CS150A Database

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Oct. 12, 2024

Today:

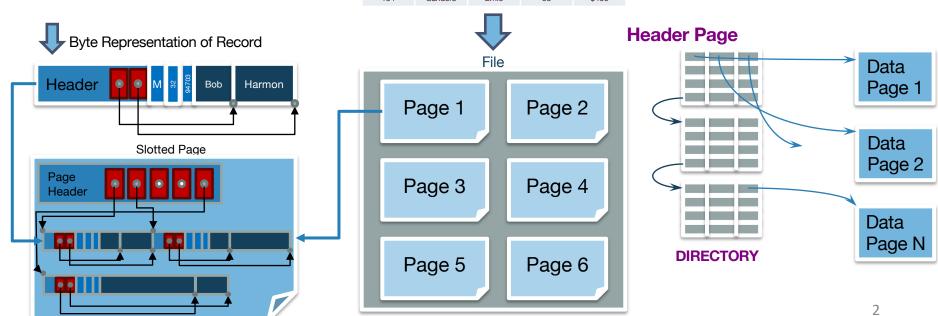
- Index Files:
 - ISAM and B+ Tree

Readings:

 Database Management Systems (DBMS), Chapter 10

Summary

- Record Age Salary SSN Last **First** Name Name Adams Elmo 31 \$400 Μ 32 Bob Harmon 400 443 Grouch Oscar 32 \$300 244 Oz 55 \$140 Int Bert Varchar Varchar Char Int 134 Sanders Ernie 55 \$400
- Tables stored as logical files
 - Consist of pages
 - Pages contain a collection of records



Cost of Operations Complete

Heap File



•	R· T	Γhe	num	her	\circ f	data	blo	cks
•	D.		Hulli	NCI	OI.	uala	יטוט	cno

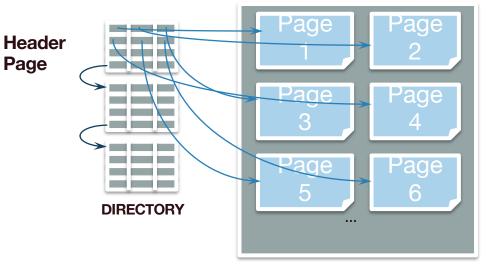
- R: Number of records per block
- D: Average time to read/write disk block

	Heap File	Sorted File
Scan all records	B*D	B*D
Equality Search	0.5*B*D	(log ₂ B)*D
Range Search	B*D	((log ₂ B)+pages)*D
Insert	2*D	((log ₂ B)+B)*D
Delete	(0.5*B+1)*D	((log ₂ B)+B)*D

Reminder on Heap Files

Page

- Two access APIs:
 - fetch by recordId (pageId, slotId)
 - scan (starting from some page)



Wouldn't it be nice...

- ...if we could look things up by value?
- Toward a Declarative access API



- But ... efficiency?
 - "If you don't find it in the index, look very carefully through the entire catalog."
 - —Sears, Roebuck, and Co., Consumers' Guide, 1897

We've seen this before

- Data structures ... in RAM:
 - Search trees (Binary, AVL, Red-Black, ...)
 - Hash tables

- Needed: disk-based data structures
 - "paginated": made up of disk pages!

Index

An **index** is data structure that enables fast **lookup** and **modification** of **data entries** by **search key**

- Lookup: may support many different operations
 - Equality, 1-d range, 2-d region, ...
- Search Key: any subset of columns in the relation
 - Do not need to be unique
 - –e.g. (firstname) or (firstname, lastname)

Index Part 2

An **index** is data structure that enables fast **lookup** and **modification** of **data entries** by **search key**

- Data Entries: items stored in the index
 - Assume for today: a pair (k, recordId) ...
 - Pointers to records in Heap Files!
 - Easy to generalize later
- Modification: want to support fast insert and delete

Many Types of indexes exist: B+-Tree, Hash, R-Tree, GiST, ...

Simple Idea?

Input Heap File



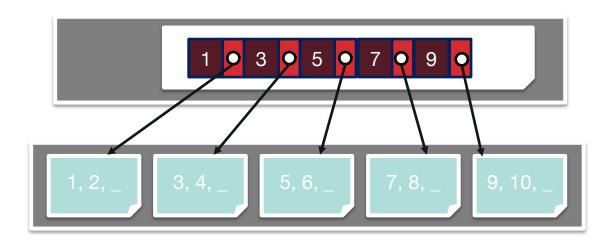
- Step 1: Sort heap file & leave some space
 - Pages physically stored in logical order (sequential access)
 - Do we need "next" pointers to link pages?
 - No. Pages are physically sorted in logical order



- **Step 2**: Build the index data structure over this...
 - Why not just use binary search in this heap file?
 - Fan-out of 2 → deep tree → lots of I/Os
 - Examine entire records just to read key during search

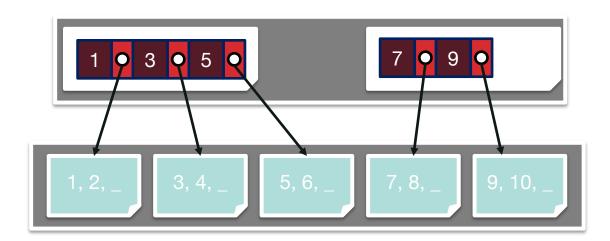
Build a high fan-out search tree

- Start simple: Sorted (key, page id) file
 - No record data
 - Binary search in the key file. Better!
 - Forgot: Need to break across pages!



