

# Numerical Optimization, Fall 2024

## Homework 5

Due 23:59 (CST), Nov. 24, 2024

1. Prove that by applying the quasi-Newton curvature condition  $s_k^T y_k > 0$  in the univariate case, the quasi-Newton method is equivalent to the secant method. [10pts]

**Solution:**

From the update of Quasi-Newton method

$$x_{k+2} = x_{k+1} - H_{k+1}^{-1} f'(x_{k+1}).$$

Then, due to the secant equation  $H_{k+1} s_k = y_k$ , then

$$H_{k+1}^{-1} = \frac{s_k}{y_k} = \frac{x_{k+1} - x_k}{f'(x_{k+1}) - f'(x_k)}.$$

Therefore,

$$x_{k+2} = x_{k+1} - \frac{x_{k+1} - x_k}{f'(x_{k+1}) - f'(x_k)} f'(x_{k+1}). \quad (\text{Secant Method})$$

2. Consider an unconstrained optimization problem:  $\min_x f(x)$ , where  $f(x) \in \mathcal{C}^2$  and  $f(x)$  is L-smooth on a bounded level set  $\{x | f(x) \leq f(x_0)\}$ . Prove the convergence of backtracking Armijo line search. [10pts]

**Solution:**

According to Taylor's Theorem, there exists  $t \in (0, 1)$  such that

$$f(x_k + \alpha_k d_k) = f(x_k) + \alpha_k \nabla f(x_k)^T d_k + \frac{1}{2} \alpha_k^2 d_k^T \nabla^2 f(x_k + t\alpha_k d_k)^T d_k,$$

since  $f(x)$  is L-smooth,

$$\|\nabla^2 f(x)\| \leq L,$$

Thus,

$$f(x_k + \alpha_k d_k) \leq f(x_k) + \alpha_k \nabla f(x_k)^T d_k + \frac{L}{2} \alpha_k^2 \|d_k\|_2^2,$$

The Armijo condition is given by:

$$f(x_k + \alpha d_k) \leq f(x_k) + c_1 \alpha \nabla f(x_k)^T d_k.$$

Backtracking Armijo line search reduces  $\alpha_k$  geometrically ( $\alpha_k = \beta^k \alpha_0, \beta \in (0, 1)$ ) until  $f(x_k) + c_1 \alpha_k \nabla f(x_k)^T d_k \leq f(x_k) + \alpha_k \nabla f(x_k)^T d_k + \frac{L}{2} \alpha^2 \|d_k\|_2^2$ , i.e.,  $\alpha_k \leq \frac{2(c_1-1)\nabla f(x_k)^T d_k}{L\|d_k\|^2}$  to satisfy the Armijo condition.

Now we have

$$\begin{aligned} f(x_k) - f(x_{k+1}) &\geq -c_1 \alpha_k \nabla f(x_k)^T d_k \\ &\geq -c_1 \nabla f(x_k)^T d_k \frac{2(c_1-1)\nabla f(x_k)^T d_k}{L\|d_k\|^2} \\ &\geq \frac{2c_1(1-c_1)}{L} \|\nabla f(x_k)\|^2, \end{aligned}$$

thus,

$$\|\nabla f(x_k)\|^2 \leq \frac{L}{2c_1(1-c_1)} (f(x_k) - f(x_{k+1})).$$

Summing from  $k = 0$  to  $K - 1$ ,

$$\begin{aligned} \frac{1}{K} \sum_{k=0}^{K-1} \|\nabla f(x_k)\|^2 &\leq \frac{L}{2c_1(1-c_1)K} \sum_{k=0}^{K-1} (f(x_k) - f(x_{k+1})) \\ &= \frac{L}{2c_1(1-c_1)K} (f(x_0) - f(x_K)) \\ &\leq \frac{L}{2c_1(1-c_1)K} (f(x_0) - f(x^*)) \\ &\xrightarrow{K \rightarrow \infty} 0. \end{aligned}$$

3. For minimizing a quadratic function  $f(x)$ ,  $f(x)$  is strictly convex. Given a current point  $x_k$  and a descent direction  $p_k$ , compute the exact line search steplength, i.e.,  $\min_{\alpha} f(x_k + \alpha p_k)$ . [20pts]

**Solution:**

Given a quadratic function  $f(x) = \frac{1}{2}x^T A x + b^T x + c$ , where  $A \succ 0$ .

$$\phi(\alpha) = f(x_k + \alpha p_k) = \frac{1}{2}(x_k + \alpha p_k)^T A (x_k + \alpha p_k) + b^T (x_k + \alpha p_k) + c.$$

Let  $\phi'(\alpha) = \alpha p_k^T A p_k + (x_k^T A p_k + b^T p_k) = 0$ , we can get  $\alpha = -\frac{x_k^T A p_k + b^T p_k}{p_k^T A p_k}$ .

