Determinant

The determinant of $\mathbf{A} \in \mathbb{R}^{m \times m}$, denoted by $det(\mathbf{A})$, is defined by induction

- For m = 1: $\det(\mathbf{A}) = a_{11}$ $A = A_{11}$
- For $m \ge 2$:
 - Let $\mathbf{A}_{ij} \in \mathbb{R}^{(m-1)\times (m-1)}$ be a submatrix of \mathbf{A} obtained by deleting the ith row and jth column of \mathbf{A}
 - Let $c_{ij} = (-1)^{i+j} \det(\mathbf{A}_{ij})$
 - Cofactor expansion:

$$\det(\mathbf{A}) = \sum_{j=1}^{m} a_{ij} c_{ij}, \text{ for any } i = 1, ..., m$$

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where c_{ij} 's are the cofactors and $det(\mathbf{A}_{ij})$'s are the minors

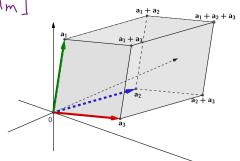


Determinant (Cont'd)

A singular

- Fact: Ax = 0 for some $x \neq 0$ if and only if det(A) = 0
- Interpretation: $|\det(\mathbf{A})|$ is the volume of the parallelepiped $\mathcal{P} = \{\mathbf{y} = \sum_{i=1}^{m} \alpha_i \mathbf{a}_i \mid \alpha_i \in [0,1] \ \forall i=1,\ldots,m\}$

A=[a1 ··· am]



Determinant (Cont'd)

Let **A**. **B** $\in \mathbb{R}^{m \times m}$

•
$$det(\mathbf{A}) = det(\mathbf{A}^T)$$

•
$$\det(\alpha \mathbf{A}) = \alpha^m \det(\mathbf{A})$$
 for any $\alpha \in \mathbb{R}$ $\det(A)$. $\det(A^{-1})$
• $\det(\mathbf{A}^{-1}) = 1/\det(\mathbf{A})$ for any nonsingular $\mathbf{A} = \det(AA^{-1}) = \det(A^{-1})$

•
$$det(\mathbf{A}^{-1}) = 1/det(\mathbf{A})$$
 for any nonsingular $\mathbf{A} = det(\mathbf{A}\mathbf{A}^{-1}) = det(\mathbf{A}\mathbf{A}^{-1})$

•
$$det(B^{-1}AB) = det(A)$$
 for any nonsingular B

•
$$\det(\mathbf{B}^{-1}\mathbf{A}\mathbf{B}) = \det(\mathbf{A})$$
 for any nonsingular $\mathbf{B} = \mathbf{A}$
• $\mathbf{A}^{-1} = \frac{1}{\det(\mathbf{A})}\tilde{\mathbf{A}}$, where $\tilde{a}_{ij} = c_{ji}$ (the cofactor) for all i, j (\mathbf{A} is nonsingular)

A is the adjoint or adjugate matrix of A

Determinant (Cont'd)

• If $\mathbf{A} \in \mathbb{R}^{m \times m}$ is triangular, either upper or lower,

$$\det(\mathbf{A}) = \prod_{i=1}^{m} a_{ii}$$

- Proof: Apply cofactor expansion inductively
- If $\mathbf{A} \in \mathbb{R}^{m \times m}$ is *block* upper or lower triangular

$$\mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{C} \\ \mathbf{0} & \mathbf{D} \end{bmatrix}, \quad \mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{0} \\ \mathbf{C} & \mathbf{D} \end{bmatrix}$$

where **B** and **D** are square (and can be of different sizes), then

$$det(\mathbf{A}) = det(\mathbf{B}) det(\mathbf{D})$$

Vector Norms

A function $f: \mathbb{R}^n \to \mathbb{R}$ is a vector norm if all of the following hold:

- 1. $f(\mathbf{x}) \ge 0$ for any $\mathbf{x} \in \mathbb{R}^n$
- 2. $f(\mathbf{x}) = 0$ if and only if $\mathbf{x} = \mathbf{0}$
- 3. $f(\mathbf{x} + \mathbf{y}) \le f(\mathbf{x}) + f(\mathbf{y})$ for any $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$
- 4. $f(\alpha \mathbf{x}) = |\alpha| f(\mathbf{x})$ for any $\alpha \in \mathbb{R}$, $\mathbf{x} \in \mathbb{R}^n$