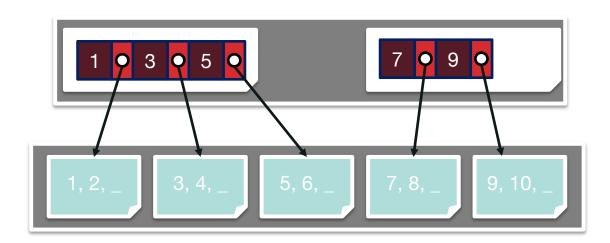
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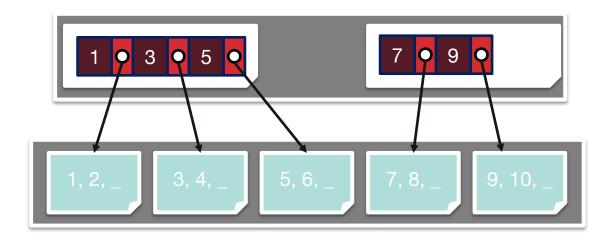
Build a high fan-out search tree Part 2

- Start simple: Sorted (key, page id) file
 - No record data
 - Binary search in the key file. Better!
 - Complexity?



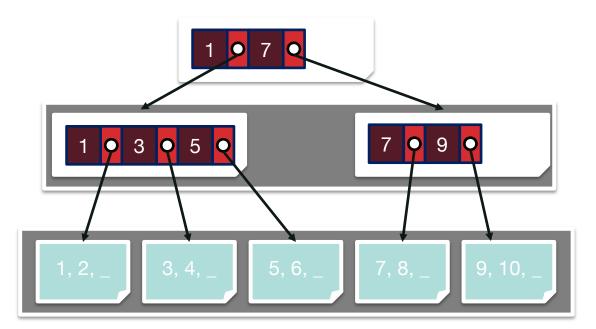
Build a high fan-out search tree Part 3

- Start simple: Sorted (key, page id) file
 - No record data
 - Binary search in the key file. Better!
 - Complexity: Still binary search, just a constant factor smaller input



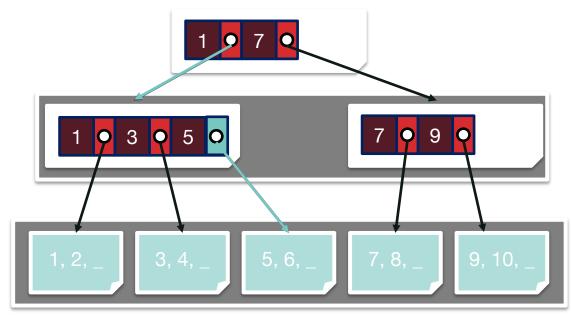
Build a high fan-out search tree Part 4

- Recursively "index" key file
- Key Invariant:
 - Node [..., (K_L, P_L) , (K_R, P_R) , ...] \rightarrow All tuples in range $K_L \le K < K_R$ are in tree P_L



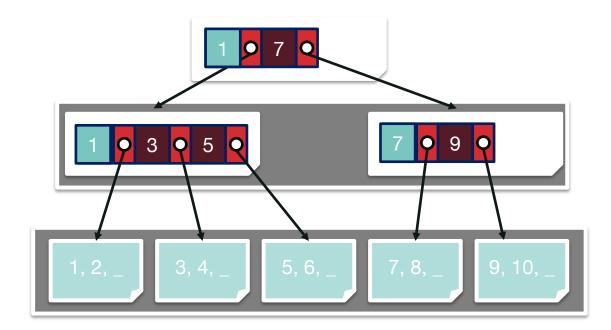
Search a high fan-out search tree

- Searching for 5?
 - Binary Search each node (page) starting at root
 - Follow pointers to next level of search tree
- Complexity? O(log_F(#Pages))



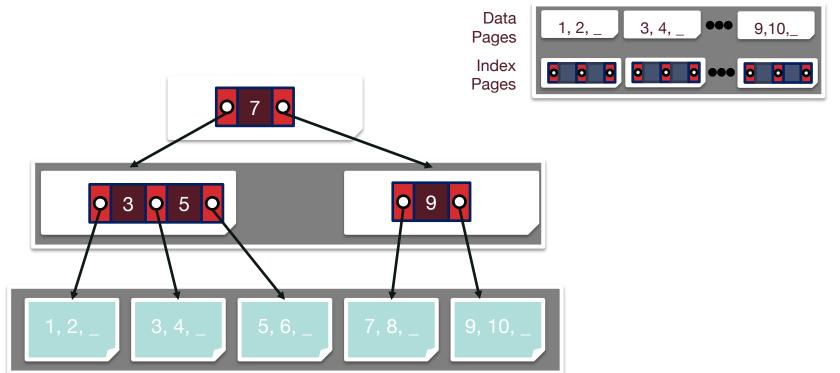
Left Key Optimization?

