## CS100 Lecture 10

C Summary

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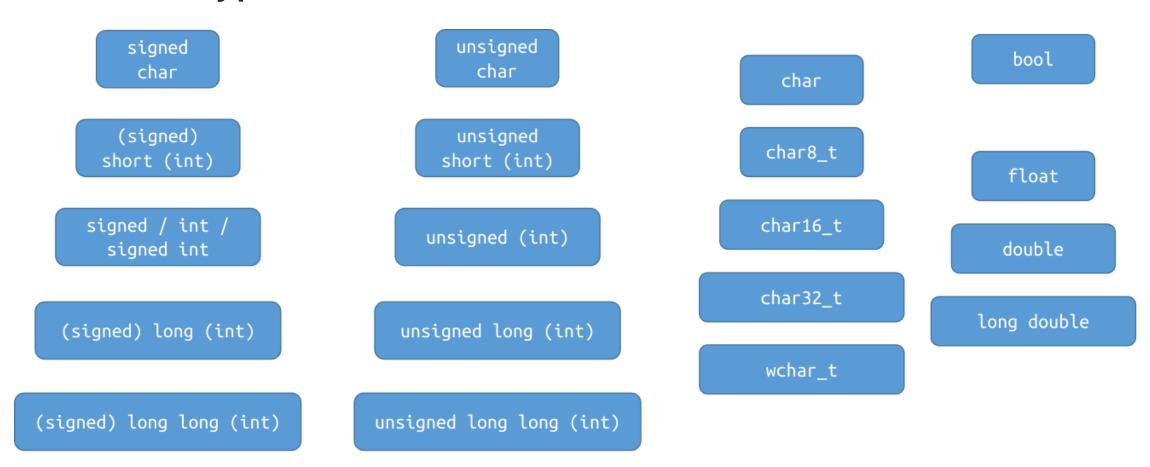
# **C** Summary

### **Types**

Types are fundamental to any program: They tell us what our data mean and what operations we can perform on those data.

C is a **statically-typed** language: The type of every expression (except those involving VLAs) is known at **compile-time**.

## Arithmetic types



## **Arithmetic types**

- 1 == sizeof(char) <= sizeof(short) <= sizeof(int) <= sizeof(long) <= sizeof(long long)
- sizeof(signed T) == sizeof(unsigned T) for every T  $\in$  { char, short, int, long, long long }
- short and int are at least 16 bits. long is at least 32 bits. long long is at least 64 bits.
- Range of signed integer types of n bits:  $\left[-2^{n-1}, 2^{n-1} 1\right]$ . Range of unsigned integer types of n bits:  $\left[0, 2^n 1\right]$ .
- Whether char is signed or not is implementation-defined.
- Signed integer overflow is **undefined behavior**.
- Unsigned integers **never overflow**: It is performed modulo  $2^n$ , where n is the number of bits of that type.

## Pointer types

### PointeeType \*

- For  $T \neq U$ , T \* and U \* are different types.
- The value of a pointer of type T \* is the address of an object of type T.
- **Null pointer**: The pointer holding the **null pointer value**, which is a special value indicating that the pointer is "pointing nowhere".
  - A null pointer can be obtained from NULL.
- &var returns the address of var. The return type is a pointer type whose pointee type is the type of var.
- Only when a pointer is actually pointing to an object is it dereferenceable.
- \*ptr , where ptr is not dereferenceable, is undefined behavior.

## **Array types**

```
ElemType [N]
```

- T [N], U [N] and T [M] are different types for  $T \neq U$  and  $N \neq M$ .
- N should be compile-time constant. Otherwise it is a VLA.
- Valid index range: [0, N). Subscript out of range is **undefined behavior**.
- Array-to-pointer conversion: T a[N], a  $\rightarrow$  &a[0].
  - o fun(a)
  - $\circ$  T \*p = a
  - $\circ$  a[i]  $\Rightarrow$  \*(a+i)

Pointer to array: T (\*)[N] . Array of pointers: T \*[N] .

## struct types

A special data type consisting of a sequence of **members**.

