	M4160	T27	Y13						Y14
		\vdash											
79	(580)						-						_
		AUTO START AUX.	CLAMP OPEN CMD REV	CLAMPING CYL/MANU AL	CLAMPING CYL/READY		CLAMP CYL RS FWD CLOSE						CLAMP C' RS REV OPEN
		M42											
		\vdash											
80		CLAMP OPEN CMD											
		REV											
		M4163	M4161										
		$\dashv\vdash$	\square										
81		CLAMPING CYL/ REV- PB	CLAMPING CYL/MANU AL										
		Y14											
00													
82		CLAMP CYL RS REV OPEN											



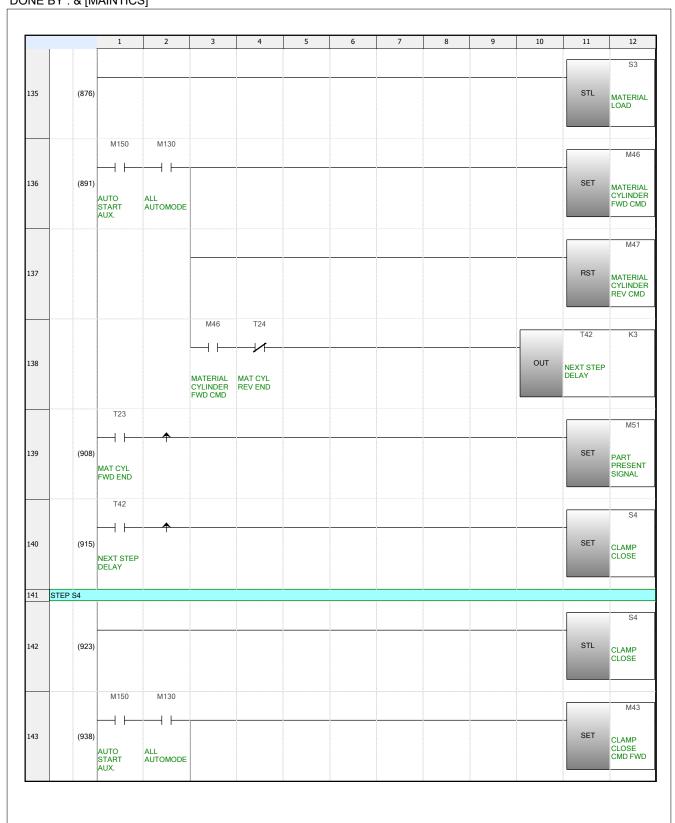
		1	2	3	4	5	6	7	8	9	10	11	12
													M4
91												SET	Swich To Home Mod Input
													M5
92												SET	Home Cm
		M15											M30
93	(662)	Homing Completed										SET	HOMING COMPLET LATCH
		M30										T63	K10
94	(666)	HOMING COMPLETE LATCH									OUT	SERVO NEXT COMMAND DELAY	
		T63											S21
95	(673)											SET	SERVO MOVE TO SOFT HOME PO
													M4
96												RST	Swich To Home Mo Input
													M8
97												RST	Velocity Mode Selection
													M30
98												RST	HOMING COMPLE LATCH

		1	2	3	4	5	6	7	8	9	10	11	12
													S21
99	(686)											STL	
	(000)											0.12	SERVO MOVE TO SOFT HOME PO
													HOME PO
		M132	M150										
		<u> </u>											M4
100	(689)											RST	Swich To
		AUTO MODE SS	AUTO START										Home Mod Input
		MODE 33	AUX.										
													M6
												-	
101												SET	Switch to
													Position Mode Pp
												E-21	D500
102											EMOV		Command Position(P Ax1
													Ax1
												E10	D502
103											EMOV		
103											EIVIOV		Command Speed Pp (rpm)
													(rpm)
		M6											
												T63	K10
104	(714)										OUT	SERVO	
		Switch to										NEXT COMMAND	
		Position Mode Pp										DELAY	
		T63											Mad
		\vdash											M11
105	(721)											SET	Start Abs
		SERVO NEXT											Positioning
		COMMAND DELAY											
		W2.A										S20	S23
		<u></u>											
106	(725)										ZRST	SERVO	
		AXIS TARGET										HOMING STEP	
		REACHED											

