Lecture 23

**CS 131: COMPILERS** 

### **Announcements**

- HW6: Analysis & Optimizations
  - Alias analysis, constant propagation, dead code elimination, register allocation
  - Due: December 30<sup>th</sup>
- Final Exam:
  - In class, Jan 2<sup>nd</sup>
  - Coverage: emphasizes material since the midterm
  - Cheat sheet: one, hand-written, double-sided, letter-sized page of notes

## **CODE ANALYSIS**

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# **Live Variable Analysis**

- A variable v is *live* at a program point if v is defined before the program point and used after it.
- Liveness is defined in terms of where variables are defined and where variables are used
- Liveness analysis: Compute the live variables between each statement.
  - May be conservative (i.e. it may claim a variable is live when it isn't) so because that's a safe approximation
  - To be useful, it should be more precise than simple scoping rules.
- Liveness analysis is one example of dataflow analysis
  - Other examples: Available Expressions, Reaching Definitions, Constant-Propagation Analysis, ...

### **Liveness information**

Consider this program:

- The scopes of a,b,c,x all overlap they're all in scope at the end of the block.
- But, a, b, c are never live at the same time.
  - So they can share the same stack slot / register

### Liveness

- Observation: %uid1 and %uid2 can be assigned to the same register if their values will not be needed at the same time.
  - What does it mean for an %uid to be "needed"?
  - Ans: its contents will be used as a source operand in a later instruction.
- Such a variable is called "live"

A variable is *live* if its value *might* be used by some future part of the execution path when the program is executed.

#### Notes:

- the use of the variable might depend on user input or other data not available until the program is run
- even if not, in general, such a property is undecidable
- ⇒ liveness is a static approximation of the dynamic behavior
- Observe: two variables can share the same register if they are not live at the same time.

## **Control-flow Graphs Revisited**

- For the purposes of dataflow analysis, we use the control-flow graph (CFG) intermediate form.
- Recall that a basic block is a sequence of instructions such that:
  - There is a distinguished, labeled entry point (no jumps into the middle of a basic block)
  - There is a (possibly empty) sequence of non-control-flow instructions
  - The block ends with a single control-flow instruction (jump, conditional branch, return, etc.)

### A control flow graph

- Nodes are blocks
- There is an edge from B1 to B2 if the control-flow instruction of B1 might jump to the entry label of B2
- There are no "dangling" edges there is a block for every jump target.

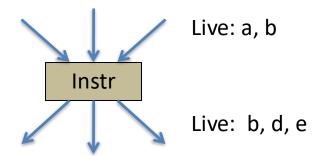
**Note:** the following slides are intentionally a bit ambiguous about the exact nature of the code in the control flow graphs:

an "imperative" C-like source level at the x86 assembly level the LLVM IR level

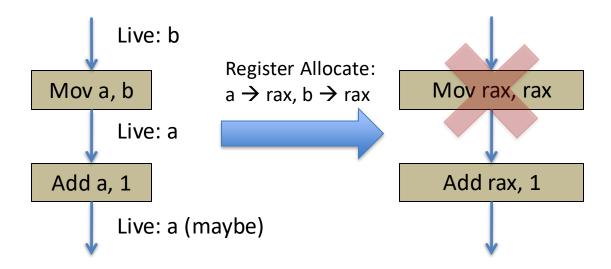
Each setting applies the same general idea, but the exact details will differ.

e.g., LLVM IR doesn't have "imperative" update of %uid temporaries.
 (The SSA structure of the LLVM IR by design! makes some of these analyses simpler.)