- The type name is struct StructName.
- sizeof(struct X)  $\geqslant \sum_{\text{member} \in X}$  sizeof(member)

### **Variables**

Declare a variable: Type varName

- ElemType varName[N] for array type ElemType[N].
- T (\*varName)[N] for pointer to array type T (\*)[N].

Initialize a variable: = initializer

- Brace-enclosed list initializer for arrays and struct s: = { ... }.
- Designators for arrays: = {[3] = 5, [7] = 4}
- Designators for struct S: = {.mem1 = x, .mem2 = y}.

### **Initialization**

If a variable is declared without explicit initializer:

- For global or local static variables, they are **empty-initialized**:
  - ø for integer types,
  - +0.0 for floating-point types,
  - null pointer value for pointer types.
- For local non-static variables, they are **uninitialized**, holding indeterminate values.

These rules apply recursively to the elements of arrays and the members of struct s.

Any use of the value of an uninitialized variable is undefined behavior.

## **Expressions**

Expressions = operators + operands.

• Operator precedence, associativity, and evaluation order of operands

- The only four operators whose operands have deterministic evaluation order:
  - && and || : short-circuit evaluation
  - o ?:
  - o , (not in a function call or in an initializer list)

## **Expressions**

- If the evaluation order of A and B is unspecified, and if
  - o both A and B contain a write to an object, or
  - one of them contains a write to an object, and the other one contains a read to that object

then the behavior is undefined.

## **Arithmetic operators**

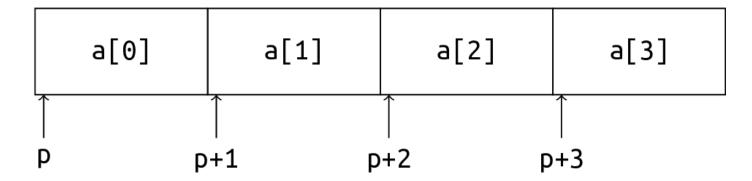
```
+, -, *, /, %
```

- Division: truncated towards zero for integer division.
- Remainder: (a / b) \* b + (a % b) == a always holds.
- For +, -, \* and /, the operands undergo a series of type conversions to a common type.

Bitwise operators: ~ , & , | , ^ , << , >>

Compound assignment operators: a op= b is equivalent to a = a op b.

### Pointer arithmetic



- Pointer arithmetic: p++ , ++p , p-- , --p , p + i , i + p , p i , p += i , p -= i , p1 p2 .
- Pointer arithmetic uses the unit of the pointed-to type.
  - o p + i == (char \*)p + i \* sizeof(\*p)
- Pointer arithmetic must be performed within an array (including its past-the-end position), otherwise **the behavior is undefined**.

### **Operators**

```
++ , --
```

- ++a and --a returns the value of a after incrementation/decrementation.
- a++ and a-- returns the original value of a.

• The operands undergo a series of type conversions to a common type before comparison.

### **Operators**

Member access: obj.member.

Member access through pointer: ptr->member , which is equivalent to (\*ptr).member .

• . has higher precedence than \*, so the parentheses around \*ptr are necessary.

### **Control flow**

if (cond) stmt1
if (cond) stmt1 else stmt2
for (init\_expr; cond; inc\_expr) loop\_body
while (cond) loop\_body
do loop\_body while (cond);
switch (expr) { ... }
break and continue

### **Functions**

Function declaration: ReturnType FunctionName(Parameters);

• Parameter names are not necessary, but types are required.

Function definition: ReturnType FunctionName(Parameters) { FunctionBody }

• A definition is also a declaration.

### **Functions**

- Argument passing:
  - Use the argument to initialize the parameter.
  - The semantic is **copy**.
  - An array argument is always converted to a pointer: One can never declare an array parameter.

### The main function

Entry point of the program (after initialization of all global and local static variables).

One of the following signatures:

- int main(void) { ... }
- int main(int argc, char \*\*argv) { ... }, for passing command-line arguments.
- /\* another implementation-defined signature \*/

Return value: 0 to indicate that the program exits successfully.