- Usually || · || denotes a norm
- $\|\mathbf{x}\|$ represents the "length" of vector \mathbf{x}
- $\|\mathbf{x} \mathbf{y}\|$ represents the "distance" of vectors \mathbf{x} , \mathbf{y}

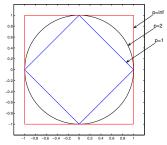
Vector Norms (Cont'd)

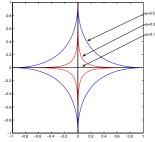
Examples:

- 2-norm or Euclidean norm: $\|\mathbf{x}\|_2 = \sqrt{\sum_{i=1}^n |x_i|^2} = (\mathbf{x}^T \mathbf{x})^{1/2}$
- 1-norm or Manhattan norm: $\|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i|$
- ∞ -norm: $\|\mathbf{x}\|_{\infty} = \max_{i=1,\dots,n} |x_i|$
- *p*-norm, $p \ge 1$: $\|\mathbf{x}\|_p = \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}}$

ℓ_p Function

$$f_p(\mathbf{x}) = \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}}, \qquad p > 0$$





- (a) Region of $f_p(\mathbf{x})=1,\ p\geq 1.$ (b) Region of $f_p(\mathbf{x})=1,\ p\leq 1.$
 - Note that f_p is *not* a norm for 0
 - when $p \to 0$, f_p is like the cardinality function $\operatorname{card}(\mathbf{x}) = \sum_{i=1}^{n} \mathbb{1}\{x_i \neq 0\}$, where $\mathbb{1}\{x \neq 0\} = 1$ if $x \neq 0$ and $\mathbb{1}\{x \neq 0\} = 0$ if x = 0



Inner Product

The inner product of two vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ is defined as

$$\langle \mathbf{x}, \mathbf{y} \rangle = \sum_{i=1}^{n} y_i x_i = \mathbf{y}^T \mathbf{x} = \chi^T \psi = \langle y, \chi \rangle$$

- \mathbf{x} , \mathbf{y} are said to be orthogonal to each other if $\langle \mathbf{x}, \mathbf{y} \rangle = 0$
- \mathbf{x} , \mathbf{y} are said to be parallel if $\mathbf{x} = \alpha \mathbf{y}$ for some α
 - $\langle \mathbf{x}, \mathbf{y} \rangle = \pm ||\mathbf{x}||_2 ||\mathbf{y}||_2$ for parallel \mathbf{x}, \mathbf{y}

The angle between two vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ is defined as

$$\theta = \cos^{-1}\left(\frac{\mathbf{y}'\mathbf{x}}{\|\mathbf{x}\|_2\|\mathbf{y}\|_2}\right)$$

- \mathbf{x}, \mathbf{y} are orthogonal if $\theta = \pm \pi/2$
- \mathbf{x} , \mathbf{y} are parallel if $\theta = 0$ or $\theta = \pm \pi$

Hölder Inequality

Hölder Inequality: For any p, q > 1 with $\frac{1}{p} + \frac{1}{q} = 1$,

$$|\mathbf{x}^T \mathbf{y}| \le ||\mathbf{x}||_p ||\mathbf{y}||_q$$

Proof. **Young's Inequality**: For any $a, b \ge 0$ and p, q > 1 with $\frac{1}{p} + \frac{1}{q} = 1$,

Hölder Inequality (Cont'd)

Hölder Inequality: For any p, q > 1 with $\frac{1}{p} + \frac{1}{q} = 1$,

$$|\mathbf{x}^T \mathbf{y}| \le ||\mathbf{x}||_p ||\mathbf{y}||_q$$

Cauchy-Schwartz Inequality: Let
$$p = q = 2$$
 in Hölder Inequality $\chi^T y = ||\chi||_2 ||y||_2 ||x||_2 ||x$

where the equality holds if and only if $\mathbf{x} = \alpha \mathbf{y}$ for some $\alpha \in \mathbb{R}$