## Liveness is Associated with Edges



- This is useful so that the same register can be used for different temporaries in the same statement.
- Example: a = b + 1
- Compiles to:



### **Uses and Definitions**

- Every instruction/statement *uses* some set of variables
  - i.e. reads from them
- Every instruction/statement *defines* some set of variables
  - i.e. writes to them
- For a node/statement s define:
  - use[s] : set of variables used by s
  - def[s]: set of variables defined by s
- General Examples:

s: 
$$a = b + c$$
 use[s] = {b,c} def[s] = {a}

$$def[s] = \{a\}$$

s: 
$$a = a + 1$$

s: 
$$a = a + 1$$
 use[s] = {a}

$$def[s] = {a}$$

### Liveness, Formally

A variable v is *live* on edge e if:

#### There is

- a node n in the CFG such that use[n] contains v, and
- a directed path from e to n such that for every statement s' on the path, def[s'] does not contain v
- The first clause says that v will be used on some path starting from edge e.
- The second clause says that v won't be redefined on that path before the use.
- Questions:
  - How to compute this efficiently?
  - How to use this information (e.g. for register allocation)?
  - How does the choice of IR affect this?
     (e.g. LLVM IR uses SSA, so it doesn't allow redefinition ⇒ simplify liveness analysis)

# **Dataflow Analysis**

- *Idea*: compute liveness information for all variables simultaneously.
  - Keep track of sets of information about each node
- Approach: define equations that must be satisfied by any liveness determination.
  - Equations based on "obvious" constraints.
- Solve the equations by iteratively converging on a solution.
  - Start with a "rough" approximation to the answer
  - Refine the answer at each iteration
  - Keep going until no more refinement is possible: a fixpoint has been reached

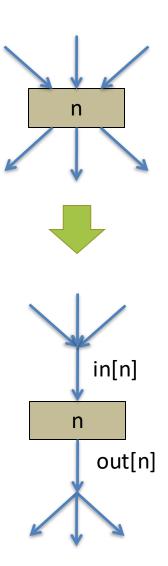
 This is an instance of a general framework for computing program properties: dataflow analysis

### **Dataflow Value Sets for Liveness**

- Nodes are program statements, so:
- use[n]: set of variables used by n
- def[n]: set of variables defined by n
- in[n]: set of variables live on entry to n
- out[n]: set of variables live on exit from n
- Associate in[n] and out[n] with the "collected" information about incoming/outgoing edges
- For Liveness: what constraints are there among these sets?
- Clearly:

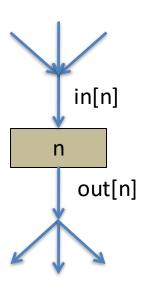
 $in[n] \supseteq use[n]$ 

What other constraints?



### **Other Dataflow Constraints**

- We have: in[n] ⊇ use[n]
  - "A variable must be live on entry to n if it is used by n"
- Also: in[n] ⊇ out[n] def[n]
  - "If a variable is live on exit from n, and n doesn't define it, it is live on entry to n"
  - Note: here '-' means "set difference"
- And: out[n] ⊇ in[n'] if n' ∈ succ[n]
  - "If a variable is live on entry to a successor node of n, it must be live on exit from n."



### **Iterative Dataflow Analysis**

- Find a solution to those constraints by starting from a rough guess.
  - Start with:  $in[n] = \emptyset$  and  $out[n] = \emptyset$
- The guesses don't satisfy the constraints:
  - in[n]  $\supseteq$  use[n]
  - in[n]  $\supseteq$  out[n] def[n]
  - out[n]  $\supseteq$  in[n'] if n' ∈ succ[n]
- Idea: iteratively re-compute in[n] and out[n] where forced to by the constraints.
  - Each iteration will add variables to the sets in[n] and out[n]
     (i.e. the live variable sets will increase monotonically)
- We stop when in[n] and out[n] satisfy these equations: (which are derived from the constraints above)
  - $in[n] = use[n] \cup (out[n] def[n])$
  - out[n] =  $U_{n' \in succ[n]}in[n']$

