

## Schur Complement (cont'd)

Previously, if  $\mathbf{D}$  and the Schur complement  $\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C}$  are nonsingular,

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{bmatrix}^{-1} = \begin{bmatrix} (\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C})^{-1} & -(\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C})^{-1}\mathbf{B}\mathbf{D}^{-1} \\ -\mathbf{D}^{-1}\mathbf{C}(\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C})^{-1} & \mathbf{D}^{-1} + \mathbf{D}^{-1}\mathbf{C}(\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C})^{-1}\mathbf{B}\mathbf{D}^{-1} \end{bmatrix}$$

Now suppose  $\mathbf{A}$  and the Schur complement  $\mathbf{D} - \mathbf{C}\mathbf{A}^{-1}\mathbf{B}$  are nonsingular.  
Likewise,

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{bmatrix}^{-1} = \begin{bmatrix} \mathbf{A}^{-1} + \mathbf{A}^{-1}\mathbf{B}(\mathbf{D} - \mathbf{C}\mathbf{A}^{-1}\mathbf{B})^{-1}\mathbf{C}\mathbf{A}^{-1} & -\mathbf{A}^{-1}\mathbf{B}(\mathbf{D} - \mathbf{C}\mathbf{A}^{-1}\mathbf{B})^{-1} \\ -(\mathbf{D} - \mathbf{C}\mathbf{A}^{-1}\mathbf{B})^{-1}\mathbf{C}\mathbf{A}^{-1} & (\mathbf{D} - \mathbf{C}\mathbf{A}^{-1}\mathbf{B})^{-1} \end{bmatrix}$$

Compare the above two expressions of  $\mathbf{X}^{-1}$ . If  $\mathbf{A}$ ,  $\mathbf{D}$  and both Schur complements  $\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C}$ ,  $\mathbf{D} - \mathbf{C}\mathbf{A}^{-1}\mathbf{B}$  are nonsingular, then

$$(\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C})^{-1} = \mathbf{A}^{-1} + \mathbf{A}^{-1}\mathbf{B}(\mathbf{D} - \mathbf{C}\mathbf{A}^{-1}\mathbf{B})^{-1}\mathbf{C}\mathbf{A}^{-1}$$

By setting  $\mathbf{D} = \mathbf{I}$  and  $\mathbf{B}' = -\mathbf{B}$ , the above equation leads to the *matrix inversion lemma*

$$(\mathbf{A} + \mathbf{B}'\mathbf{C})^{-1} = \mathbf{A}^{-1} - \mathbf{A}^{-1}\mathbf{B}'(\mathbf{I} + \mathbf{C}\mathbf{A}^{-1}\mathbf{B}')^{-1}\mathbf{C}\mathbf{A}^{-1}$$

# Schur Complement of PSD Matrices

Let  $\mathbf{X} \in \mathbb{S}^n$  and partition it as

$$\mathbf{X} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B}^T & \mathbf{C} \end{bmatrix}$$

where  $\mathbf{A} \in \mathbb{S}^m$  and  $\mathbf{C} \in \mathbb{S}^{n-m}$

The Schur complements are  $\mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^T$  and  $\mathbf{C} - \mathbf{B}^T\mathbf{A}^{-1}\mathbf{B}$

**Properties:**

- With nonsingular  $\mathbf{C}$ ,  $\mathbf{X} \succ 0 \iff \mathbf{C} \succ 0$  and  $\mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^T \succ 0$
- With  $\mathbf{C} \succ 0$ ,  $\mathbf{X} \succeq 0 \iff \mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^T \succeq 0$
- With nonsingular  $\mathbf{A}$ ,  $\mathbf{X} \succ 0 \iff \mathbf{A} \succ 0$  and  $\mathbf{C} - \mathbf{B}^T\mathbf{A}^{-1}\mathbf{B} \succ 0$
- With  $\mathbf{A} \succ 0$ ,  $\mathbf{X} \succeq 0 \iff \mathbf{C} - \mathbf{B}^T\mathbf{A}^{-1}\mathbf{B} \succeq 0$

**Example:** For any  $\mathbf{b} \in \mathbb{R}^n$  and any symmetric and PD  $\mathbf{C}$ ,

$$\mathbf{X} = \begin{bmatrix} 1 & \mathbf{b}^T \\ \mathbf{b} & \mathbf{C} \end{bmatrix}$$