- Optimization
 - Do we need the left most key?



Build a high fan-out search tree

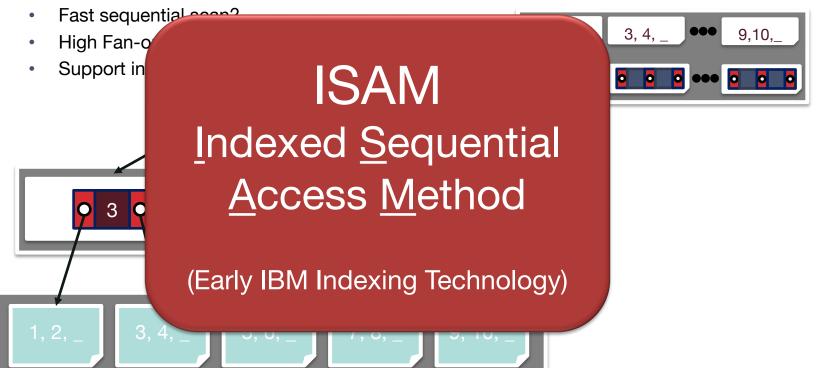
Disk Layout? All in a single file, Data Pages first.



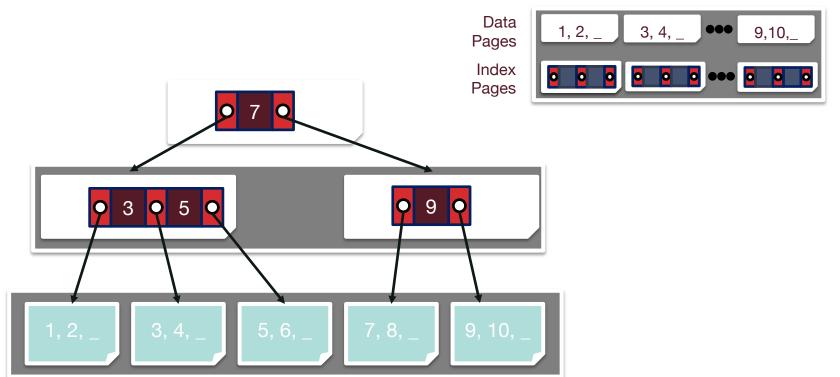
Status Check

Indexed File

Some design goals:

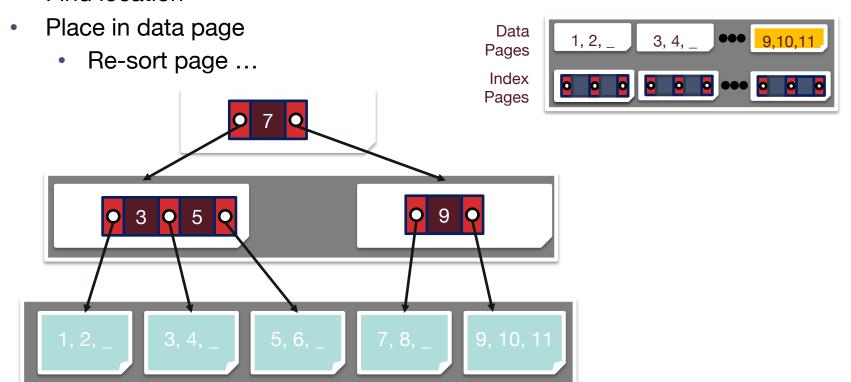


Insert 11, Before



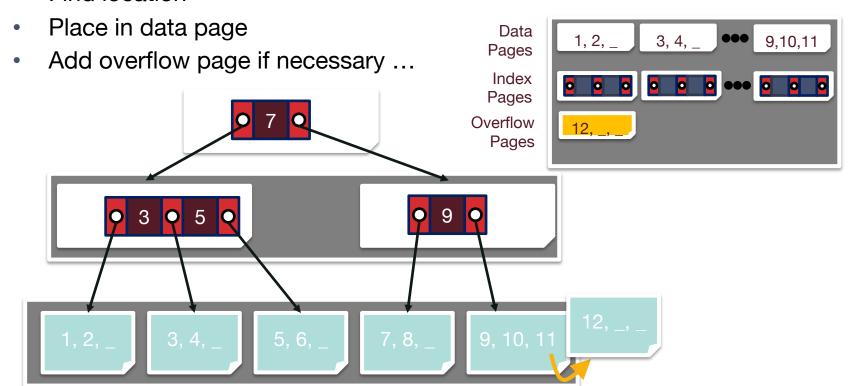
Insert 11, After

Find location



Insert 12?