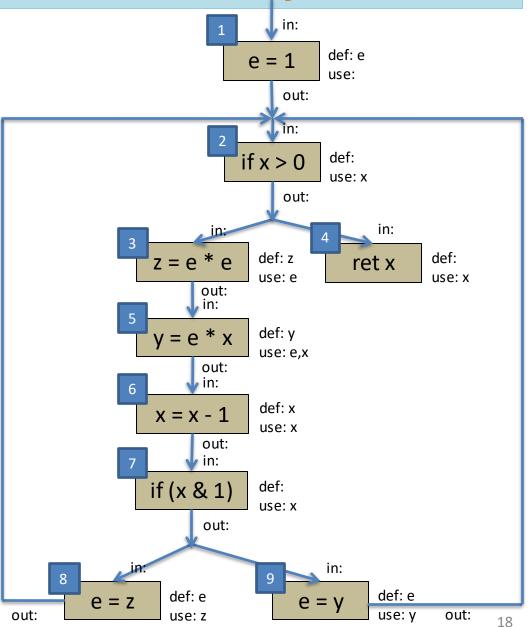
## **Complete Liveness Analysis Algorithm**

```
for all n, in[n] := \emptyset, out[n] := \emptyset
repeat until no change in 'in' and 'out'
for all n
out[n] := U_{n' \in succ[n]} in[n']
in[n] := use[n] \cup (out[n] - def[n])
end
end
```

- Finds a fixpoint of the in and out equations.
  - The algorithm is guaranteed to terminate... Why?
- Why do we start with Ø?

• Example flow graph:

```
e = 1;
while(x>0) {
  z = e * e;
  y = e * x;
  x = x - 1;
  if (x & 1) {
     e = z;
  } else {
     e = y;
  }
}
return x;
```



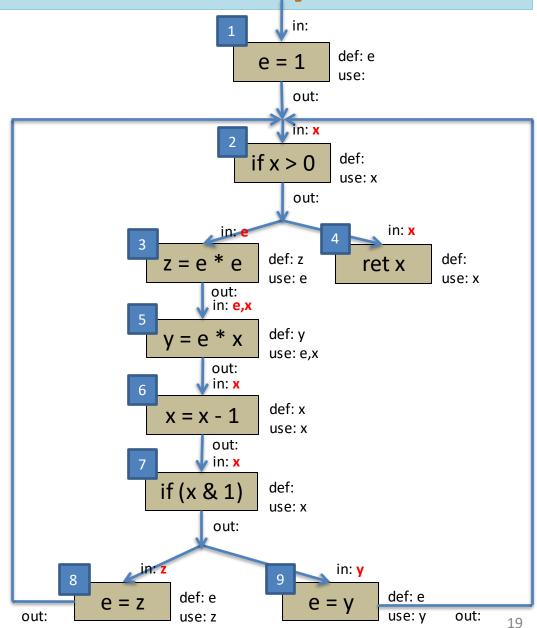
### Each iteration update:

```
out[n] := U_{n' \in succ[n]}in[n']
in[n] := use[n] \cup (out[n] - def[n])
```

### Iteration 1:

in[9] = y

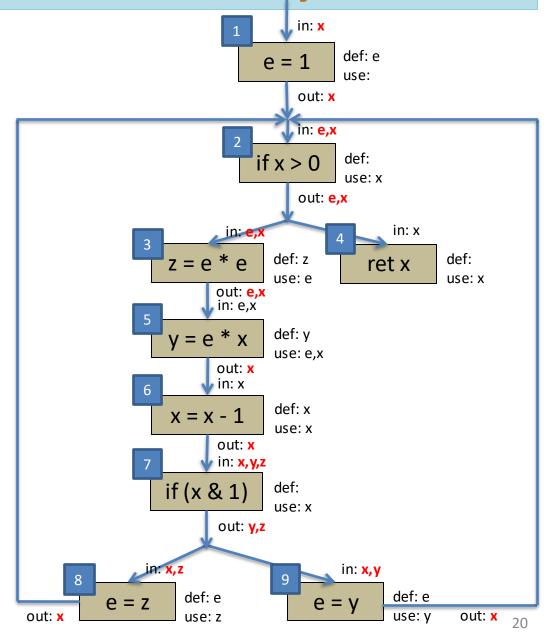
(showing only updates that make a change)