$1 - \mathbf{b}^T \mathbf{C}^{-1} \mathbf{b} \geq 0 \iff \mathbf{C} - \mathbf{b} \mathbf{b}^T \succeq 0$

*Schur complement of 1*      *Schur complement of C*

$\mathbf{X} \succeq 0$

## Important Facts for Proving the Properties of Schur Complement

Let  $\mathbf{Y} = \begin{bmatrix} \mathbf{I} & \mathbf{0} \\ -\mathbf{C}^{-1}\mathbf{B}^T & \mathbf{I} \end{bmatrix}$ , which is nonsingular. Then consider  $\mathbf{Y}^T \mathbf{X} \mathbf{Y}$

According to Property 3 on Page 14, Sec 5.1,

$$\mathbf{X} \succeq \mathbf{0} \iff \mathbf{Y}^T \mathbf{X} \mathbf{Y} \succeq \mathbf{0}$$

$$\begin{aligned} \mathbf{Y}^T \mathbf{X} \mathbf{Y} &= \begin{bmatrix} \mathbf{I} & -\mathbf{B}\mathbf{C}^{-1} \\ \mathbf{0} & \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B}^T & \mathbf{C} \end{bmatrix} \begin{bmatrix} \mathbf{I} & \mathbf{0} \\ -\mathbf{C}^{-1}\mathbf{B}^T & \mathbf{I} \end{bmatrix} \\ &= \begin{bmatrix} \mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^T & \mathbf{0} \\ \mathbf{0} & \mathbf{C} \end{bmatrix} \text{ block diagonal} \end{aligned}$$

The eigenvalues of  $\mathbf{Y}^T \mathbf{X} \mathbf{Y} =$  the eigenvalues of  $\mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^T$  and the eigenvalues of  $\mathbf{C}$

# Matrix Computations

## Chapter 6: Singular value, Singular Vectors, and Singular Value Decomposition

### Section 6.1 Singular Value Decomposition

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# Singular Value Decomposition

## Theorem

Given any  $\mathbf{A} \in \mathbb{R}^{m \times n}$ , there exists a 3-tuple  $(\mathbf{U}, \Sigma, \mathbf{V}) \in \mathbb{R}^{m \times m} \times \mathbb{R}^{m \times n} \times \mathbb{R}^{n \times n}$  s.t.

$$\mathbf{A} = \mathbf{U}\Sigma\mathbf{V}^T$$

where  $\mathbf{U}$  and  $\mathbf{V}$  are orthogonal matrices and

$$[\Sigma]_{ij} = \begin{cases} \sigma_i, & i=j \\ 0, & i \neq j \end{cases} \quad \text{with } \sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_p \geq 0, \quad p = \min\{m, n\}$$

$p=n$   
 $\sigma_1, \dots, \sigma_p$   
 may have zero entry

$m > n$

$$\Sigma = \begin{bmatrix} \text{diag}(\sigma_1, \dots, \sigma_p) \\ \mathbf{0} \end{bmatrix}$$

$m < n$

$$\Sigma = \begin{bmatrix} \text{diag}(\sigma_1, \dots, \sigma_p) & \mathbf{0} \end{bmatrix}$$

$\sigma_1, \dots, \sigma_m$

- The above decomposition is called the **singular value decomposition (SVD)**  $p=m$
- $\sigma_i$  is called the  $i$ th **singular value**
- $\mathbf{u}_i$  and  $\mathbf{v}_i$  are called the  $i$ th **left and right singular vectors**, respectively
- Notations denoting singular values of  $\mathbf{A}$ :

$$\sigma_{\max}(\mathbf{A}) = \sigma_1(\mathbf{A}) \geq \sigma_2(\mathbf{A}) \geq \dots \geq \sigma_p(\mathbf{A}) = \sigma_{\min}(\mathbf{A})$$

## Different Forms of SVD

- Partitioned form:** Let  $r$  be the number of nonzero singular values, so that  $\sigma_1 \geq \dots \sigma_r > 0$ ,  $\sigma_{r+1} = \dots = \sigma_p = 0$ . Then,

$$\mathbf{A} = [\mathbf{U}_1 \quad \mathbf{U}_2] \underbrace{\begin{bmatrix} \tilde{\Sigma} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}}_{\Sigma} \begin{bmatrix} \mathbf{V}_1^T \\ \mathbf{V}_2^T \end{bmatrix}$$