Find location



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Recap: ISAM

- Data entries in sorted heap file
- High fan-out static tree index
- Fast search + good locality
 - Assuming nothing changes
- Insert into overflow pages

A Note of Caution

- ISAM is an old-fashioned idea
 - Introduced by IBM in 1960s
 - B+ trees are usually better, as we'll see
 - Though not always (← we'll come back to this)
- But, it's a good place to start
 - Simpler than B+ tree, many of the same ideas
- Upshot
 - Do understand ISAM, and tradeoffs with B+ trees

B+-TREE

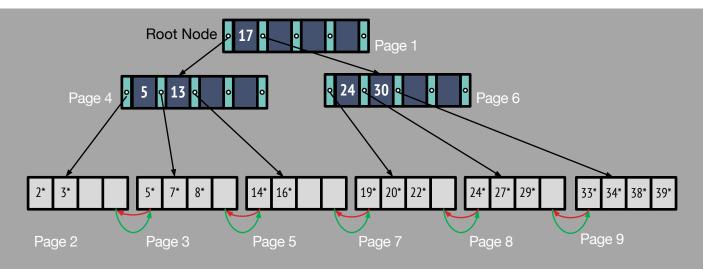
Enter the B+ Tree

- Similar to ISAM
 - Same interior node structure
 - Key, Page Ptr> pairs with same key invariant
 - Same search routine as before

Dynamic Tree Index

- Always Balanced
- Support efficient insertion & deletion
 - Grows at root not leaves!
- "+"? B-tree that stores data entries in leaves only

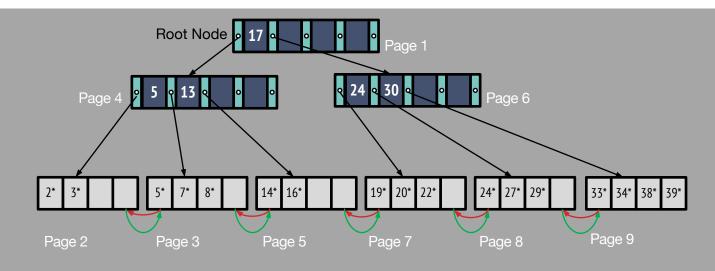
Example of a B+ Tree



- Occupancy Invariant
 - Each interior node is at least partially full:
 - d <= #entries <= 2d
 - d: order of the tree (max fan-out = 2d + 1)
- Data pages at bottom need not be stored in logical order

Next and prev pointers

Sanity Check



What is the value of d?

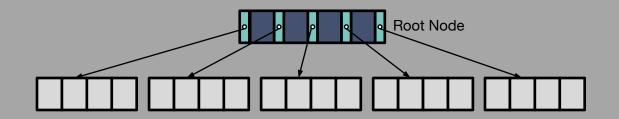
What about the root?

The root is special

Why not in sequential order?

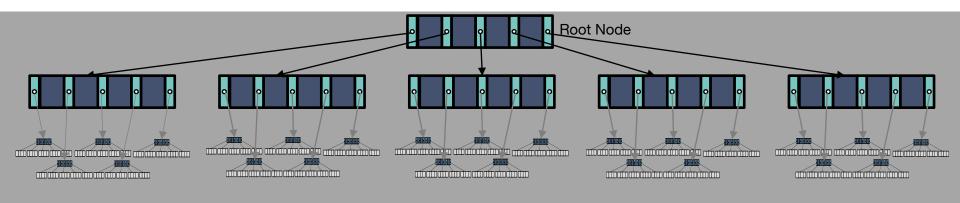
Data pages allocated dynamically

B+ Trees and Scale



- How big is a height 1 B+ tree
 - $d = 2 \rightarrow Fan-out?$
 - Fan-out = 2d + 1 = 5
 - **Height 1:** 5 x 4 = 20 Records

B+ Trees and Scale Part 2

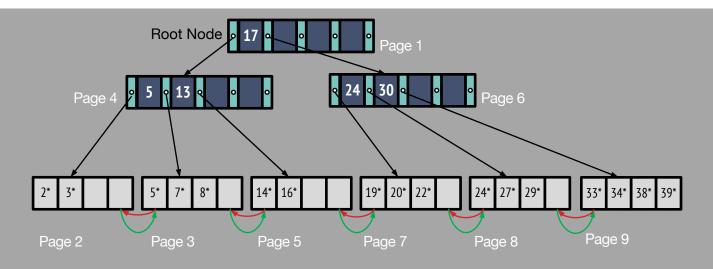


- How big is a height 3 B+ tree
 - $d = 2 \rightarrow Fan-out$?
 - Fan-out = 2d + 1 = 5
 - Height 3:

B+ Trees in Practice

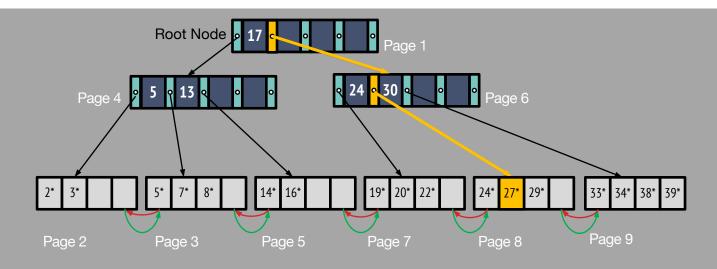
- Typical order: 1600. Typical fill-factor: 67%.
 - average fan-out = 2144
 - (assuming 128 Kbytes pages at 40Bytes per record)
- At typical capacities
 - Height 1: 2144² = 4,596,736 records
 - Height 2: 2144³ = **9,855,401,984 records**