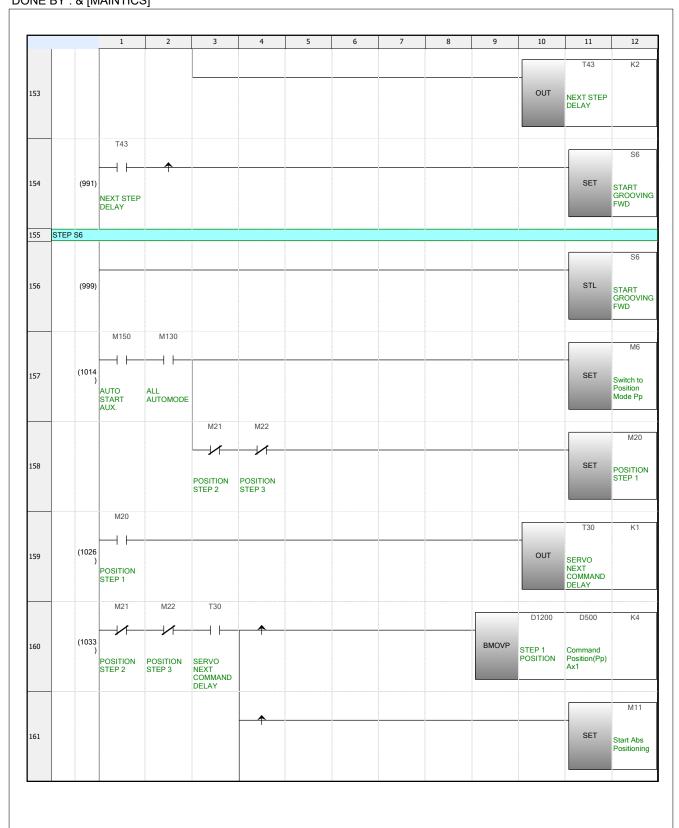
		1	2	3	4	5	6	7	8	9	10	11	12
													M6
107												RST	
													Switch to Position Mode Pp
													M8
												4	····o
108												SET	Velocity Mode
													Selection
													M160
109												RST	SERVO
													HOMING START
110	(740)												RETST
.11 [Ti	tle]AUTO S	STEPS								<u></u>			
		SM400	M150										Y17
		\vdash											 0-
112	(741)		ALITO										PANEL
		Always ON	START AUX.										EXHAUST FAN
		M130	M150										
													S0
113	(770)											SET	AUTO
		ALL AUTOMODE	AUTO START										AUTO CYCLE START
			AUX.										
													S0
												CTI	
114	(779)											STL	AUTO CYCLE START
													START
		SM400											
		<u> </u>										M43	M52
115	(782)										ZRST	CLAMP	PART
		Always ON										CLAMP CLOSE CMD FWD	PART PRESENT BYPASS