## **Standard library**

- IO library <stdio.h>: scanf, printf, fgets, puts, putchar, getchar, ...
- String library <string.h>: strlen , strcpy , strcmp , strchr , ...
- Character classification <ctype.h>: isdigit, isalpha, tolower, ...
- <stdlib.h> : Several general-purpose functions: malloc / free , rand , ...
- limits.h> : Macros like INT\_MAX that describe the limits of built-in types.
- <math.h> : Mathematical functions like sqrt , sin , acos , exp , ...

## **Example: Vector**

A "vector" in linear algebra:

$$\mathbf{x} = egin{bmatrix} x_1 \ dots \ x_n \end{bmatrix}.$$

It is a sequence of n numbers, where n is its dimension.

## **Example: Vector**

```
struct Vector {
  double *entries;
  size_t dimension;
};
```

Do not name them with x and n!

[Best practice] Use meaningful names in programs.

#### Creation and destruction

#### Usage:

```
struct Vector v = create_vector(10);
// some operations ...
destroy_vector(&v);
```

The default copy semantics of Vector is not satisfactory:

```
struct Vector v = something();
struct Vector u = v;
```

Now u.entries and v.entries point to the same memory block!

```
destroy_vector(&u);
destroy_vector(&v); // undefined behavior: double free!
```

```
void vector_assign(struct Vector *to, const struct Vector *from) {
  to->entries = malloc(from->dimension * sizeof(double));
  memcpy(to->entries, from->entries, from->dimension * sizeof(double));
  to->dimension = from->dimension;
}
```

Is this correct?

free the memory block that is not used anymore!

```
void vector_assign(struct Vector *to, const struct Vector *from) {
  free(to->entries); // Don't forget this!!
  to->entries = malloc(from->dimension * sizeof(double));
  memcpy(to->entries, from->entries, from->dimension * sizeof(double));
  to->dimension = from->dimension;
}
```

Is this correct?

```
void vector_assign(struct Vector *to, const struct Vector *from) {
  free(to->entries); // Don't forget this!!
  to->entries = malloc(from->dimension * sizeof(double));
  memcpy(to->entries, from->entries, from->dimension * sizeof(double));
  to->dimension = from->dimension;
}
```

What happens if to == from ?

• This is not impossible. Consider vector\_assign(&vecs[i], &vecs[j]) where i
and j have a chance to be equal.

```
void vector_assign(struct Vector *to, const struct Vector *from) {
  free(to->entries); // Don't forget this!!
  to->entries = malloc(from->dimension * sizeof(double));
  memcpy(to->entries, from->entries, from->dimension * sizeof(double));
  to->dimension = from->dimension;
}
```

What happens if to == from ?

- This is not impossible. Consider vector\_assign(&x[i], &x[j]) where i and j have a chance to be equal.
- The memory block is free d, and the data are gone.

```
void vector_assign(struct Vector *to, const struct Vector *from) {
  if (to == from)
    return;
  free(to->entries); // Don't forget this!!
  to->entries = malloc(from->dimension * sizeof(double));
  memcpy(to->entries, from->entries, from->dimension * sizeof(double));
  to->dimension = from->dimension;
}
```

Why do we declare the parameters as pointers?

```
void vector_assign(struct Vector *to, const struct Vector *from) {
   if (to == from)
      return;
   free(to->entries); // Don't forget this!!
   to->entries = malloc(from->dimension * sizeof(double));
   memcpy(to->entries, from->entries, from->dimension * sizeof(double));
   to->dimension = from->dimension;
}
```

Why do we declare the parameters as pointers?

- For to , we need to modify it.
- For from , this is a read-only operation. Pass the address to avoid copies.

## **Equality comparison**

```
bool vector_equal(const struct Vector *lhs, const struct Vector *rhs) {
  if (lhs->dimension != rhs->dimension)
    return false;
  for (size_t i = 0; i != lhs->dimension; ++i)
    if (lhs->entries[i] != rhs->entries[i])
    return false;
  return true;
}
```

Here we use  $|\cdot|$  to compare two double s directly. It's better to use  $|a-b|>\epsilon$ , considering the floating-point errors.