4. The Newton direction is  $p_k = -\nabla^2 f(x_k)^{-1} \nabla f(x_k)$ . When is the Newton direction a descent direction? How do you modify the Newton direction as small as possible to generate a descent direction when the Newton direction is not a descent direction? [20pts]

**Solution:**

The Newton direction  $p_k$  is a descent direction if:

$$\nabla f(x_k)^T p_k < 0.$$

Substituting  $p_k$ :

$$\nabla f(x_k)^T (-\nabla^2 f(x_k)^{-1} \nabla f(x_k)) = -\nabla f(x_k)^T \nabla^2 f(x_k)^{-1} \nabla f(x_k).$$

This holds if  $\nabla^2 f(x_k)$  is positive definite in the gradient direction.  
If  $\nabla^2 f(x_k)$  is not positive definite in the gradient direction, modify  $\nabla^2 f(x_k)$  by adding a multiple of the identity matrix  $\lambda I$  such that  $\nabla^2 f(x_k) + \lambda I$  is positive definite in the gradient direction.

5. Derive the simplified Conjugate Gradient (CG) iteration formula (see page 34 of lec11). [20pts]

**Solution:**

Applying  $p_k = -r_k + \beta_k p_{k-1}$  and  $r_k^T p_i = 0$  ( $i = 0, 1, \dots, k-1$ ), we can get  $r_k^T p_k = r_k^T (-r_k + \beta_k p_{k-1}) = -r_k^T r_k + \beta_k r_k^T p_{k-1} = -r_k^T r_k$ .  
Thus,

$$\alpha_k = -\frac{r_k^T p_k}{p_k^T A p_k} = \frac{r_k^T r_k}{p_k^T A p_k}.$$

From  $r_k = Ax_k - b$  and  $x_{k+1} = x_k + \alpha_k p_k$ , we can get

$$r_{k+1} = Ax_{k+1} - b = A(x_k + \alpha_k p_k) - b = r_k + \alpha_k A p_k.$$

Applying  $p_k = -r_k + \beta_k p_{k-1}$  and  $r_k^T p_i = 0$  ( $i = 0, 1, \dots, k-1$ ) once again, we can get

$$\beta_{k+1} = \frac{r_{k+1}^T A p_k}{p_k^T A p_k} = \frac{r_{k+1}^T (r_{k+1} - r_k)}{p_k^T A p_k} = \frac{r_{k+1}^T r_{k+1} - r_{k+1}^T r_k}{r_k^T r_k} = \frac{r_{k+1}^T r_{k+1}}{r_k^T r_k}.$$

Thus, we derive the simplified Conjugate Gradient (CG) iteration formula from the preliminary Conjugate Gradient (CG) iteration formula.

6. Write a code to implement the Conjugate Gradient (CG) algorithm to solve the quadratic programming (QP) problems:

$$\min_x \frac{1}{2} x^T A x - b^T x,$$

where  $A$  is a positive definite  $100 \times 100$  matrix.

1)  $A$  with uniformly distributed eigenvalues.

2)  $A$  with 2-3 clusters of eigenvalues.

Output the residual at each iteration and count the number of matrix-vector multiplications. [20pts]