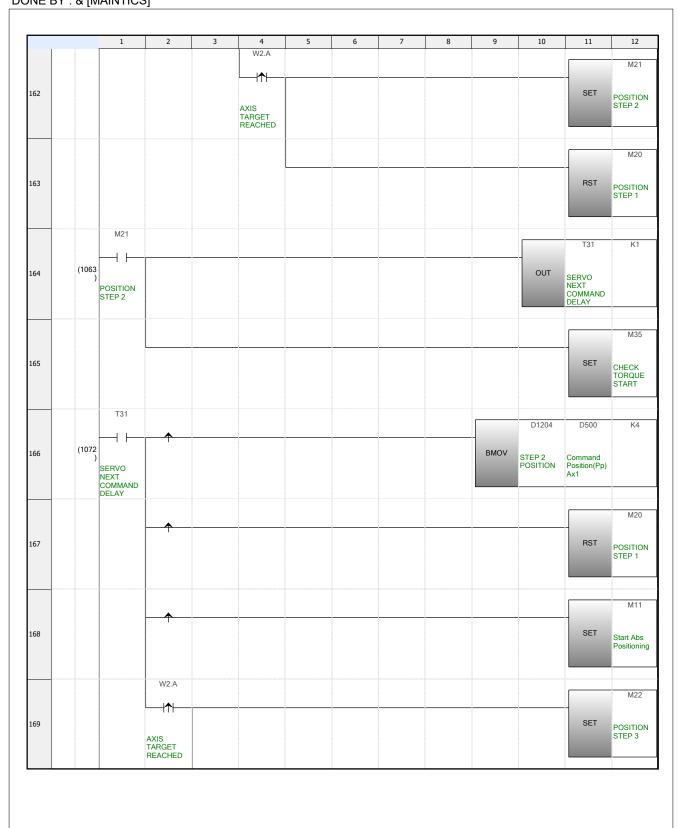
		1 M150	2 M130	3	4	5	6	7	8	9	10	11	12
			WITSO										M40
		$\vdash\vdash\vdash$	 										
116	(788)	AUTO	ALL									SET	SPINDLE MOTOR
		START AUX.	AUTOMODE										MOTOR RUN CMD
													M48
117												SET	
117												SET	SPINDLE BRAKE ON CMD
													СМО
													M41
118												SET	FLUID
													FLUID PUMP RUI CMD
												= 10	
												T40	K1
119											OUT	NEXT STEP	
												DELAY	
		T40											S1
		\vdash										4	31
120	(803)											SET	FEED CYL
		NEXT STEP DELAY											FWD
121 ST	EP S1												
													S1
122	(808)											STL	
122	(606)											OIL	FEED CYL FWD
		M130	M150										
		<u> </u>	<u> </u>										M44
123	(823)	1 1	1 1									SET	FFFD
		ALL	AUTO										FEED CYLINDER FWD CMD
		ALL AUTOMODE	AUX.										
													M45
124												RST	FEED
													FEED CYLINDER REV CMD

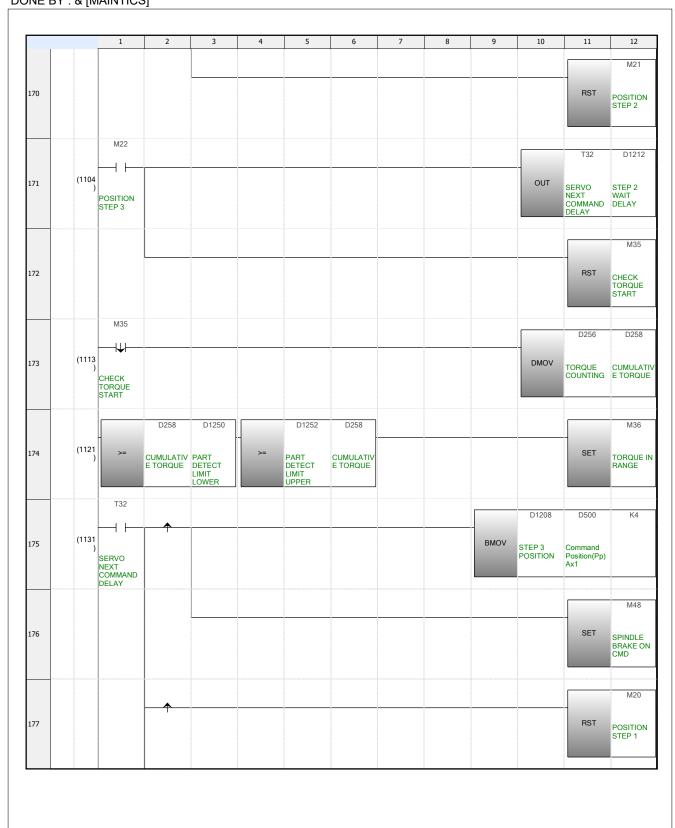
		1	2	3	4	5	6	7	8	9	10	11	12
													M42
			-									+	
125												SET	CLAMP OPEN CM
													OPEN CM REV
													M43
126												RST	
120												1.01	CLAMP CLOSE CMD FWI
													CMD FWL
													M26
127												RST	REPEAT
													REPEAT CYCLE BI
		T20											S2
		\vdash										4	02
128	(837)											SET	BRAKE O
		FEED CYL FWD END											
129 ST	TEP S2	1											
													S2
120	(0.40)											CTI	
130	(842)											STL	BRAKE O
		M150	M130										
													M48
131	(857)	' '	11									SET	SPINDLE
	` ′	AUTO	ALL										BRAKE O
		AUX.	AUTOMODE										05
												T41	K2
132											OUT	NEXT STEP	
												DELAY	
		T41											S3
		<u> </u>	_										33
133	(868)											SET	MATERIA LOAD
		NEXT STEP DELAY											LOAD
134 S1	TEP S3												