### Each iteration update:

```
out[n] := U_{n' \in succ[n]}in[n']
in[n] := use[n] \cup (out[n] - def[n])
```

#### • Iteration 2:



### Each iteration update:

 $out[n] := U_{n' \in succ[n]} in[n']$  $in[n] := use[n] \cup (out[n] - def[n])$ 

#### Iteration 3:

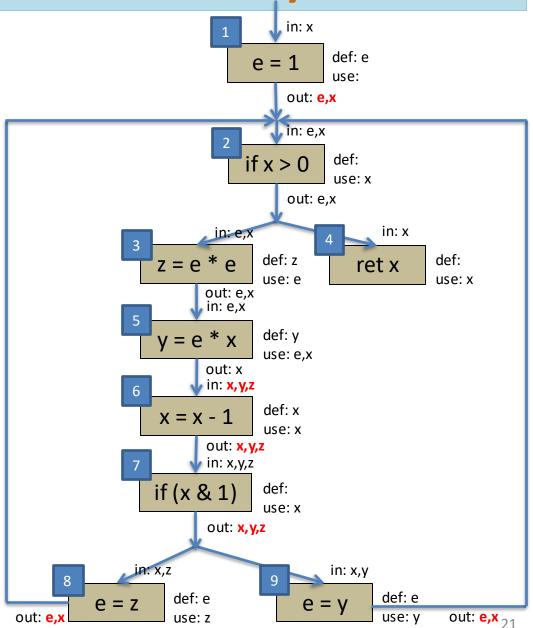
$$out[6] = x,y,z$$

$$in[6] = x,y,z$$

$$out[7] = x,y,z$$

$$out[8] = e,x$$

$$out[9] = e,x$$

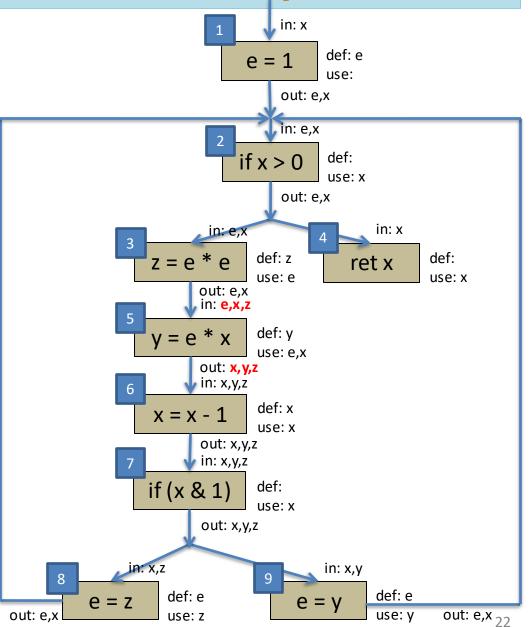


### Each iteration update:

out[n] :=  $U_{n' \in succ[n]}$ in[n'] in[n] := use[n]  $\cup$  (out[n] - def[n])

Iteration 4:

out[5]= x,y,z in[5]= e,x,z



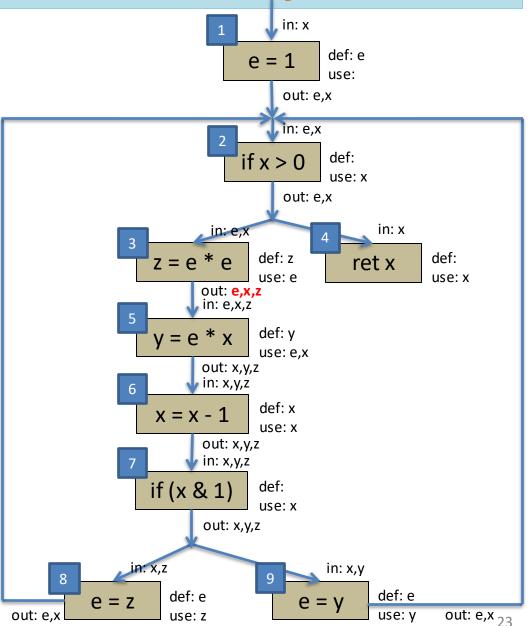
### Each iteration update:

out[n] :=  $U_{n' \in succ[n]}$ in[n'] in[n] := use[n]  $\cup$  (out[n] - def[n])

Iteration 5:

out[3]=e,x,z

Done!