**Solution:**

```
1 import numpy as np
2
3 # Conjugate Gradient algorithm to solve Ax = b
```

```

4 def conjugate_gradient(A, b, tol=1e-6, max_iter=1000)
5     :
6     n = len(b)
7     x = np.zeros(n)
8     r = b - A @ x
9     p = r
10    residuals = []
11    mat_vec_count = 0
12    for k in range(max_iter):
13        Ap = A @ p
14        mat_vec_count += 1
15        alpha = np.dot(r, r) / np.dot(p, Ap)
16        x += alpha * p
17        r_new = r - alpha * Ap
18        residuals.append(np.linalg.norm(r_new))
19        if np.linalg.norm(r_new) < tol:
20            break
21        beta = np.dot(r_new, r_new) / np.dot(r, r)
22        p = r_new + beta * p
23        r = r_new
24    return x, residuals, mat_vec_count
25
26    # Generate A with uniformly distributed eigenvalues
27    def generate_uniform_A(n):
28        Q = np.random.randn(n, n)
29        Q, _ = np.linalg.qr(Q)
30        eigenvalues = np.random.uniform(0.1, 10, size=n)
31        A = Q @ np.diag(eigenvalues) @ Q.T
32    return A
33
34    # Generate A with clustered eigenvalues
35    def generate_clustered_A(n):
36        Q = np.random.randn(n, n)
37        Q, _ = np.linalg.qr(Q)
38        eigenvalues = np.concatenate([np.random.normal(1,
39            0.1, size=n // 3),
40            np.random.normal(5, 0.2, size=n // 3),
41            np.random.normal(10, 0.3, size=n-2*(n // 3))])
42        np.random.shuffle(eigenvalues)
43        A = Q @ np.diag(eigenvalues) @ Q.T # A = Q * D * Q.T
44    return A
45
46    # Main function to test the conjugate gradient method
47    def main():
48        n = 10

```

```

48 b = np.random.randn(n)
49
50 # Generate A with uniformly distributed eigenvalues
51 A_uniform = generate_uniform_A(n)
52
53 # Solve the quadratic problem using Conjugate
    Gradient
54 x_uniform, residuals_uniform, mat_vec_count_uniform =
    conjugate_gradient(A_uniform, b)
55
56 print("Conjugate Gradient with Uniform Eigenvalues:")
57 print("Residual at each iteration:",
    residuals_uniform)
58 print("Number of matrix-vector multiplications:",
    mat_vec_count_uniform)
59
60 # Generate A with clustered eigenvalues
61 A_clustered = generate_clustered_A(n)
62
63 # Solve the quadratic problem using Conjugate
    Gradient
64 x_clustered, residuals_clustered,
    mat_vec_count_clustered = conjugate_gradient(
    A_clustered, b)
65
66 print("\nConjugate Gradient with Clustered
    Eigenvalues:")
67 print("Residual at each iteration:",
    residuals_clustered)
68 print("Number of matrix-vector multiplications:",
    mat_vec_count_clustered)
69
70 if __name__ == "__main__":
71     main()

```

1) Conjugate Gradient with Uniform Eigenvalues:

Residual at each iteration:

5.169894959300269,	3.7392404290561494,	3.0008180033976313,
3.3115065468953437,	2.740471796115691,	1.4108447074842965,
1.005011992456244,	0.6991816683838671,	0.34705354229234114,
0.2847502730561696,	0.22556164640232565,	0.23171901479967222,
0.20662880749497223,	0.16686984008187333,	0.15089594511689072,
0.10875554339542888,	0.09863161580317795,	0.07868770633862061,
0.05251366627512177,	0.03427582510580179,	0.026095163231704355,
0.017591302930239045,	0.014711331224339706,	0.010444712806052036,

0.007026244002107074,	0.005050418974069619,	0.0033742066237358093,
0.0023635926848029586,	0.001795338254547266,	0.0012812722077705297,
0.000865090994102751,	0.0006015387945271139,	0.0003261157886889722,
0.0002536254991547981,	0.0002246865753562579,	0.00012198544482934101,
6.484170838400927e-05,	3.695228005941589e-05,	2.155433496887668e-05,
1.5068116717848343e-05,	1.5147285598976634e-05,	1.3548610319199826e-05,
8.646217963873538e-06,	3.942956851444215e-06,	2.554499067635557e-06,
2.71614907540718e-06,	2.104559326381829e-06,	1.6625889374415396e-06,
6.846126490045413e-07]		

Number of matrix-vector multiplications: 49

2) Conjugate Gradient with Clustered Eigenvalues:

Residual at each iteration:

[5.31926729790938,	4.055122899163675,	1.4498736530712544,
0.3369145433830931,	0.2777763669084279,	0.22532911586652246,
0.03192878728378892,	0.02773471200091442,	0.021173392880193476,
0.0034648443932144284,	0.0022876319373354367,	0.0018626350505418267,
0.0004078552205091622,	0.00016359311562878594,	0.0001325561254927638,
6.340304314447973e-05,	1.0728168993587029e-05,	9.461720101462244e-06,
8.43875642295306e-06,	9.478107270508043e-07]	

Number of matrix-vector multiplications: 20