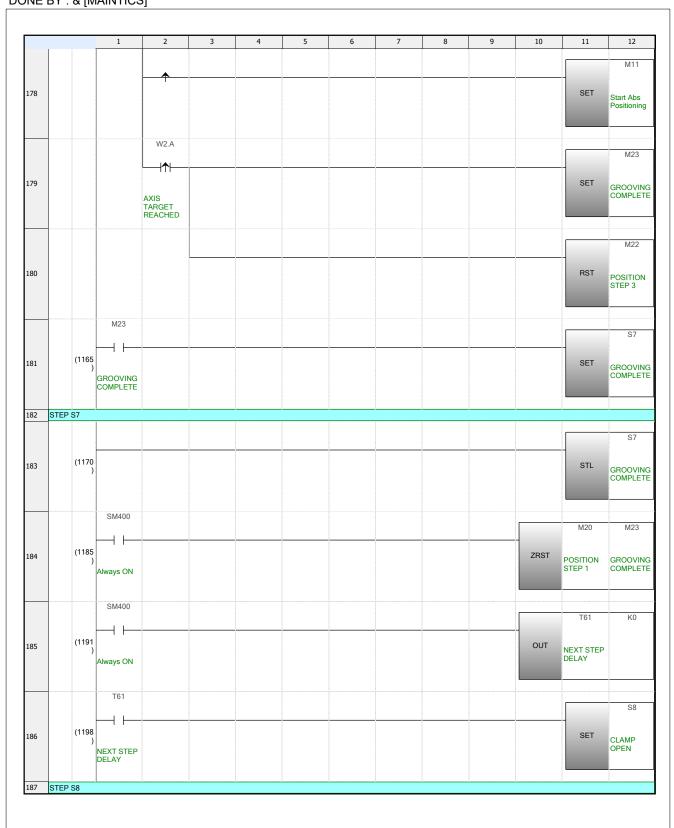


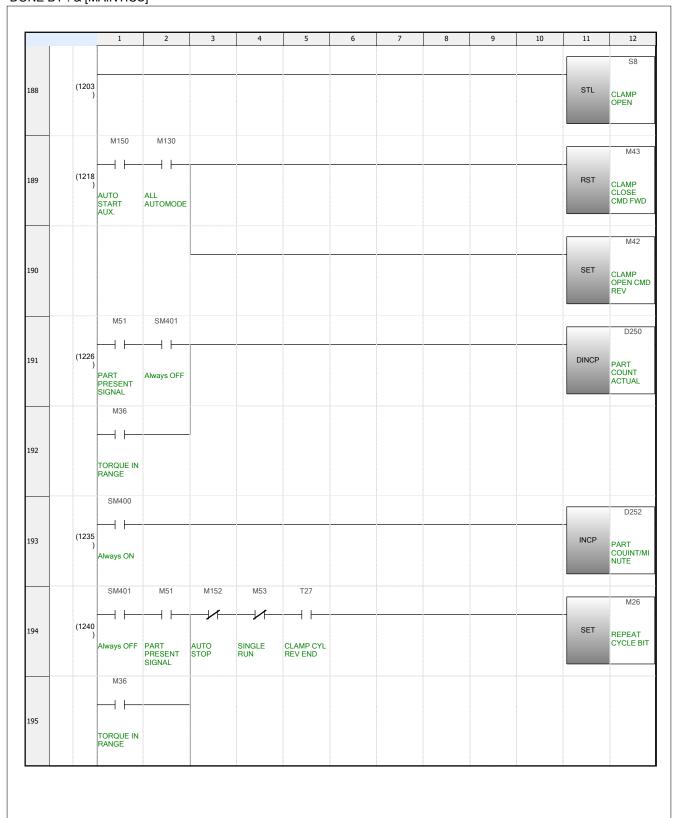
		1	2	3	4	5	6	7	8	9	10	11	12
													M42
144												RST	
												1.01	CLAMP OPEN CM REV
													NEV
		T26											1440
		<u> </u>											M46
145	(946)											RST	MATERIAL
		CLAMP CYL FWD END											CYLINDER FWD CMD
													M47
146												SET	MATERIAI CYLINDER
													REV CMD
		T24											
													M45
147	(952)											SET	
	()	MAT CYL											FEED CYLINDER REV CMD
		REV END											TILV CIVID
													M44
148												RST	FEED
													CYLINDER FWD CMD
		T26	T24										S5
		\vdash											
149	(958)	CLAMP CYL	MAT CYI									SET	BRAKE O
		FWD END	REV END										
50 S1	TEP S5												
													S5
													00
151	(965)											STL	BRAKE O
		M150	M130										M48
		\vdash											
152	(980)		ΔΙΙ									RST	SPINDLE BRAKE OI CMD
		AUTO START AUX.	ALL AUTOMODE										CMD