• Hölder Inequality holds for p = 1 and $q = \infty$

$$|\mathbf{x}^T \mathbf{y}| \le \sum_{i=1}^n |x_i y_i| \le \max_j |y_j| (\sum_{i=1}^n |x_i|) = ||\mathbf{x}||_1 ||\mathbf{y}||_{\infty}.$$

Equivalence of Norms

All norms on \mathbb{R}^n are equivalent in the sense that if $\|\cdot\|_{\alpha}$ and $\|\cdot\|_{\beta}$ are norms on \mathbb{R}^n , then there exist $c1, c_2 > 0$ such that

$$c_1 \|\mathbf{x}\|_{\alpha} \le \|\mathbf{x}\|_{\beta} \le c_2 \|\mathbf{x}\|_{\alpha}, \quad \forall \mathbf{x} \in \mathbb{R}^n$$

- $\|\mathbf{x}\|_2 \le \|\mathbf{x}\|_1 \le \sqrt{n} \|\mathbf{x}\|_2$
- $\|\mathbf{x}\|_{\infty} \le \|\mathbf{x}\|_2 \le \sqrt{n} \|\mathbf{x}\|_{\infty}$
- $\|\mathbf{x}\|_{\infty} \leq \|\mathbf{x}\|_{1} \leq n\|\mathbf{x}\|_{\infty}$

Projections on Subspaces

Let $S \subseteq \mathbb{R}^m$ be a nonempty closed set (not necessarily a subspace) Given $\mathbf{y} \in \mathbb{R}^m$, a projection of \mathbf{y} onto S is any solution to

$$\min_{\boldsymbol{z} \in \mathcal{S}} \ \|\boldsymbol{z} - \boldsymbol{y}\|_2^2$$

- a point in S that is closest to y
 - Projection of $\mathbf{y} \in \mathcal{S}$ onto \mathcal{S} is \mathbf{y} itself
- If for any $\mathbf{y} \in \mathbb{R}^m$, there always exists a unique projection of \mathbf{y} onto S, then we denote

$$\Pi_{\mathcal{S}}(\mathbf{y}) = \arg\min_{\mathbf{z} \in \mathcal{S}} \|\mathbf{z} - \mathbf{y}\|_{2}^{2}$$

and $\Pi_{\mathcal{S}}$ is called the projection (or projection operator) of **y** onto \mathcal{S}

Projection Theorem

Theorem (Projection Theorem)

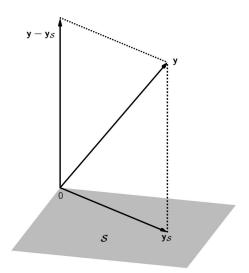
Let S be a subspace of \mathbb{R}^m .

- 1. For any $\mathbf{y} \in \mathbb{R}^m$, there exists a unique vector $\mathbf{y}_s \in \mathcal{S}$ that minimizes $\|\mathbf{z} \mathbf{y}\|_2^2$ over $\mathbf{z} \in \mathcal{S}$ (so that we can use the notation $\Pi_{\mathcal{S}}(\mathbf{y}) = \arg\min_{\mathbf{z} \in \mathcal{S}} \|\mathbf{z} \mathbf{y}\|_2^2$).
- 2. Given $\mathbf{y} \in \mathbb{R}^m$,

$$\mathbf{y}_s = \Pi_{\mathcal{S}}(\mathbf{y}) \iff \mathbf{y}_s \in \mathcal{S}, \quad \mathbf{z}^T(\mathbf{y}_s - \mathbf{y}) = 0 \text{ for all } \mathbf{z} \in \mathcal{S}.$$

- Statement 1 of Projection Theorem also holds for closed convex set (more general)
 - Very important to convex optimization

Projection Theorem (Cont'd)



Orthogonal Complement

Let $S \subseteq \mathbb{R}^m$ be a nonempty closed set The orthogonal complement of S is defined as

$$S^{\perp} = \{ \mathbf{y} \in \mathbb{R}^m \mid \mathbf{z}^T \mathbf{y} = 0 \text{ for all } \mathbf{z} \in S \}$$