Searching the B+ Tree



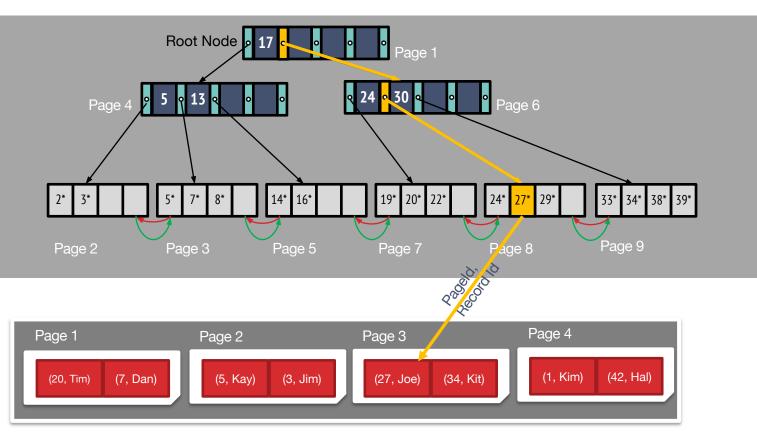
- Same as ISAM
- Find key = 27
 - Find split on each node (Binary Search)
 - Follow pointer to next node

Searching the B+ Tree: Find 27

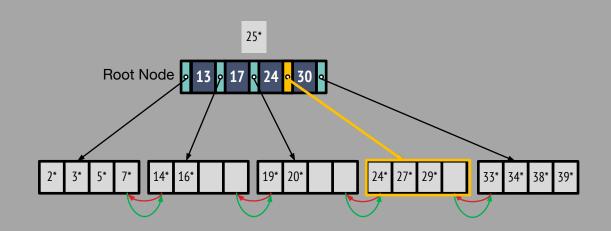


- Same as ISAM
- Find key = 27
 - Find split on each node (Binary Search)
 - Follow pointer to next node

Searching the B+ Tree: Fetch Data

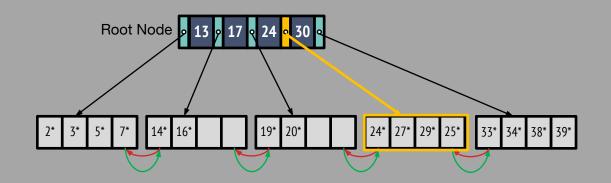


Inserting 25* into a B+ Tree Part 1



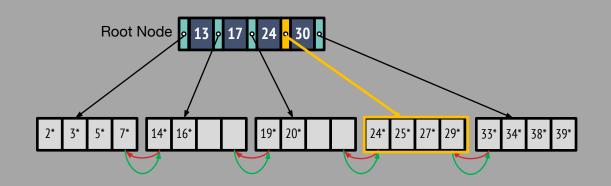
Find the correct leaf

Inserting 25* into a B+ Tree Part 2



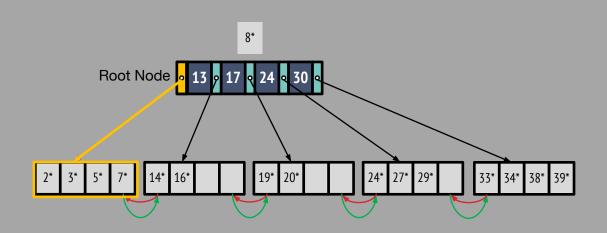
- Find the correct leaf
- If there is room in the leaf just add the entry

Inserting 25* into a B+ Tree Part 3



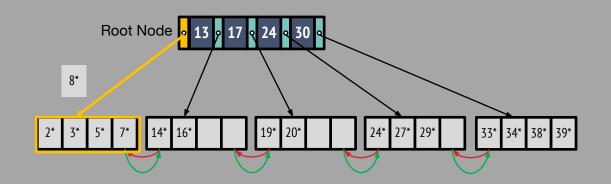
- Find the correct leaf
- If there is room in the leaf just add the entry
 - Sort the leaf page by key

Inserting 8* into a B+ Tree: Find Leaf



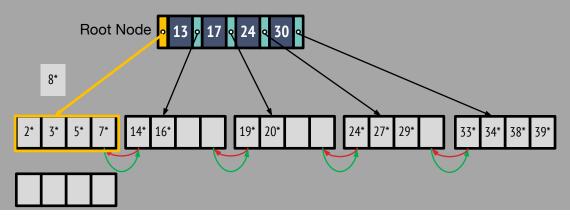
Find the correct leaf

Inserting 8* into a B+ Tree: Insert



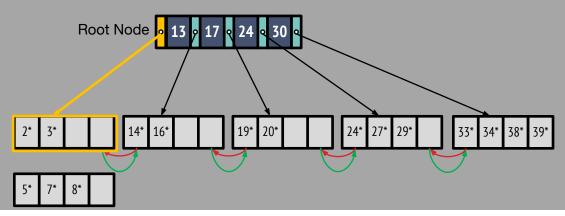
- Find the correct leaf
 - Split leaf if there is not enough room