where

- $\tilde{\Sigma} = \text{Diag}(\sigma_1, \dots, \sigma_r)$
  - $\mathbf{U}_1 = [\mathbf{u}_1, \dots, \mathbf{u}_r] \in \mathbb{R}^{m \times r}$ ,  $\mathbf{U}_2 = [\mathbf{u}_{r+1}, \dots, \mathbf{u}_m] \in \mathbb{R}^{m \times (m-r)}$
  - $\mathbf{V}_1 = [\mathbf{v}_1, \dots, \mathbf{v}_r] \in \mathbb{R}^{n \times r}$ ,  $\mathbf{V}_2 = [\mathbf{v}_{r+1}, \dots, \mathbf{v}_n] \in \mathbb{R}^{n \times (n-r)}$
- Thin SVD:**  $\mathbf{A} = \mathbf{U}_1 \tilde{\Sigma} \mathbf{V}_1^T$   *$\mathbf{U}_1, \mathbf{V}_1$  semi-orthogonal*
  - Outer-product form:**  $\mathbf{A} = \sum_{i=1}^p \sigma_i \mathbf{u}_i \mathbf{v}_i^T = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T$

# SVD and Eigendecomposition

Note from the SVD  $\mathbf{A} = \mathbf{U}\Sigma\mathbf{V}^T$  that

$$\mathbf{A}\mathbf{A}^T = \mathbf{U}\mathbf{D}_1\mathbf{U}^T, \mathbf{D}_1 = \Sigma\Sigma^T = \text{Diag}(\sigma_1^2, \dots, \sigma_p^2, \underbrace{0, \dots, 0}_{m-p \text{ zeros}}) \quad (*)$$

$$\underbrace{\mathbf{U}\Sigma\mathbf{V}^T}_{\mathbf{A}} \cdot \underbrace{\mathbf{V}\Sigma^T\mathbf{U}^T}_{\mathbf{A}^T} = \mathbf{U}\Sigma\Sigma^T\mathbf{U}^T$$

$$\mathbf{A}^T\mathbf{A} = \mathbf{V}\mathbf{D}_2\mathbf{V}^T, \mathbf{D}_2 = \Sigma^T\Sigma = \text{Diag}(\sigma_1^2, \dots, \sigma_p^2, \underbrace{0, \dots, 0}_{n-p \text{ zeros}}) \quad (**)$$

$$\text{If } \Sigma = \begin{bmatrix} \boxed{\tilde{\mathbf{D}}} & \mathbf{0} \end{bmatrix}, \Sigma^T = \begin{bmatrix} \boxed{\tilde{\mathbf{D}}} \\ \mathbf{0} \end{bmatrix}, \Sigma\Sigma^T = \tilde{\mathbf{D}}^2 = \begin{bmatrix} \sigma_1^2 & & \\ & \ddots & \\ & & \sigma_p^2 & \\ & & & \mathbf{0}_{p \times p} \end{bmatrix}$$

Observations:

- (\*) is an eigendecomposition of  $\mathbf{A}\mathbf{A}^T$
- (\*\*) is an eigendecomposition of  $\mathbf{A}^T\mathbf{A}$
- The left singular vector matrix  $\mathbf{U}$  of  $\mathbf{A}$  is the eigenvector matrix of  $\mathbf{A}\mathbf{A}^T$
- The right singular vector matrix  $\mathbf{V}$  of  $\mathbf{A}$  is the eigenvector matrix of  $\mathbf{A}^T\mathbf{A}$
- $\sigma_1^2, \dots, \sigma_r^2$  are the nonzero eigenvalues of both  $\mathbf{A}\mathbf{A}^T$  and  $\mathbf{A}^T\mathbf{A}$

# Insights of the Proof of SVD

- To see the insights of the constructive proof, consider the special case of square nonsingular  $\mathbf{A}$
- $\mathbf{A}\mathbf{A}^T$  is PD with eigendecomposition

$$\mathbf{A}\mathbf{A}^T = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^T, \quad \lambda_1 \geq \dots \geq \lambda_n > 0$$

- Let  $\mathbf{\Sigma} = \text{Diag}(\sqrt{\lambda_1}, \dots, \sqrt{\lambda_m})$  and  $\mathbf{V} = \mathbf{A}^T \mathbf{U} \mathbf{\Sigma}^{-1}$
- It can be verified that  $\mathbf{U} \mathbf{\Sigma} \mathbf{V}^T = \mathbf{A}$ ,  $\mathbf{V}^T \mathbf{V} = \mathbf{I}$



Let  $A \in \mathbb{R}^{m \times n}$ .