1hs and rhs are pointers, to avoid unnecessary copies.

## Basic operations on Vector

```
struct Vector vector add(const struct Vector *lhs, const struct Vector *rhs) {
  assert(lhs->dimension == rhs->dimension);
  struct Vector result = create vector(lhs->dimension);
 for (size_t i = 0; i != lhs->dimension; ++i)
    result.entries[i] = lhs->entries[i] + rhs->entries[i];
 return result;
struct Vector vector scale(const struct Vector *lhs, double scale) {
  struct Vector result = create_vector(lhs->dimension);
 for (size_t i = 0; i != lhs->dimension; ++i)
    result.entries[i] = lhs->entries[i] * scale;
 return result;
```

For vector\_add, our design is to claim that "the behavior is undefined if the vectors have different dimensions".

## Dot product, norm and distance ( $\ell_2$ )

```
double vector dot product(const struct Vector *lhs, const struct Vector *rhs) {
  assert(lhs->dimension == rhs->dimension);
 double result = 0;
 for (size t i = 0; i != lhs->dimension; ++i)
    result += lhs->entries[i] * rhs->entries[i];
  return result;
double vector_norm(const struct Vector *vec) {
  return sqrt(vector dot product(vec, vec));
double vector distance(const struct Vector *lhs, const struct Vector *rhs) {
  struct Vector diff = vector_minus(lhs, rhs); // Define this on your own.
  return vector norm(&diff);
```

For vector\_dot\_product, our design is to claim that "the behavior is undefined if the vectors have different dimensions".

### Print a Vector

```
void print_vector(const struct Vector *vec) {
  putchar('(');
  if (vec->dimension > 0) {
    printf("%lf", vec->entries[0]);
    for (size_t i = 1; i != vec->dimension; ++i)
        printf(", %lf", vec->entries[i]);
  }
  putchar(')');
}
```

#### What we have done

```
struct Vector {
 double *entries;
  size t dimension;
struct Vector create_vector(size_t n);
void destroy vector(struct Vector *vec);
void vector_assign(struct Vector *to, const struct Vector *from);
bool vector equal(const struct Vector *lhs, const struct Vector *rhs);
struct Vector vector add(const struct Vector *lhs, const struct Vector *rhs);
struct Vector vector minus(const struct Vector *lhs, const struct Vector *rhs);
struct Vector vector_scale(const struct Vector *lhs, double scale);
double vector dot product(const struct Vector *lhs, const struct Vector *rhs);
double vector_norm(const struct Vector *vec);
double vector_distance(const struct Vector *lhs, const struct Vector *rhs);
void print vector(const struct Vector *vec);
```

## Problems of the current implementation

- 1. The call to create\_vector is not mandatory. One can easily create a Vector with some garbage values.
- 2. destroy\_vector is not called automatically. If we forget to call it manually, memory leak happens.
- 3. We always need to pass the address of Vector's to these functions. The extra & and \* are annoying.
- 4. The "deep copy" is implemented by a function, but the default copy semantics are still there. If we forget to call vector\_assign when copying a Vector, disaster will happen.
- 5. No prevention from modifying a Vector : Disaster is caused easily by a simple free(vec->entries); .

## Problems of the current implementation

6. The named functions are inconvenient: To compute  ${f u}^T({f v}+2{f w})$ , we need to write

```
struct Vector scaled = vector_scale(&w, 2);
struct Vector added = vector_add(&v, &scaled);
return vector_dot_product(&u, &added);
```

Can we express it directly by return u \* (v + 2 \* w); ?

We will see the solutions to these problems in C++, by data abstraction, and by OOP (object-oriented programming).

### Enter the world of C++ ...

From *The Design and Evolution of C++*, by Bjarne Stroustrup who invented C++:

C++ is a general-purpose programming language that

- is a better C, and
- supports data abstraction, and
- supports object-oriented programming.

```
#include <iostream>
int main() {
   std::cout << "Hello world\n";
   return 0;
}</pre>
```