Inserting 8* into a B+ Tree: Split Leaf



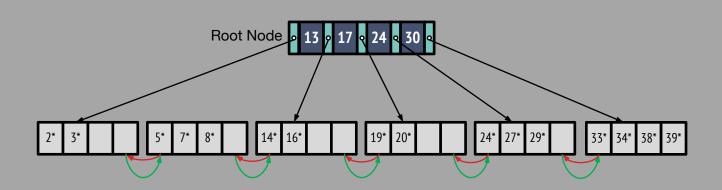
- Find the correct leaf
 - Split leaf if there is not enough room
 - Redistribute entries evenly

Inserting 8* into a B+ Tree: Split Leaf, cont



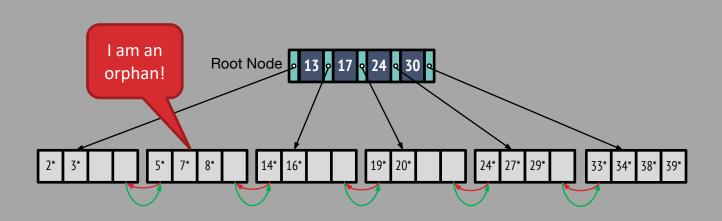
- Find the correct leaf
 - Split leaf if there is not enough room
 - Redistribute entries evenly
 - Fix next/prev pointers

Inserting 8* into a B+ Tree: Fix Pointers



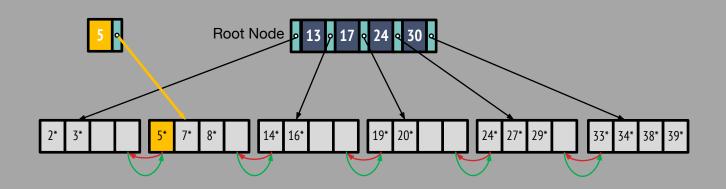
- Find the correct leaf
 - Split leaf if there is not enough room
 - Redistribute entries evenly
 - Fix next/prev pointers

Inserting 8* into a B+ Tree: Mid-Flight



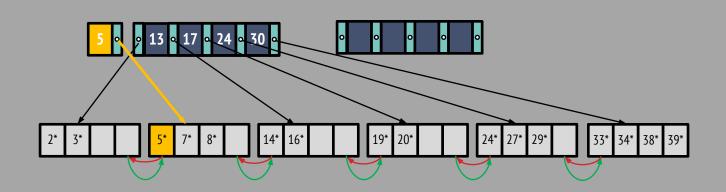
Something is still wrong!

Inserting 8* into a B+ Tree: Copy Middle Key



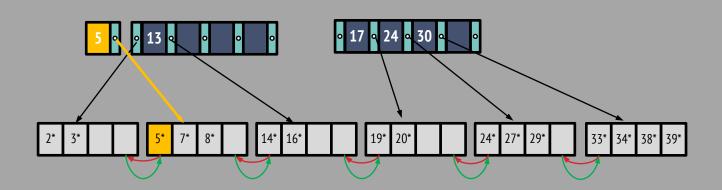
- Copy up from leaf the middle key
- No room in parent? Recursively split index nodes

Inserting 8* into a B+ Tree: Split Parent, Part 1



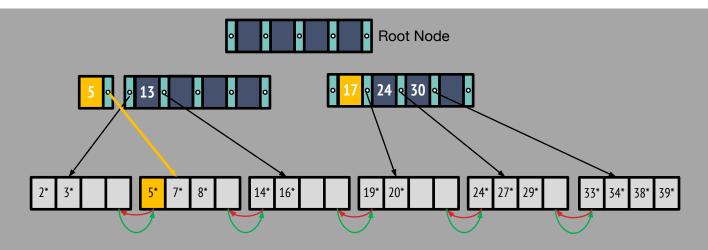
- Copy up from leaf the middle key
- No room in parent? Recursively split index nodes
 - Redistribute the rightmost d keys

Inserting 8* into a B+ Tree: Split Parent, Part 2



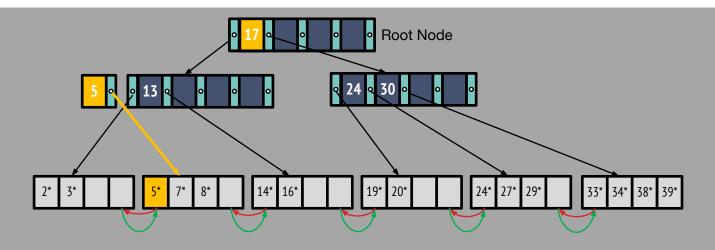
- Copy up from leaf the middle key
- No room in parent? Recursively split index nodes
 - Redistribute the rightmost d keys

Inserting 8* into a B+ Tree: Root Grows Up



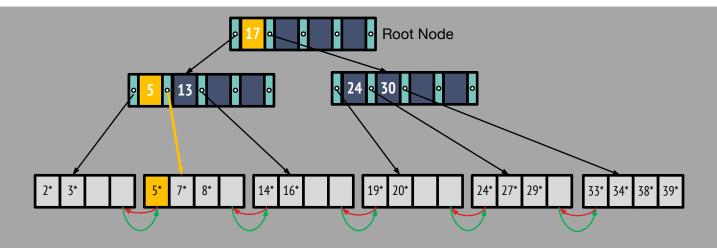
- Push up from interior node the middle key
 - Now the last key on left
- No room in parent? Recursively split index nodes
 - Redistribute the rightmost d keys