## Proof of SVD

Since  $AA^T$  is symmetric and PSD, it has eigenvalues  $\lambda_1 \geq \dots \geq \lambda_r > 0 = \lambda_{r+1} = \dots = \lambda_m$  and eigendecomposition

$$AA^T = U \Lambda U^T = [U_1 \ U_2] \begin{bmatrix} \tilde{\Lambda} & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} U_1^T \\ U_2^T \end{bmatrix} = U_1 \tilde{\Lambda} U_1^T \quad (*)$$

where  $\tilde{\Lambda} = \text{Diag}(\lambda_1, \dots, \lambda_r)$

Note that

$$(U_2^T A)(U_2^T A)^T = U_2^T \underbrace{AA^T}_{(*)} U_2 = U_2^T U_1 \tilde{\Lambda} \underbrace{U_1^T U_2}_{=0} = 0$$

$$\Rightarrow U_2^T A = 0 \quad (**)$$

## Proof of SVD (cont'd)

Let  $\tilde{\Sigma} = \tilde{\Lambda}^{\frac{1}{2}} = \text{Diag}(\tilde{\lambda}_1, \dots, \tilde{\lambda}_r)$  and  $V_1 = A^T U_1 \tilde{\Sigma}^{-1} \in \mathbb{R}^{n \times r}$

$$\begin{aligned} V_1^T V_1 &= \tilde{\Sigma}^{-1} U_1^T \underbrace{A A^T}_{(*)} U_1 \tilde{\Sigma}^{-1} \quad (\text{similar to the special case}) \\ &= \tilde{\Sigma}^{-1} \underbrace{U_1^T U_1}_{I} \tilde{\Lambda} \underbrace{U_1^T U_1}_{I} \tilde{\Sigma}^{-1} \\ &= \begin{bmatrix} \frac{1}{\tilde{\lambda}_1} & & \\ & \ddots & \\ & & \frac{1}{\tilde{\lambda}_r} \end{bmatrix} \cdot \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_r \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\tilde{\lambda}_1} & & \\ & \ddots & \\ & & \frac{1}{\tilde{\lambda}_r} \end{bmatrix} = I \end{aligned}$$

Let  $V_2 \in \mathbb{R}^{n \times (n-r)}$  be s.t.  $V = [V_1 \ V_2]$  is orthogonal.

$$\text{Then, } U_1^T A V_1 = U_1^T \underbrace{A A^T}_{(*)} U_1 \tilde{\Sigma}^{-1} = \underbrace{U_1^T U_1}_{I} \tilde{\Lambda} \underbrace{U_1^T U_1}_{I} \tilde{\Sigma}^{-1} = \tilde{\Sigma} \quad (*)$$

$$U_1^T A V_2 = \underbrace{\tilde{\Sigma} \tilde{\Sigma}^{-1}}_{V_1^T} U_1^T A V_2 = 0 \quad (**)$$

## Proof of SVD (cont'd)

Finally,

$$U^T A V = \begin{bmatrix} U_1^T \\ U_2^T \end{bmatrix} A \begin{bmatrix} V_1 & V_2 \end{bmatrix} = \begin{bmatrix} \underbrace{U_1^T A V_1}_{(*)} & \underbrace{U_1^T A V_2}_{(*)} \\ \underbrace{U_2^T A V_1}_{(*)} & \underbrace{U_2^T A V_2}_{(*)} \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} \tilde{\Sigma} & 0 \\ 0 & 0 \end{bmatrix}}_{\Sigma}$$

$$\Leftrightarrow A = U \Sigma V^T$$

## SVD and Subspaces

$$A = U \Sigma V^T$$
$$A^T = V \Sigma^T U^T$$

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$$\text{SVD of } A^T$$

### Properties:

- (a)  $\mathcal{R}(\mathbf{A}) = \mathcal{R}(\mathbf{U}_1)$ ,  $\mathcal{R}(\mathbf{A})^\perp = \mathcal{R}(\mathbf{U}_2)$
- (b)  $\mathcal{R}(\mathbf{A}^T) = \mathcal{R}(\mathbf{V}_1)$ ,  $\mathcal{R}(\mathbf{A}^T)^\perp = \mathcal{N}(\mathbf{A}) = \mathcal{R}(\mathbf{V}_2)$
- (c)  $\text{rank}(\mathbf{A}) = r$  (the number of nonzero singular values)