# Improving the Algorithm

- Can we do better?
- Observe: the only way information propagates from one node to another is using:  $out[n] := \bigcup_{n' \in succ[n]} in[n']$ 
  - This is the only rule that involves more than one node
- If a node's successors haven't changed, then the node itself won't change.
- Idea for an improved version of the algorithm:
  - Keep track of which node's successors have changed

### **A Worklist Algorithm**

Use a FIFO queue of nodes that might need to be updated.

```
for all n, in[n] := \emptyset, out[n] := \emptyset
w = new queue with all nodes
repeat until w is empty
   let n = w.pop()
                                        // pull a node off the queue
     old in = in[n]
                                        // remember old in[n]
     out[n] := \bigcup_{n' \in succ[n]} in[n']
     in[n] := use[n] \cup (out[n] - def[n])
     if (old in != in[n]),
                                             // if in[n] has changed
       for all m in pred[n], w.push(m) // add to worklist
end
```

### **OTHER DATAFLOW ANALYSES**

# **Generalizing Dataflow Analyses**

- The kind of iterative constraint solving used for liveness analysis applies to other kinds of analyses as well.
  - Reaching definitions analysis
  - Available expressions analysis
  - Alias Analysis
  - Constant Propagation
  - These analyses follow the same 3-step approach as for liveness.

- To see these as an instance of the same kind of algorithm, the next few examples to work over a canonical intermediate instruction representation called *quadruples*
  - Allows easy definition of def[n] and use[n]
  - A slightly "looser" variant of LLVM's IR that doesn't require the "static single assignment" i.e. it has mutable local variables

We will use LLVM-IR-like syntax

# Def / Use for SSA

Instructions n:def[n] use[n] description {b,c} arithmetic a = op b c{a} {b} a = load b {a} load store a, b Ø {a,b} store Ø {a} a = alloca talloca a = bitcast b to u {a} {b} bitcast  $a = gep b [c,d, ...] {a}$ {b,c,d,...}getelementptr  $a = f(b_1,...,b_n)$  {a} {b<sub>1</sub>,...,b<sub>n</sub>}call w/return  $f(b_1,...,b_n)$ {b<sub>1</sub>,...,b<sub>n</sub>}void call (no return)

### Terminators

br L  $\emptyset$   $\emptyset$  jump br a L1 L2  $\emptyset$  {a} conditional branch return a  $\emptyset$  {a} return

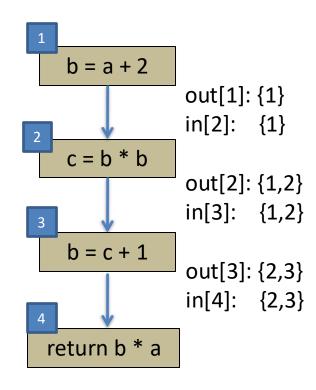
### **REACHING DEFINITIONS**

# **Reaching Definition Analysis**

- Question: what uses in a program does a given variable definition reach?
- This analysis is used for constant propagation & copy prop.
  - If only one definition reaches a particular use, can replace use by the definition (for constant propagation).
  - Copy propagation additionally requires that the copied value still has its same value – computed using an available expressions analysis (next)
- Input: Quadruple CFG
- Output: in[n] (resp. out[n]) is the set of nodes defining some variable such that the definition may reach the beginning (resp. end) of node n

# **Example of Reaching Definitions**

Results of computing reaching definitions on this simple CFG:



## **Reaching Definitions Step 1**

- Define the sets of interest for the analysis
- Let defs[a] be the set of *nodes* that define the variable a
- Define gen[n] and kill[n] as follows:

•	Quadruple forms n:		gen[n]	kill[n]
	a = b op c	{n}		defs[a] - {n}
	a = load b	{n}		defs[a] - {n}
	store b, a		Ø	Ø
	$a = f(b_1,, b_n)$	{n}		defs[a] - {n}
	$f(b_1,,b_n)$	Ø		Ø
	br L		Ø	Ø
	braL1 L2		Ø	Ø
	return a		Ø	Ø