- · S¹ is a subspace (Why?) IN nother & i's subspace or not
- Any $\mathbf{z} \in \mathcal{S}$ and any $\mathbf{y} \in \mathcal{S}^{\perp}$ are orthogonal
- Either $S \cap S^{\perp} = \{0\}$ or $S \cap S^{\perp} = \emptyset$ Eacts:
- Facts:
 - $\mathcal{R}(\mathbf{A})^{\perp} = \mathcal{N}(\mathbf{A}^{T})$
 - $\mathcal{N}(\mathbf{A}) = \mathcal{R}(\mathbf{A}^T)^{\perp}$
 - Recall that range and nullspace of a matrix are subspaces

For any
$$x \in \mathcal{N}(A^T)$$
 and $y \in \mathcal{R}(A)$,
 $A^T x = D$ $\exists z s.t. y = Az$.
 $\langle y, x \rangle = y^T x = (Az)^T x = z^T A^T x = 0$

Orthogonal Complement of Subspace

Theorem

Let $S \subseteq \mathbb{R}^m$ be a subspace. For any $\mathbf{y} \in \mathbb{R}^m$, there uniquely exists $(\mathbf{y}_s, \mathbf{y}_c) \in S \times S^{\perp}$ such that

$$\mathbf{y} = \mathbf{y}_s + \mathbf{y}_c$$
.

In particular, $\mathbf{y}_s = \Pi_{\mathcal{S}}(\mathbf{y}), \mathbf{y}_c = \mathbf{y} - \Pi_{\mathcal{S}}(\mathbf{y}) = \Pi_{\mathcal{S}^{\perp}}(\mathbf{y}).$

• Proof sketch: From Statement 2 of the Projection Theorem,

$$\mathbf{y}_s \in \mathcal{S}, \ \mathbf{y} - \mathbf{y}_s \in \mathcal{S}^{\perp} \iff \mathbf{y}_s \in \Pi_{\mathcal{S}}(\mathbf{y})$$



Orthogonal Complement of Subspace (Cont'd)

Let $\mathcal{S} \subseteq \mathbb{R}^m$ be a subspace. It follows from the above theorem that

- $S + S^{\perp} = \mathbb{R}^m$
- $\dim S + \dim S^{\perp} = m$
 - Proof: $\dim S + \dim S^{\perp} = \dim(S + S^{\perp}) + \dim(S \cap S^{\perp}) = \dim(S + S^{\perp}) + 0 = \dim\mathbb{R}^m$
- $(S^{\perp})^{\perp} = S$

Example: Let $\mathbf{A} \in \mathbb{R}^{m \times n}$

$$\dim \mathcal{Z}(A^T) + \dim \mathcal{N}(A) = \mathcal{N}$$

- $\dim \mathcal{R}(\mathbf{A}) + \dim \mathcal{R}(\mathbf{A})^{\perp} = \dim \mathcal{R}(\mathbf{A}) + \dim \mathcal{N}(\mathbf{A}^{T}) = m$
- Rank-Nullity Theorem: $\dim \mathcal{N}(\mathbf{A}) = n \dim \mathcal{R}(\mathbf{A}^T) = n \operatorname{rank}(\mathbf{A})$

Orthogonal and Orthonormal Vectors

A collection of *nonzero* vectors $\mathbf{a}_1, \dots, \mathbf{a}_n \in \mathbb{R}^m$ are said to be

- orthogonal if $\mathbf{a}_i^T \mathbf{a}_j = 0$ for all i, j with $i \neq j$
- orthonormal if they are orthogonal and $\|\mathbf{a}_i\|_2 = 1$ for all i

Same definition applies to complex \mathbf{a}_i 's by replacing transpose (T) with Hermitian transpose (H)

Example: Any vectors from $\{\mathbf{e}_1, \dots, \mathbf{e}_m\}$ are orthonormal and $\{\mathbf{e}_1, \dots, \mathbf{e}_m\} \subset \mathbb{R}^m$ is an orthonormal basis for \mathbb{R}^m