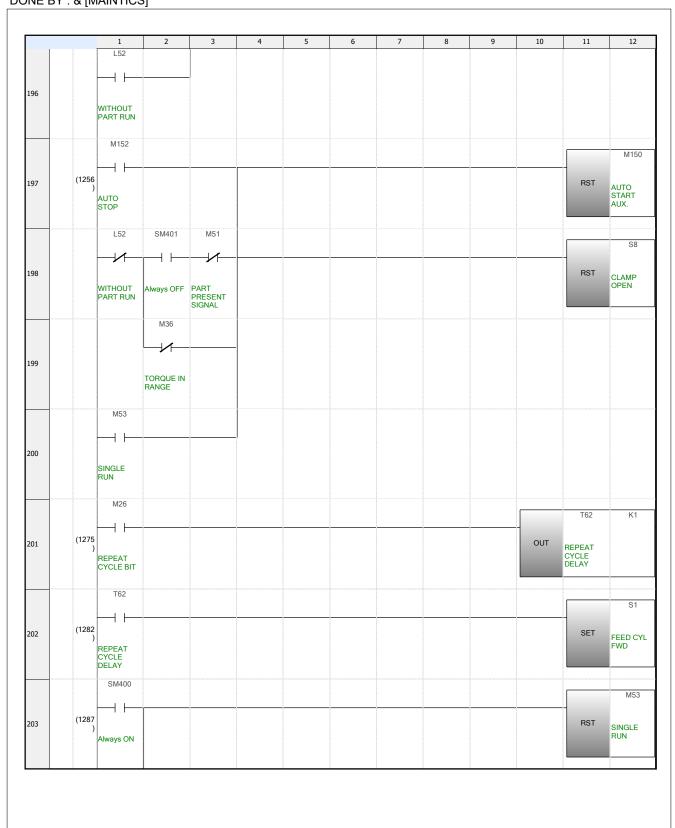












			1	2	3	4	5	6	7	8	9	10	11	12
														M51
204													RST	PART PRESENT SIGNAL
.05	(1:	293												RETSTI
			SM412	M150										D50
206	(1:	294	— —	+									INCP	
.00)	1 s Clock	AUTO START AUX.									IIVOI	SECONDS COUNTER
				K59	D50									M27
.07	(1:	301	=		OF CONDO									- 0-
)			SECONDS COUNTER									1 MINUTE PULSE
				K60	D50								K0	D50
208	(1:	307	-		SECONDS COUNTER							MOVP		SECONDS COUNTER
			M27											
			— ↑										D252	D254
209	(1:	315	1 MINUTE PULSE									MOVP	PART COUINT/MI NUTE	CYCLE TIME
													K0	D252
210												MOVP		PART COUINT/N NUTE
211	(1:	327												—{END
)												