" the number of nonzero eigenvalues of  $\mathbf{A}\mathbf{A}^T$  and  $\mathbf{A}^T\mathbf{A}$

$\dim \mathcal{R}(\mathbf{A}) = \dim \mathcal{R}(\mathbf{U}_1) = r$

- In practice, SVD can be used a numerical tool for computing bases of  $\mathcal{R}(\mathbf{A})$ ,  $\mathcal{R}(\mathbf{A})^\perp$ ,  $\mathcal{R}(\mathbf{A}^T)$ ,  $\mathcal{N}(\mathbf{A})$
- Using SVD, we can easily show the following facts:
  - $\text{rank}(\mathbf{A}^T) = \text{rank}(\mathbf{A})$
  - $\dim \mathcal{N}(\mathbf{A}) = n - \text{rank}(\mathbf{A})$

# Matrix Computations

## Chapter 6: Singular value, Singular Vectors, and Singular Value Decomposition

### Section 6.2 Matrix Norms

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# Matrix Norms

**Definition:** A function  $f : \mathbb{R}^{m \times n} \rightarrow \mathbb{R}$  is a **matrix norm** if (i)  $f(\mathbf{A}) \geq 0$  for all  $\mathbf{A}$ ; (ii)  $f(\mathbf{A}) = 0$  if and only if  $\mathbf{A} = \mathbf{0}$ ; (iii)  $f(\mathbf{A} + \mathbf{B}) \leq f(\mathbf{A}) + f(\mathbf{B})$  for any  $\mathbf{A}, \mathbf{B}$ ; (iv)  $f(\alpha \mathbf{A}) = |\alpha|f(\mathbf{A})$  for any  $\mathbf{A}$  and any scalar  $\alpha$

- For example, the Frobenius norm  $\|\mathbf{A}\|_F = \sqrt{\sum_{i,j} |a_{ij}|^2} = [\text{tr}(\mathbf{A}^T \mathbf{A})]^{1/2}$  is a norm
- Induced norm or operator norm: the function

$$f(\mathbf{A}) = \max_{\|\mathbf{x}\|_\beta \leq 1} \|\mathbf{Ax}\|_\alpha$$

where  $\|\cdot\|_\alpha, \|\cdot\|_\beta$  denote any vector norms

- Matrix norms induced by the vector  $p$ -norm ( $p \geq 1$ ):

$$\|\mathbf{A}\|_p = \sup_{\mathbf{x} \neq \mathbf{0}} \frac{\|\mathbf{Ax}\|_p}{\|\mathbf{x}\|_p} = \max_{\|\mathbf{x}\|_p \leq 1} \|\mathbf{Ax}\|_p$$

- $\|\mathbf{A}\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^m |a_{ij}|$
- $\|\mathbf{A}\|_\infty = \max_{1 \leq i \leq m} \sum_{j=1}^n |a_{ij}|$
- $\|\mathbf{A}\|_2 = ?$

# Matrix 2-Norm

The **Matrix 2-norm** or **spectral norm** is given by

$$\|\mathbf{A}\|_2 = \sigma_{\max}(\mathbf{A}) = \sqrt{\lambda_{\max}(\mathbf{A}\mathbf{A}^T)} = \sqrt{\lambda_{\max}(\mathbf{A}^T\mathbf{A})}$$

Prove this using SVD  $\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$

For any  $\mathbf{x} \in \mathbb{R}^n$  with  $\|\mathbf{x}\|_2 \leq 1$ ,

$$\begin{aligned} \|\mathbf{A}\mathbf{x}\|_2^2 &= \|\mathbf{U}\mathbf{\Sigma}\mathbf{V}^T\mathbf{x}\|_2^2 \stackrel{\substack{\uparrow \\ \text{orthogonal}}}{=} \|\mathbf{\Sigma}(\mathbf{V}^T\mathbf{x})\|_2^2 \leq \sigma_1^2 \|\mathbf{V}^T\mathbf{x}\|_2^2 \\ &\stackrel{\substack{\uparrow \\ \text{orthogonal}}}{=} \sigma_1^2 \|\mathbf{x}\|_2^2 \leq \sigma_1^2 \end{aligned}$$

where the equality holds when  $\mathbf{x} = \mathbf{v}_1$

Implication to linear systems: Let  $\mathbf{y} = \mathbf{A}\mathbf{x}$  be a linear system. Under the input energy constraint  $\|\mathbf{x}\|_2 \leq 1$ , the system output energy  $\|\mathbf{y}\|_2^2$  is maximized when  $\mathbf{x}$  is chosen as the 1st right singular vector