Inserting 8* into a B+ Tree: Root Grows Up, Pt 2



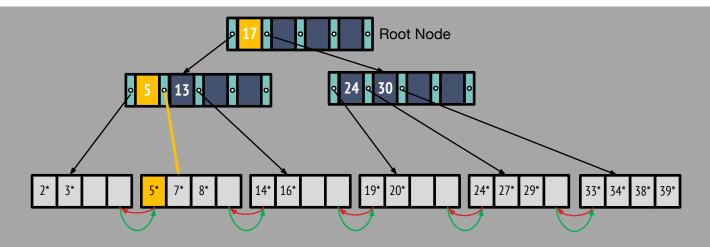
- Recursively split index nodes
 - Redistribute right d keys
 - Push up middle key

Inserting 8* into a B+ Tree: Root Grows Up, Pt 3



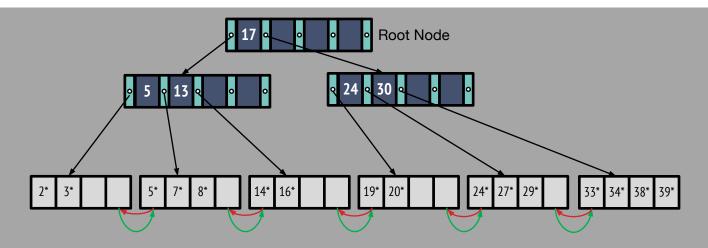
- Recursively split index nodes
 - Redistribute right d keys
 - Push up middle key

Copy up vs Push up!



- Notice:
 - The leaf entry (5) was copied up
 - The index entry (17) was pushed up

Inserting 8* into a B+ Tree: Final



- Check invariants
- **Key Invariant:**
 - Node[..., (K_L, P_L), ...] →
 K_L<= K for all K in P_L Sub-tree
- Occupancy Invariant:
 - d <= # entries <= 2d

B+ Tree Insert: Algorithm Sketch

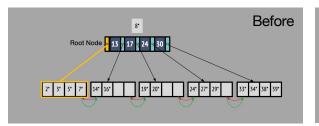
- Find the correct leaf L.
- Put data entry onto L.
 - If L has enough space, done!
 - Else, must split L (into L and a new node L2)
 - Redistribute entries evenly, copy up middle key
 - Insert index entry pointing to L2 into parent of L.

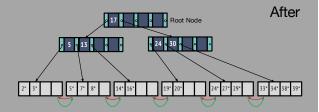
B+ Tree Insert: Algorithm Sketch Part 2

- Step 2 can happen recursively
 - To split index node, redistribute entries evenly, but push up middle key. (Contrast with leaf splits)
- Splits "grow" tree; root split increases height.
 - Tree growth: gets wider or one level taller at top.

Before and After Observations

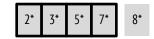
- Notice that the root was split to increase the height
 - Grow from the root not the leaves
 - All paths from root to leaves are equal lengths
- Does the occupancy invariant hold?
 - Yes! All nodes (except root) are at least half full
 - Proof?



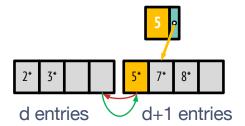


Splitting a Leaf

- Start with full leaf (2d) entries (let d = 2)
 - Add a 2d + 1 entry (8*)



- Split into leaves with (d, d+1) entries
 - Copy key up to parent
- Why copy key and not push key up to parent?



Splitting an Inner Node

- Start with full interior node (2d) entries: (let d = 2)
 - Add a 2d + 1 entry



- Split into nodes with (d, d+1) entries
 - Push key up to parent



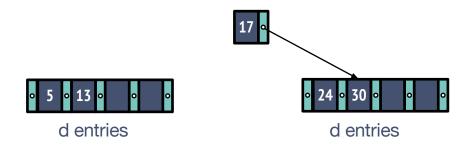


Splitting an Inner Node Pt 2

- Start with full interior node (2d) entries: (let d = 2)
 - Add a 2d + 1 entry



- Split into nodes with (d, d) entries
 - Push key up to parent



Splitting an Inner Node Pt 3

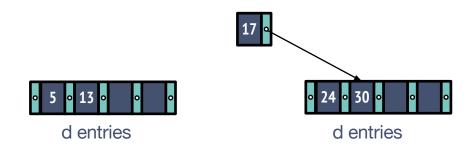
- Start with full interior node (2d) entries: (let d = 2)
 - Add a 2d + 1 entry



- Why push not copy?
 - Routing key not needed in child

Occupancy invariant holds after split

- Split into nodes with (d, d) entries
 - Push key up to parent



B+-TREE DELETION

We will skip deletion

- In practice, occupancy invariant often not enforced
- Just delete leaf entries and leave space
- If new inserts come, great
 - This is common
- If page becomes completely empty, can delete
 - Parent may become underfull
 - That's OK too
- Guarantees still attractive: log_F(max size of tree)