Orthonormal vectors are linearly independent or house for all

Orthogonal and Orthonormal Vectors (Cont'd)

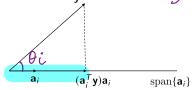
Fact: Let $\{a_1, \ldots, a_n\} \subset \mathbb{R}^m$ be an orthonormal set of vectors and $\mathbf{y} \in \operatorname{span}\{\mathbf{a}_1,\ldots,\mathbf{a}_n\}$. Then, the coefficient α for the representation

$$\mathbf{y} = \sum_{i=1}^{n} \alpha_i \mathbf{a}_i$$

is uniquely given by
$$\alpha_i = \mathbf{a}_i^T \mathbf{y}$$
, $i = 1, ..., n$

$$\mathbf{y}$$

$$\mathbf{a}_i^T \mathbf{y} = \|\mathbf{a}_i\|_2 \cdot \|\mathbf{y}\|_2 \cdot \cos\theta_1$$



Fact: Every subspace S with $S \neq \{0\}$ has an orthonormal basis

It can be shown using Gram-Schmidt



Orthogonal Matrix

A real matrix Q is said to be

- orthogonal if it is square and its columns are orthonormal
- semi-orthogonal if its columns are orthonormal



a semi-orthogonal Q must be tall or square

A complex matrix \mathbf{Q} is said to be unitary if it is square and its columns are orthonormal, and semi-unitary if its columns are orthonormal

Example: Consider the transformation y = Qx with

$$\mathbf{Q} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \quad \text{rotation counterclock-wise by } \theta \in [0, 2\pi)$$

$$\mathbf{Q} = \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ \sin(\theta) & -\cos(\theta) \end{bmatrix}$$
 reflection about the $\theta/2$ line, $\theta \in [0, 2\pi)$

The rotation and reflection matrices are orthogonal



Orthogonal Matrix (Cont'd)

Facts:

• $\mathbf{Q}^T \mathbf{Q} = \mathbf{I}$ and $\mathbf{Q} \mathbf{Q}^T = \mathbf{I}$ for orthogonal \mathbf{Q}

$$Q^T = Q^{-1}$$

- $\mathbf{Q}^T \mathbf{Q} = \mathbf{I}$ (but *not* necessarily $\mathbf{Q} \mathbf{Q}^T = \mathbf{I}$) for semi-orthogonal \mathbf{Q}
- $\|\mathbf{Q}\mathbf{x}\|_2 = \|\mathbf{x}\|_2$ for orthogonal \mathbf{Q}
 - For example, rotation and reflection do not change the vector length
- For any tall and semi-orthogonal matrix $\mathbf{Q}_1 \in \mathbb{R}^{n \times k}$, there exists a matrix $\mathbf{Q}_2 \in \mathbb{R}^{n \times (n-k)}$ such that $[\mathbf{Q}_1 \mathbf{Q}_2]$ is orthogonal

Matrix Product Representations

Let $\mathbf{A} \in \mathbb{R}^{m \times k}$ and $\mathbf{B} \in \mathbb{R}^{k \times n}$. Consider

$$C = AB$$

where c_i and b_i are the *i*th columns of C and B

• Inner-product representation: Let $\tilde{\mathbf{a}}_i^T \in \mathbb{R}^{1 \times k}$ be the *i*th row of **A**

$$\mathbf{AB} = \begin{bmatrix} \tilde{\mathbf{a}}_1^T \\ \vdots \\ \tilde{\mathbf{a}}_m^T \end{bmatrix} \begin{bmatrix} \mathbf{b}_1 & \cdots & \mathbf{b}_n \end{bmatrix} = \begin{bmatrix} \tilde{\mathbf{a}}_1^T \mathbf{b}_1 & \cdots & \tilde{\mathbf{a}}_1^T \mathbf{b}_n \\ \vdots & & \vdots \\ \tilde{\mathbf{a}}_m^T \mathbf{b}_1 & \cdots & \tilde{\mathbf{a}}_m^T \mathbf{b}_n \end{bmatrix}$$

Thus,

$$c_{ij} = \tilde{\mathbf{a}}_i^T \mathbf{b}_i$$
, for all i, j