**Corollary:**  $\min_{\|\mathbf{x}\|_2=1} \|\mathbf{A}\mathbf{x}\|_2 = \sigma_{\min}(\mathbf{A})$  if  $m \geq n$   
↳ not matrix norm

## Properties of Matrix 2-Norm

- $\|\mathbf{AB}\|_2 \leq \|\mathbf{A}\|_2 \|\mathbf{B}\|_2$ 
  - In fact,  $\|\mathbf{AB}\|_p \leq \|\mathbf{A}\|_p \|\mathbf{B}\|_p$  for any  $p \geq 1$
- $\|\mathbf{Ax}\|_2 \leq \|\mathbf{A}\|_2 \|\mathbf{x}\|_2$ 
  - A special case of the first property
- $\|\mathbf{QAW}\|_2 = \|\mathbf{A}\|_2$  for any orthogonal  $\mathbf{Q}, \mathbf{W}$ 
  - We also have  $\|\mathbf{QAW}\|_F = \|\mathbf{A}\|_F$  for any orthogonal  $\mathbf{Q}, \mathbf{W}$
- $\|\mathbf{A}\|_2 \leq \|\mathbf{A}\|_F \leq \sqrt{p} \|\mathbf{A}\|_2$  (here  $p = \min\{m, n\}$ )

$$\begin{aligned}
 \|\mathbf{A}\|_F^2 &= \text{tr}(\mathbf{A}^T \mathbf{A}) \underset{\mathbf{A} = \mathbf{U} \Sigma \mathbf{V}^T}{=} \text{tr}(\mathbf{V} \Sigma^T \Sigma \mathbf{V}^T) = \text{sum of eigenvalues of } \Sigma^T \Sigma \\
 &\quad \text{eigendecomposition of } \mathbf{A}^T \mathbf{A} \\
 &= \text{tr}(\Sigma^T \Sigma) = \|\Sigma\|_F^2 = \underbrace{\sigma_1^2 + \dots + \sigma_p^2}_{= \|\mathbf{A}\|_2^2} \leq p \sigma_1^2 \geq \sigma_1^2
 \end{aligned}$$



# Schatten $p$ -Norm

- The function

$$f(\mathbf{A}) = \left( \sum_{i=1}^{\min\{m,n\}} \sigma_i(\mathbf{A})^p \right)^{1/p}, \quad p \geq 1,$$

is a matrix norm called the Schatten  $p$ -norm

- Nuclear norm:

$$\|\mathbf{A}\|_* = \sum_{i=1}^{\min\{m,n\}} \sigma_i(\mathbf{A}) = \text{tr}(\sqrt{\mathbf{A}^T \mathbf{A}})$$

- A special case of the Schatten  $p$ -norm
- A way to prove the nuclear norm is a matrix norm:
  - Show that  $f(\mathbf{A}) = \max_{\|\mathbf{B}\|_2 \leq 1} \text{tr}(\mathbf{B}^T \mathbf{A})$  is a norm
  - Show that  $f(\mathbf{A}) = \sum_{i=1}^{\min\{m,n\}} \sigma_i$
- Applications in rank approximation, e.g., for compressive sensing and matrix completion<sup>1</sup>

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<sup>1</sup>B. Recht, M. Fazel, and P. A. Parrilo, "Guaranteed minimum-rank solutions of linear matrix equations via nuclear norm minimization," *SIAM Review*, vol. 52, no. 3, pp. 471–501, 2010.

## Schatten $p$ -Norm

- $\text{rank}(\mathbf{A})$  is *nonconvex* in  $\mathbf{A}$  and is arguably hard to do optimization with it
- **Idea:** The rank function can be expressed as

$$\text{rank}(\mathbf{A}) = \sum_{i=1}^{\min\{m,n\}} \mathbb{1}\{\sigma_i(\mathbf{A}) \neq 0\},$$

└ true 1  
false 0

and we may approximate it via

$$f(\mathbf{A}) = \sum_{i=1}^{\min\{m,n\}} \varphi(\sigma_i(\mathbf{A}))$$

for some friendly function  $\varphi$

- Using  $\varphi(z) = z$ ,  $f(\mathbf{A})$  becomes the nuclear norm

$$\|\mathbf{A}\|_* = \sum_{i=1}^{\min\{m,n\}} \sigma_i(\mathbf{A})$$

which is *convex* in  $\mathbf{A}$