Nice Animation Online

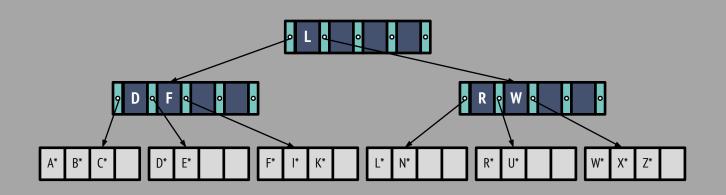
- Great animation online of B+ Trees
- One small difference to note
 - Upon deletion of leftmost value in a node, it updates the parent index entry
 - Incurs unnecessary extra writes

BULK LOADING B+-TREES

Bulk Loading of B+ Tree Part 1

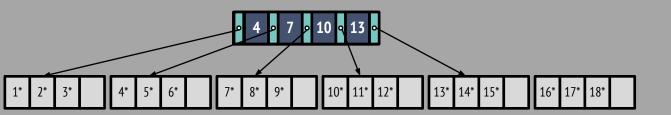
- Suppose we want to build an index on a large table
- Would it be efficient to just call insert repeatedly
 - No ... Why not?
 - Random Order: CLZARNDXEKFWIUB. Order 2.
 - Try it: Interactive demo

Bulk Loading of B+ Tree Part 2



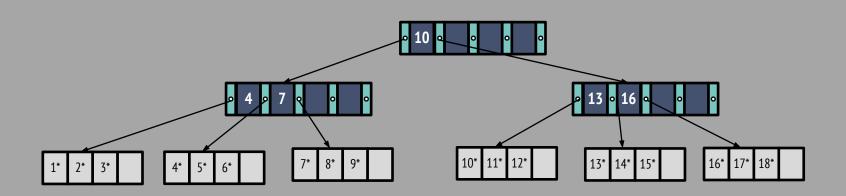
- Constantly need to search from root
- Leaves and internal nodes mostly half-empty
- Modifying random pages: poor cache efficiency

Smarter Bulk Loading a B+ Tree



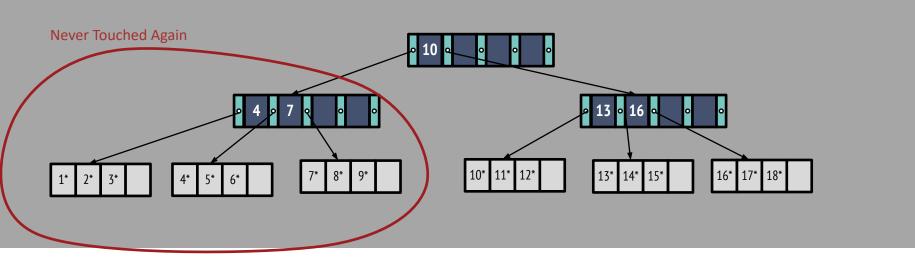
- Sort the input records by key:
 - 1*, 2*, 3*, 4*, ...
 - We'll learn a good disk-based sort algorithm soon!
- Fill leaf pages to some fill factor (e.g. ¾)
 - Updating parent until full

Smarter Bulk Loading a B+ Tree Part 2



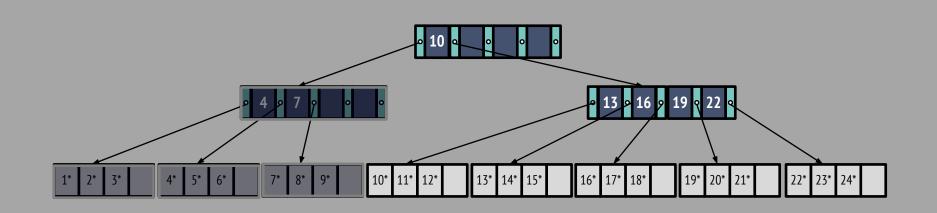
- Sort the input records by key:
 - 1*, 2*, 3*, 4*, ...
- Fill leaf pages to some fill factor (e.g. ¾)
 - Update parent until full
 - Then split parent (50/50) and copy to sibling

Smarter Bulk Loading a B+ Tree Part 3



- Lower left part of the tree is never touched again
- Occupancy invariant maintained

Smarter Bulk Loading a B+ Tree Part 4



- Sort the input records by key:
 - 1*, 2*, 3*, 4*, ...
- Fill leaf pages to some fill factor (e.g. ¾)
 - Update parent until full
 - Then split parent

Summary of Bulk Loading

- Option 1: Multiple inserts
 - Slow
 - Does not give sequential storage of leaves
- Option 2: Bulk Loading
 - Fewer I/Os during build. (Why?)
 - Leaves will be stored sequentially (and linked, of course)
 - Can control "fill factor" on pages.

Summary

- ISAM is a static structure
 - Only leaf pages modified; overflow pages needed
 - Overflow chains can degrade performance unless size of data set and data distribution stay constant

B+ Tree is a dynamic structure

- Inserts/deletes leave tree height-balanced; log_FN cost
- High fanout (F) means depth rarely more than 3 or 4.
- Almost always better than maintaining a sorted file.
- Typically, 67% occupancy on average
- Usually preferable to ISAM; adjusts to growth gracefully.

Summary Cont.

- Bulk loading can be much faster than repeated inserts for creating a B+ tree on a large data set.
- B+ tree widely used because of its versatility
 - One of the most optimized components of a DBMS.
 - Concurrent Updates
 - In-memory efficiency