# **Reaching Definitions Step 2**

- Define the constraints that a reaching definitions solution must satisfy.
- out[n] ⊇ gen[n]
   "The definitions that reach the end of a node at least include the definitions generated by the node"
- in[n] ⊇ out[n'] if n' is in pred[n]
   "The definitions that reach the beginning of a node include those that reach the exit of any predecessor"
- out[n] ∪ kill[n] ⊇ in[n]
   "The definitions that come in to a node either reach the end of the node or are killed by it."
  - Equivalently:  $out[n] \supseteq in[n] kill[n]$

# **Reaching Definitions Step 3**

- Convert constraints to iterated update equations:
- $in[n] := U_{n' \in pred[n]} out[n']$
- out[n] := gen[n] ∪ (in[n] kill[n])
- Algorithm: initialize in[n] and out[n] to Ø
  - Iterate the update equations until a fixed point is reached
- The algorithm terminates because in[n] and out[n] increase only monotonically
  - At most to a maximum set that includes all variables in the program
- The algorithm is precise because it finds the smallest sets that satisfy the constraints.

### **AVAILABLE EXPRESSIONS**

### **Available Expressions**

Idea: want to perform common subexpression elimination:

$$- a = x + 1$$
  $a = x + 1$  ...  $b = x + 1$   $b = a$ 

- This transformation is safe if x+1 means computes the same value at both places (i.e. x hasn't been assigned).
  - "x+1" is an available expression
- Dataflow values:
  - in[n] = set of nodes whose values are available on entry to n
  - out[n] = set of nodes whose values are available on exit of n

# **Available Expressions Step 1**

- Define the sets of values
- Define gen[n] and kill[n] as follows:

Quadruple forms n:	gen[n]	kill[n]	
a = b op c	{n} - kill[n]	uses[a]	
a = load b	{n} - kill[n]	uses[a]	
store b, a	Ø	uses[ [x] ]	
		(for all x that may equal a)	
br L	Ø	Ø	Note the need for "may
br a L1 L2	Ø	Ø	alias" information
$a = f(b_1,, b_n)$	Ø	uses[a]U uses	[ [x] ]
		(for all x)	
$f(b_1,,b_n)$	Ø	uses[ [x] ]	(for all x)
return a	Ø	Ø	Note that functions are assumed to be impure
	a = b  op  c a = load b store b, a br L br a L1 L2 $a = f(b_1,,b_n)$	$a = b \text{ op c}$ $a = load b$ $store b, a$ $\begin{cases} n - kill[n] \\ n - kill[n] \end{cases}$ $\emptyset$ $\begin{cases} br L \\ br a L1 L2 \\ a = f(b_1,, b_n) \end{cases}$ $\emptyset$	$ a = b \text{ op } c \\ a = load b \\ store b, a \\                                 $

# **Available Expressions Step 2**

- Define the constraints that an available expressions solution must satisfy.
- out[n] ⊇ gen[n]
   "The expressions made available by n that reach the end of the node"
- in[n] ⊆ out[n'] if n' is in pred[n]
   "The expressions available at the beginning of a node include those that reach the exit of every predecessor"
- out[n] ∪ kill[n] ⊇ in[n]
   "The expressions available on entry either reach the end of the node or are killed by it."
  - Equivalently:  $out[n] \supseteq in[n] kill[n]$

Note similarities and differences with constraints for "reaching definitions".

# **Available Expressions Step 3**

- Convert constraints to iterated update equations:
- $in[n] := \bigcap_{n' \in pred[n]} out[n']$
- out[n] := gen[n] ∪ (in[n] kill[n])
- Algorithm: initialize in[n] and out[n] to {set of all nodes}
  - Iterate the update equations until a fixed point is reached
- The algorithm terminates because in[n] and out[n] decrease only monotonically
  - At most to a minimum of the empty set
- The algorithm is precise because it finds the largest sets that satisfy the constraints.